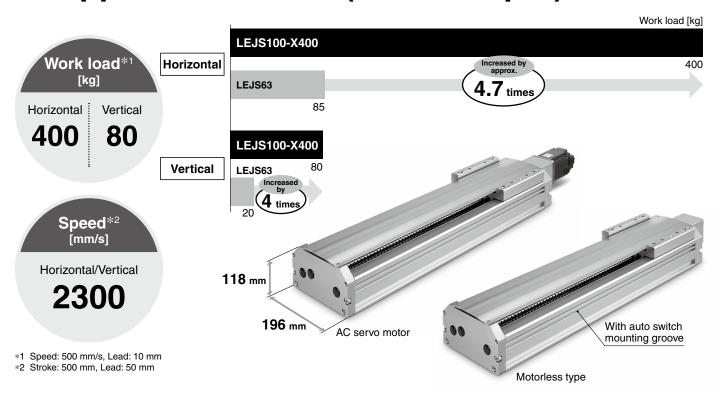
AC Servo Motor Motorless Type

# **Electric Actuator/High Rigidity Slider Type Ball Screw Drive**

# Supports 750 w (Motor output)



# Max. acceleration/deceleration: 9800 mm/s<sup>2</sup>

# AC Servo Motor Absolute Type

Pulse input type/Positioning type LECSB-T Series

- Positioning by up to 255 point tables
- Input type: Pulse input (Sink (NPN) type interface/Source (PNP) type interface)
- Control encoder: Absolute 22-bit encoder (Resolution: 4194304 p/rev)
- STO (Safe Torque Off) safety function available
- Parallel input: 10 inputs output: 6 outputs



#### Motorless Type Compatible Motors by Manufacturer

			Compatible interfaces						
Manufacturer	Series	Туре	Pulse	CC-1:1-	SSCNET!!!	SSCNETIII/H	MECH	ATROLINK	Device Vet
			input	CC-Link	SE MO SYSTEM CONTRICCTED METWORK	SEMO SYSTEM COMMOULEN NETWORK	П	Ⅲ	Deviceret
Mitsubishi	MELSERVO-J3	HF-KP73		•					
Electric Corporation	MELSERVO-J4	HG-KR73				-	_	_	
YASKAWA Electric	Σ-V	SGMJV-08					-	-	-
Corporation	Σ-7	SGM7J-08					•	•	_

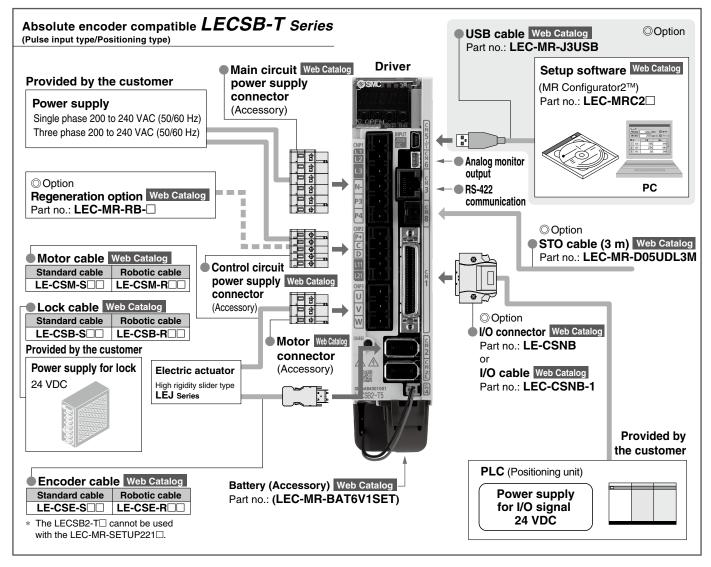
Trademark: DeviceNet™ is a trademark of ODVA.



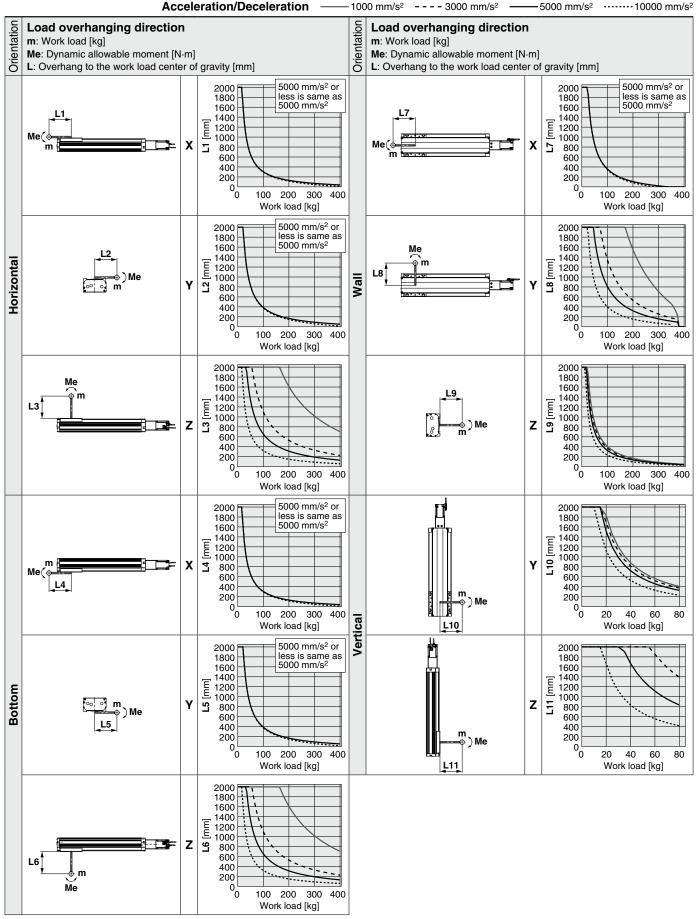




## **System Construction**



# **Model Selection**



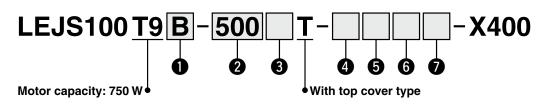
AC Servo Motor

# Electric Actuator/High Rigidity Slider Type

Ball Screw Drive LEJS100-X400



#### **How to Order**



#### Lead [mm]

Н	50
Α	25
В	10

## 2 Stroke [mm]

500	500
1000	1000
1500	1500

#### Motor option\*1

Nil	Without option
В	With lock

#### 4 Cable type\*1

<u> </u>								
Nil	Without cable							
S	Standard cable							
R	Robotic cable							

### **5** Cable length [m]\*1

Nil	Without cable					
2	2					
5	5					
Α	10					

### 6 Driver type\*1

	Compatible driver Model	Power supply voltage [V]	Applicable network	
Nil	Without driver	_	_	
B2	LECSB2-T9	200 to 240	Pulse input/Point table	

\*1 When a driver type is selected, a cable is included.

Select the cable type and cable length.

Example)

S2B2: Standard cable (2 m) + Driver (LECSB2)

S2 : Standard cable (2 m)
Nil : Without cable and driver

## 1/O cable length [m]\*2

	<u> </u>					
Nil	Without cable					
Н	Connector only					
1	1.5					

\*2 When "Without driver" is selected for driver type, only "Nil: Without cable" can be selected.

#### **Compatible Driver**

Compatible Driver			
Driver type	Pulse input type		
Series	LECSB-T		
Number of point tables	Up to 255		
Pulse input	0		
Applicable network	_		
Control encoder	Absolute 22-bit encoder		
Communication function	USB communication, RS422 communication		
Power supply voltage [V]	200 to 240 VAC (50/60 Hz)		

# Electric Actuator/High Rigidity Slider Type Ball Screw Drive LEJS100-X400



# **Specifications**

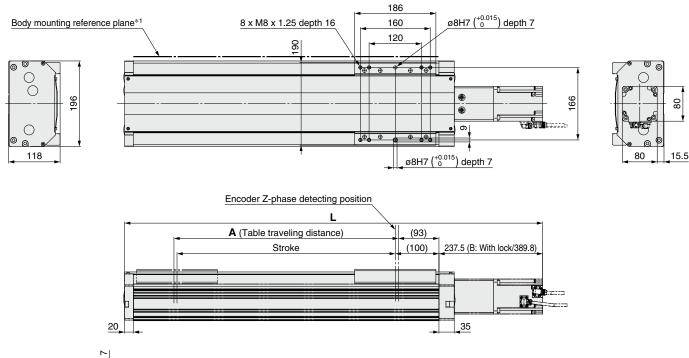
Stroke [mm]				500, 1000, 1500			
Lead [mm]			50	25	10		
Horizontal 3000 [mm/s <sup>2</sup> ]		mm/s²]	60	150	400		
work load	5000 [ı	mm/s²]	43	93	150		
[kg]	9800 [ı	mm/s²]	22	36	_		
Vertical	3000 [1	mm/s²]	14	29	80		
work load	5000 [ı	mm/s²]	12	29	30		
[kg]	9800 [1	mm/s²]	8	9	<del>_</del>		
	Stroke range	500	2300	1250	500		
Max. speed [mm/s]		1000	1600	800	320		
[11111/9]		1500	900	450	180		
Max. accelerat	ion/decelerati	on [mm/s <sup>2</sup> ]	9800				
Positioning rep	eatability [m	m]	±0.01				
Lost motion [m	nm]	,	0.05 or less				
Impact/Vibration	on resistance	[m/s <sup>2</sup> ]	50/20				
Motor capacity	•		750 W				
Actuation type			Ball screw				
Guide type			Linear guide (Double axis)				
Operating temperature range [°C]				5 to 40			
Operating humidity range [%RH] 90 or less (No condensation)							

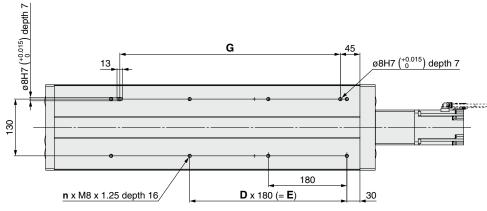
<sup>\*</sup> Do not allow collisions at either end of the table traveling distance. Additionally, when running the positioning operation, do not set within 7 mm of both ends.





### **Dimensions: Ball Screw Drive**





- \*1 Use a pin when mounting the actuator using the body mounting reference plane. Set the height of the pin to be 5 mm or more because of round chamfering. (Recommended height 6 mm)
- \* Please consult with SMC for adjusting the Z-phase detecting position at the stroke end of the end side.

#### **Dimensions and Weight**

Stroke	L			_	_	٦		Weight [kg]	
Stroke	Without lock	With lock	Α	11	0		G	Without lock	With lock
500	957.5	997.8	514	8	3	540	505	26.7	27.7
1000	1457.5	1497.8	1014	14	6	1080	1045	37.1	38.1
1500	1957.5	1997.8	1514	20	9	1620	1585	47.6	48.6

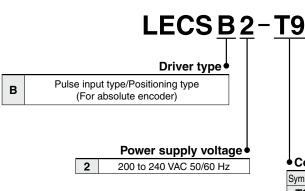


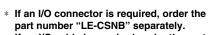
# **AC Servo Motor Driver Absolute Type**

LECSB-T (Pulse input type/Positioning type)



#### **How to Order**





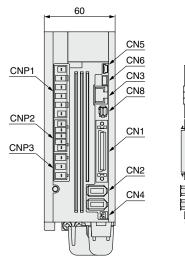
\* If an I/O cable is required, order the part number "LEC-CSNB-1" separately. (Since the electric actuator will not operate without forced stop (EM2) wiring when using the LECSB-T in any mode other than positioning mode, an I/O connector or an I/O cable is required.)

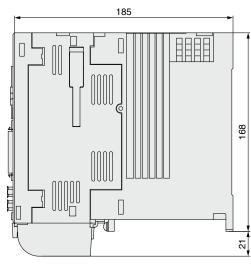
Compatible motor type

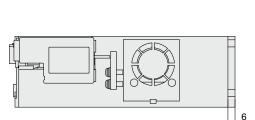
Symbol	Type	Capacity	Encoder
T9	AC servo motor (T9*1)	750 W	Absolute

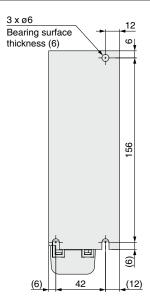
\*1 The symbol shows the motor type (actuator).

#### **Dimensions**









Connector name	Description		
CN1	I/O signal connector		
CN2	Encoder connector		
CN3	RS-422 communication connector		
CN4	Battery connector		
CN5	USB communication connector		
CN6	Analog monitor connector		
CN8	STO input signal connector		
CNP1	Main circuit power supply connector		
CNP2	Control circuit power supply connector		
CNP3	Servo motor power connector		



# LECSB-T

# **Specifications**

Model		LECSB2-T9	
Compatible motor capacity [W]		750	
Compatible encoder		Absolute 22-bit encoder (Resolution: 4194304 p/rev)	
Main	Power voltage [V]	Three phase 200 to 240 VAC (50/60 Hz), Single phase 200 to 240 VAC (50/60 Hz)	
power	Allowable voltage fluctuation [V]	Three phase 170 to 264 VAC (50/60 Hz), Single phase 170 to 264 VAC (50/60 Hz)	
supply	Rated current [A]	3.8	
Control	Control power supply voltage [V]	Single phase 200 to 240 VAC (50/60 Hz)	
power	Allowable voltage fluctuation [V]	Single phase 170 to 264 VAC	
supply	Rated current [A]	0.2	
Parallel i	nput	10 inputs	
Parallel o	output	6 outputs	
Max. input pulse frequency [pps]		4 M (for differential receiver), 200 k (for open collector)	
	In-position range setting [pulse]	0 to $\pm65535$ (Command pulse unit)	
	Error excessive	±3 rotations	
Function	Torque limit	Parameter setting or external analog input setting (0 to 10 VDC)	
Function	Communication	USB communication, RS422 communication*1	
	Point table	Up to 255 points	
	Pushing operation	Point table no. input method, Up to 127 points	
Operatin	g temperature range [°C]	0 to 55 (No freezing)	
Operatin	g humidity range [%RH]	90 or less (No condensation)	
Storage t	temperature range [°C]	-20 to 65 (No freezing)	
Storage I	humidity range [%RH]	90 or less (No condensation)	
Insulatio	n resistance [M $\Omega$ ]	Between the housing and SG: 10 (500 VDC)	
Weight [	al	1400	

 $<sup>\</sup>ast 1~$  USB communication and RS422 communication cannot be performed at the same time.



Motorless Type

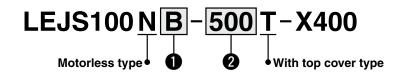
# **Electric Actuator/High Rigidity Slider Type**

**Ball Screw Drive** 





#### **How to Order**



<b>0</b> L	ead [	mm]
Н		

O Loud [iiiii]					
Н	50				
Α	25				
В	10				

<b>a</b>		
W	Stroke	[mm]

500	500
1000	1000
1500	1500

### **Specifications**

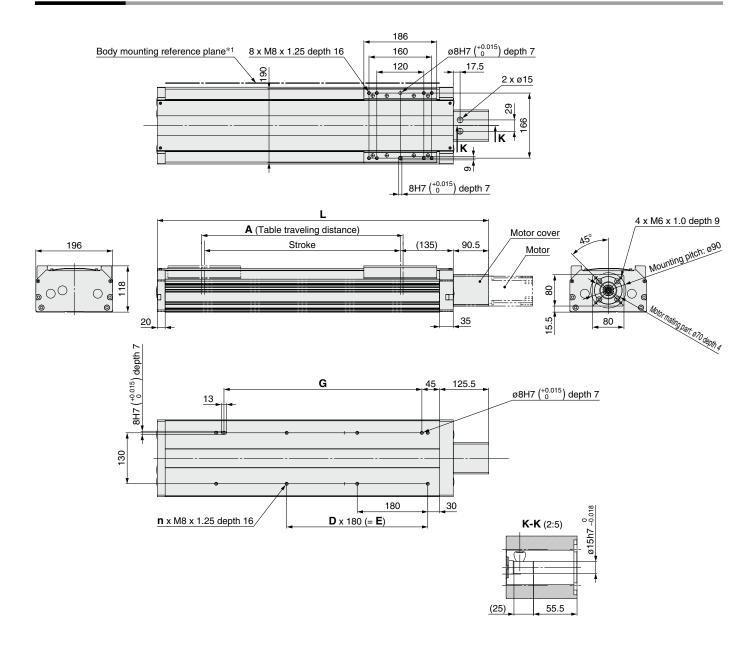
9	Stroke [mm] Lead [mm]			500, 1000, 1500			
L			50	25	10		
F	Horizontal	3000 [	mm/s²]	60	150	400	
v	work load [kg]	5000 [mm/s <sup>2</sup> ]		43	93	150	
[1		9800 [	mm/s²]	22	36	_	
V	Vertical	3000 [mm/s <sup>2</sup> ]		14	29	80	
v	work load	5000 [	mm/s²]	12	29	30	
<u> </u>	kg]	9800 [	mm/s²]	8	9	_	
N [1	.a	041	500	2300	1250	500	
	Max. speed mm/s]	Stroke range	1000	1600	800	320	
		runge	1500	900	450	180	
, V	Max. accelera	tion/decelera	tion [mm/s²]		9800		
F L	Positioning re	epeatability [n	nm]	±0.01			
L	Lost motion [mm]		0.05 or less				
	Ball screw specifications  Thread size [mm] Shaft length [mm]		ø25				
Ľ			Shaft length [mm]	Stroke + 284.5			
l li	Impact/Vibration resistance [m/s²]		50/20				
٨	Motor capacity		750 W				
A	Actuation type		Ball screw				
C	Guide type		Linear guide (Double axis)				
C	Operating temperature range [°C]		5 to 40				
	Operating humidity range [%RH]		90 or less (No condensation)				
specifications F	Actuation uni	t weight [kg]		4.58			
E F	Friction coeffi	icient		0.05			
§ 1	Mechanical ef	fficiency		0.8			
ဖျှ	Motor shape		□80				
≂⊸	Motor type			AC servo motor (200 V)			
<u>ੂੰ</u> F	Rated output	capacity [W]			750		
မွ် F	Rated torque [N·m]			2.4			
ຶ F	Rated rotation [rpm] 3000						

- Values in this specifications table are the allowable values of the actuator body with the standard motor mounted. Do not use the actuator so that it exceeds these values.
- Before mounting the coupling, remove any dust, oil, etc., adhered to the shaft and the inner surface of the coupling.
- This product does not come with a motor, motor mounting screw, or couplings. They should be prepared separately by the customer.
- Take measures to prevent the loosening of the motor mounting screws.
- Do not allow collisions at either end of the table traveling distance. Additionally, when running the positioning operation, do not set within 7 mm of both ends.





### **Dimensions**



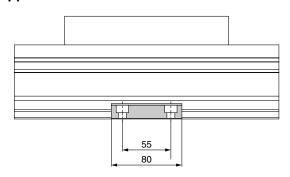
\*1 Use a pin when mounting the actuator using the body mounting reference plane or the side supports. Set the height of the pin to be 5 mm or more because of round chamfering. (Recommended height 6 mm)

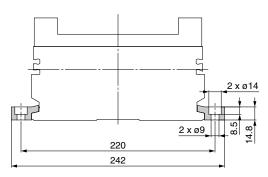
# Electric Actuator/High Rigidity Slider Type Ball Screw Drive LEJS100-X40



#### Side Supports

#### Side supports: MY-S50A

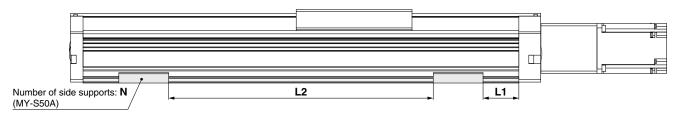




\* The side supports consist of a set of right and left brackets.

### Usage Guide for Side Supports

When mounting with the side supports, be sure to use the number of side supports (N) and the support spacing (L1 and L2) shown in the figure and table below as a guide.



Stroke	N (Qty.)	<b>L1</b> [mm]	<b>L2</b> [mm]	Screw size	Max. tightening torque [N⋅m]
500 st	6		165		
1000 st	10	15	175	M8 x 1.25	12.5
1500 st	14		180		

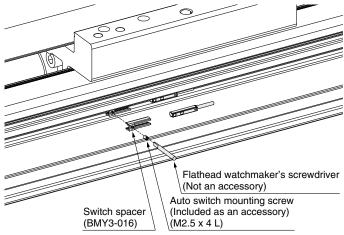
- · When mounting with the side supports, use in combination with the pin on the bottom of the body.
- · For vertical or bottom mounting, please refrain from using only the side supports.

### Auto Switch Mounting

When mounting an auto switch, first, hold a switch spacer between your fingers and press it into the auto switch mounting groove. When doing this, confirm that it is set in the correct mounting orientation, or reattach it if necessary.

Next, insert an auto switch into the auto switch mounting groove and slide it until it is positioned under the switch spacer.

After establishing the mounting position, use a flathead watchmaker's screwdriver to tighten the included auto switch mounting screw.



#### **Auto Switch Mounting Screw Tightening Torque**

Auto switch model	Tightening torque	
D-M9□(V)	0.10 to 0.15	
D-M9□W(V)	0.10 to 0.15	



