



# Operation Manual

PRODUCT NAME

Magnet Gripper for Collaborative Robots

MODEL / Series / Product Number

MHM-25D-X7400A-(DTP/HC10DT/HC10)-(N/P)

**SMC Corporation**

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# Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of "Caution," "Warning" or "Danger." They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC)\*1), and other safety regulations.

\*1) ISO 4414: Pneumatic fluid power -- General rules relating to systems.

ISO 4413: Hydraulic fluid power -- General rules relating to systems.

IEC 60204-1: Safety of machinery -- Electrical equipment of machines.(Part 1: General requirements)

ISO 10218: Manipulating industrial robots -Safety.

etc.



**Caution**

**Caution** indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.

**Warning**

**Warning** indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.

**Danger**

**Danger** indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.

## Warning

### **1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications.**

Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results.

The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product.

This person should also continuously review all specifications of the product referring to its latest catalog information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

### **2. Only personnel with appropriate training should operate machinery and equipment.**

The product specified here may become unsafe if handled incorrectly.

The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained and experienced.

### **3. Do not service or attempt to remove product and machinery/equipment until safety is confirmed.**

1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.

2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions

of all relevant products carefully.

3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.

### **4. Contact SMC beforehand and take special consideration of safety measures if the product is to be used in any of the following conditions.**

1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.

2. Installation on equipment in conjunction with atomic energy, railways, air navigation, space, shipping, vehicles, military, medical treatment, combustion and recreation, or equipment in contact with food and beverages, emergency stop circuits, clutch and brake circuits in press applications, safety equipment or other applications unsuitable for the standard specifications described in the product catalog.

3. An application which could have negative effects on people, property, or animals requiring special safety analysis.

4. Use in an interlock circuit, which requires the provision of double interlock for possible failure by using a mechanical protective function, and periodical checks to confirm proper operation.



# Safety Instructions

## **Caution**

**The product is provided for use in manufacturing industries.**

The product herein described is basically provided for peaceful use in manufacturing industries.

If considering using the product in other industries, consult SMC beforehand and exchange specifications or a contract if necessary.

If anything is unclear, contact your nearest sales branch.

## **Limited warranty and Disclaimer/Compliance Requirements**

The product used is subject to the following "Limited warranty and Disclaimer" and "Compliance Requirements".

Read and accept them before using the product.

### **Limited warranty and Disclaimer**

1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered, whichever is first.

Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.

2. For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided.

This limited warranty applies only to our product independently, and not to any other damage incurred due to the failure of the product.

3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalog for the particular products.

### **Compliance Requirements**

1. The use of SMC products with production equipment for the manufacture of weapons of mass destruction (WMD) or any other weapon is strictly prohibited.

2. The export of SMC products or technology from one country to another is governed by the relevant security laws and regulations of the countries involved in the transaction. Prior to the shipment of an SMC product to another country, ensure that all local rules governing that export are known and followed.

## **Caution**

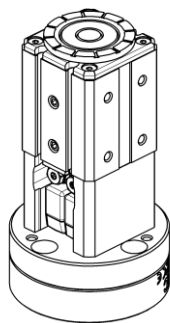
**SMC products are not intended for use as instruments for legal metrology.**

Measurement instruments that SMC manufactures or sells have not been qualified by type approval tests relevant to the metrology (measurement) laws of each country.

Therefore, SMC products cannot be used for business or certification ordained by the metrology (measurement) laws of each country.

# 1. List of included items

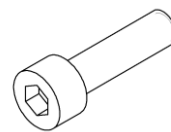
MHM-25D-X7400A-DTP



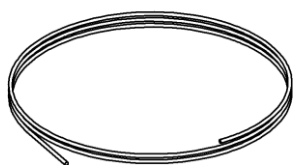
Magnet gripper 1pc.



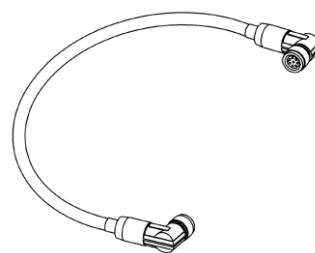
Positioning pin (6x10) 1pcs.  
For positioning the product.



Hexagon socket head cap  
screw (M6x23) 4pcs.  
For mounting the product.



Polyurethane Tube for piping  $\phi 4$   
(TU0425BU-100) 2m



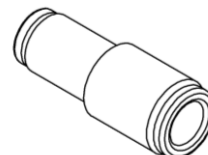
Conversion cable 1pc.



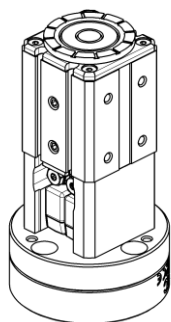
One touch fittings  
(KQ2L04-M5A1) 2pcs.



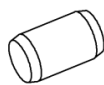
One touch fittings  
(KQ2L06-08A) 1pc.



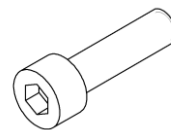
One touch fittings  
(KQ2H04-06A) 1pc.



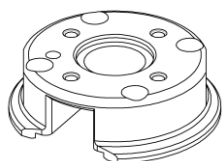
Magnet gripper 1pc.



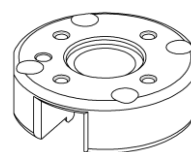
Positioning pin (6x10) 1pcs.  
For positioning the product.



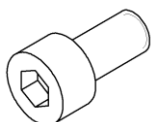
Hexagon socket head cap  
screw (M6x23) 4pcs.  
For mounting the product



Flange for MOTOMAN-HC10 1pc.  
\* For MHM-25D-X7400A-HC10-(\*).



Flange for MOTOMAN-HC10DT 1pc.  
\* For MHM-25D-X7400A-HC10DT-(\*).



Hexagon socket head cap screw (M6x12) 4pcs.  
For mounting the flange.



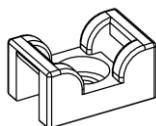
Parallel pin (6x10mm) 1pc.  
For positioning the flange.



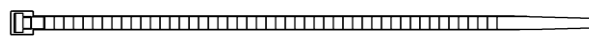
Cross recessed resin round head screw (M4x6) 2pcs.  
For plugging when INSULOK® cable tie fixtures  
are not used.



Hexagon socket head cap screw  
(M4x8) 2pcs.  
For fixing INSULOK® tie mount.



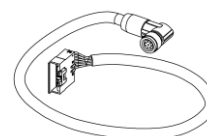
INSULOK® tie mount 2pcs.



INSULOK® tie 2pcs.



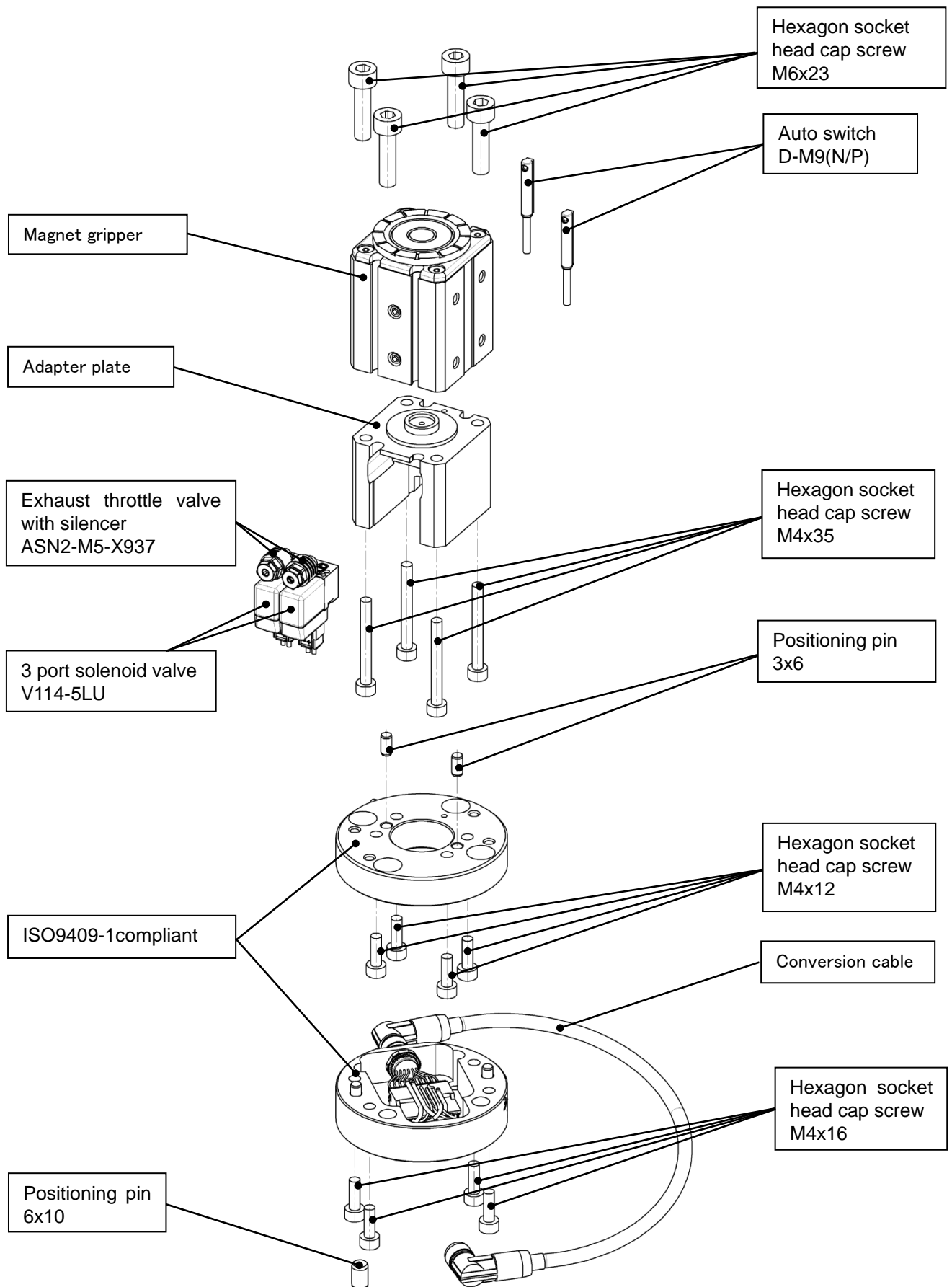
Poriurethane tube for piping  $\phi 4$   
(TU0425BU-100) 2m.

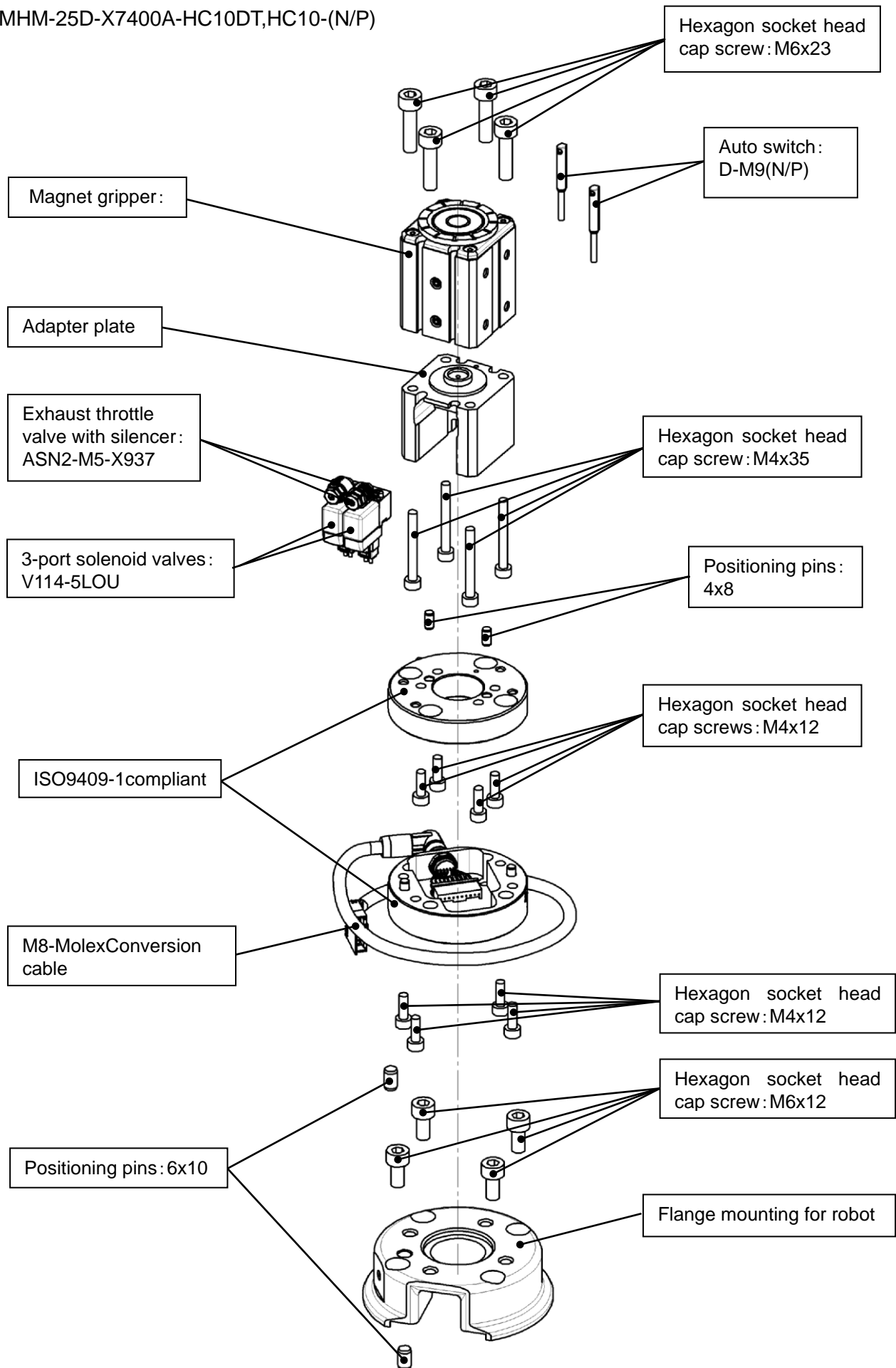


M8-Molex Conversion cable 1pc.

## 2. Parts description of the magnet gripper

MHM-25D-X7400A-DTP-(N/P)







### 3. Product Specifications

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#### 3-1. How to order

MHM - 25 D - X7400A - DTP - N

● Bore size

φ25

● Compatible robot

DTP	MOTOMAN-HC10DTP,HC20DTP,HC20SDTP
HC10DT	MOTOMAN-HC10DT
HC10	MOTOMAN-HC10

● Auto switch output method

No.	Auto switch No.	Medium	QTY
N	D-M9N	NPN	2
P	D-M9P	PNP	2

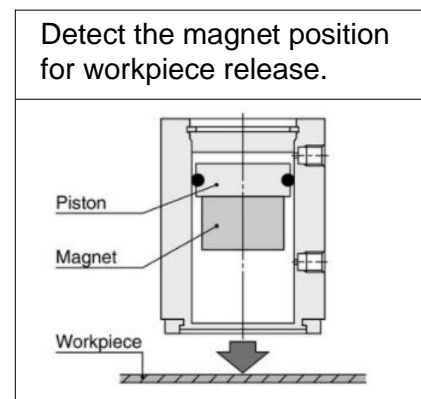
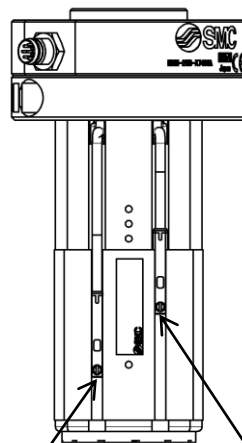
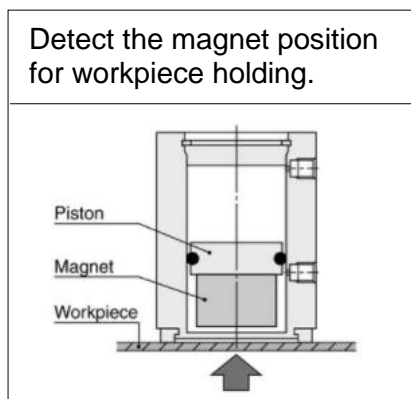
## 3-2. Specifications

### Specifications

		MHM-25D-X7400A -DTP-(N/P)	MHM-25D-X7400A -HC10DT-(N/P)	MHM-25D-X7400A -HC10-(N/P)
Fluid		Air		
Operating method		Double acting		
Operating pressure (MPa)		0.2 to 0.6MPa		
Proof pressure		0.9MPa		
Ambient and operating fluid temperature(°C)		-10 to 50(No freezing)		
Gripping Force *1	Workpiece thickness:2mm	160N		
	Workpiece thickness:6mm	200N		
Residual holding force		0.3 N or less		
Lubrication		Non-lube		
Weight (g)		590g	820g	
Connector configuration of the accessory		Both side M8 8 pin connector (Socket)	One side M8 8 pin connector(Socket) One side Connector made by MOLEX(51227-0800)	

\*1 Theoretical holding force (reference value) when a low carbon steel plate is held by entire surface attraction surface

\*2 In the default setting, the auto switch is fixed at the workpiece release position.



Detection location at workpiece holding position.

Detection location at workpiece release position.

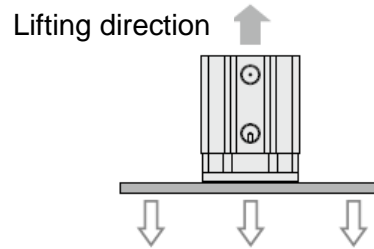
\* For examples of setting auto switch and setting of mounting position of auto switches, please refer to the MHM Series catalogue P.12 onwards on our website ([www.smcworld.com](http://www.smcworld.com)).

\* Auto switches are used for checking the operation of the magnet gripper. They do not guarantee the actual holding and release of the workpiece. For checking the holding / release of the workpiece, a proximity sensor should be mounted separately.

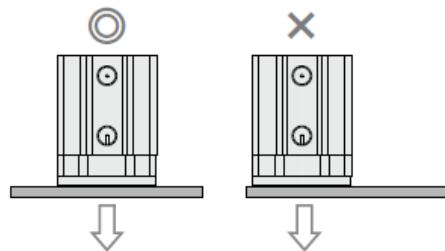
### 3-3. Gripping force

Holding conditions.

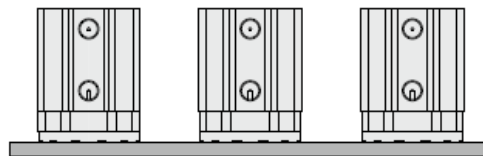
- To lift workpieces vertically, be sure to take into consideration the acceleration rate, air pressure, impact etc., in addition to the mass of the workpieces.



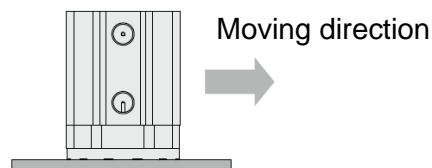
- Consider the center of gravity of the workpiece to avoid moments being applied the magnet gripper as much as possible.



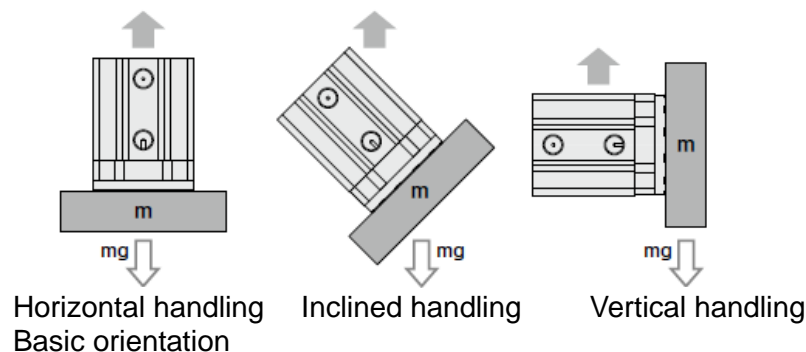
- If multiple magnet grippers are used for transferring a workpiece with a large surface area, properly allocate the magnet grippers to maintain balance.



- Horizontal movement of the magnet gripper may cause sideslip of the workpiece depending on the acceleration or friction coefficient between the pad and workpiece. Therefore, the acceleration rate of the lateral movement must be minimized.



- Use the magnet gripper for horizontal handling. Adequate safety factor needs to be considered for inclined handling or vertical



- Thin workpieces may be deformed during transportation. It is recommended to use multiple magnet grippers for scenarios such as this.

Calculate the required holding force.

$$W = S \frac{mg}{n}$$

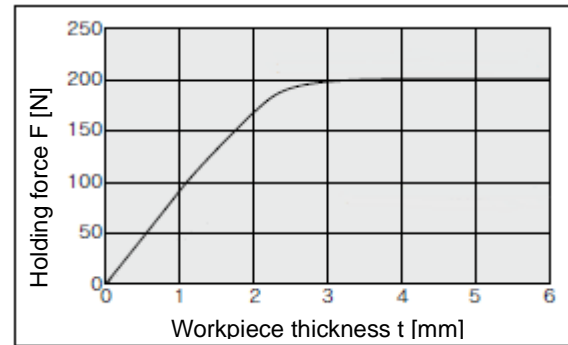
**W**: Required holding force

**n** : Number of magnet grippers [pcs.]

**m**: Workpiece mass [kg]

**g** : Gravitational acceleration [= 9.8 m/s<sup>2</sup>]

**S** : Safety factor Horizontal lifting: 4 or more

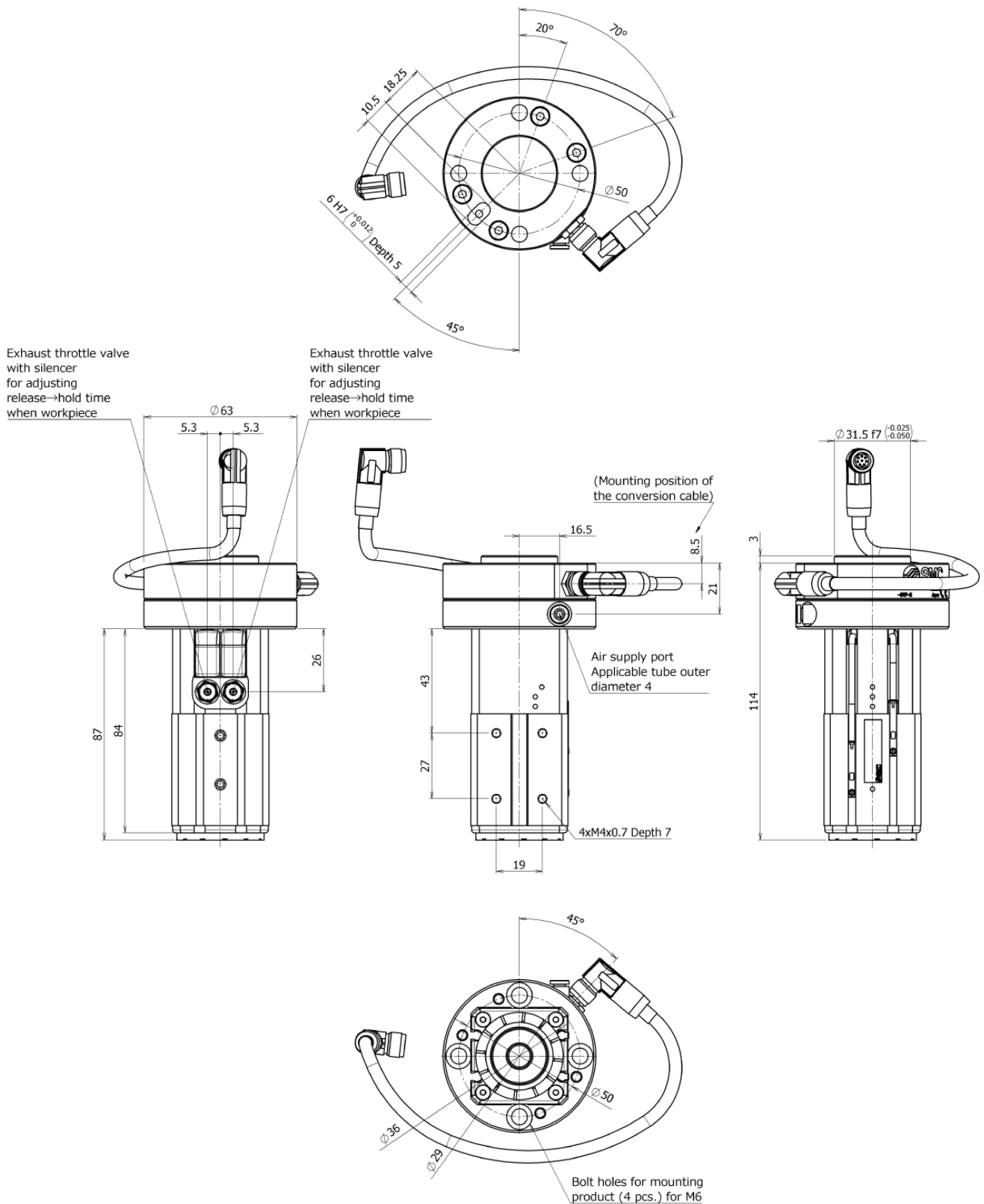


The holding force graph shows the theoretical value for low carbon steel plate. Holding forces very depending on the material and shape of the workpiece. Please perform a holding test referring to the value selected based on the graph.

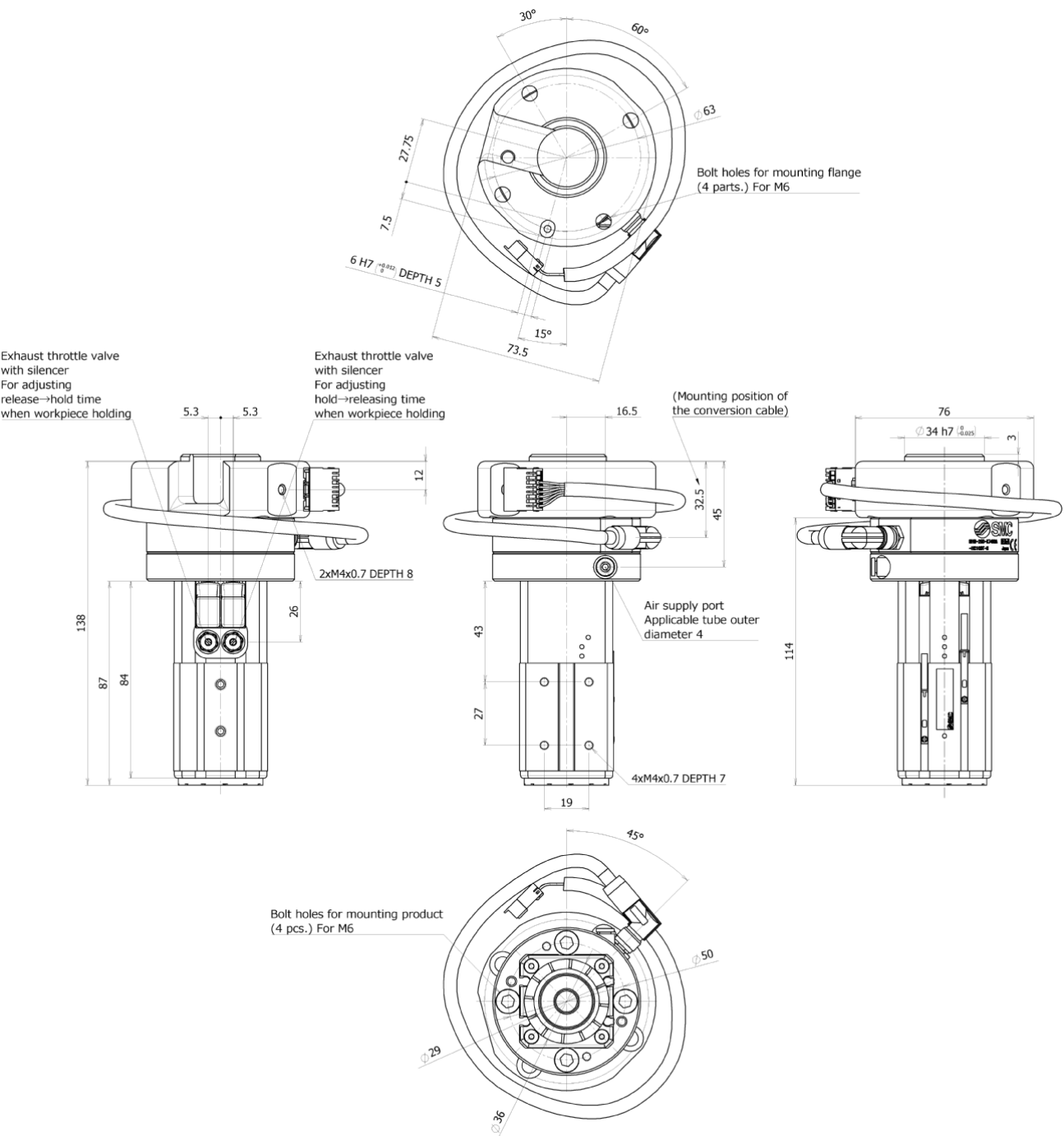
### 3-4. Dimensions

Refer to P17, P18 and P19 for the dimensions of the magnet gripper, valves and auto switches.

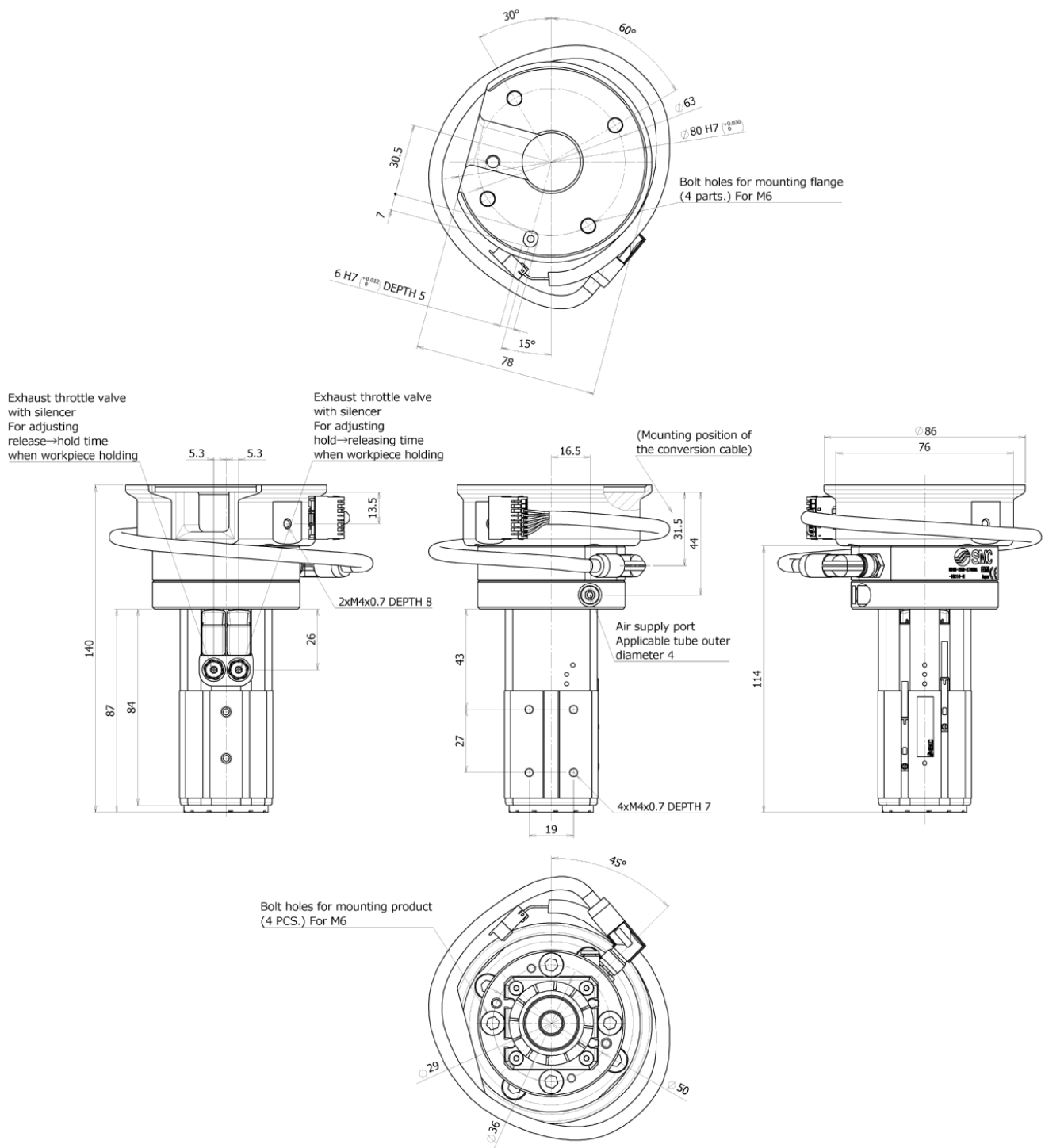
#### 3-4-1.MHM-25D-X7400A-DTP-(N/P)



3-4-2.MHM-25D-X7400A-HC10DT



### 3-4-3.MHM-25D-X7400A-HC10

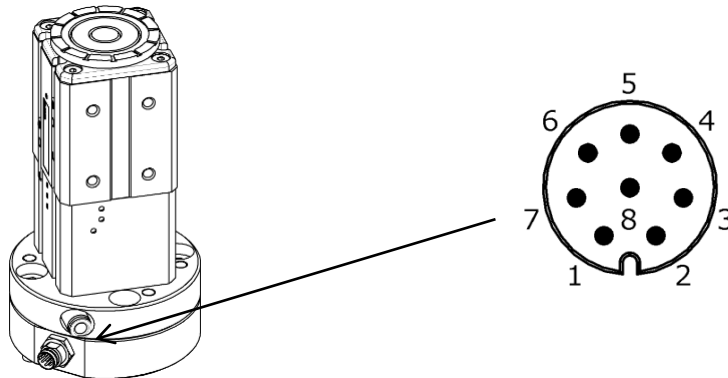


### 3-5. Connector and pin layout

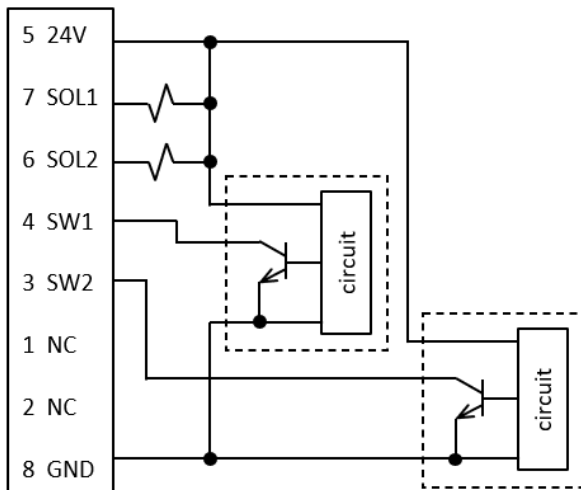
Attached cable is fixed to the product.

Connect the communication cable correctly. Refer to P. for assembling method.

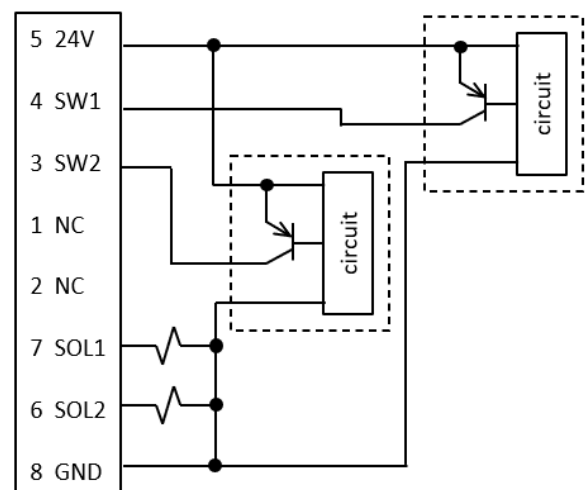
#### 3-5-1. MHM-25D-X7400A-DTP-(N/P)



NPN output

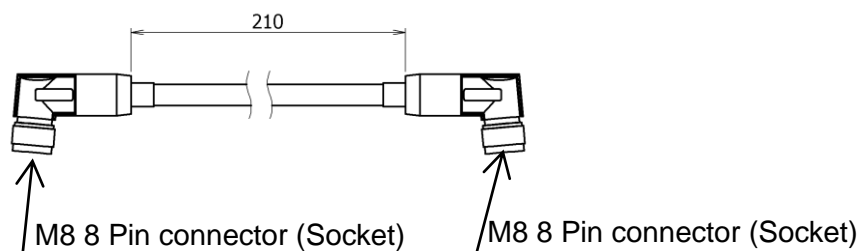


PNP output



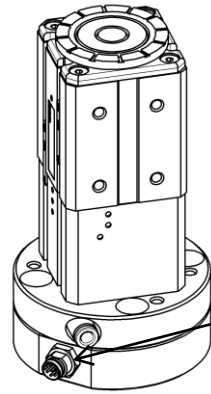
PIN No.	Function	Explanation
1	-	
2	-	
3	Auto switch(For holding workpiece)	-
4	Auto switch(For releasing workpiece)	-
5	+24V	Power supply for 24 VDC
6	Valve ON/OFF(For holding workpiece)	-
7	Valve ON/OFF(For releasing workpiece)-	
8	GND	Power supply for 0 VDC

Conversion cable

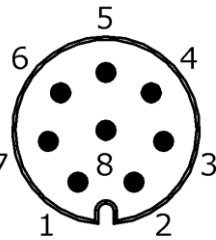




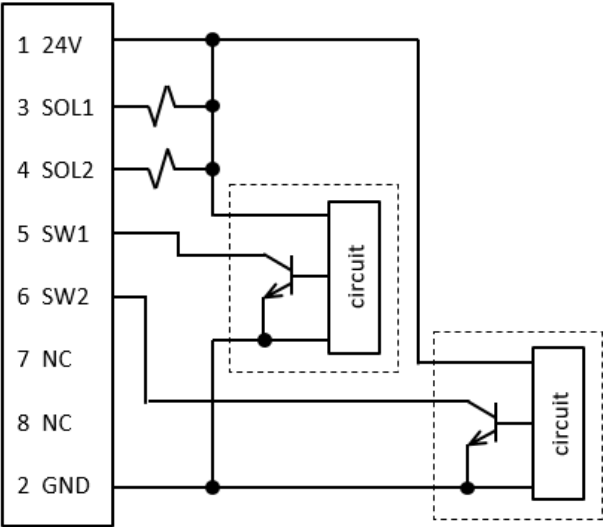
3-5-2. MHM-25D-X7400A-(HC10DT,HC10)-(N/P)



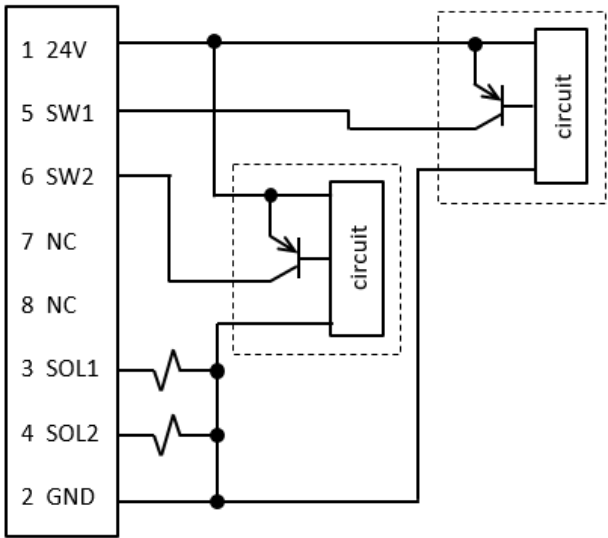
M8 8 Pin connector (plug)



NPN output

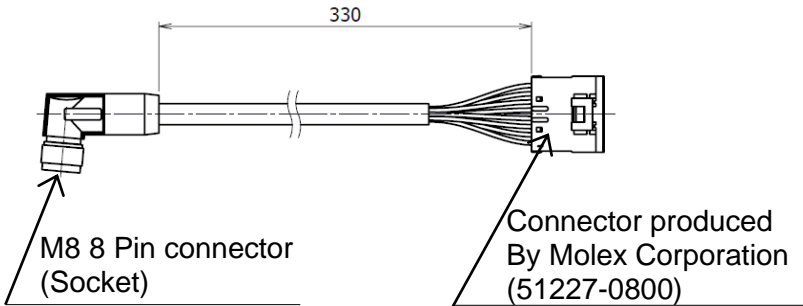


PNP output

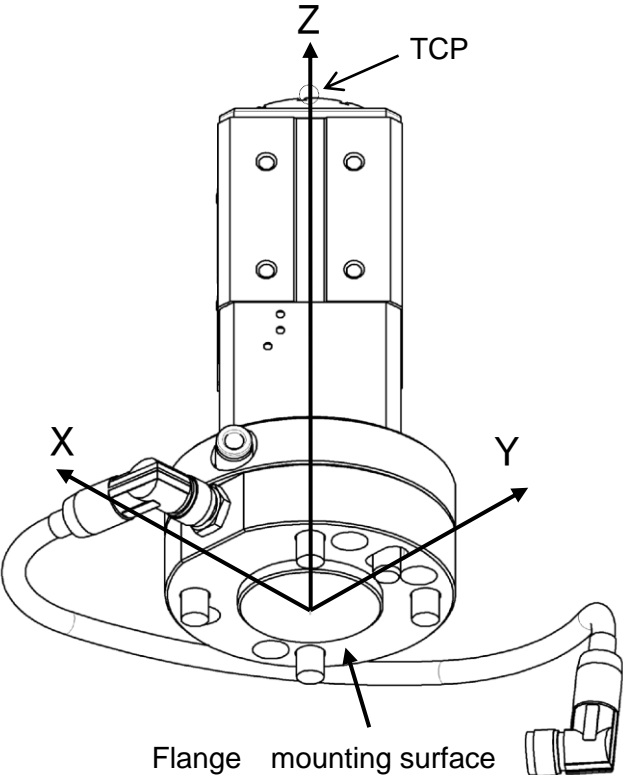


PIN No.	Function	Explanation
1	+24V	Power supply for 24 VDC
2	GND	Power supply for 0 VDC
3	Valve ON/OFF(For releasing workpiece)	-
4	Valve ON/OFF(For holding workpiece)	-
5	Auto switch(For releasing workpiece)	-
6	Auto switch(For holding workpiece)	-
7	-	
8	-	

Conversion cable



3-6. Center of gravity



\*MHM-25D-X7400A-DTP

	MHM-25D-X7400A-DTP			MHM-25D-X7400A-HC10DT			MHM-25D-X7400A-HC10		
Center of gravity(mm)	X	Y	Z	X	Y	Z	X	Y	Z
	2.4	0.0	42.6	1.0	-0.4	57.1	1.0	-0.4	57.9
Tool Center Point(TCP)	X	Y	Z	X	Y	Z	X	Y	Z
	0	0	114	0	0	138	0	0	140

## 4. Product Specifications

\* For detailed specifications not included in this document, please refer to the our website ([www.smcworld.com](http://www.smcworld.com)) or operation manual.

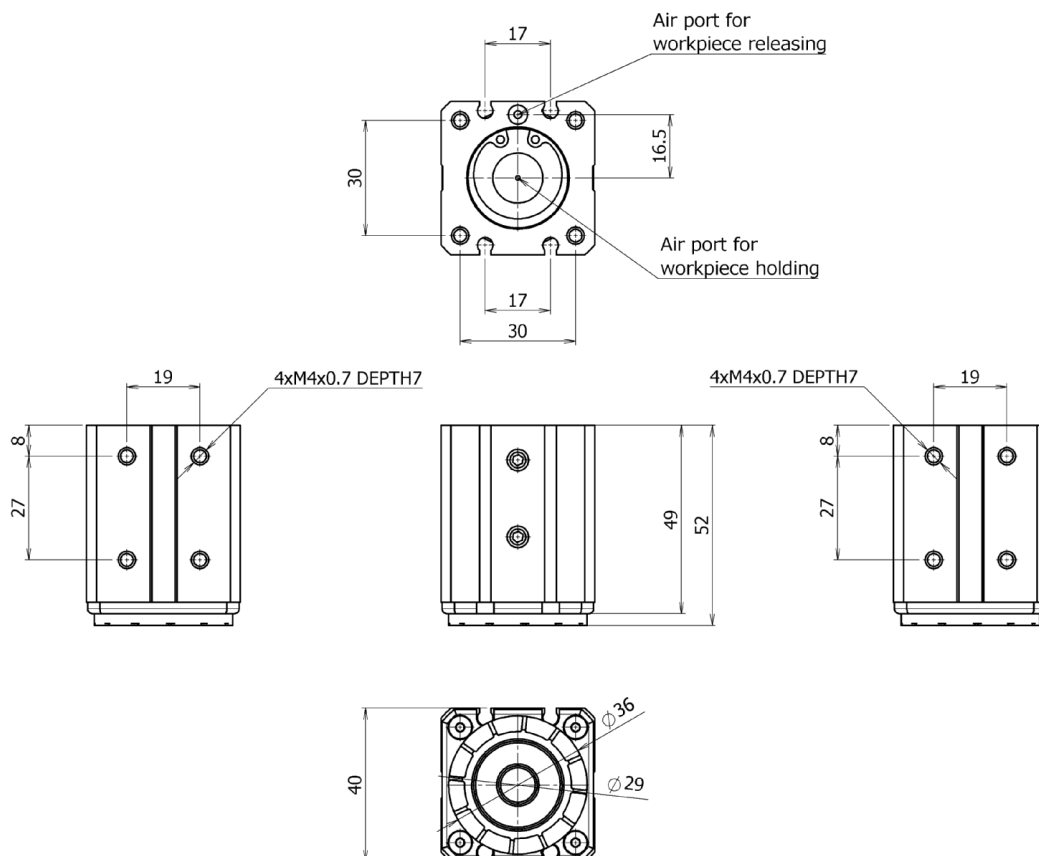
### 4-1. Magnet gripper

#### Specifications

Fluid		Air
Operating pressure [MPa]		0.2 to 0.6
Operating method		Double acting
Proof pressure		0.9MPa
Ambient and operating fluid temperature(°C)		-10 to 60
Gripping force *	Workpiece thickness:2mm	160N
	Workpiece thickness:6mm	200N
Residual holding force		0.3 N or less
Lubrication		Non-lube

\*1 Theoretical holding force (reference value) when a low carbon steel plate is held by entire surface attraction surface

Dimensions.



#### ⚠ Caution

This special magnet gripper cannot be replaced with MHM-25D because the piping direction is different.

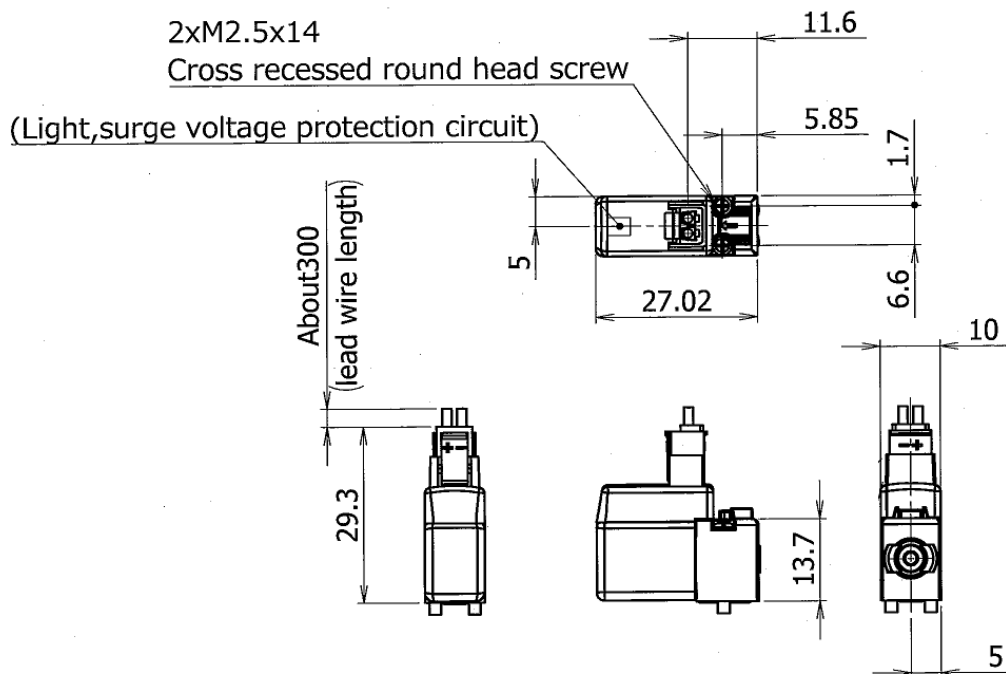
## 4-2. 3-port solenoid valve

### Specifications

Model No.	V114-5LOU
Fluid	Air
Ambient and operating fluid temperature(°C)	-10 to 50 (No freezing)
Response time [ms]	ON : 5 or less OFF : 4 or less
Minimum operation frequency [Hz]	20
Lubrication	Non-lube
Mounting orientation	Free
Impact resistance/Vibration resistance (m/s <sup>2</sup> )	150/30
Enclosure rating	Dustproof

### Solenoid specifications

Model No.	V114-5LOU
Electrical entry	L shaped plug connector (L)
Coil rated voltage [V]	24
Allowable voltage fluctuation	-10 to 10%
Power consumption [W]	0.4 [Starting 0.4,Holding 0.1]
Surge voltage suppressor	Varistor
Indicator LED	LED



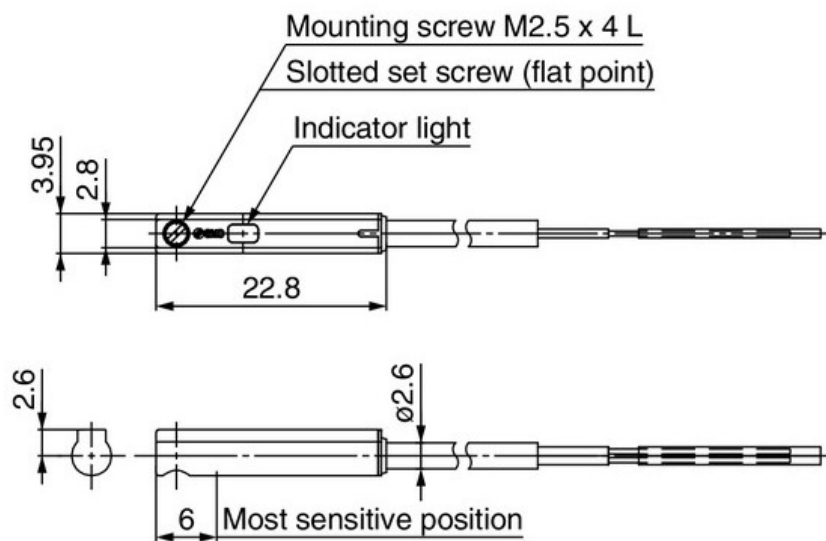
### 4-3. Auto switch

#### Auto Switch Specifications

D-M9□(With indicator light)		
Auto switch model	D-M9N	D-M9P
Electrical entry direction	In-line	
Wiring	3-wire	
Output	NPN type	PNP type
Applicable load	IC circuit, Relay, PLC	
Power supply voltage	DC5 · 12 · 24V(4.5 to 28V)	
Current consumption	10 mA or less	
Load voltage	DC28V or less	-
Load current	40 mA or less	
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)	
Current leakage	100 $\mu$ A or less at 24 VDC	
Indicator LED	Red LED illuminates when turned ON.	
Standard	CE marking、RoHS	

#### Dimensions

##### D-M9(N/P)



## 5. Operating method or operation

---

### 5-1. Precautions for Design



#### Warning

##### 1. Confirm the specifications.

Products represented in this catalog are designed only for use in compressed air systems (including vacuum). Do not operate at pressures, temperatures, etc., beyond the range of specifications, as this can cause damage or malfunction. (Refer to the specifications.) Please contact SMC when using a fluid other than compressed air (including vacuum). We do not guarantee against any damages if the product is used outside of the specification range.

##### 2. Take safety measures (e.g. mounting protective covers) when there is a danger of fingers being caught between the magnet gripper and the workpiece or with moving workpieces causing personal injury.

##### 3. Select a model whose holding force is compatible with the workpiece mass.

Expected holding force may not be obtained depending on the material or shape of the workpiece, please evaluate the safety against the fall of workpiece with actual machine.

##### 4. Do not use in applications where excessive external force or impact force may be applied to the gripper.

##### 5. Consider the possibility of a power source related malfunction.

Measures should be taken to prevent injury and equipment damage in the event that there is a power malfunction to equipment controlled by air pressure, electricity or hydraulics, etc.

##### 6. Consider the action of the product in the event of an emergency stop.

Devise a safe system so that if a person engages the emergency stop or if a safety device is tripped during a system malfunction, such as a power outage, the operation of the magnet gripper will not cause a hazard to humans or damage the equipment.

##### 7. Consider the action when operation is restarted after an emergency or abnormal stop.

Design machinery so that bodily injury or equipment damage will not occur upon the restart of operation.

##### 8. Do not disassemble the product or make any modifications, including additional machining.

Doing so may cause human injury and/or an accident.

##### 9. Refer to the Auto Switches Precautions (Web Catalog) if using with an auto switch.

##### 10. Risk to people with pacemakers

The product has a magnet inside. It may interfere with the use of an electronic equipment such as a pacemaker. People with pacemakers should stay away from the magnet gripper or take safety measures to block the magnetic force.

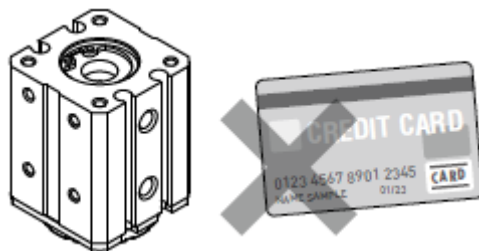


#### Caution

##### 1. If pressure is applied to the external magnet gripper parts, there is a possibility that air will get inside the cylinder from the rod seal section. ( Example : inside a chamber, etc.)

##### 2. Keep away from objects which are influenced by magnets.

As the body magnets are built-in, do not allow close contact with magnetic disks, magnetic cards, or magnetic tapes. Data may be erased.



## 5-2. Installation

### Warning

1. **Keep the manual in a safe place for future reference. The product should be mounted and operated only after thoroughly reading the operation manual and understanding its contents.**
2. **Ensure sufficient space for maintenance activities.**

When installing the products, allow access for maintenance and inspection.

3. **Observe the tightening torque for screws.**

Tighten the screws to the recommended torque for mounting the product.

4. **Do not place a magnetic object near the product.**

The auto switch is a magnetic sensing type product. If a magnetic object is placed close to it, the product could operate suddenly, which could pose a hazard to humans or damage the machinery and equipment. When the magnet grippers are used in parallel, keep the specified gap between them to avoid malfunction.

5. **Do not perform additional machining to the product.**

Additional machining to the product can result in insufficient strength and cause damage to the product. This can lead to possible human injury or damage to the surrounding equipment.

6. **Do not enlarge the fixed orifice by modifying the pipe connectors.**

If the fixed orifice is enlarged, the speed of switching between holding and releasing increases which results in higher impact forces. This may lead to damage to the product, which can lead to human injury and damage to other equipment and machinery.

7. **When the magnet moves toward the magnetic attraction surface, holding force is generated on the attraction surface, Make sure that holding force is not generated when working around the magnet gripper so that your fingers do not get caught in the magnet gripper.**

### Caution

1. **Do not scratch or dent the magnet gripper by dropping or bumping it when mounting.**

Even a slight deformation can cause malfunction.

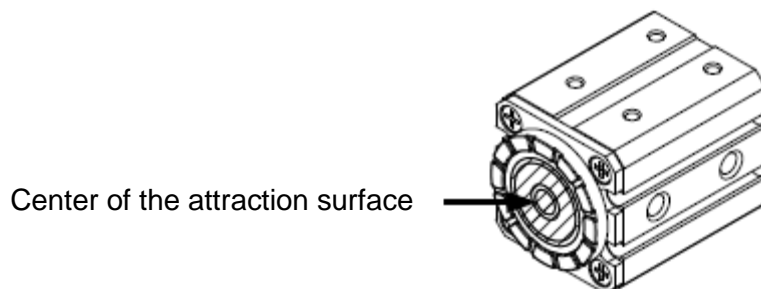
2. **Be careful with the magnetic attraction of parts of objects around the magnet gripper when mounting the magnet gripper while it is in its holding position (the piston is on the attraction side). They may cause injury.**

3. **When mounting the product, tighten it with screws of appropriate length at an appropriate torque.**

Tightening with a torque greater than the specified torque can cause malfunction, while insufficient tightening can cause slippage and dropping.

4. **Do not apply impact load to the center of the magnetic attraction surface.**

Otherwise, it may result in a breakage or malfunction.



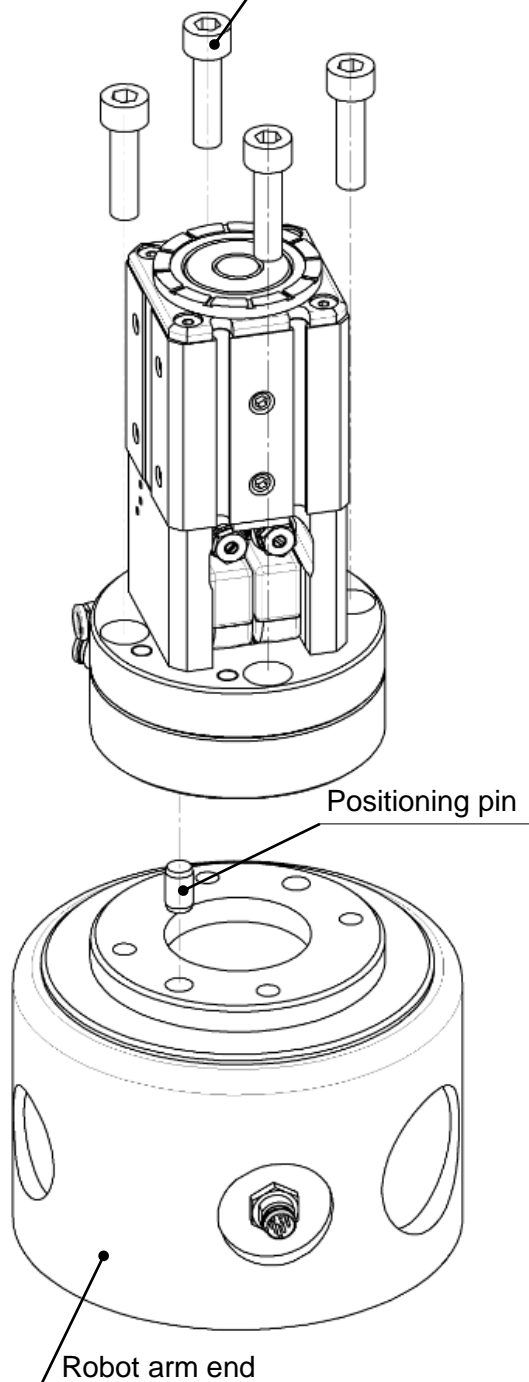
## How to Mount Magnet Gripper (MHM-25D-X7400A-DTP)

Mounting orientation: On robot arms adjust the robot arm position before mounting so that the mounting is easy.

### (1) Mounting to the robot arm.

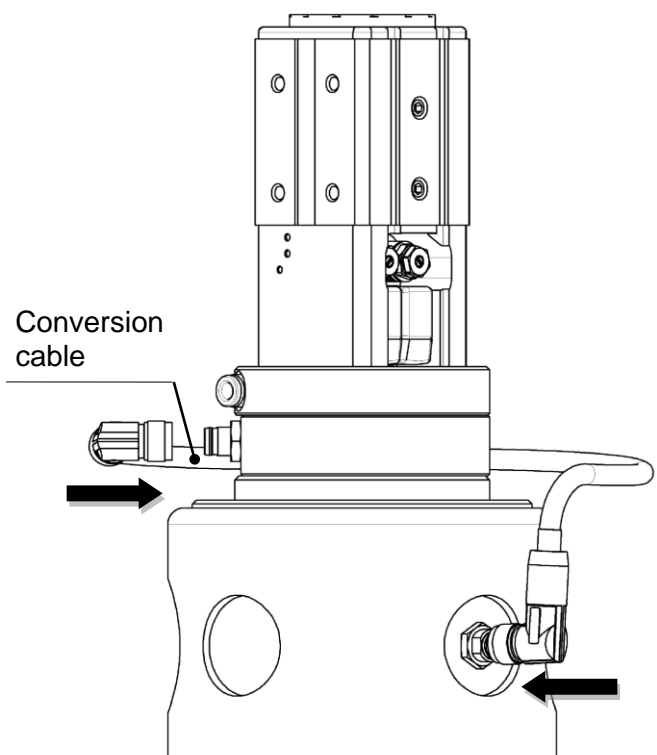
Hexagon socket head cap screw (M6 x 23)

Max. tightening torque :  
5.2Nm



### (2) Connecting the M8 connector

- Mount the conversion cable to the M8 connector.
- \* Do not energize while securing the connector.
- \* Check that the connector is not loose.





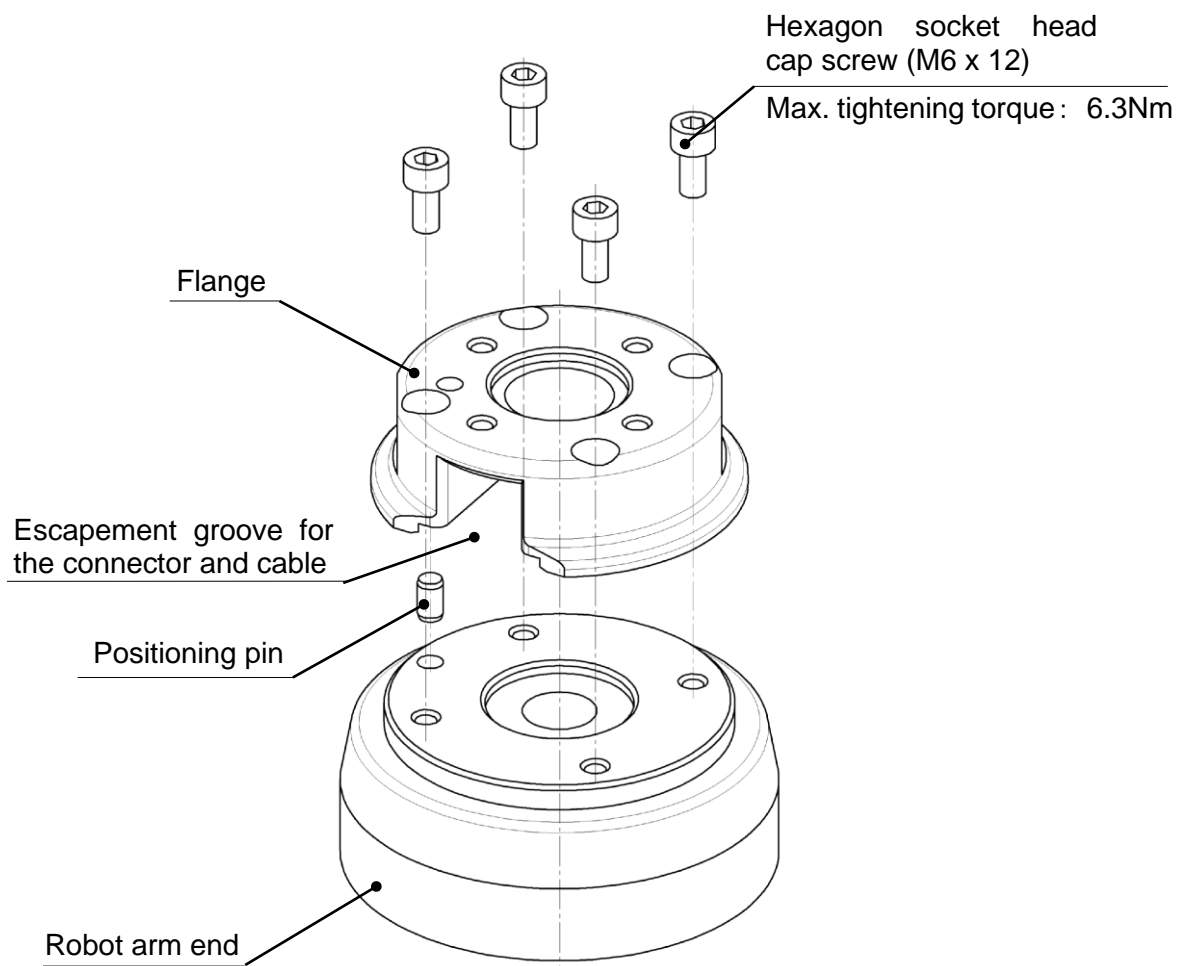
## How to Mount Magnet Gripper (MHM-25D-X7400A-HC10DT,HC10)

(1) Mounting orientation: On robot arms

Let the connectors and cables coming out of the end of the robot arm out of the escapement groove of the flange.

Make sure that the cable is not caught by the hexagon socket head cap screw when it is tightened.

\* The drawing shows the flange for MOTOMAN-HC10.



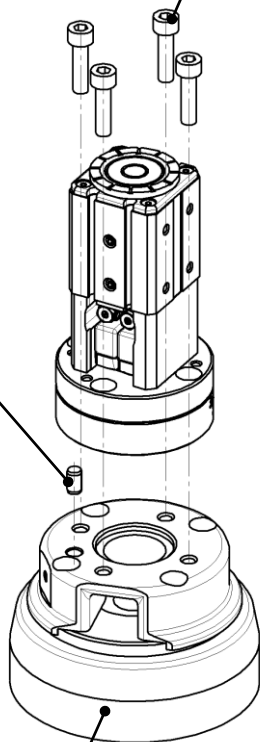
(2) Mounting to the robot arm.

Hexagon socket head  
cap screw (M6 x 23)

Max. tightening torque :  
5.2Nm

Positioning pin

Robot arm end



(3) Connecting the M8 connector

- Mount the conversion cable to the M8 connector.

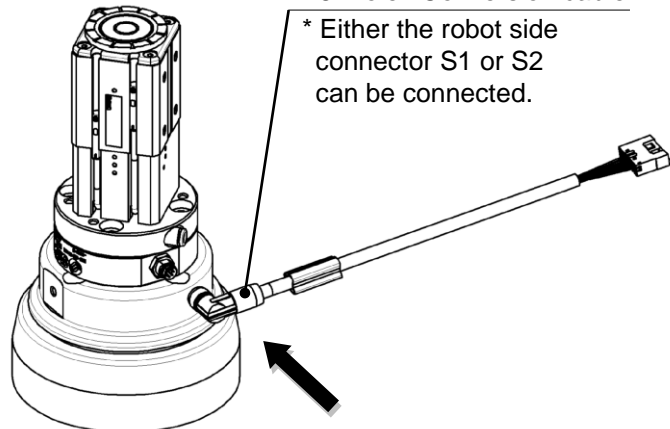
- After mounting the conversion cable, connect the robot arm end connector and conversion cable connector.

\* Do not energize while securing the connector.

\* Check that the connector is not loose.

M8-Molex Conversion cable

\* Either the robot side  
connector S1 or S2  
can be connected.



(4) Secure the cable

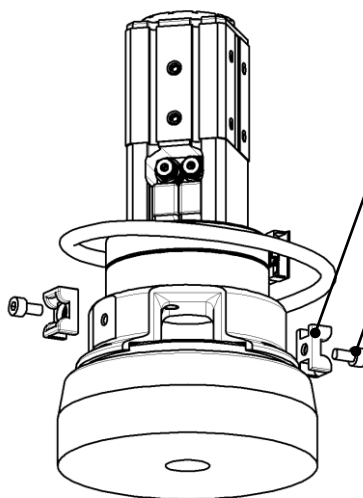
Cable is secured by the INSULOK® tie and cable tie mount included in the accessories.

\* After securing the table, cut off the excessive part of the INSULOK® tie.

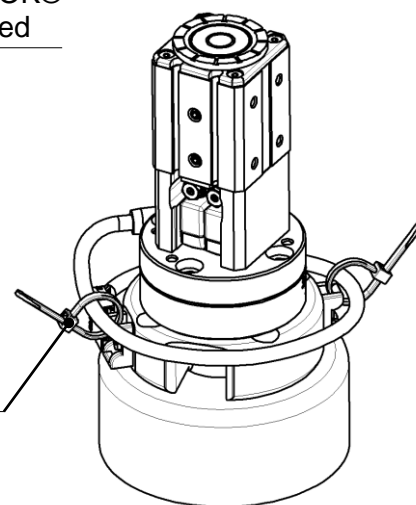
For plugging when INSULOK®  
cable tie fixtures are not used

Hexagon socket head  
cap screw (M4x8)

Max. tightening torque  
: 1.0Nm



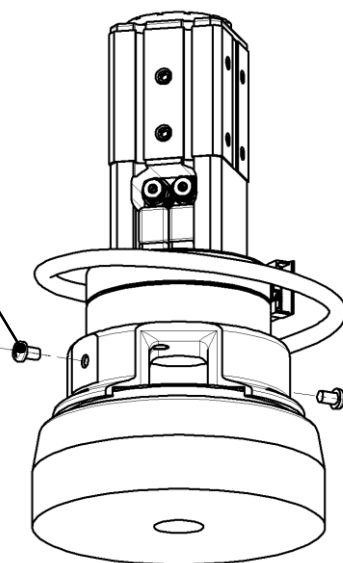
INSULOK® tie



\* Use a cross recessed resin round head screw (M4 x 6) as a plug when the INSULOK® cable tie is not used.

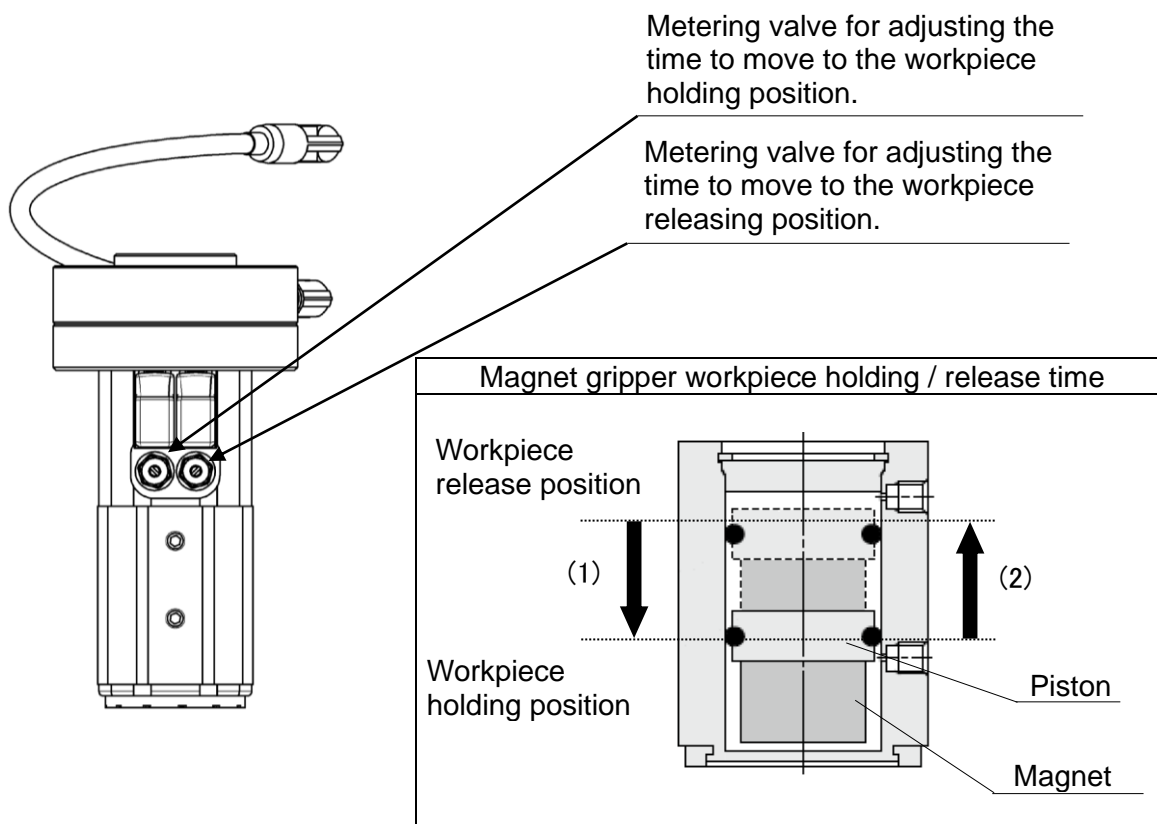
Cross recessed resin round head  
screw (M4x6)

Max. tightening torque  
1.0Nm

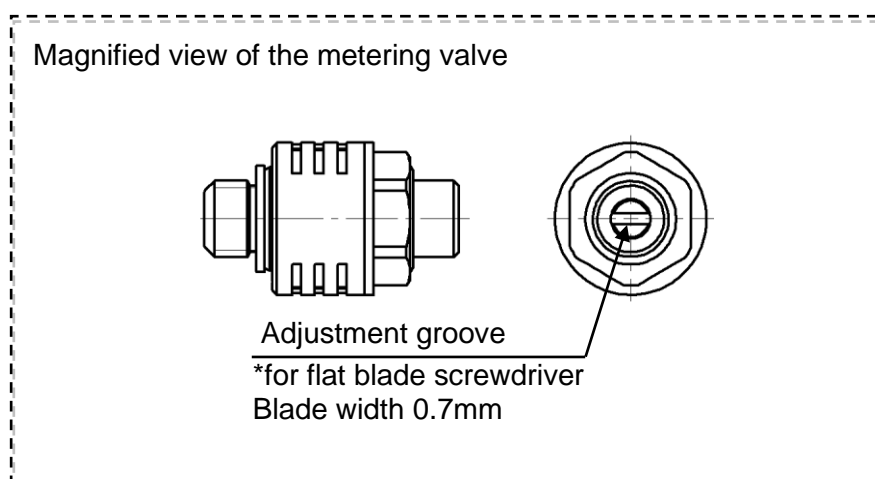


## Operation time adjustment method for holding / releasing the workpiece

The piston operation time during workpiece holding / release can be adjusted by adjusting the opening of the metering speed controller valve.



- \* (1) Workpiece holding time: Time required when the piston and magnet travel from the workpiece release position to the workpiece holding position
- \* (2) Workpiece release time: Time required when the piston and magnet travel from the workpiece holding position to the workpiece release position



- \* Use a flat blade screwdriver for adjusting the restriction of the metering valves.
- \* Keep the restriction of the two metering valves approximately the same. If they are different too much, the operation may become unstable.

### 5-3. YASKAWA Plug & Play Kit

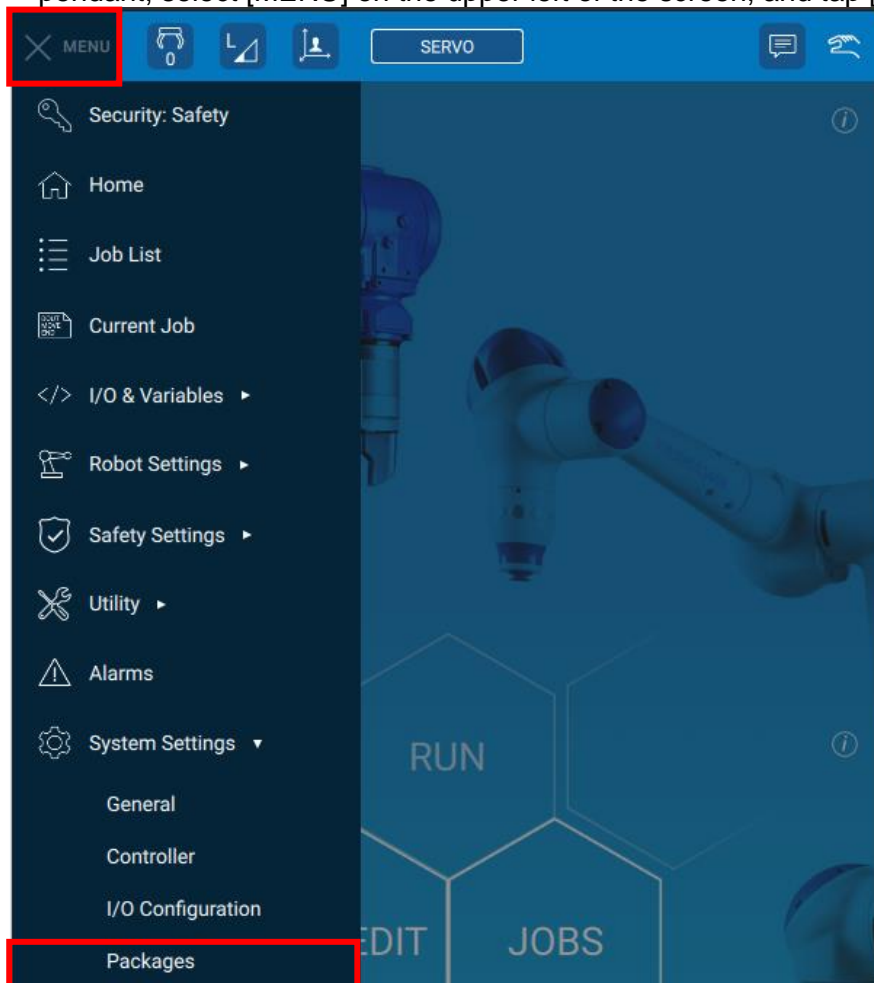
The YASKAWA Plug & Play Kit allows you to easily connect the magnet gripper to the robot and operate it.

#### 5-3-1. Installing YASKAWA Plug & Play Kit

The YASKAWA Plug & Play Kit is installed by means of the YASKAWA Installation Packages(.yip) file.

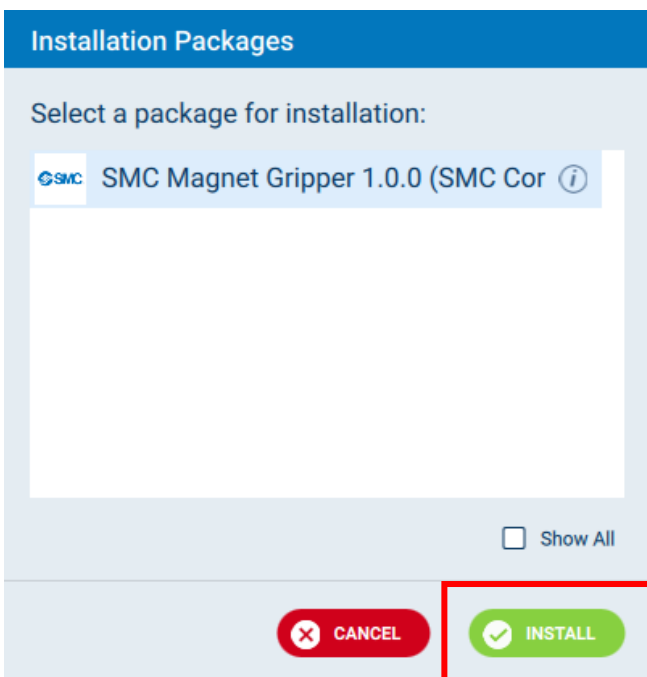
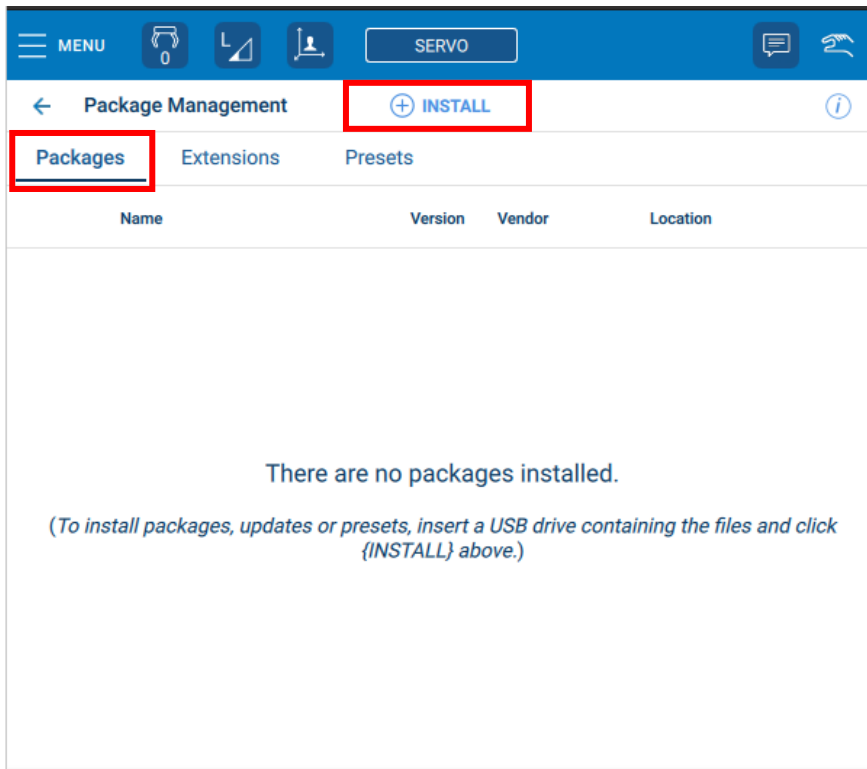
\* Set the security access level to the administration level.

- 1.Download YASKAWA Installation Packages “SmcMagnetGripperExt.yip” from the SMC website.
- 2.Copy the downloaded file to a USB memory stick, insert the stick to the USB port of the smart pendant, select [MENU] on the upper left of the screen, and tap [System settings] -> [Packages].



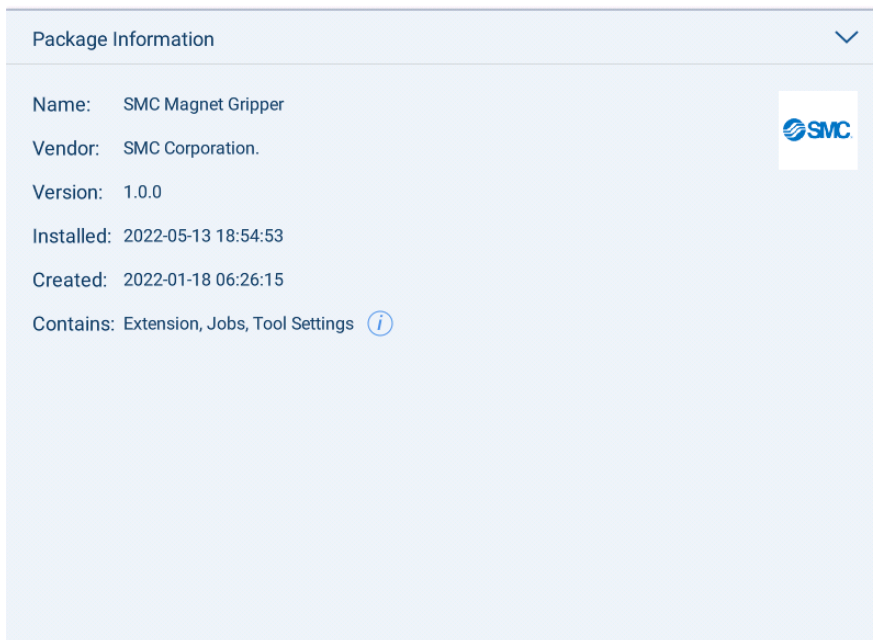
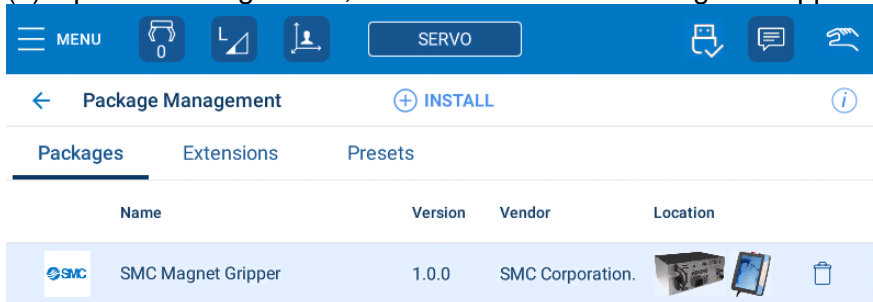
3. Open the “Packages” tab and tap [+INSTALL] at the upper part of the screen. A pop-up dialog box showing the installable packages will appear. From the package list, select “SMC Magnet Gripper” and install it.

Normally, when the installation has completed, the packages, extension, and tool presets are added to the appropriate list.



4. On the package administration screen, confirm that the installation has completed.

(1) Tap the “Packages” tab, and confirm that SMC Magnet Gripper is added to the list.



(2) Tap the “Extensions” tab, and confirm that the SMC Magnet Gripper is added to the list.

MENU

0

SERVO



Package Management

INSTALL

Packages

Extensions

Presets

Name	Version	Vendor	Status	
 SMC Magnet Gripper Extension	1.0.0	SMC Corporation.	<input type="radio"/>	

Extension Information


Name: SMC Magnet Gripper Extension

Vendor: SMC Corporation.

Version: 1.0.0

Status: Inactive

Enabled: ☒





(3) Tap the “Presets” tab, and confirm that SMC Magnet Gripper is added to the list.

MENU

0

SERVO



Package Management

INSTALL

Packages

Extensions

Presets

Name	Version	Vendor	
 SMC Magnet Gripper	1.0.0	SMC Corpor...	Tool 

Presets Information


Name: SMC Magnet Gripper

Type: Tool

ID: com.smc.gripper.mag.mhm.tools

Vendor: SMC Corporation.

Version: 1.0.0



EXPORT

## 5-3-2. Tool Presets

When you select 'SMC Magnet Gripper' from the drop-down list of installed tool presets, the settings of the tool properties of the SMC Magnet Gripper are immediately copied to the text fields of appropriate tool settings of the currently selected tool. As the properties cannot be immediately applied, they can be further manually edited before they are saved.

Tool #5: CTool5

Select preset to apply: **SMC Magnet Gripper**

**General** Interference

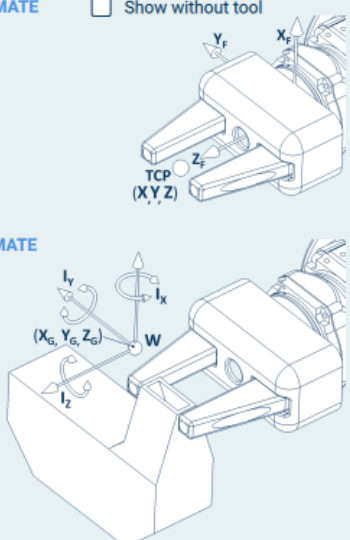
Name: CTool5 Block I/O: Not Assigned

Tool Center Point (TCP) Orientation: **ESTIMATE** ☐ Show without tool

$X_F$  0.000 mm  $R_X$  0.0000 deg  
 $Y_F$  0.000 mm  $R_Y$  0.0000 deg  
 $Z_F$  0.000 mm  $R_Z$  0.0000 deg

Weight **ESTIMATE**

$W$  0.000 kg  
 Center of Gravity  $(X_G, Y_G, Z_G)$  Moment of Inertia  
 $X_G$  0.000 mm  $I_X$  0.000 kg-m<sup>2</sup>  
 $Y_G$  0.000 mm  $I_Y$  0.000 kg-m<sup>2</sup>  
 $Z_G$  0.000 mm  $I_Z$  0.000 kg-m<sup>2</sup>



Tool #5: SMC Magnet Gripp

**PRESETS**

**General** Interference

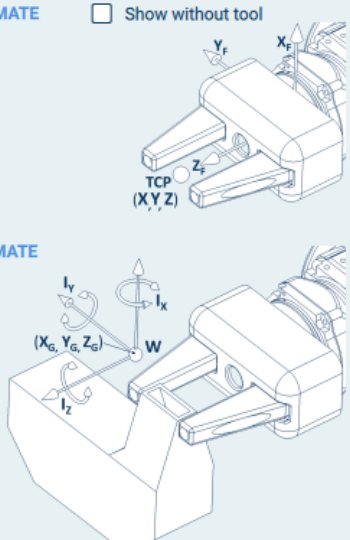
Name: SMC Magnet Gripp Block I/O: Not Assigned

Tool Center Point (TCP) Orientation: **ESTIMATE** ☐ Show without tool

$X_F$  0.000 mm  $R_X$  0.0000 deg  
 $Y_F$  0.000 mm  $R_Y$  0.0000 deg  
 $Z_F$  138.000 mm  $R_Z$  0.0000 deg

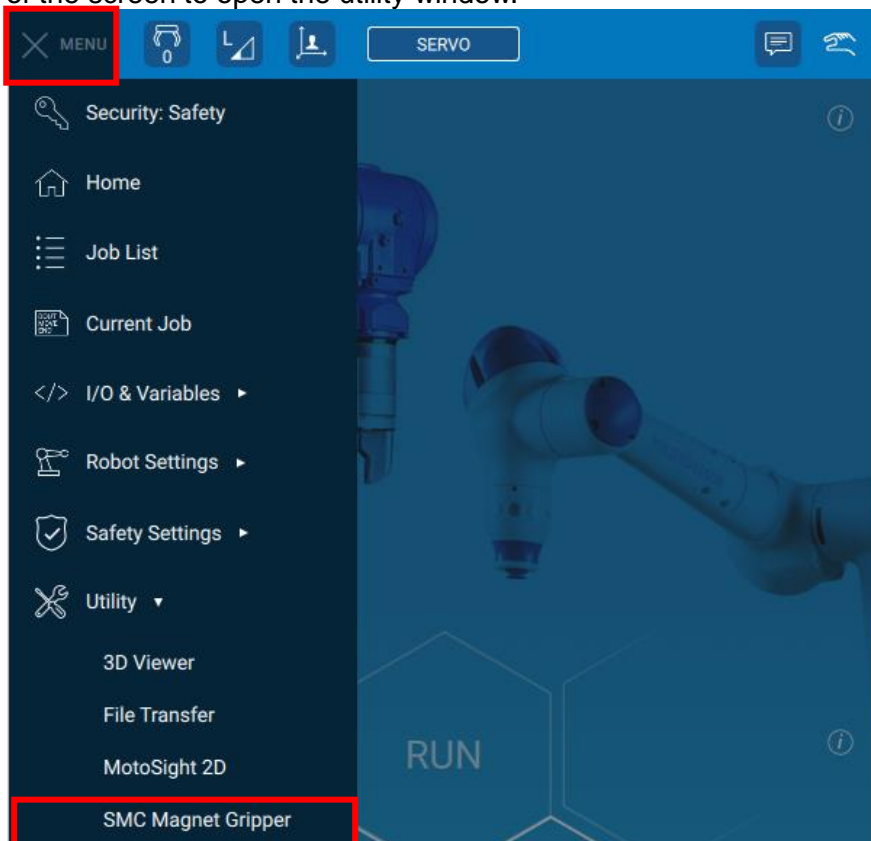
Weight **ESTIMATE**

$W$  0.590 kg  
 Center of Gravity  $(X_G, Y_G, Z_G)$  Moment of Inertia  
 $X_G$  1.000 mm  $I_X$  0.001 kg-m<sup>2</sup>  
 $Y_G$  -0.400 mm  $I_Y$  0.001 kg-m<sup>2</sup>  
 $Z_G$  57.100 mm  $I_Z$  0.000 kg-m<sup>2</sup>



### 5-3-3. Utility Window

1. Select [MENU] at the upper left of the screen, tap [Utility] -> [SMC Magnet Gripper], or tap [JOGGING] on the job contents review screen and then tap the “Magnet gripper” icon at the lower right of the screen to open the utility window.



## 2. Utility Window Features

### (1) Manual operation

It is possible to check the manual operation of the Magnet gripper.

By tapping the HOLD or RELEASE button, it is possible to perform a holding or releasing action of the gripper.

### (2) Monitor sensor Signal

It is possible to confirm whether the Hold or Release position auto switches react.



## 5-3-4. Magnet Gripper Integration Window

1. On the Job Contents review screen, tapping [MAGNETGRIPPER] on the navigation bar opens the "Magnet Gripper" Integration Window.



## 2. Insert Commands Tab

### (1) Selection Operation

Select the behaviour of the Hold or Release operations.

- **HOLD ONLY**

Puts the gripper into the “Hold state”, recognises it as “Hold success” without checking the Hold position signal, and proceeds to the next operation.

- **HOLD AND CHECK SIGNAL**

Puts the gripper into the “Hold state” and waits for the Hold position signal input before proceeding to the next operation. When the signal is turned on, the software recognises it as “Hold success” and proceeds to the next operation.

- **RELEASE**

Puts the gripper into the “Release state”, recognises it as “Release success” without checking the Release position signal, and proceeds to the next operation.

- **RELEASE AND CHECK SIGNAL**

Puts the gripper into the “Releasing state” and waits for the Release position signal input before proceeding to the next operation. When the signal is turned on, the software recognises it as “Close success” and proceeds to the next operation.

### (2) INSERT COMMAND

It is possible to add commands for controlling the gripper holding/releasing action to the job.

- **SMC\_HOLD\_MAGNETGRIPPER**

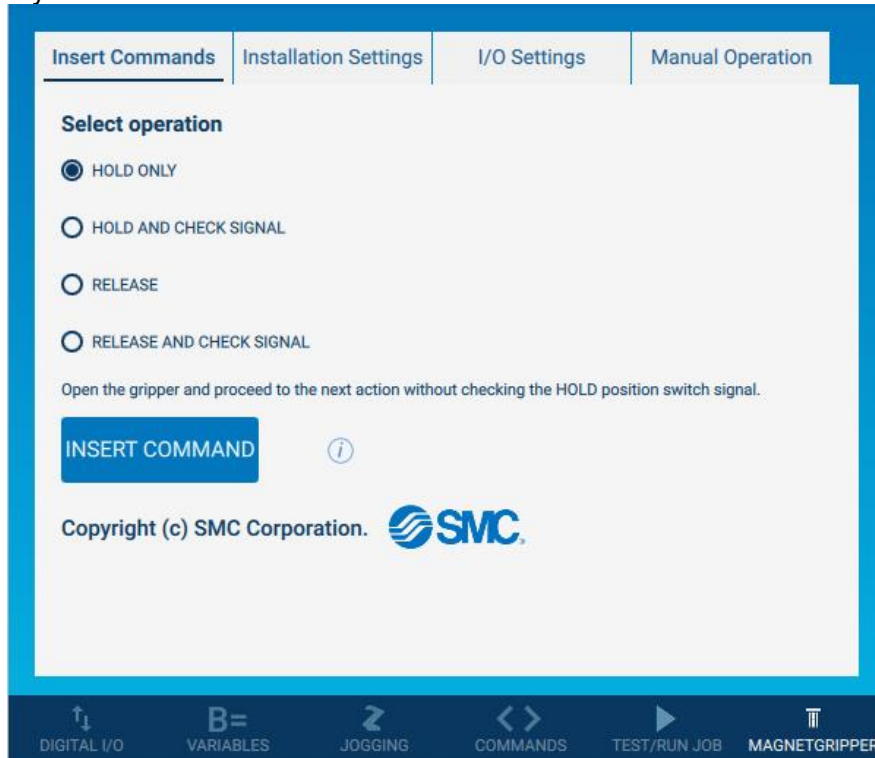
This command is used to make a gripper holding action.

If you select “Hold ONLY” or “HOLD AND CHECK SIGNAL” this command will be added.

- **SMC\_RELEASE\_MAGNETGRIPPER**

This command is used to make a gripper releasing action.

If you select “RELEASE ONLY” or “RELEASE AND CHECK SIGNAL” this command will be added.



### 3. Installation Settings Tab

\* To change the setting, set the security access level to the administration level.

#### (1) Gripper operation completion waiting time

This is the set value for the waiting time after the valve is operated for the gripper holding/releasing action to turn on.

Adjust the holding of the exhaust restrictor and enter an appropriate value according to the gripper holding/releasing operation time. The default value is 500ms. It can be set in the range of 0 to 1000ms.

#### (2) Status signal output to digital output port.

Select whether to output a status signal to the digital output port when "Hold/Release success" or "Hold/Release failure" is detected.

When "Enabled" is selected:

Selection of the digital output port is enabled. If either of "Hold/Release success" and "Hold/Release failure" is detected, the corresponding digital output port is turned on.

When "Disabled" is selected:

The selection of the digital output port is disabled. Even if either of "Hold/Release success" and "Hold/Release failure" is detected, no status signal is output.

#### (3) Select a digital output port

Selected box operation is enabled when "Output status signal to digital output port" is enabled. Select the digital output port to which a status signal is output when "Hold/Release success" or "Hold/Release failure" is detected.

The screenshot displays the 'Installation Settings' tab within the SMC MagnetGripper software. The interface has a blue header with four tabs: 'Insert Commands', 'Installation Settings' (active), 'I/O Settings', and 'Manual Operation'. Below the tabs, the 'Installation Settings' section is visible. It includes a 'Gripper operation completion waiting time' set to '0.500 (Sec)'. The 'Status signal output to digital output port' is set to 'Enable' with a radio button. Below this, there are two dropdown menus for selecting digital output ports: 'Output HOLD/RELEASE success' is set to 'Output#(5)' and 'Output HOLD/RELEASE failure' is set to 'Output#(6)'. At the bottom of the settings area, it says 'Copyright (c) SMC Corporation.' followed by the SMC logo. The bottom of the screen features a dark blue navigation bar with icons and labels for 'DIGITAL I/O', 'VARIABLES', 'JOGGING', 'COMMANDS', 'TEST/RUN JOB', and 'MAGNETGRIPPER'.

#### 4. I/O Settings Tab

\* To change the setting, set the security access level to the administration level.

##### (1) I/O settings for gripper operation

At the time of installation of the YASKAWA Plug & Play Kit, the I/O assignment is already set. If wiring is made as per the manual, it can be used with the default setting.

However, if the wiring is changed to connect with another device, it is possible to change the signal setting for gripper operation from this tab.

If you intend to return the I/O setting to the factory default condition, pressing the button at the lower part of the screen can initialize this setting.

##### (2) Tool setting for the gripper

The collaborative robot calculates the external force by canceling the tool mass. For this purpose, it is necessary to set the tool to be mounted on the manipulator and the masses and the centers of gravity of the tool and workpiece should be set in the tool file.

In the initial setting, the tool number 0 is selected when the HOLD button is pressed. Tool number 1 is selected when the RELEASE button is pressed. The tool number can be changed.

The screenshot shows the 'I/O Settings' tab of a robot control interface. At the top, there are four tabs: 'Insert Commands', 'Installation Settings', 'I/O Settings' (which is active), and 'Manual Operation'. Below the tabs, the section is titled 'I/O settings for gripper operation'. It contains four rows of settings, each with a label and a dropdown menu: 'Select output signal to HOLD gripper.' with 'Output#(8)' selected, 'Select output signal to RELEASE gripper.' with 'Output#(7)' selected, 'Select input signal to monitor HOLD position.' with 'Input#(8)' selected, and 'Select input signal to monitor RELEASE position.' with 'Input#(7)' selected. Below this section is the 'Tool setting for the gripper' section, which has two input fields: 'HOLD Tool number#' with the value '0' and 'RELEASE Tool number#' with the value '1'. At the bottom of this section is a large blue button labeled 'INITIALIZE SETTINGS' and a small circular information icon. The bottom of the screen features a dark blue navigation bar with icons and labels for 'DIGITAL I/O', 'VARIABLES', 'JOGGING', 'COMMANDS', 'TEST/RUN JOB', and 'MAGNETGRIPPER'.

## 5. Manual Operation tab

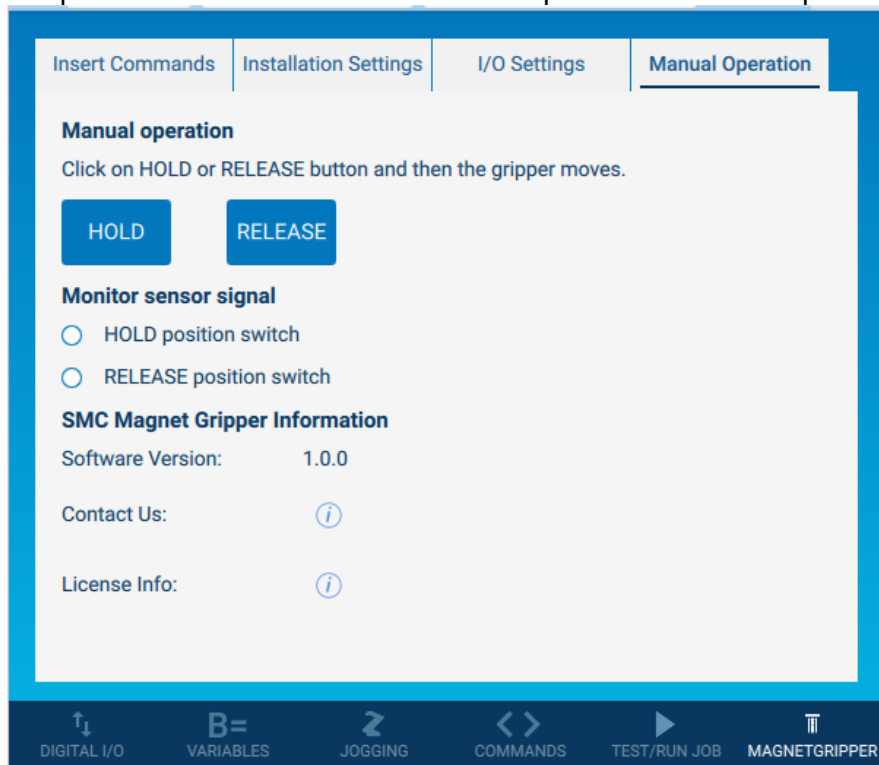
### (1) Manual operation

The manual operation of the magnet gripper can be checked.

By tapping the HOLD or RELEASE button, it is possible to perform a holding or releasing action of the gripper.

### (2) Monitor sensor signal

It is possible to confirm whether the Hold position or Release position auto switch reacts.



## 5-4. Air supply



### Warning

#### 1. Type of fluids

Please consult with SMC when using the product in applications other than compressed air.

#### 2. When there is a large amount of drainage

Compressed air containing a large amount of drainage can cause the malfunction of pneumatic equipment. An air dryer or water separator should be installed upstream from filters.

#### 3. Drain flushing

If condensation in the drain bowl is not emptied on a regular basis, the bowl will overflow and allow the condensation to enter the compressed air lines. This causes the malfunction of pneumatic equipment. If the drain bowl is difficult to check and remove, the installation of a drain bowl with an auto drain option is recommended. For compressed air quality, refer to the SMC Best Pneumatics No. 6 catalog.

#### 4. Use clean air.

Do not use compressed air that contains chemicals, synthetic oils that include organic solvents, salt, corrosive gases, etc., as it can cause damage or malfunction.



### Caution

**1. When extremely dry air is used as the fluid, degradation of the lubrication properties inside the equipment may occur, resulting in reduced reliability (or reduced service life) of the equipment. Please consult with SMC.**

#### 2. Install an air filter.

Install an air filter upstream near the valve. Select an air filter with a filtration size of 5 µm or smaller.

#### 3. Take measures to ensure air quality, such as by installing an aftercooler, air dryer, or water separator.

Compressed air that contains a large amount of drainage can cause the malfunction of pneumatic equipment, such as magnet grippers. Therefore, take appropriate measures to ensure air quality, such as by providing an aftercooler, air dryer, or water separator.



#### 4. Ensure that the fluid and ambient temperatures are within the specified range.

If the fluid temperature is 5°C or less, the moisture in the circuit could freeze, causing damage to the seals or equipment malfunction. Therefore, take appropriate measures to prevent freezing. For compressed air quality, refer to the SMC Best Pneumatics No. 6 catalog.

#### 5. Precautionary measures against condensation

Moisture condensation can occur inside pneumatic systems due to a drop in temperatures caused by the piping or operating conditions. This can degrade or wash away grease, resulting in a shortened service life or a malfunction. For details, refer to the catalog "Precautionary measures against condensation in a pneumatic system" (CAT.P-E01-11).

### 5-5. Piping



#### Caution

1. Refer to the Fittings and Tubing Precautions (Best Pneumatics) for handling one touch fittings.
2. Before piping, blow air (flush) or clean the piping to remove any cutting chips, cutting oil, dust, etc.

### 5-6. Operating environment



#### Warning

1. Do not use in an atmosphere containing corrosive gases, chemicals, sea water, water, water steam, or where there is direct contact with any of these.  
Refer to each construction drawing for information on the materials of magnet grippers.
2. Do not expose the product to direct sunlight for an extended period of time.
3. Do not use in a place subject to heavy vibration and/or shock.
4. Do not mount the product in locations where it is exposed to radiant heat.
5. Do not use in dusty locations or where water, oil, etc., splash on the equipment.
6. A decrease in the base oil of grease may be accelerated by the properties of the compressed air used in pneumatic equipment, the external environment, operating conditions, etc., and the resulting drop in lubricating performance may have an effect on the equipment's service life.



#### Caution

1. Internal lubricant or the base oil of grease may seep out of the cylinder depending on the operating conditions (an ambient temperature of 40°C or more, pressure retention, low-frequency actuation, etc.). Take great care when a clean environment is required.

### 5-7. Lubrication



#### Caution

1. Magnet gripper is lubricating non-lube type.  
These cylinders have been lubricated for life at the factory and can be used without any further lubrication. However, in the event that it is additionally lubricated, be sure to use class 1 turbine oil (with no additives) ISO VG320. Do not use machine oil or spindle oil. Stopping lubrication later on may lead to a malfunction because the new lubricant will displace the original lubricant. Therefore, lubrication must be continued once it has been started. If turbine oil is used, refer to the corresponding Safety Data Sheet (SDS).

## 6. Maintenance or inspection

---

### 6-1. Maintenance or inspection



#### Warning

1. Perform maintenance and inspection according to the procedures indicated in the operation manual.  
If handled improperly, human injury and/or malfunction or damage of machinery and equipment may occur.
2. Maintenance work  
If handled improperly, compressed air can be dangerous. Assembly, handling, repair, and element replacement of pneumatic systems should be performed by a knowledgeable and experienced

person.

### 3. Drain flushing

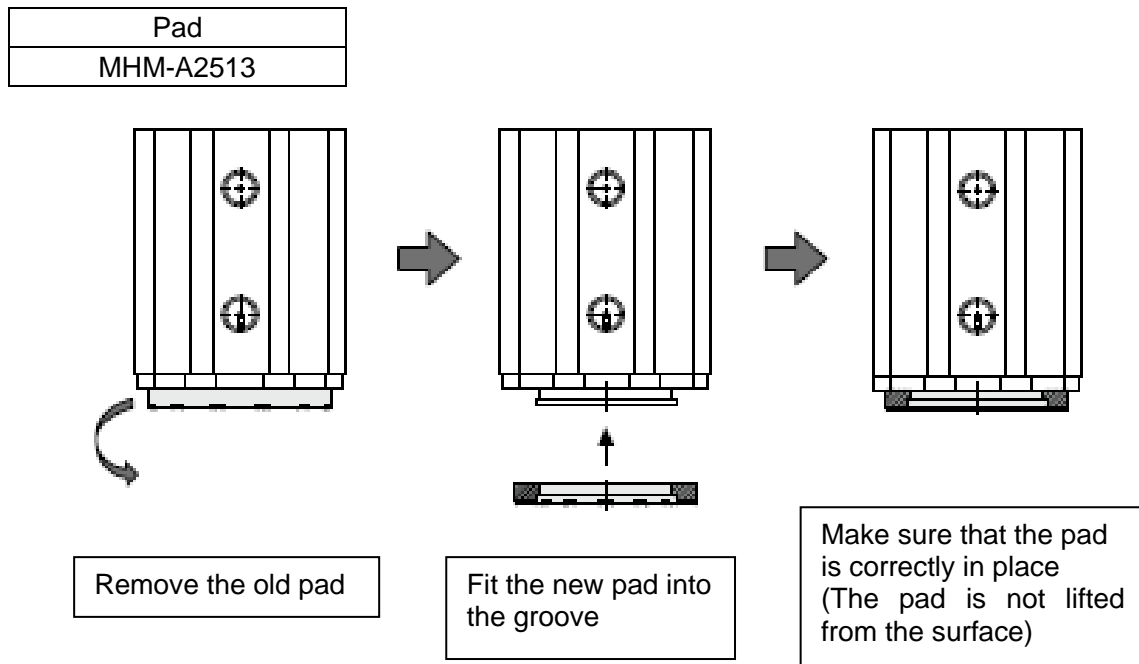
Remove drainage from air filters regularly.

### 4. Removal of equipment, and supply/exhaust of compressed air

Before components are removed, first confirm that measures are in place to prevent workpieces from dropping, run-away equipment, etc. Then, cut off the supply pressure and electric power, and exhaust all compressed air from the system using the residual pressure release function. When machinery is restarted, proceed with caution after confirming that appropriate measures are in place to prevent sudden movement.

## 6-2. Replacement part

### 1. Replace the pad using the following procedure.



## 6-3. Maintenance

### Warning

There is a strong magnet in the magnet gripper. Do not disassemble the product as the magnet may attract parts and peripheral objects which may cause an accident. When it is necessary to disassemble, please contact the SMC Sales representative.

Revision history
C. YASKAWA Plug & Play Kit edition.

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Note: Specifications are subject to change without prior notice and any obligation on the part of the manufacturer.  
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