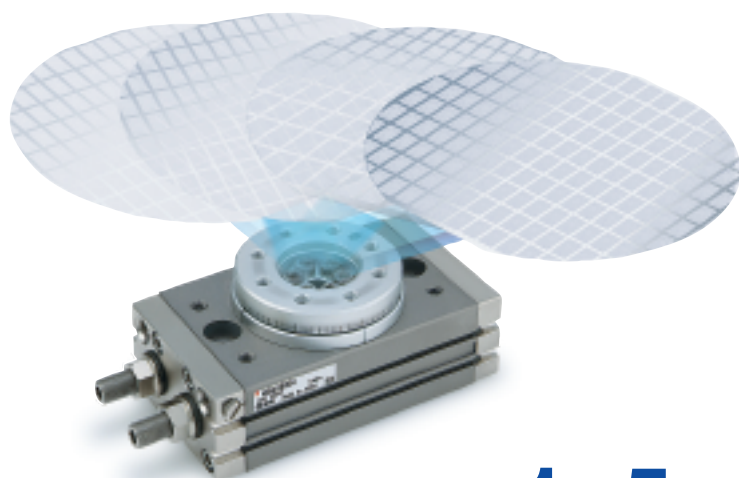


# Low-Speed Rotary Actuator

Possible to transfer a workpiece at low-speed.

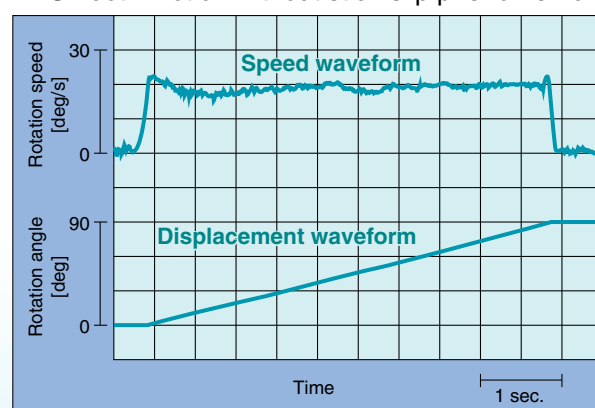


- Rotation time adjustment range: **1 to 5** (s/90°)

Model	Size	Rotation time adjustment range (s/90°)					
		1	2	3	4	5	
Low-speed	CRQ2X	10, 15, 20, 30, 40	1 to 5 (0.7 to 5 for CRQ2X□10,15)				
	MSQX	10, 20, 30, 50					
Standard	CRQ2	10, 15, 20, 30, 40	0.2 to 1 (0.2 to 0.7 for CRQ2□10,15)				
	MSQ	10, 20, 30, 50					

- Realized a stable motion at 5s/90°.

Smooth motion without stick-slip phenomenon



Measurement conditions / Fluid: Air

Mounting orientation: Horizontal without load

Operating pressure: 0.5 MPa

Pneumatic circuit: Meter-out circuit

Ambient temperature: Room temperature

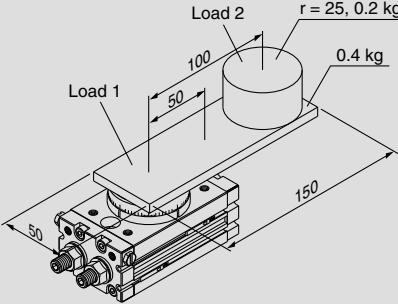
- Dimensions compatible with the CRQ2, MSQ series



Series **CRQ2X/MSQX**

# Series CRQ2X/MSQX Model Selection

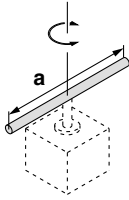
\* The selection procedure of the rotary for low-speed is the same as for an ordinary rotary. If the rotation time exceeds 2s per 90°, however, the necessary torque and the kinetic energy are calculated with rotation time of 2s per 90°.

Selection Procedure	Remarks	Selection Example
<p><b>0</b> Operating conditions</p> <p>Operating conditions are as follows:</p> <ul style="list-style-type: none"> <li>Provisionally selected model</li> <li>Operating pressure: MPa</li> <li>Mounting position</li> <li>Load type           <ul style="list-style-type: none"> <li>Static load: N·m</li> <li>Resistance load: N·m</li> <li>Inertial load: N·m</li> </ul> </li> <li>Load dimension: m</li> <li>Load mass: kg</li> <li>Rotation time: s</li> <li>Rotation angle: rad</li> </ul>	<ul style="list-style-type: none"> <li>See P.3 for load type.</li> <li>The unit of the rotation angle is Radians. 180° = πrad 90° = π/2rad</li> </ul>	 <p>Provisionally selected model: MSQXB10A Operating pressure: 0.3 MPa Mounting position: Vertical, Type of load: Inertial load Rotation time: 6s Rotation angle: πrad (180°)</p>
<p><b>1</b> Calculation of moment of inertia</p> <p>Calculate the moment of inertia of the load. ⇒ P.2</p>	<ul style="list-style-type: none"> <li>If the moment of inertia of the load is made up of multiple components, calculate the moment of inertia of each component and add them together.</li> </ul>	<p>Load 1 moment of inertia: <math>I_1</math>  <math display="block">I_1 = 0.4 \times \frac{0.15^2 + 0.05^2}{12} + 0.4 \times 0.05^2 = 0.001833</math>           Load 2 moment of inertia: <math>I_2</math>  <math display="block">I_2 = 0.2 \times \frac{0.025^2}{2} + 0.2 \times 0.1^2 = 0.002063</math>           Total moment of inertia: <math>I</math>  <math display="block">I = I_1 + I_2 = 0.003896 \text{ [kg} \cdot \text{m}^2\text{]}</math> </p>
<p><b>2</b> Calculation of necessary torque</p> <p>Calculate necessary torque corresponding to the load type, and ensure it is within effective torque range.</p> <ul style="list-style-type: none"> <li>Static load (Ts) Necessary torque <math>T = T_s</math></li> <li>Resistance load (Tf) Necessary torque <math>T = T_f \times (3 \text{ to } 5)</math></li> <li>Inertial load (Ta) Necessary torque <math>T = T_a \times 10</math> ⇒ P.3</li> </ul>	<ul style="list-style-type: none"> <li>When calculating the inertial load, if the rotation time exceeds 2s per 90°, inertial load is calculated with rotation time of 2s per 90°.</li> <li>Even for resistance load, when the load is rotated, necessary torque calculated from inertial load shall be added.</li> </ul> <p>Necessary torque <math>T = T_f \times (3 \text{ to } 5) + T_a \times 10</math></p>	<p>Inertial load: <math>T_a</math>  <math display="block">T_a = I \cdot \dot{\omega}</math> <math display="block">\dot{\omega} = \frac{2\theta}{t^2} \text{ [rad/s}^2\text{]}</math>           Necessary torque: <math>T</math>  <math display="block">T = T_a \times 10</math> <math display="block">= 0.003896 \times \frac{2 \times \pi}{4^2} \times 10 = 0.015 \text{ [N} \cdot \text{m]}</math>           (t is calculated with 2s per 90°.)  <math>0.109 \text{ N} \cdot \text{m} &lt; \text{Effective torque OK}</math> </p>
<p><b>3</b> Checking rotation time</p> <p>Confirm that it is within the adjustable range of rotation time. ⇒ P.4</p>	<ul style="list-style-type: none"> <li>Converted to the time per 90° for comparison. (For comparison, 6s/180° is converted to 3s/90°.)</li> </ul>	<p><math>1.0 \leq t \leq 5</math>  <math>t = 3\text{s}/90^\circ \text{ OK}</math></p>
<p><b>4</b> Calculation of kinetic energy</p> <p>Confirm that the load's kinetic energy is within the allowable value. Can be confirmed by the graph of the moment of inertia and the rotation time. ⇒ P.4</p>	<ul style="list-style-type: none"> <li>If the rotation time exceeds 2s per 90°, kinetic energy is calculated with rotation time of 2s per 90°.</li> <li>If the allowable value is exceeded, an external cushioning mechanism such as an absorber needs to be installed.</li> </ul>	<p><math display="block">E = \frac{1}{2} \cdot I \cdot \omega^2</math> <math display="block">\omega = \frac{2 \cdot \theta}{t}</math>           Kinetic energy  <math display="block">\frac{1}{2} \times 0.003896 \times \left(\frac{2 \times \pi}{4}\right)^2 = 0.0048 \text{ [J]}</math>           (t is calculated with 2s per 90°.)  <math>0.0048 \text{ [J]} &lt; \text{Allowable energy OK}</math> </p>
<p><b>5</b> Checking allowable load</p> <p>Check if the load applied to the product is within the allowable range. ⇒ P.5</p>	<ul style="list-style-type: none"> <li>If the allowable value is exceeded, an external bearing needs to be installed.</li> </ul>	<p><math display="block">M = 0.4 \times 9.8 \times 0.05 + 0.2 \times 9.8 \times 0.1</math> <math display="block">= 0.392 \text{ [N} \cdot \text{m]}</math> <math>0.392 \text{ [N} \cdot \text{m]} &lt; \text{Allowable moment load OK}</math></p>
<p><b>6</b> Calculation of air consumption and necessary air quantity</p> <p>Calculate air consumption and necessary air quantity as required. ⇒ P.6</p>		

## Equation Table of Moment of Inertia (Calculation of moment of inertia I) I: Moment of inertia (kg·m<sup>2</sup>) m: Load mass (kg)

### 1. Thin shaft

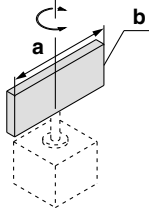
Position of rotational axis:  
Perpendicular to the shaft through the center of gravity



$$I = m \cdot \frac{a^2}{12}$$

### 2. Thin rectangular plate

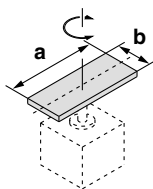
Position of rotational axis:  
Parallel to side b through the center of gravity



$$I = m \cdot \frac{a^2}{12}$$

### 3. Thin rectangular plate (Including rectangular parallelepiped)

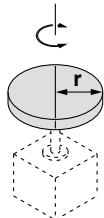
Position of rotational axis:  
Perpendicular to the plate through the center of gravity



$$I = m \cdot \frac{a^2 + b^2}{12}$$

### 4. Round plate (Including column)

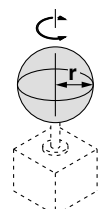
Position of rotational axis:  
Passing through the center axis



$$I = m \cdot \frac{r^2}{2}$$

### 5. Solid sphere

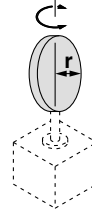
Position of rotational axis:  
Passing through the diameter



$$I = m \cdot \frac{2r^2}{5}$$

### 6. Thin round plate

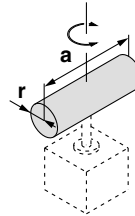
Position of rotational axis:  
Passing through the diameter



$$I = m \cdot \frac{r^2}{4}$$

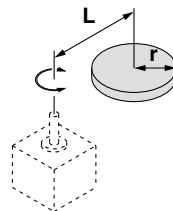
### 7. Cylindrical

Position of rotational axis:  
Passing through the diameter and the center of gravity



$$I = m \cdot \frac{3r^2 + a^2}{12}$$

### 8. When rotational axis and the center of the load are not concentric.

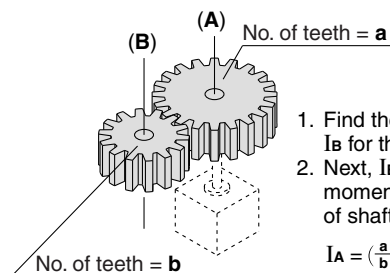


$$I = K + m \cdot L^2$$

**K:** The moment of inertia around the center of gravity of the load

In case of 4. Round plate  $K = m \cdot \frac{r^2}{2}$

### 9. Gear transmission



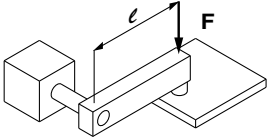
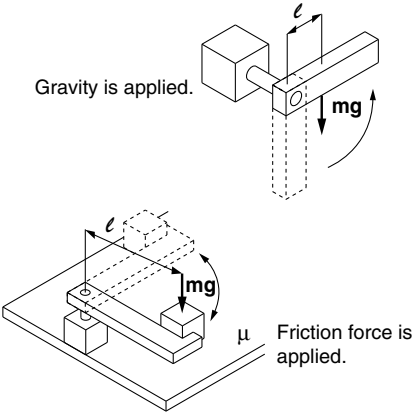
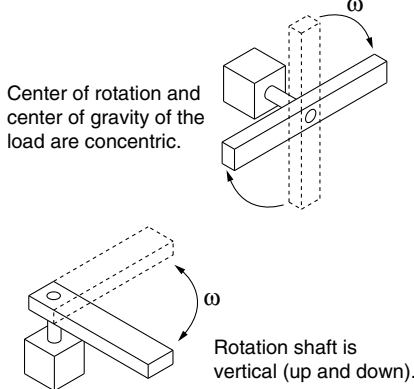
1. Find the moment of inertia  $I_B$  for the rotation of shaft (B).
2. Next,  $I_B$  is entered to find  $I_A$  the moment of inertia for the rotation of shaft (A) as

$$I_A = \left(\frac{a}{b}\right)^2 \cdot I_B$$

# Model Selection

## Load Type

Calculation method of necessary torque depends on the load type. Refer the below table.

Load type		
Static load: $T_s$	Resistance load: $T_f$	Inertial load: $T_a$
<p>Only pressing force is necessary. (e.g. for clamping)</p> 	<p>Weight or friction force is applied to rotating direction.</p> 	<p>Rotate the load with inertia.</p> 
<p><math>T_s = F \cdot l</math></p> <p><math>T_s</math>: Static load (N·m)  <math>F</math>: Clamping force (N)  <math>l</math>: Distance from the rotation center to the clamping position (m)</p>	<p>Gravity is applied in rotating direction.</p> <p><math>T_f = m \cdot g \cdot l</math></p> <p>Friction force is applied in rotating direction.</p> <p><math>T_f = \mu \cdot m \cdot g \cdot l</math></p> <p><math>T_f</math>: Resistance load (N·m)  <math>m</math>: Load mass (kg)  <math>g</math>: Gravitational acceleration 9.8 (m/s<sup>2</sup>)  <math>l</math>: Distance from the rotation center to the point of application of the weight or friction force (m)  <math>\mu</math>: Friction coefficient</p>	<p><math>T_a = I \cdot \omega = I \cdot \frac{2\theta}{t^2}</math></p> <p><math>T_a</math>: Inertial load (N·m)  <math>I</math>: Moment of inertia (kg·m<sup>2</sup>)  <math>\omega</math>: Angular acceleration (rad/s<sup>2</sup>)  <math>\theta</math>: Rotation angle (rad)  <math>t</math>: Rotation time (s)</p> <p>For low speed rotary, if the rotation time exceeds 2s per 90°, inertial load is calculated with rotation time of 2s per 90°.</p>
Necessary torque: $T = T_s$	Necessary torque: $T = T_f \times (3 \text{ to } 5)$ <sup>Note)</sup>	Necessary torque: $T = T_a \times 10$ <sup>Note)</sup>
<p>• Resistance load: Gravity or friction force is applied to rotating direction.            Ex. 1) Rotation shaft is horizontal (lateral), and the rotation center and the center of gravity of the load are not concentric.            Ex. 2) Load moves by sliding on the floor            * The total of resistance load and inertial load is the necessary torque. <math>T = T_f \times (3 \text{ to } 5) + T_a \times 10</math></p> <p>• Not resistance load: Neither weight or friction force is applied in rotating direction.            Ex. 1) Rotation shaft is vertical (up and down).            Ex. 2) Rotation shaft is horizontal (lateral), and rotation center and the center of gravity of the load are not concentric.            * Necessary torque is inertial load only. <math>T = T_a \times 10</math></p>		

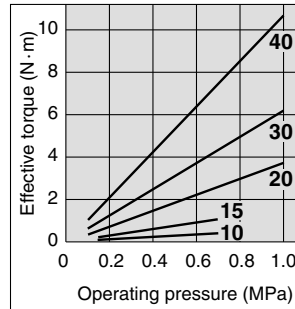
Note) To adjust the speed, margin is necessary for  $T_f$  and  $T_a$ .

## Effective Torque

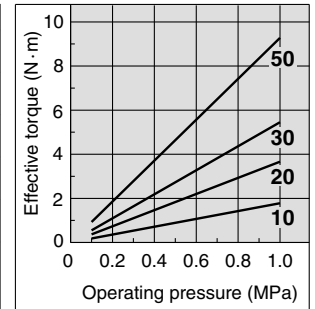
Unit: N·m

Model	Size	Operating pressure (MPa)										
		0.1	0.15	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0
CRQ2X	10	—	0.09	0.12	0.18	0.24	0.30	0.36	0.42	—	—	—
	15	—	0.22	0.30	0.45	0.60	0.75	0.90	1.04	—	—	—
	20	0.37	0.55	0.73	1.10	1.47	1.84	2.20	2.57	2.93	3.29	3.66
	30	0.62	0.94	1.25	1.87	2.49	3.11	3.74	4.37	4.99	5.60	6.24
	40	1.06	1.59	2.11	3.18	4.24	5.30	6.36	7.43	8.48	9.54	10.6
MSQX	10	0.18	—	0.36	0.53	0.71	0.89	1.07	1.25	1.42	1.60	1.78
	20	0.37	—	0.73	1.10	1.47	1.84	2.20	2.57	2.93	3.29	3.66
	30	0.55	—	1.09	1.64	2.18	2.73	3.19	3.82	4.37	4.91	5.45
	50	0.93	—	1.85	2.78	3.71	4.64	5.57	6.50	7.43	8.35	9.28

CRQ2X



MSQX



Note 1) Values of operating torque in the above table are representative values, and not guaranteed. Make use of the values as a reference when ordering.  
 Note 2) Except for cases when an external stopper is used, the holding torque at the operation end is half of the table value.

## Kinetic Energy/Rotating Time

In a rotational movement, the kinetic energy of a load may damage the internal parts, even if the required torque for a load is small. Consider the moment of inertia and rotation time before selecting a model.  
 (For model selection, refer to the moment of inertia and rotation time graph as shown on the below table.)

### Allowable kinetic energy and rotation time adjustment range

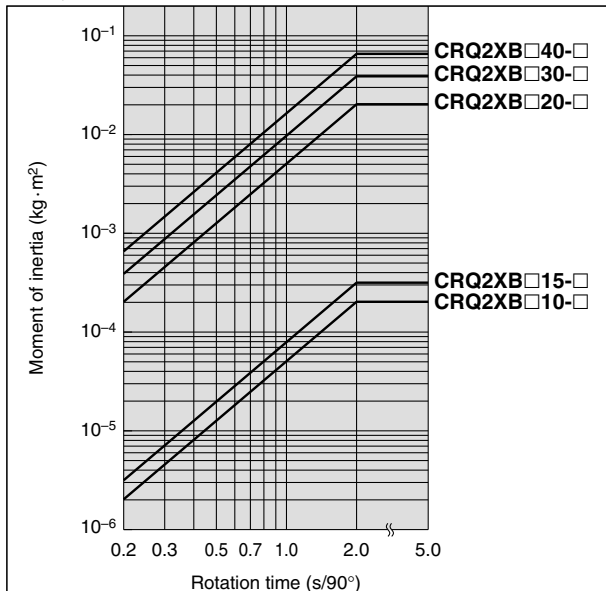
Set the rotation time, within stable operational guidelines, using the adjustment range specification table as detailed below. When operating at low-speeds which exceed the rotation time adjustment range, use caution as it may result in sticking or malfunction.

Model	Size	Allowable kinetic energy (J)	Stable operational rotation time adjustment range (s/90°)
CRQ2X	10	0.00025	0.7 to 5
	15	0.00039	
	20	0.025	
	30	0.048	
	40	0.081	
MSQX	10	0.007	1 to 5
	20	0.025	
	30	0.048	
	50	0.081	

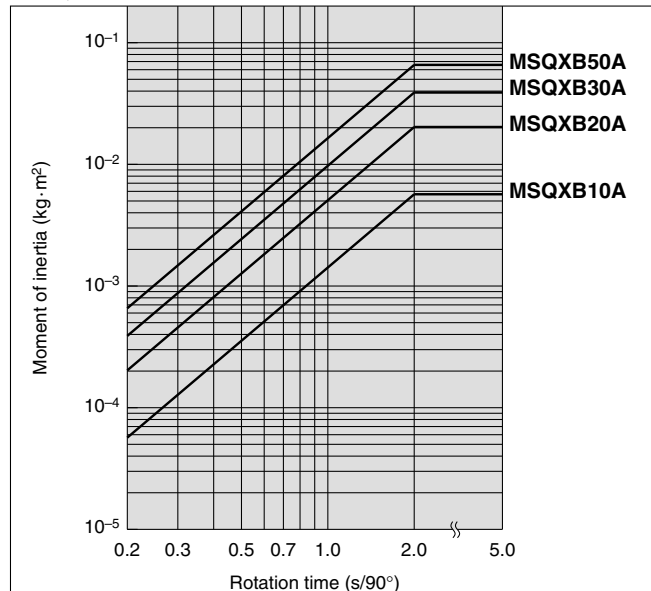
## Model Selection

Select a model based on the moment of inertia and rotation time as shown graph below.

CRQ2X



MSQX



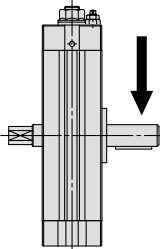
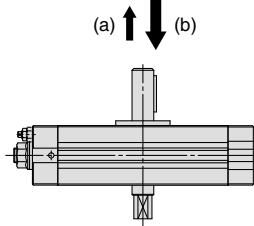
\* If the rotation time exceeds 2s per 90°, kinetic energy is calculated with rotation time of 2s per 90°.

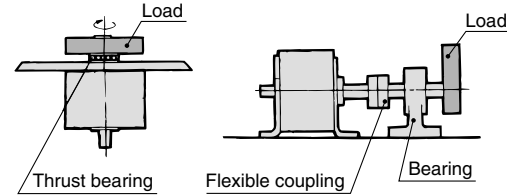
# Model Selection

## Allowable Load

### CRQ2X

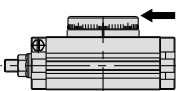
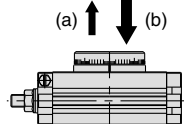

A load up to the allowable radial/thrust load can be applied provided that a dynamic load is not generated. However, applications which apply a load directly to the shaft should be avoided whenever possible. In order to further improve the operating conditions, a method such as that shown in the drawing on the right side is recommended so that a direct load is not applied to the shaft.

Size			
	Allowable radial load (N)	Allowable thrust load (N)	
		(a)	(b)
10	14.7	7.8	15.7
15	19.6	9.8	19.6
20	49	29.4	49
30	78	49	98
40	98	59	108



### MSQX

Do not allow the load and moment applied to the table to exceed the allowable values shown in the below table. (Operation beyond the allowable values can cause adverse effects on service life, such as play in the table and loss of accuracy.)

Size				
	Allowable radial load (N)	Allowable thrust load (N)		Allowable moment (N·m)
		(a)	(b)	
10	78	74	78	2.4
20	147	137	137	4.0
30	196	197	363	5.3
50	314	296	451	9.7

# Rotary Actuator Technical Data

## Air Consumption

Air consumption is the volume of air which is expended by the rotary actuator's reciprocal operation inside the actuator and in the piping between the actuator and the switching valve, etc. This is necessary for selection of a compressor and for calculation of its running cost.

\* The air consumption ( $Q_{CR}$ ) required for one reciprocation of the rotary actuator alone is shown in the below table, and can be used to simplify the calculation.

### Formulas

$$Q_{CR} = 2V \times \left( \frac{P + 0.1}{0.1} \right) \times 10^{-3}$$

$$Q_{CP} = 2 \times a \times \ell \times \left( \frac{P}{0.1} \right) \times 10^{-6}$$

$$Q_C = Q_{CR} + Q_{CP}$$

$Q_{CR}$ = Air consumption of rotary actuator	[ℓ (ANR)]
$Q_{CP}$ = Air consumption of tubing or piping	[ℓ (ANR)]
$V$ = Internal volume of rotary actuator	[cm <sup>3</sup> ]
$P$ = Operating pressure	[MPa]
$\ell$ = Length of piping	[mm]
$a$ = Internal cross section of piping	[mm <sup>2</sup> ]
$Q_C$ = Air consumption required for one reciprocation of rotary actuator	[ℓ (ANR)]

When selecting a compressor, it is necessary to choose one which has sufficient reserve for the total air consumption of pneumatic actuators downstream. This is affected by factors such as leakage in piping, consumption by drain valves and pilot valves, etc., and reduction of air volume due to drops in temperature.

### Formulas

$$Q_{C2} = Q_C \times n \times \text{Number of actuators} \times \text{Reserve factor}$$

$Q_{C2}$ = Compressor discharge flow rate	[ℓ/min (ANR)]
$n$ = Actuator reciprocations per minute	
<b>Reserve factor:</b> 1.5 or greater	

### Internal Cross Section of Tubing and Steel Piping

Nominal size	O.D. (mm)	I.D. (mm)	Internal cross section $a$ (mm <sup>2</sup> )
T□0425	4	2.5	4.9
T□0604	6	4	12.6
TU0805	8	5	19.6
T□0806	8	6	28.3
1/8B	—	6.5	33.2
T□1075	10	7.5	44.2
TU1208	12	8	50.3
T□1209	12	9	63.6
1/4B	—	9.2	66.5
TS1612	16	12	113
3/8B	—	12.7	127
T□1613	16	13	133
1/2B	—	16.1	204
3/4B	—	21.6	366
1B	—	27.6	598

### Air Consumption

Air consumption:  $Q_{CR}$  ℓ (ANR)

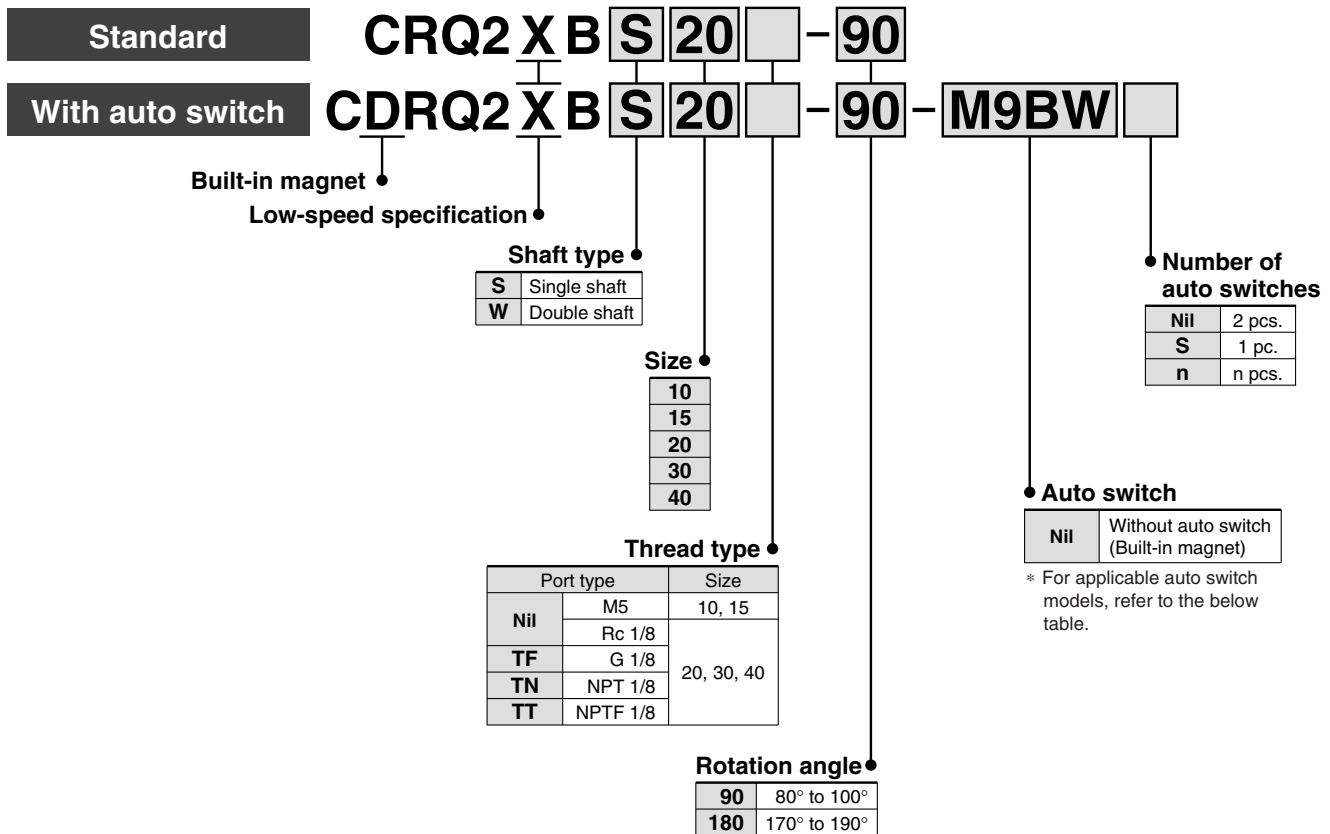
Model	Size	Rotation angle (°)	Internal volume $V$ (cm <sup>3</sup> )	Operating pressure (MPa)										
				0.1	0.15	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0
CRQ2X	10	90	1.2	—	0.006	0.007	0.009	0.012	0.014	0.016	0.018	—	—	—
		180	2.2	—	0.011	0.013	0.018	0.022	0.026	0.031	0.035	—	—	—
	15	90	2.9	—	0.015	0.017	0.023	0.029	0.035	0.041	0.046	—	—	—
		180	5.5	—	0.028	0.033	0.044	0.055	0.066	0.077	0.088	—	—	—
	20	90	7.1	0.028	0.036	0.043	0.057	0.071	0.085	0.099	0.114	0.128	0.142	0.156
		180	13.5	0.054	0.068	0.081	0.108	0.135	0.162	0.189	0.216	0.243	0.270	0.297
	30	90	12.1	0.048	0.060	0.073	0.097	0.121	0.145	0.169	0.193	0.218	0.242	0.266
		180	23.0	0.092	0.115	0.138	0.184	0.230	0.276	0.322	0.368	0.413	0.459	0.505
40	90	20.6	0.082	0.103	0.123	0.164	0.206	0.247	0.288	0.329	0.370	0.411	0.452	
	180	39.1	0.156	0.195	0.234	0.313	0.391	0.469	0.547	0.625	0.703	0.781	0.859	
MSQX	10	190	6.6	0.026	0.033	0.040	0.053	0.066	0.079	0.092	0.106	0.119	0.132	0.145
	20		13.5	0.054	0.068	0.081	0.108	0.135	0.162	0.189	0.216	0.243	0.270	0.297
	30		20.1	0.080	0.101	0.121	0.161	0.201	0.241	0.281	0.322	0.362	0.402	0.442
	50		34.1	0.136	0.171	0.205	0.273	0.341	0.409	0.477	0.546	0.614	0.682	0.750

# Low-Speed Compact Rotary Actuator Rack & Pinion Type

## Series **CRQ2X**

Size: 10, 15, 20, 30, 40

### How to Order



### Applicable Auto Switches/Refer to pages 24 through to 27 for further information on auto switches.

Type	Special function	Electrical entry	Indicator light	Wiring (Output)	Load voltage			Auto switch model		Lead wire length (m)*				Applicable load			
					DC		AC	Perpendicular	In-line	0.5 (Nil)	1 (M)	3 (L)	5 (Z)				
					24 V	12 V	100 V or less										
Solid state switch	—	Grommet	Yes	3-wire (NPN)	5 V, 12 V	—	—	M9NV	M9N	●	—	●	○	IC circuit	Relay, PLC		
				3-wire (PNP)				M9PV	M9P	●	—	●	○				
				2-wire	M9BV			M9B	●	—	●	○					
				3-wire (NPN)	M9NWV			M9NW	●	●	●	○					
	Diagnostic indication (2-color)			Water resistant (2-color)**	3-wire (PNP)			24 V	12 V	M9PWV	M9PW	●	●	●		○	IC circuit
					2-wire					M9BWV	M9BW	●	●	●		○	
					3-wire (NPN)			5 V, 12 V	M9NAV	M9NA	○	○	●	○		IC circuit	
					3-wire (PNP)				M9PAV	M9PA	○	○	●	○			
2-wire	12 V	M9BAV	M9BA	○	○	●	○	—									
Reed switch	—	Grommet	No	2-wire	24 V	12 V	100 V or less	A90V	A90	●	—	●	—	IC circuit	Relay, PLC		
			Yes	3-wire (NPN equiv.)	—	5 V	—	A96V	A96	●	—	●	—		—	—	
				2-wire	24 V	12 V	100 V	A93V	A93	●	—	●	—	—		Relay, PLC	

\*\* Although it is possible to mount water resistant type auto switches, note that the rotary actuator itself is not of water resistant construction.

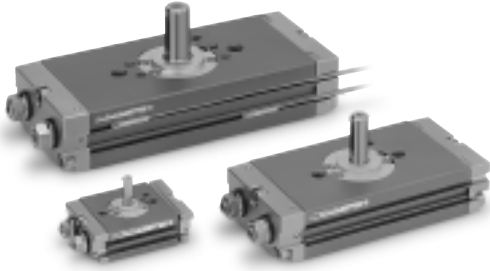
\* Lead wire length symbols: 0.5 m ..... Nil (Example) M9NW  
 1 m ..... M M9NWM  
 3 m ..... L M9NWL  
 5 m ..... Z M9NWX

- Auto switches marked with "○" are manufactured upon a receipt of order.
- For details about auto switches with pre-wired connector, refer to "SMC Best Pneumatics 2004" Vol. 11 catalog.
- Auto switches are shipped together, (but not assembled).



# Low-Speed Compact Rotary Actuator Rack & Pinion Type **Series CRQ2X**

## Specifications

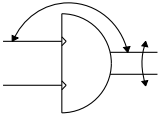


Size	10	15	20	30	40
<b>Fluid</b>	Air (Non-lube)				
<b>Max. operating pressure</b>	0.7 MPa		1 MPa		
<b>Min. operating pressure</b>	0.15 MPa		0.1 MPa		
<b>Ambient and fluid temperature</b>	0° to 60°C (No freezing)				
<b>Cushion</b>	Not attached				
<b>Angle adjustment range</b>	Rotation end ±5°				
<b>Rotation angle</b>	80° to 100°, 170° to 190°				
<b>Port size</b>	M5 x 0.8		Rc 1/8, G 1/8, NPT 1/8, NPTF 1/8		
<b>Output (N·m)*</b>	0.30	0.75	1.8	3.1	5.3

\* Output under the operating pressure at 0.5 MPa. Refer to page 4 for further information.

## Allowable Kinetic Energy and Rotation Time Adjustment Range

### JIS Symbol



Size	Allowable kinetic energy (J)	Stable operational rotation time adjustment range (s/90°)
10	0.00025	0.7 to 5
15	0.00039	
20	0.025	1 to 5
30	0.048	
40	0.081	

Note) If operated where the kinetic energy exceeds the allowable value, this may cause damage to the internal parts and result in product failure. Please pay special attention to the kinetic energy levels when designing, adjusting and during operation to avoid exceeding the allowable limit.

## Weight

Size	Standard weight* (g)	
	90°	180°
10	120	150
15	220	270
20	600	700
30	900	1100
40	1400	1600

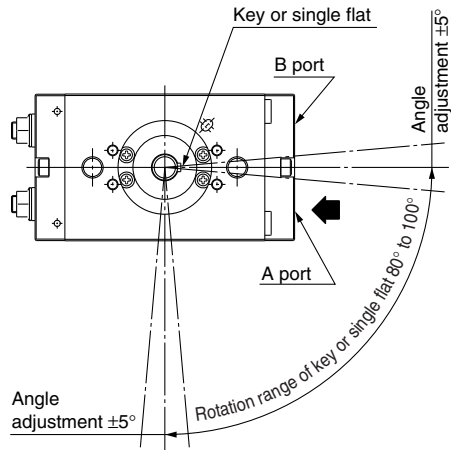
\* Not including the weight of auto switch.

# Series CRQ2X

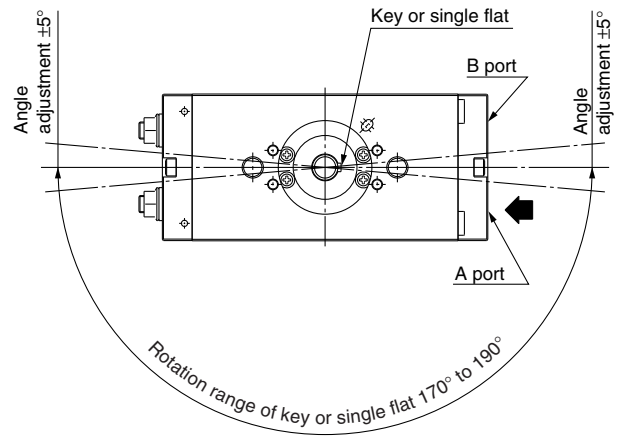
## Rotation Range

When pressurized from the port indicated by the arrow, the shaft will rotate in a clockwise direction.

### Rotation angle: 90°

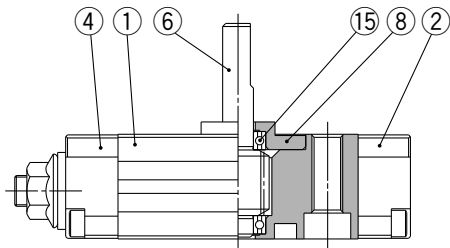
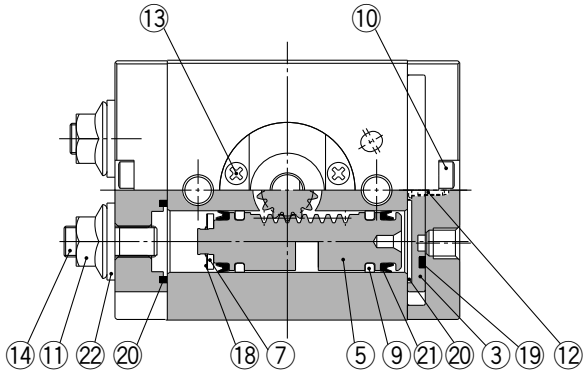


### Rotation angle: 180°

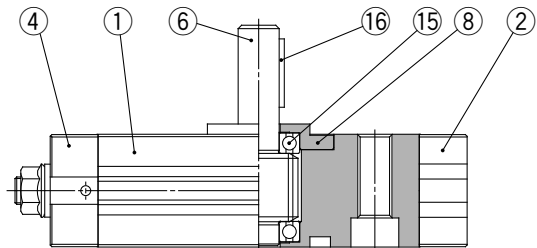
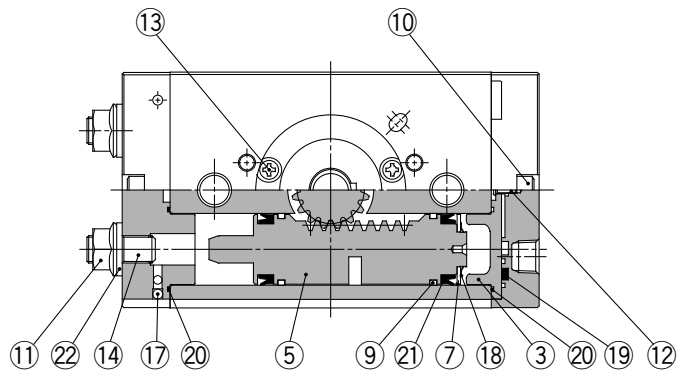


## Construction

### Standard Size 10/15



### Standard Size 20/30/40



### Component Parts

No.	Description	Material
1	Body	Aluminum alloy
2	Cover	Aluminum alloy
3	Plate	Aluminum alloy
4	End cover	Aluminum alloy
5	Piston	Stainless steel
6	Shaft	Stainless steel
		Chrome molybdenum steel
7	Seal retainer	Aluminum alloy
8	Bearing retainer	Aluminum alloy
9	Wear ring	Resin
10	Hexagon socket head cap screw	Stainless steel
11	Hexagon nut with flange	Steel wire
12	Cross recessed screw No. 0	Steel wire

### Component Parts

No.	Description	Material
13	Size: 10, 15 Cross recessed screw No. 0	Steel wire
	Size: 20, 30, 40 Cross recessed screw	
14	Hexagon socket head set screw	Chrome molybdenum steel
15	Bearing	Bearing steel
16	Size: 20, 30, 40 only Parallel key	Carbon steel
17	Size: 20, 30, 40 only Steel ball	Stainless steel
18	CS-type retaining ring	Stainless steel
19	Seal	NBR
20	Gasket	NBR
21	Piston seal	NBR
22	Seal washer	NBR
23	With auto switch only Magnet	—

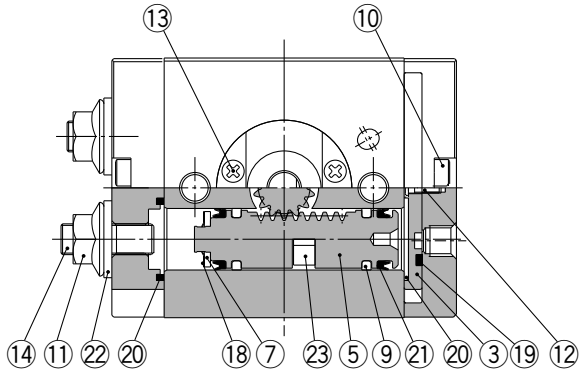
### Replacement Parts

Description	Part no.					Note
	10	15	20	30	40	
Seal kit	P473010-23	P473020-23	P473030-23	P473040-23	P473050-23	A set of above numbers ⑨, ⑰, ⑳, ㉑ and ㉒

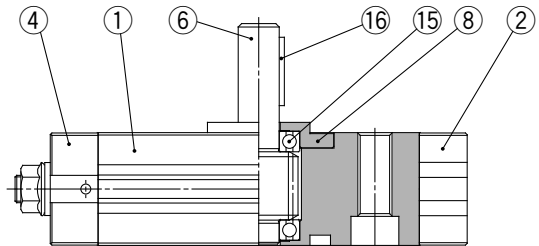
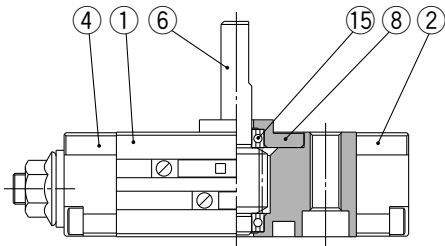
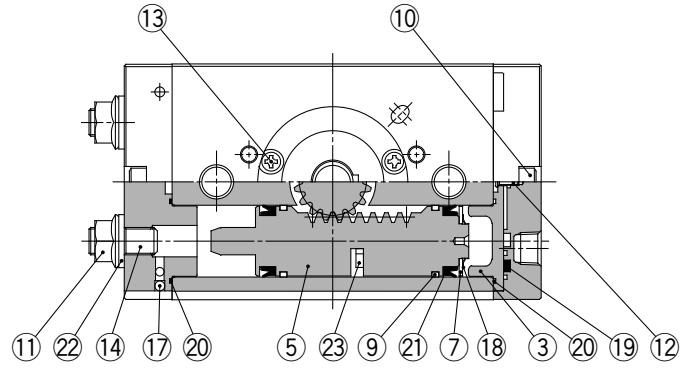
# Series CRQ2X

## Construction

With auto switch  
Size 10/15

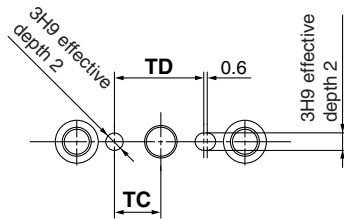
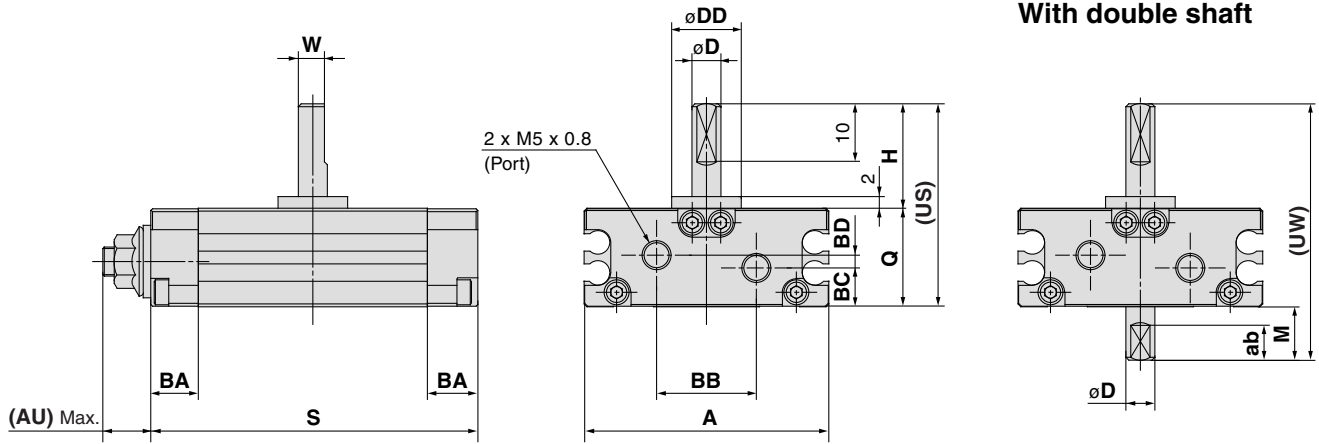
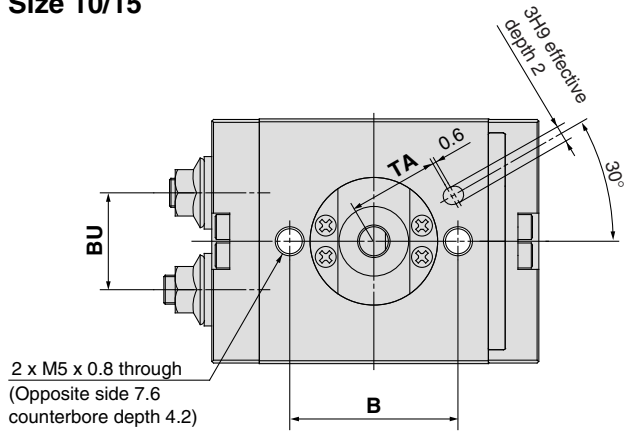


With auto switch  
Size 20/30/40



## Dimensions

### Size 10/15



(mm)

Size	Rotation angle	A	AU*	B	BA	BB	BC	BD	BU	D (g6)	DD (h9)	H
10	90°, 180°	42	(8.5)	29	8.5	17	6.7	2.2	16.7	5	12	18
15	90°, 180°	53	(9.5)	31	9	26.4	10.6	—	23.1	6	14	20

Size	Rotation angle	W	Q	S	US	UW	ab	M	TA	TC	TD
10	90°	4.5	17	56	35	44	6	9	15.5	8	15.4
	180°			69							
15	90°	5.5	20	65	40	50	7	10	16	9	17.6
	180°			82							

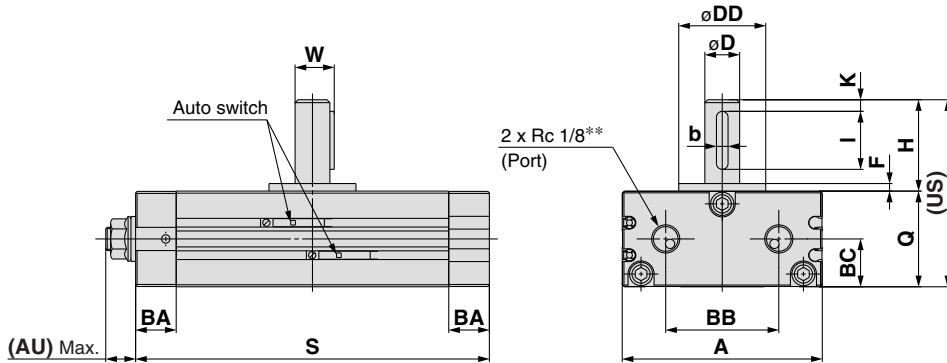
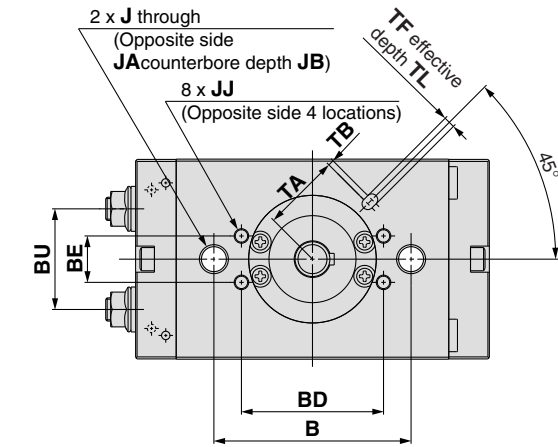
\* The AU dimension is not the dimension at the time of shipment, since its dimension is for adjustment parts.

S: Upper 90°, Lower 180°

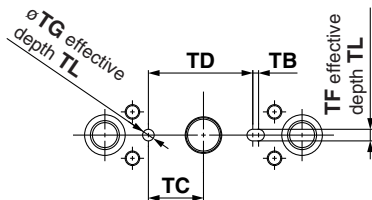
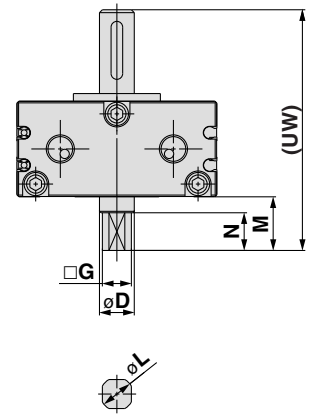
# Series CRQ2X

## Dimensions

### Size 20/30/40



### With double shaft



Size	Rotation angle	A	AU*	B	BA	BB	BC	BD	BE	BU	D (g6)	DD (h9)	F	H	J	JA	JB	JJ	K
20	90°, 180°	63	(11)	50	14	34	14.5	—	—	30.4	10	25	2.5	30	M8 x 1.25	11	6.5	—	3
30	90°, 180°	69	(11)	68	14	39	16.5	49	16	34.7	12	30	3	32	M10 x 1.5	14	8.5	M5 x 0.8 depth 6	4
40	90°, 180°	78	(13)	76	16	47	18.5	55	16	40.4	15	32	3	36	M10 x 1.5	14	8.6	M6 x 1 depth 7	5

Size	Rotation angle	Q	S	W	Keyway dimensions		US	TA	TB	TC	TD	TF (H9)	TG (H9)	TL	UW	G	M	N	L
					b	I													
20	90°	29	104	11.5	4 <sup>0</sup> <sub>-0.03</sub>	20	59	24.5	1	13.5	27	4	4	2.5	74	8 <sup>0</sup> <sub>-0.1</sub>	15	11	9.6 <sup>0</sup> <sub>-0.1</sub>
	180°		130		11.4 <sup>0</sup> <sub>-0.1</sub>														
30	90°	33	122	13.5	4 <sup>0</sup> <sub>-0.03</sub>	20	65	27	2	19	36	4	4	2.5	83	10 <sup>0</sup> <sub>-0.1</sub>	18	13	11.4 <sup>0</sup> <sub>-0.1</sub>
	180°		153		11.4 <sup>0</sup> <sub>-0.1</sub>														
40	90°	37	139	17	5 <sup>0</sup> <sub>-0.03</sub>	25	73	32.5	2	20	39.5	5	5	3.5	93	11 <sup>0</sup> <sub>-0.1</sub>	20	15	14 <sup>0</sup> <sub>-0.1</sub>
	180°		177		14 <sup>0</sup> <sub>-0.1</sub>														

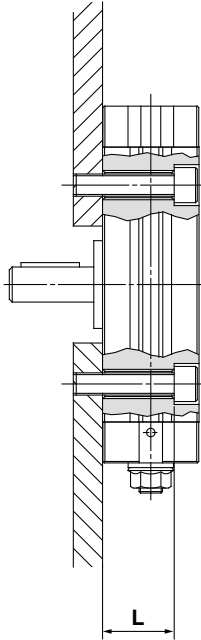
\* The AU dimension is not the dimension at the time of shipment, since its dimension is for adjustment parts.

\*\* In addition to Rc 1/8, G 1/8, NPT 1/8, NPTF 1/8 are also available.

S: Upper 90°, Lower 180°

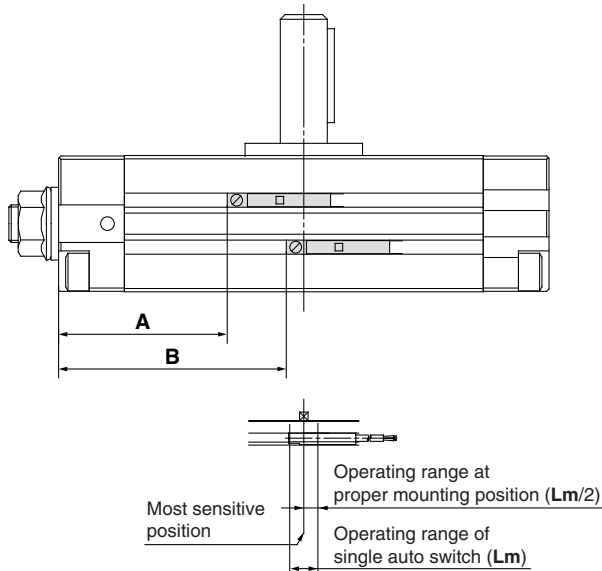
### Unit Used as Flange Mount

The L dimensions of this unit are shown in the below table. When hexagon socket head cap bolt of the JIS standard is used, the head of the bolt will recess into the groove of actuator.



Size	L	Screw
10	13	M4
15	16	M4
20	22.5	M6
30	24.5	M8
40	28.5	M8

### Auto Switch Proper Mounting Position (at Rotation End Detection)



Size	Rotation angle	Reed switch				Solid state switch			
		A	B	Operating angle ( $\theta$ m)	Hysteresis angle	A	B	Operating angle ( $\theta$ m)	Hysteresis angle
10	90°	15	21.5	63°	12°	19	25.5	75°	3°
	180°	18	31			22	35		
15	90°	18.5	27	52°	9°	22.5	31	69°	3°
	180°	22.5	39.5			26.5	43.5		
20	90°	36	48.5	41°	9°	40	52.5	56°	4°
	180°	42	67.5			46	71.5		
30	90°	43	59	32°	7°	47	63	43°	3°
	180°	51	82			55	86		
40	90°	50	69	24°	5°	54	73	36°	4°
	180°	59.5	97.5			63.5	101.5		

Operating angle  $\theta$ m: Value of the operating range of single auto switch (Lm) as represented by rotation angle for shaft

Hysteresis angle: Value of the auto switch hysteresis as represented by angle

Note) For actual setting, adjustment shall be made after checking the auto switch operating condition.

# Series CRQ2X/MSQX Auto Switch Specifications

## Auto Switch Common Specifications

Type	Reed switch	Solid state switch
Leakage current	None	3-wire: 100 $\mu$ A or less 2-wire: 0.8 mA or less
Operating time	1.2 ms	1 ms or less
Impact resistance	300 m/s <sup>2</sup>	1000 m/s <sup>2</sup>
Insulation resistance	50 M $\Omega$ or more at 500 VDC Mega (between lead wire and case)	
Withstand voltage	1500 VAC for 1 minute (between lead wire and case)	1000 VAC for 1 minute (between lead wire and case)
Ambient temperature	-10 to 60°C	
Enclosure	IEC60529 standard IP67, JIS C 0920 waterproof construction	
Standard	Conforming to CE Standards	

## Lead Wire Length

Lead wire length indication

(Example) **D-M9BW** **L**

Lead wire length

Nil	0.5 m
M	1 m
L	3 m
Z	5 m

Note 1) Applicable auto switch with 5 m lead wire "Z"

Solid state switch: Manufactured upon receipt of order as standard.

Note 2) To designate solid state switches with flexible specifications, add "-61" after the lead wire length. Flexible cable is used for D-M9□(V), D-M9□W(V), D-M9□A(V) as standard. There is no need to place the suffix -61 to the end of part number.

Note 3) 1 m (M): D-M9□W, D-M9□A(V).

Note 4) Lead wire length tolerance

Lead wire length	Tolerance
0.5 m	±15 mm
1 m	±30 mm
3 m	±90 mm
5 m	±150 mm

## Contact Protection Box: CD-P11, CD-P12

### <Applicable switch model>

D-A9□(V) type

The above auto switch type does not have a built-in contact protection circuit.

- ① Where the operation load is an inductive load.
- ② Where the wiring length to load is greater than 5 m.
- ③ Where the load voltage is 100 VAC.

Therefore, use a contact protection box with the switch for any of the above cases:

The contact life may be shortened (due to permanent energizing conditions). Since the solid state auto switch is a semiconductor switch which has no contacts, no contact protection box is needed.

- ④ Where the load voltage is 110 VAC.

When the load voltage is increased by more than 10% to the rating of applicable auto switches above, use a contact protection box (CD-P11) to reduce the upper limit of the load current by 10% so that it can be set within the range of the load current range.

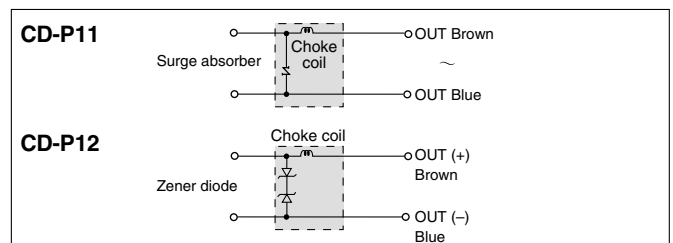
### Specifications

Part no.	CD-P11		CD-P12
Load voltage	100 VAC	200 VAC	24 VDC
Max. load current	25 mA	12.5 mA	50 mA

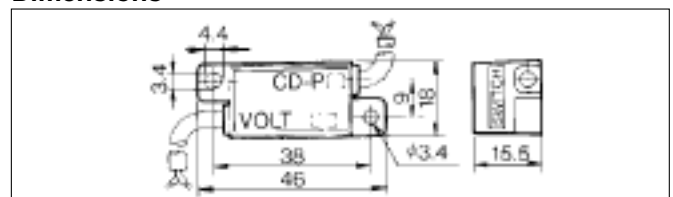
\* Lead wire length — Switch connection side 0.5 m  
Load connection side 0.5 m



### Internal Circuit



### Dimensions



### Connection

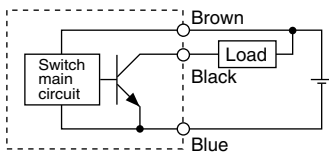
To connect a switch unit to a contact protection box, connect the lead wire from the side of the contact protection box marked SWITCH to the lead wire coming out of the switch unit. Keep the switch as close as possible to the contact protection box, with a lead wire length of no more than 1 meter.



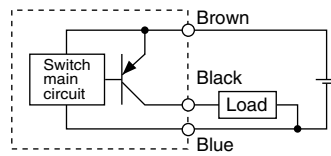
# Auto Switch Connections and Examples

## Basic Wiring

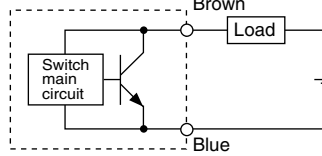
### Solid state 3-wire, NPN



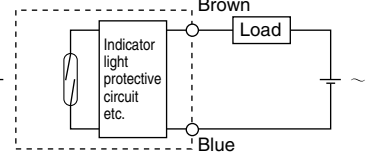
### Solid state 3-wire, PNP



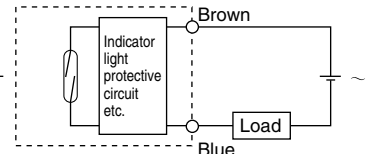
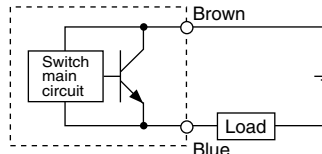
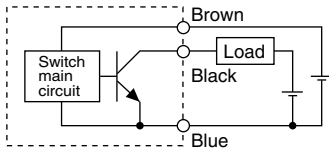
### 2-wire (Solid state)



### 2-wire (Reed)

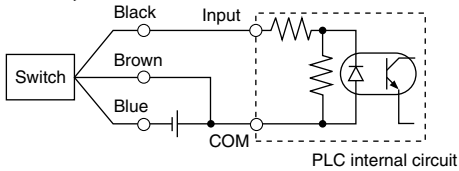


(Power supplies for switch and load are separate.)

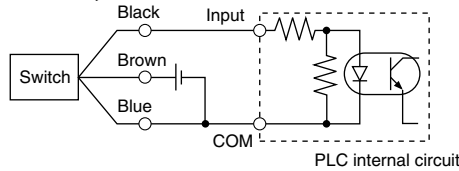


## Example of Connection to PLC (Programmable Logic Controller)

### • Sink input specification 3-wire, NPN

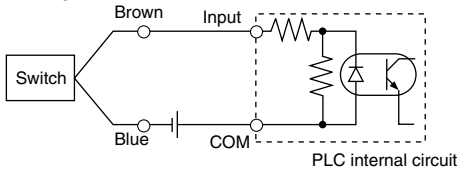


### • Source input specification 3-wire, PNP

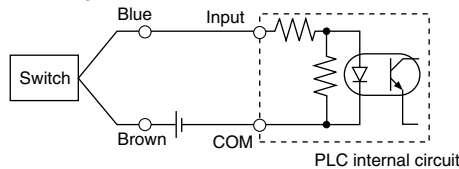


Connect according to the applicable PLC input specifications, since the connection method will vary depending on the PLC input specifications.

### 2-wire



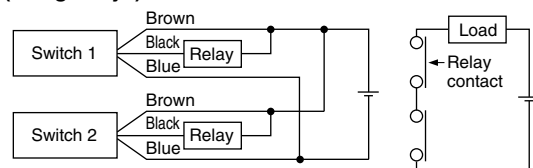
### 2-wire



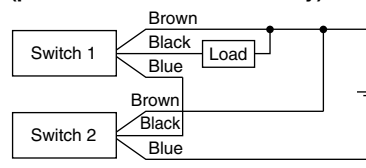
## Example of AND (Serial) and OR (Parallel) Connection

### • 3-wire

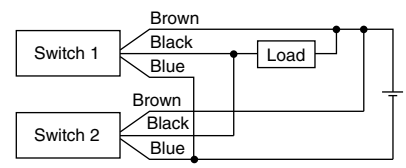
#### AND connection for NPN output (using relays)



#### AND connection for NPN output (performed with switches only)

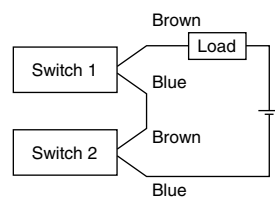


#### OR connection for NPN output



The indicator lights will illuminate when both switches are turned ON.

#### 2-wire with 2-switch AND connection

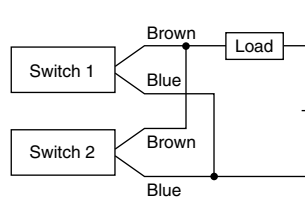


When two switches are connected in series, a load may malfunction because the load voltage will decrease when in the ON state. The indicator lights will illuminate if both of the switches are in the ON state.

$$\begin{aligned} \text{Load voltage at ON} &= \text{Power supply voltage} - \text{Residual voltage} \times 2 \text{ pcs.} \\ &= 24 \text{ V} - 4 \text{ V} \times 2 \text{ pcs.} \\ &= 16 \text{ V} \end{aligned}$$

Example: Power supply is 24 VDC.  
Internal voltage drop in switch is 4 V.

#### 2-wire with 2-switch OR connection



(Solid state)

When two switches are connected in parallel, a malfunction may occur because the load voltage will increase when in the OFF state.

$$\begin{aligned} \text{Load voltage at OFF} &= \text{Leakage current} \times 2 \text{ pcs.} \\ &\quad \times \text{Load impedance} \\ &= 1 \text{ mA} \times 2 \text{ pcs.} \times 3 \text{ k}\Omega \\ &= 6 \text{ V} \end{aligned}$$

Example: Load impedance is 3 kΩ.  
Leakage current from switch is 1 mA.

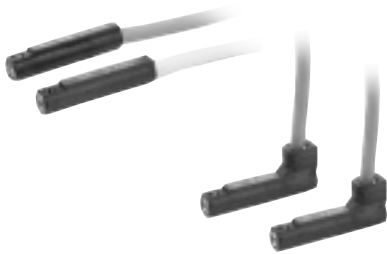
(Reed)

Because there is no current leakage, the load voltage will not increase when turned OFF. However, depending on the number of switches in the ON state, the indicator lights may sometimes dim or not light because of the dispersion and reduction of the current flowing to the switches.

# Reed Switch: Direct Mounting Style

## D-A90(V)/D-A93(V)/D-A96(V)

### Grommet



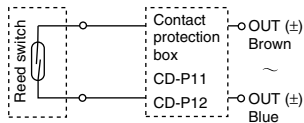
### Caution

#### Precautions

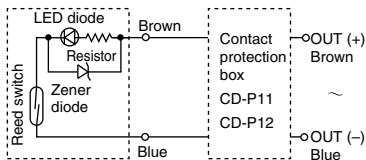
Fix the switch with the existing screw installed on the switch body. The switch may be damaged if a screw other than the one supplied is used.

### Auto Switch Internal Circuit

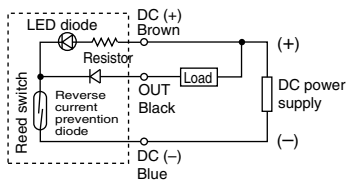
#### D-A90(V)



#### D-A93(V)



#### D-A96(V)



- Note) ① In a case where the operation load is an inductive load.  
 ② In a case where the wiring load is greater than 5 m.  
 ③ In a case where the load voltage is 100 VAC.

Use the auto switch with a contact protection box in any of the above mentioned cases. (For details about the contact protection box, refer to page 22.)

### Auto Switch Specifications

PLC: Programmable Logic Controller

D-A90/D-A90V (Without indicator light)						
Auto switch part no.	D-A90	D-A90V	D-A90	D-A90V	D-A90	D-A90V
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Applicable load	IC circuit, Relay, PLC					
Load voltage	24 VAC/DC or less		48 VAC/DC or less		100 VAC/DC or less	
Maximum load current	50 mA		40 mA		20 mA	
Contact protection circuit	None					
Internal resistance	1 Ω or less (including lead wire length of 3 m)					
Standard	Conforming to CE Standards					
D-A93/D-A93V/D-A96/D-A96V (With indicator light)						
Auto switch part no.	D-A93	D-A93V	D-A93	D-A93V	D-A96	D-A96V
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Applicable load	Relay, PLC				IC circuit	
Load voltage	24 VDC		100 VAC		4 to 8 VDC	
Load current range and max. load current	5 to 40 mA		5 to 20 mA		20 mA	
Contact protection circuit	None					
Internal voltage drop	D-A93 — 2.4 V or less (to 20 mA)/3 V or less (to 40 mA)				D-A93V — 2.7 V or less	
Indicator light	Red LED illuminates when turned ON.					
Standard	Conforming to CE Standards					

#### Lead wires

D-A90(V)/D-A93(V) — Oilproof heavy-duty vinyl cable:  $\phi 2.7$ , 0.18 mm<sup>2</sup> x 2 cores (Brown, Blue), 0.5 m

D-A96(V) — Oilproof heavy-duty vinyl cable:  $\phi 2.7$ , 0.15 mm<sup>2</sup> x 3 cores (Brown, Black, Blue), 0.5 m

Note 1) Refer to page 22 for reed switch common specifications.

Note 2) Refer to page 22 for lead wire lengths.

Note 3) If load current is less than 5 mA, the visibility of the indicator light is decreased. If less than 2.5 mA, the light may become invisible. From the point of view of contact output, however, it is not a problem as long as the load current is more than 1 mA.

### Weight

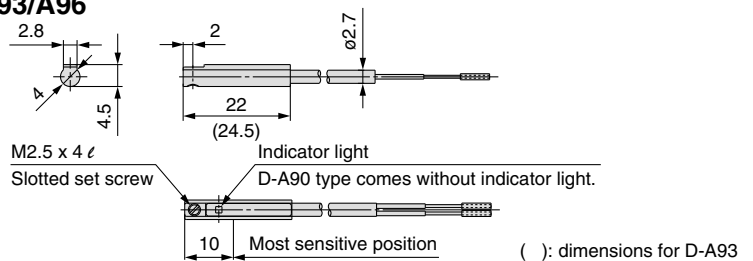
Unit: g

Auto switch part no.	D-A90(V)	D-A93(V)	D-A96(V)
Lead wire length (m)	0.5	6	8
	3	30	41

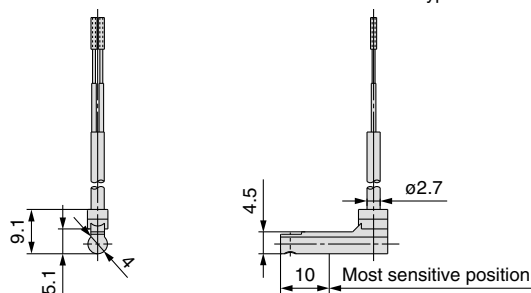
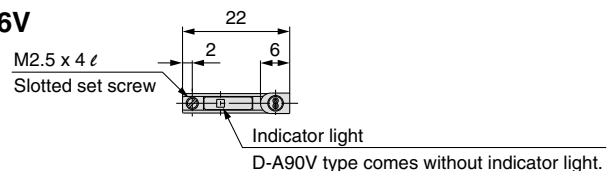
### Dimensions

Unit: mm

#### D-A90/A93/A96



#### D-A90V/A93V/A96V



# Solid State Switch: Direct Mounting Style D-M9N(V)/D-M9P(V)/D-M9B(V)

## Grommet

- 2-wire load current is reduced (2.5 to 40 mA).
- UL certified (style 2844) lead cable is used.
- Flexibility is 1.5 times greater than the conventional model (SMC comparison).
- Using flexible cable as standard spec.
- Brightness of indicator light is 2 times greater than the conventional model (SMC comparison).



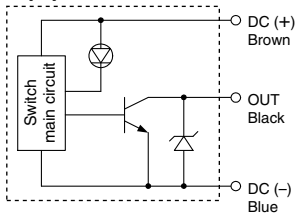
## Caution

### Precautions

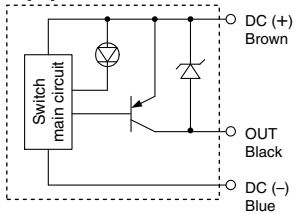
Fix the switch with the existing screw installed on the switch body. The switch may be damaged if a screw other than the one supplied is used.

## Auto Switch Internal Circuit

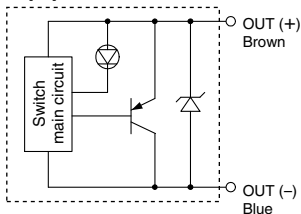
### D-M9N(V)



### D-M9P(V)



### D-M9B(V)



## Auto Switch Specifications

PLC: Programmable Logic Controller

D-M9□/D-M9□V (With indicator light)						
Auto switch part no.	D-M9N	D-M9NV	D-M9P	D-M9PV	D-M9B	D-M9BV
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3-wire				2-wire	
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24 VDC relay, PLC	
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)				—	
Current consumption	10 mA or less				—	
Load voltage	28 VDC or less		—		24 VDC (10 to 28 VDC)	
Load current	40 mA or less				2.5 to 40 mA	
Internal voltage drop	0.8 V or less				4 V or less	
Leakage current	100 μA or less at 24 VDC				0.8 mA or less	
Indicator light	Red LED illuminates when turned ON.					
Standard	Conforming to CE Standards					

- Lead wires — Oilproof heavy-duty vinyl cable:  $\phi 2.7 \times 3.2$  ellipse
  - D-M9B(V) 0.15 mm<sup>2</sup> x 2 cores
  - D-M9N(V), D-M9P(V) 0.15 mm<sup>2</sup> x 3 cores

Note 1) Refer to page 22 for solid state switch common specifications.

Note 2) Refer to page 22 for lead wire lengths.

## Weight

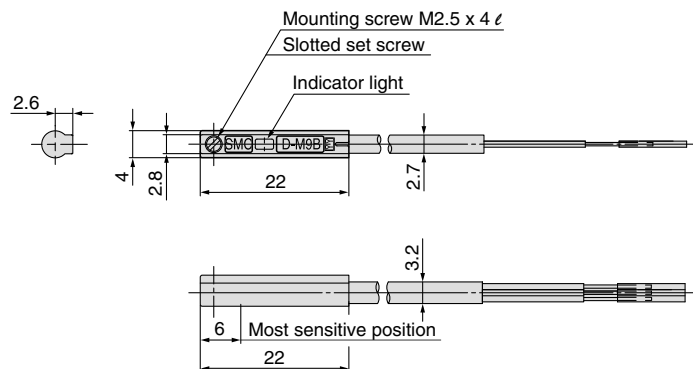
Unit: g

Auto switch part no.	D-M9N(V)	D-M9P(V)	D-M9B(V)
Lead wire length (m)	0.5	8	7
	3	41	38
	5	68	63

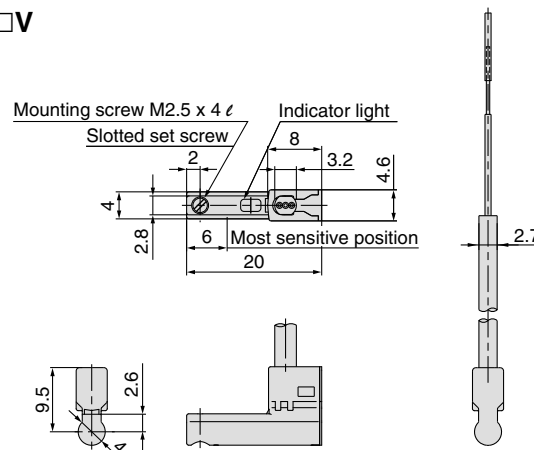
## Dimensions

Unit: mm

### D-M9□



### D-M9□V



# 2-Color Indication Solid State Switch: Direct Mounting Style

## D-M9NW(V)/D-M9PW(V)/D-M9BW(V)



### Grommet

- 2-wire load current is reduced (2.5 to 40 mA).
- UL certified (style 2844) lead cable is used.
- Flexibility is 1.5 times greater than the conventional model (SMC comparison).
- Using flexible cable as standard spec.
- The optimum operating position can be determined by the color of the light. (Red → Green ← Red)
- Brightness of indicator light is 2 times greater than the conventional model (SMC comparison).



### Auto Switch Specifications

PLC: Programmable Logic Controller

D-M9□W/D-M9□WV (With indicator light)						
Auto switch part no.	D-M9NW	D-M9NWV	D-M9PW	D-M9PWV	D-M9BW	D-M9BWV
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3-wire			2-wire		
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24 VDC relay, PLC	
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)				—	
Current consumption	10 mA or less				—	
Load voltage	28 VDC or less		—		24 VDC (10 to 28 VDC)	
Load current	40 mA or less				2.5 to 40 mA	
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)				4 V or less	
Leakage current	100 μA or less at 24 VDC				0.8 mA or less	
Indicator light	Operating position ..... Red LED illuminates. Optimum operating position ..... Green LED illuminates.					
Standard	Conforming to CE Standards					

- Lead wires — Oilproof heavy-duty vinyl cable:  $\phi 2.7 \times 3.2$  ellipse  
D-M9BW(V) 0.15 mm<sup>2</sup> x 2 cores  
D-M9NW(V), D-M9PW(V) 0.15 mm<sup>2</sup> x 3 cores

Note 1) Refer to page 22 for solid state switch common specifications.

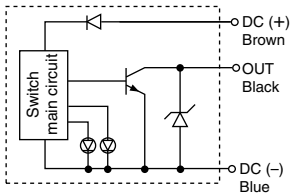
Note 2) Refer to page 22 for lead wire lengths.

### Weight

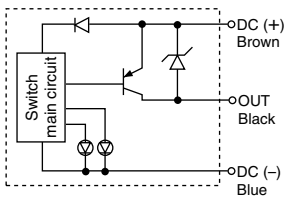
Unit: g

### Auto Switch Internal Circuit

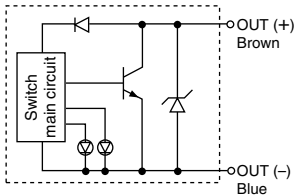
#### D-M9NW(V)



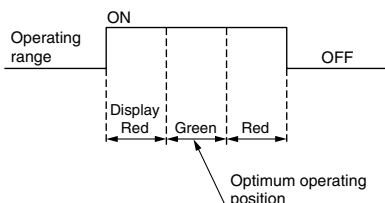
#### D-M9PW(V)



#### D-M9BW(V)



### Indicator light / Display method

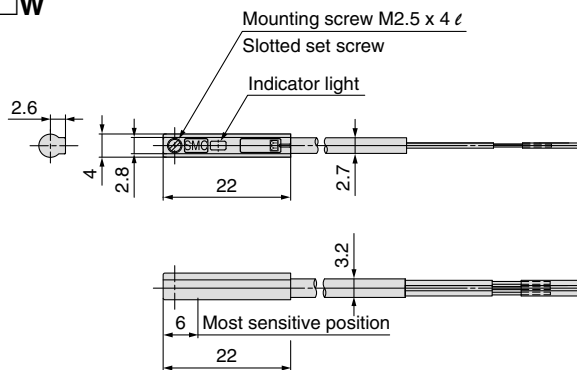


Auto switch part no.	D-M9NW(V)	D-M9PW(V)	D-M9BW(V)
Lead wire length (m)	0.5	8	8
	1	14	14
	3	41	41
	5	68	68

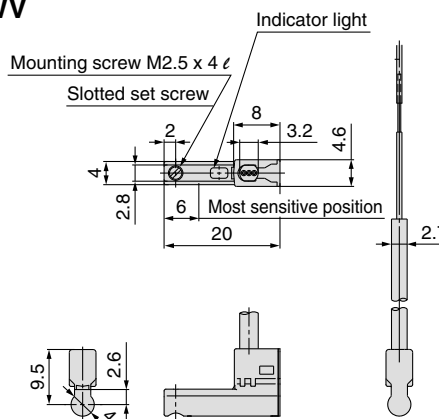
### Dimensions

Unit: mm

#### D-M9□W



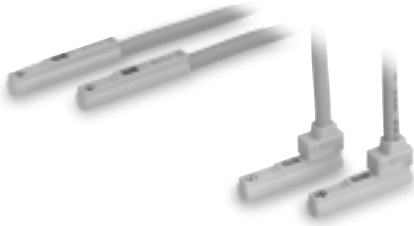
#### D-M9□WV



# Water Resistant 2-Color Indication Solid State Switch: Direct Mounting Style D-M9NA(V)/D-M9PA(V)/D-M9BA(V) C €

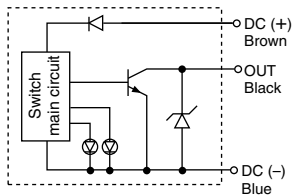
## Grommet

- Water (coolant) resistant type
- 2-wire load current is reduced (2.5 to 40 mA).
- UL certified (style 2844) lead cable is used.
- The optimum operating position can be determined by the color of the light. (Red Green Red)

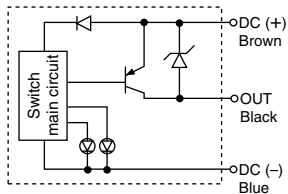


## Auto Switch Internal Circuit

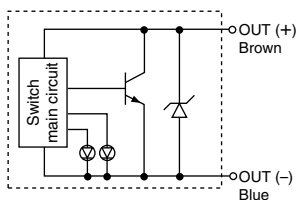
### D-M9NA(V)



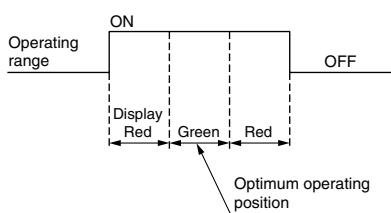
### D-M9PA(V)



### D-M9BA(V)



## Indicator light / Display method



## Auto Switch Specifications

PLC: Programmable Logic Controller

D-M9□A/D-M9□AV (With indicator light)						
Auto switch part no.	D-M9NA	D-M9NAV	D-M9PA	D-M9PAV	D-M9BA	D-M9BAV
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3-wire			2-wire		
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24 VDC relay, PLC	
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)				—	
Current consumption	10 mA or less				—	
Load voltage	28 VDC or less		—		24 VDC (10 to 28 VDC)	
Load current	40 mA or less				2.5 to 40 mA	
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)				4 V or less	
Leakage current	100 μA or less at 24 VDC				0.8 mA or less	
Indicator light	Operating position ..... Red LED illuminates. Optimum operating position ..... Green LED illuminates.					
Standard	Conforming to CE Standards					

- Lead wires — Oilproof heavy-duty vinyl cable:  $\phi 2.7 \times 3.2$  ellipse  
D-M9BA(V) 0.15 mm<sup>2</sup> x 2 cores  
D-M9NA(V), D-M9PA(V) 0.15 mm<sup>2</sup> x 3 cores

Note 1) Refer to page 22 for solid state switch common specifications.

Note 2) Refer to page 22 for lead wire lengths.

## Weight

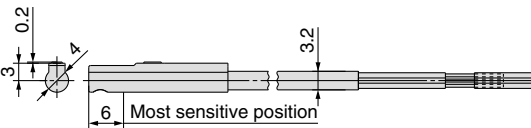
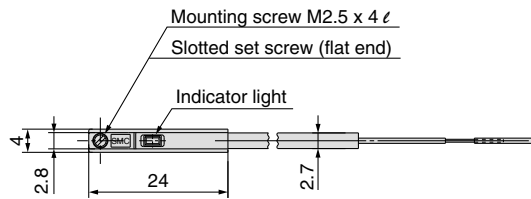
Unit: g

Auto switch part no.	D-M9NA(V)	D-M9PA(V)	D-M9BA(V)
Lead wire length (m)	0.5	8	7
	1	14	13
	3	41	38
	5	68	63

## Dimensions

Unit: mm

### D-M9□A



### D-M9□AV

