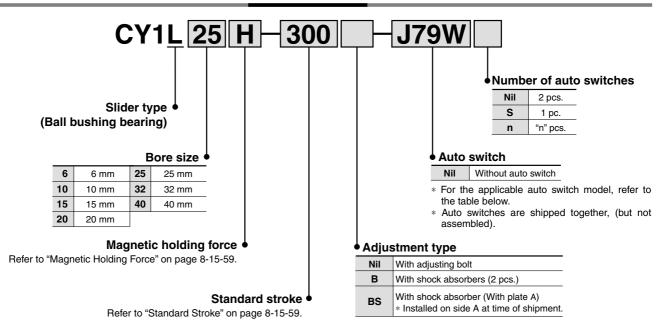
Magnetically Coupled Rodless Cylinder Slider Type: Ball Bushing Bearing

Series CY1L

ø6, ø10, ø15, ø20, ø25, ø32, ø40





Applicable Auto Switch/Refer to page 8-30-1 for further information on auto switches.

		Electrical	r light	Wiring	L	oad volta	age	Auto swite	ch model	Lead v			<u> </u>	Pre-wire	Appli	cable				
Туре	Special function	entry	Indicator I	(Output)	D	C	AC	Perpendicular	In-line	0.5 (Nil)	(L)		None (N)	connector		ad				
_		0		3-wire (NPN equivalent)	_	5 V	_	_	A76H	•	•	_	_	_	IC circuit					
switch	_	Grommet		, ,	_	_	200V	A72	A72H	•	•	_	_	_						
જ			Yes			12 V	100 V	A73	A73H	•	•	•	_	_		Relay,				
Reed		Connector		2-wire	24 V	12 V	_	A73C	_	•	•	•	•	_] —	PLC				
Œ	Diagnostic indication (2-color indication)	Grommet				24 V		24 V	24 V		_	A79W	_	•	•	_	_	_		
		Grommet		3-wire (NPN)	,	5 V, 12 V	F7NV	F79	•	•	0	_	0	IC						
				3-wire (PNP)				F7PV	F7P	•	•	0	_	0	circuit					
_			Connector 2-wire		12 V		F7BV	J79	•	•	0	_	0							
switch		Connector				12 V	J79C	_	•	•	•	•	_	-						
S	Diamantia indication			3-wire (NPN)	-1/ /21/		F7NWV	F79W	•	•	0	_	0	IC	Relay,					
state	Diagnostic indication (2-color indication)		Yes	3-wire (PNP)	24 V	5 V, 12 V	_	_	F7PW	•	•	0	—	0	circuit	PLC				
S S	(2-color indication)				2-wire 12 V F7BW J79W — F7BA	J79W	•	•	0	_	0									
Solid	Water resistant	Grommet		2-wire			12 V	12 V	12 V		_	F7BA	_	•	0	—	0	_		
U)	(2-color indication)								F7BAV	_	_	•	0	_	_					
	With diagnostic output (2-color indication)			4-wire (NPN)		5 V, 12 V		_	F79F	•	•	0	_	0	IC circuit					

* Solid state switches marked with "O" are produced upon receipt of order.

3 m L (Example) A73CL 5 m Z (Example) A73CZ None N (Example) A73CN

• Since there are other applicable auto switches than listed, refer to page 8-15-67 for details.

• For details about auto switches with pre-wire connector, refer to page 8-30-52.



^{*} Lead wire length symbols: 0.5 mNil (Example) A73C

Magnetically Coupled Rodless Cylinder Slider Type: Ball Bushing Bearing Series CY1L



Long service life design

Ball bushings having excellent trafficability are used in the guides.

Ball bushing: With grease cup

Easy piping and wiring

Hollow shafts are used, and centralization of ports on one side makes piping easy. Auto switches can be mounted through the use of special switch rails.

Shock absorbers and adjusting bolt are standard equipment

Impacts at stroke end due to high speed use can be absorbed, and fine adjustment of the stroke is possible.



Made to Order Specifications (For details, refer to page 8-31-1.)

Symbol	Specifications
-XB13	Low speed cylinder (5 to 50 mm/s)
-X116	Hydro specifications rodless cylinder
-X168	Helical insert thread specifications
-X322	Outside of cylinder tube with hard chrome plated

Amount of Adjustment by Adjusting Bolt

Bore size (mm)	Amount of adjustment (both ends) by adjusting bolt (mm)
6	12
10	11
15	7
20	11
25	10
32	11
40	9

^{*} Since the cylinder is in an intermediate stop condition when stroke adjustment is performed, use caution regarding the operating pressure and the kinetic energy of the load.

Principal Parts Material

Description	Material	Note
Cylinder tube	Stainless steel	_
Magnet	Rare earth magnet	_
Slide block	Aluminum alloy	Hard anodized

Model

Туре	Bearing type	Model	Bore size (mm)	With auto switch	Adjustment type
Slider type	Ball bushing bearing	CY1L	6, 10, 15, 20, 25, 32, 40	D-A7/A8 D-F7/J7	With adjusting bolt With shock absorber

Specifications

Fluid	Air		
Proof pressure	1.05 MPa		
Maximum operating pressure	0.7 MPa		
Minimum operating pressure	0.18 MPa		
Ambient and fluid temperature	−10 to 60°C		
Piston speed *	50 to 1000 mm/s		
Cushion	Shock absorber/Rubber bumper		
Lubrication	Non-lube		
Stroke length tolerance	0 to 250 st: $^{+1.0}_{0}$, 251 to 1000 st: $^{+1.4}_{0}$, 1001 st and up: $^{+1.8}_{0}$		
Mounting orientation	Free		
Standard equipment	Auto switch mounting rail		

^{*} In the case of setting an auto switch at the intermediate position, the maximum piston speed is subject to restrict for detection upon the response time of a load (Relays, Sequence controller, etc.) the maximum detectable piston speed is controlled by the response time of the load (relays, sequence controller, etc.).

bearing 23, 32, 40 D-F7/37 With Shock absorber

— MG□ CX□

D-

 $MX\square$

MTS

 $MY \square$

CY

D-

-X

20-

Data

Standard Stroke

Bore size (mm)	Standard stroke (mm)	Maximum available stroke (mm)
6	50, 100, 150, 200	300
10	50, 100, 150, 200, 250, 300	500
15	50, 100, 150, 200, 250, 300, 350 400, 450, 500	750
20		1000
25 32	100, 150, 200, 250, 300, 350 400, 450, 500, 600, 700, 800	1500
40	100, 150, 200, 250, 300, 350 400, 450, 500, 600, 700, 800 900, 1000	1500

Magnetic Holding Force (N)

Bore size (mm)		6	10	15	20	25	32	40
Holding force	Type H	19.6	53.9	137	231	363	588	922
	Type L	_	_	81.4	154	221	358	569

Weight

								(kg)
Bore size (mm)		6	10	15	20	25	32	40
Basic weight	CY1L□H	0.324	0.580	1.10	1.85	2.21	4.36	4.83
	CY1L□L	_	_	1.02	1.66	2.04	4.18	4.61
Additional weight per each 50mm of stroke		0.044	0.077	0.104	0.138	0.172	0.267	0.406

Calculation

(Example) CY1L32H-500

[•] Basic weight ····· 4.36 kg • Additional weight ····· 0.267/50 st • Cylinder stroke ····· 500 st 4.36 + 0.267 x 500 ÷ 50 = 7.03 kg

A Precautions

Be sure to read before handling. Refer to pages 8-34-3 to 8-34-6 for Safety Instructions and Actuator Precautions.

Operation

Marning

Be aware of the space between the plates and the slide block.

Take sufficient care to avoid getting your hands or fingers caught when the cylinder is operated.

2. Do not apply a load to a cylinder which is greater than the allowable value stated in the "Model Selection" pages.

Mounting

⚠ Caution

1. Avoid operation with the external slider fixed to the mounting surface.

The cylinder should be operated with the plates fixed to the mounting surface.

2. Perform mounting so that the external slider will operate through the entire stroke at the minimum operating pressure.

If the mounting surface is not flat, the guides will be warped, increasing the minimum operating pressure and causing premature wear of the bearings. Therefore, mounting should be performed so that the external slider will operate through the entire stroke at the minimum operating pressure. A mounting surface with a high degree of flatness is desirable, but in cases where this is not possible, adjust with shims, etc.

Disassembly and Maintenance

⚠ Warning

1. Use caution as the attractive power of the magnets is very strong.

When removing the external slider and piston slider from the cylinder tube for maintenance, etc., handle with caution, since the magnets installed in each slider have a very strong attractive force.

⚠ Caution

 Use caution when removing the external slider, as the piston slider will be directly attracted to it.

When removing the external slider or piston slider from the cylinder tube, first force the sliders out of their magnetically coupled positions, and then remove them individually when there is no longer any holding force. If they are removed while still magnetically coupled, they will be directly attracted to one another and will not come apart.

- Since the magnetic holding force can be changed (for example, from CY1S25L to CY1S25H), please contact SMC if this is necessary.
- 3. Do not disassemble the magnetic components (piston slider, external slider).

This can cause a loss of holding force and malfunction.

- When disassembling to replace the seals and wear ring, refer to the separate disassembly instructions.
- 5. Use caution to the direction of the external slider and the piston slider.

Since the external slider and piston slider are directional for Ø6, Ø10 and holding force type L, refer to the figures below when performing disassembly or maintenance. Put the external slider and piston slider together, and insert the piston slider into the cylinder tube so that they will have the correct positional relationship as shown in Fig. (1). If they align as shown in Fig. (2), insert the piston slider after turning it around 180°. If the direction is not correct, it will be impossible to obtain the specified holding force.

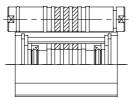


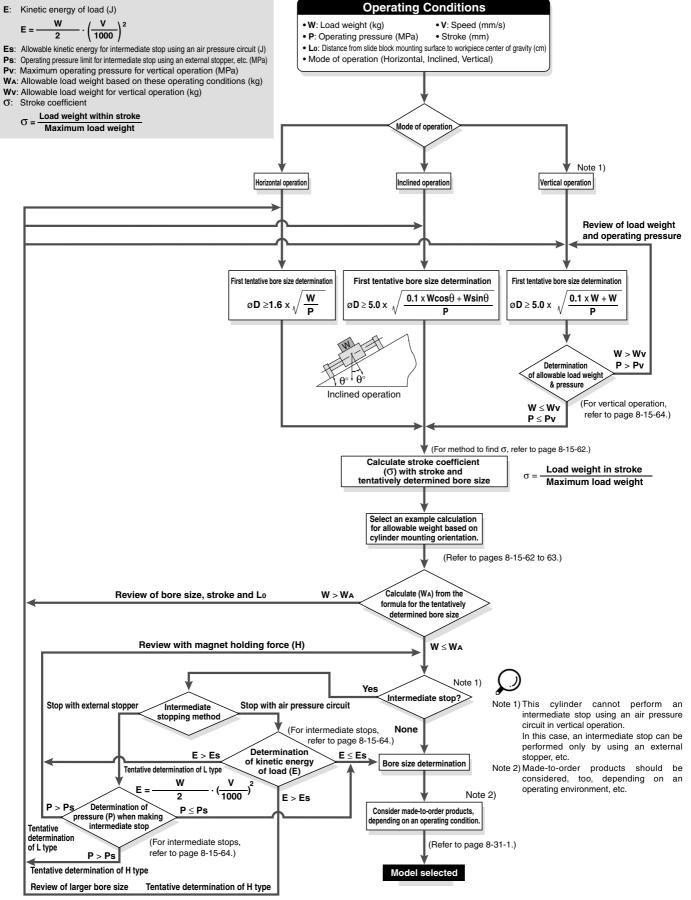


Fig. (1) Correct position

Fig. (2) Incorrect position

Example of ø15 with holding force type L

Model Selection 1



SMC

 $MX\square$

MTS

 $MY \square$

CY

MG

CX

D-

20

Data

Model Selection 2

Caution on Design (1)

How to Find σ when Selecting the Allowable Load Weight

Since the maximum load weight with respect to the cylinder stroke changes as shown in the table below, σ should be considered as a coefficient determined in accordance with each stroke.

Example) CY1L25□-650

- (1) Maximum load weight = 20 kg
- (2) Load weight for 650 st = 13.6 kg

(3)
$$\sigma = \frac{13.6}{20} = 0.68$$
 is the result.

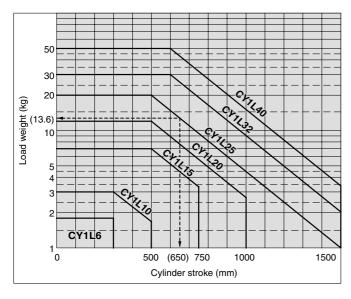
Calculation Formula for σ (σ < 1)

ST: Stroke (mm)

Model	CY1L6	CY1L10	CY1L15				
σ=	1	$\frac{10^{(0.86-1.3\times10^{-3}\times\text{ST})}}{3}$	10 (1.5 - 1.3 x 10 ⁻³ x ST) 7				
Model	CY1L20	CY1L25	CY1L32				
σ=	10 (1.71 – 1.3 x 10 ⁻³ x ST)	10 ^(1.98 - 1.3 x 10⁻³ x ST) 20	10 (2.26 – 1.3 x 10 ⁻³ x ST) 30				
	12	20	30				

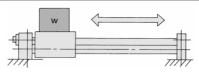
Model	CY1L40
σ=	10 (2.48 – 1.3 x 10 ⁻³ x ST)
	50

Note) Calculate with σ = 1 for all applications up to ø10 – 300 mmST, ø15 – 500 mmST, ø20 – 500 mmST, ø25 – 500 mmST, ø32 – 600 mmST and ø40 – 600 ST.



Examples of Allowable Load Weight Calculation Based on Cylinder Mounting Orientation

1. Horizontal Operation (Floor mounting)



Maximum Load Weight (Center of slide block)

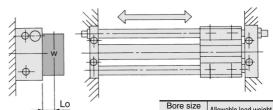
(kg)

Bore size (mm)	6	10	15	20	25	32	40
Max. load weight (kg)	1.8	3	7	12	20	30	50
Stroke (Max)	300 st	300 st	500 st	500 st	500 st	600 st	600 st

The above maximum load weight values will change with the stroke length for each cylinder size, due to limitation from warping of the guide shafts. (Take note of the coefficient $\sigma.)$

Moreover, depending on the operating direction, the allowable load weight may be different

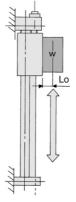
2. Horizontal Operation (Wall mounting)



Lo: Distance from mounting surface to load center of gravity (cm)

(mm)	Allowable load weight (WA) (kg
6	<u> </u>
10	<u>σ⋅15.0</u> 8.9 + 2Lo
15	
20	
25	
32	
40	<u></u>

3. Vertical Operation



Bore size (mm)	Allowable load weight (WA) (kg)
6	<u> </u>
10	
15	<u>σ⋅15.96</u> 2.4 + Lo
20	<u> </u>
25	<u> </u>
32	<u> </u>
40	<u>σ⋅212.09</u> 4.75 + Lo

Lo: Distance from mounting surface to load center of gravity (cm)

Note) A safety factor for drop prevention has been taken into account.

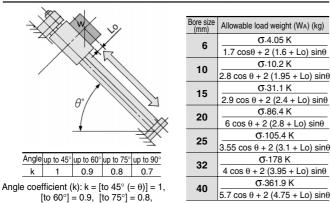
Note) Operating pressure should be equal to or less than the maximum operating pressure in the article, "Vertical Operation" listed on page 8-15-64.

Model Selection 3

Caution on Design (2)

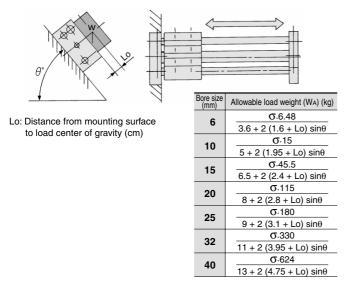
Example of Allowable Load Weight Calculation Based on Cylinder Mounting Orientation

4. Inclined Operation (In operating direction)

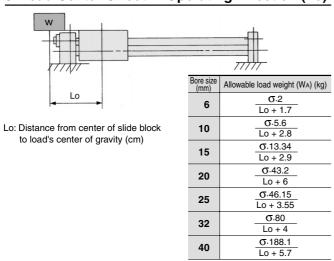


 $\label{eq:continuous} \begin{tabular}{ll} to 90°] = 0.7 \\ \begin{tabular}{ll} Lo: Distance from mounting surface to load center of gravity (cm) \\ \end{tabular}$

5. Inclined Operation (At a right angle to operating direction)



6. Load Center Offset in Operating Direction (Lo)



7. Horizontal Operation (Pushing load, Pusher)

 $\mathsf{MX}\square$

MTS

 $MY \square$

CY

 $MG\square$

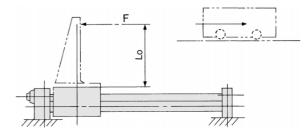
CX□

D-

-X

20-

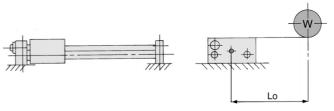
Data



F: Drive (from slide block to position Lo) resistance force (kg) Lo: Distance from mounting surface to load center of gravity (cm)

Bore size (mm)	6	10	15	20
Allowable load weight (WA) (kg)	<u>σ⋅2.72</u> 1.6 + Lo	$\frac{\sigma.5.55}{1.95 + Lo}$	<u>σ⋅15.96</u> 2.4 + Lo	$\frac{\text{G.41.7}}{2.8 + \text{Lo}}$
Bore size (mm)	25	32	40	
Allowable load weight	σ.58.9	σ.106.65	σ.228	

8. Horizontal Operation (Load, Lateral offset Lo)



Lo: Distance from center of side block to load's center of gravity (cm)

Bore size (mm)	6	10	15	20
Allowable load weight (WA) (kg)	<u></u> 0.6.48 3.6 + Lo	5 + Lo	<u>σ.45.5</u> 6.5 + Lo	<u>σ⋅80.7</u> 8 + Lo
Bore size (mm)	25	32	40	

Bore size (mm)	25	32	40
Allowable load weight	σ.144	_ σ⋅275	σ.520
(WA) (kg)	9 + Lo	11 + Lo	13 + Lo

Series CY1L Model Selection 4

Caution on Design (3)

Vertical Operation

When operating a load vertically, it should be operated within the allowable load weights and maximum operating pressures shown in the table below. Use caution, as operating above the prescribed values may lead to dropping of the load.

Bore size (mm)	Model	Allowable load weight (Wv) (kg)	Maximum operating pressure (Pv) (MPa)
6	CY1L6H	1.0	0.55
10	CY1L10H	2.7	0.55
15	CY1L15H	7.0	0.65
15	CY1L15L	4.1	0.40
20	CY1L20H	11.0	0.65
20	CY1L20L	7.0	0.40
25	CY1L25H	18.5	0.65
25	CY1L25L	11.2	0.40
32	CY1L32H	30.0	0.65
32	CY1L32L	18.2	0.40
40	CY1L40H	47.0	0.65
40	CY1L40L	29.0	0.40

Note) Use caution, since the magnetic coupling may be dislocated if it is used over the maximum operating pressure.

Intermediate Stop

1. Intermediate stopping of load with an external stopper, etc.

When stopping a load in mid-stroke using an external stopper (adjusting bolt, etc.), operate within the operating pressure limits shown in the table below. Use caution, as operation at a pressure exceeding these limits can result in breaking of the magnetic coupling.

Bore size (mm)	Model	Operating pressure limit for intermediate stop (Ps) (MPa)
6	CY1L6H	0.55
10	CY1L10H	0.55
15	CY1L15H	0.65
15	CY1L15L	0.40
20	CY1L20H	0.65
20	CY1L20L	0.40
25	CY1L25H	0.65
25	CY1L25L	0.40
32	CY1L32H	0.65
32	CY1L32L	0.40
40	CY1L40H	0.65
40	CY1L40L	0.40

2. Intermediate stopping of load with an air pressure circuit

When stopping a load using an air pressure circuit, operate at or below the kinetic energy shown in the table below. Use caution, as operation when exceeding the allowable value can result in breaking of the magnetic coupling.

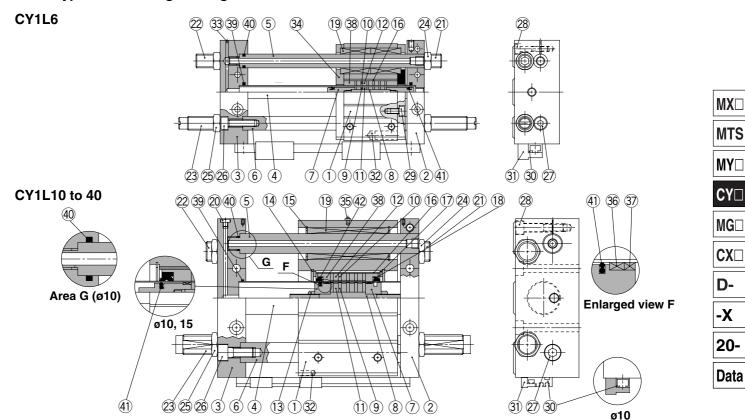
(Reference values)

Bore size (mm)	Model	Allowable kinetic energy for intermediate stop (Es) (J)
6	CY1L6H	0.007
10	CY1L10H	0.03
15	CY1L15H	0.13
15	CY1L15L	0.076
20	CY1L20H	0.24
20	CY1L20L	0.16
25	CY1L25H	0.45
25	CY1L25L	0.27
32	CY1L32H	0.88
32	CY1L32L	0.53
40	CY1L40H	1.53
40	CY1L40L	0.95

Magnetically Coupled Rodless Cylinder Slider Type: Ball Bushing Bearing Series CY1L

Construction

Slider type/Ball bushing bearing



Component Parts

No.	Description	Material	Note
1	Slide block	Aluminum alloy	Hard anodized
2	Plate A	Aluminum alloy	Hard anodized
3	Plate B	Aluminum alloy	Hard anodized
4)	Cylinder tube	Stainless steel	
5	Guide shaft A	Carbon steel	Hard chrome plated
6	Guide shaft B	Carbon steel	Hard chrome plated
7)	Piston	Aluminum alloy Note)	Chromated
8)	Shaft	Stainless steel	
9)	Piston side yoke	Rolled steel	Zinc chromated
0	External slider side yoke	Rolled steel	Zinc chromated
11)	Magnet A	Rare earth magnet	
2	Magnet B	Rare earth magnet	
3	Piston nut	Carbon steel	Zinc chromated ø25 to ø40
4)	Snap ring	Carbon tool steel	Nickel plated
5	Snap ring	Carbon tool steel	Nickel plated
3	External slider tube	Aluminum alloy	
7	Slider spacer	Rolled steel	Nickel plated
8	Spacer	Rolled steel	Nickel plated
9	Ball bushing		
20	Plug	Brass	ø25, ø32, ø40 only
21)	Adjusting bolt A	Chromium molybdenum steel	Nickel plated
22)	Adjusting bolt B	Chromium molybdenum steel	Nickel plated
23)	Shock absorber		
24)	Hexagon nut	Carbon steel	Nickel plated
25)	Hexagon nut	Carbon steel	Nickel plated
26)	Hexagon socket head cap screw	Chromium molybdenum steel	Nickel plated
27)	Hexagon socket head cap screw	Chromium molybdenum steel	Nickel plated
28	Hexagon socket head cap screw	Chromium molybdenum steel	Nickel plated

Note) Brass for Ø6, Ø10 and Ø15

No.	Description	Material	Note
29	Hexagon socket head cap screw	Chromium molybdenum steel	Nickel plated
30	Switch mounting rail	Aluminum alloy	
31)	Auto switch		
32	Magnet for auto switch	Rare earth magnet	
33	Steel ball		ø6, ø10, ø15 only
34)	Side cover	Carbon steel	ø6 only
35	Grease cup	Carbon steel	ø15 or larger
36*	Wear ring A	Special resin	
37)*	Wear ring	Special resin	
38*	Wear ring B	Special resin	
39*	Cylinder tube gasket	NBR	
40*	Guide shaft gasket	NBR	
41)*	Piston seal	NBR	
42*	Scraper	NBR	-

Replacement Parts: Seal Kit

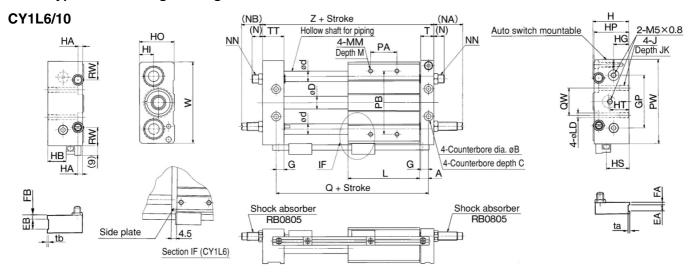
Bore size (mm)	Kit no.	Contents
6	CY1L6-PS-N	Set of nos. above 38, 39, 40, 41
10	CY1L10-PS-N	Set of nos. above
15	CY1L15-PS-N	36, 38, 39, 40, 41, 42
20	CY1L20-PS-N	Set of nos. above
25	CY1L25-PS-N	36, 37, 38, 39, 40,
32	CY1L32-PS-N	41, 42
40	CY1L40-PS-N	
	0.0.	

^{*} Seal kit includes 36, 39, 40, 41 for ø6. 36, 38 to 42 are for ø10, ø18. 36 to 42 are for ø20 to ø40. Order the seal kit, based on each bore size.



Dimensions

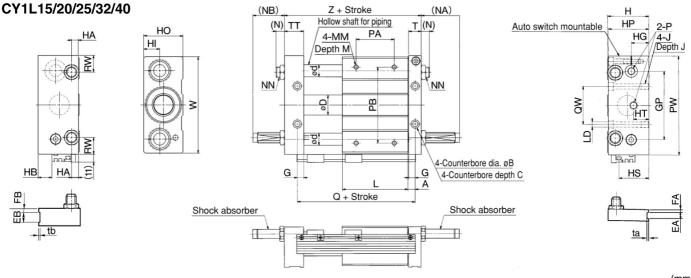
Slider type/Ball bushing bearing



Model	Α	В	С	D	d	EA	EB	FA	FB	G	GP	Н	НА	НВ	HG	н	но	HP	HS	НТ	•	J	JK
CY1L6	7	6.5	3	7.6	8	_	_	_	_	6	36	27	6	10	11	9	25	26	14	16	M4	x 0.7	6.5
CY1L10	8.5	8	4	12	10	6	12	3	5	7.5	50	34	6	17.5	14.5	13.5	33	33	21.	5 18	M5	x 0.8	9.5
									_													_	
Model	L	LD	М	М	VI	(N)	(NA)	(NB))	NN		PA*	РВ	PW	Q (QW F	RW	Т	TT	ta	tb	W	Z
Model CY1L6	L 40	LD 3.5	M 6	MI M4 x		(N)	(NA) 30	(NB)		NN //8 x 1.		PA *						T 10	TT 16	ta —	tb	W 56	Z 68

 $[\]ast$ PA dimensions are for split from center.

(mm)



																										((mm)
Model	Α	В	С	D	d	EA	ЕВ	FA	FB	G	GP	Н	НА	HE	H C	à l	11	но	HP	HS	нт		J		JK	L	LD
CY1L15	7.5	9.5	5	16.6	12	6	13	3	6	6.5	65	40	6.5	4	16	1-	4	38	39	25	16		M6 x 1	.0	9.5	75	5.6
CY1L20	9.5	9.5	5.2	21.6	16	_	_	_	_	8.5	80	46	9	10	18	1	6	44	45	31	20		M6 x 1	.0	10	86	5.6
CY1L25	9.5	11	6.5	26.4	16	8	14	4	7	8.5	90	54	9	18	23	2	1	52	53	39	20	ı	И8 x 1.	25	10	86	7
CY1L32	10.5	14	8	33.6	20	8	16	5	7	9.5	110	66	12	26	.5 26	.5 2	4.5	64	64	47.5	25	ı	V110 x 1	1.5	15	100	9.2
CY1L40	11.5	14	8	41.6	25	10	20	5	10	10.5	130	78	12	35	30	.5 2	8.5	76	74	56	30	1	V110 x 1	1.5	15	136	9.2
Model	М	MI	Л	(N)	(NA)	(NB	3)	NN	1		Р	PA	* P	В	PW	Q	G	W F	RW	Т	ta	tb	TT	W	Z	Shock a	absorber
CY1L15	8	M5 x	0.8	7.5	27	17	N	18 x	1.0	M5	x 0.8	45	7	70	95	90	3	30	15	12.5	0.5	1.0	22.5	92	112	RBC	0805
CY1L20	10	M6 x	1.0	10	29	20	N	110 x	1.0	Ro	1/8	50	(90	120	105	4	10	28	16.5	_		25.5	117	130	RB1	1006
CY1L25	10	M6 x	1.0	11	49	40	N	114 x	1.5	Ro	1/8	60	10	00	130	105	5	50	22	16.5	0.5	1.0	25.5	127	130	RB1	1411
CY1L32	12	M8 x	1.25	11.5	52	42	N	120 x	1.5	Ro	1/8	70	12	20	160	121	6	60	33	18.5	0.5	1.0	28.5	157	149	DD	2015
CY1L40	12	M8 x	1.25	10.5	51	36	N	120 x	1.5	Ro	1/4	90	14	40	190	159	8	34	35	20.5	1.0	1.0	35.5	187	194	ND2	2015

 $[\]ast$ PA dimensions are for split from center.

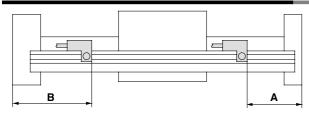
Shock Absorber Specifications/Series RB

For detailed specifications about shock absorber, refer to "Series RB" of Best Pneumatics Vol. 10.

Applicable rodless	cylinder	6 CY1L10 15	CY1L20	CY1L25	CY1L ₄₀				
Shock absorber model		RB0805	RB1006	RB1411	RB2015				
Maximum energy absor	ption: (J)	0.98	58.8						
Weight equivalent to imp	oact object	* Select a model from data D of Shock Absorber (RB series) of Best Pneumatics Vol. 10.							
Stroke absorption: (mm)		5	6	11	15				
Collision speed: (m/s)		0.05 to 5							
Max. operating frequence	cy: (cycle/min)*	80	45	25					
Ambient temperature range	e	-10 to 80°C							
Caring forces (N)	Extended	1.96	4.22	6.86	8.34				
Spring force: (N)	Retracted	3.83	6.18	15.3	20.50				

^{*} It denotes the values at the maximum energy absorption per one cycle. Therefore, the operating frequency can be increased according to the energy absorption.

Proper Auto Switch Mounting Position (Detection at stroke end)

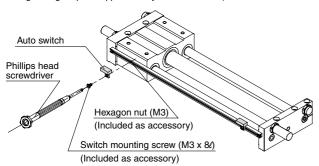


		Applicable auto switch												
Bore size (mm)	D-A73/	A80	D-A72 D-A7□H/ D-A73C// D-F7□/J D-F7□W/ D-F7□W D-F7□W	A80C 79 J79C /J79W V	D-F7	'9F	D-F7NTL							
	Α	В	A	В	A	В	Α	В						
6	23	45	23.5	44.5	27.5	40.5	28.5	39.5						
10	58	45	58.5	44.5	62.5	40.5	63.5	39.5						
15	65	47	65.5	46.5	69.5	42.5	70.5	41.5						
20	76	54	76.5	53.5	80.5	49.5	81.5	48.5						
25	76	54	76.5	53.5	80.5	49.5	81.5	48.5						
32	92	57	92.5	56.5	96.5	52.5	97.5	51.5						
40	130	64	130.5	63.5	134.5	59.5	135.5	58.5						

Note) 50 mm is the minimum stroke available with 2 auto switches mounted. In the case of a stroke less than this, please contact SMC.

Mounting of Auto Switch

When mounting an auto switch, the switch mounting screw should be screwed into a hexagon nut (M3 x 0.5) which has been inserted into the groove of the switch rail. (Use a tightening torque of approximately 0.05 to 0.1 N·m.)



Operating Range

Auto switch model	Bore size (mm)									
Auto Switch model	6	10	15	20	25	32	40			
D-A7□/A8□	6	6	6	6	6	6	6			
D-F7□/J7□	3	3	4	3	3	3	3.5			
D-F79F	4.5	4.5	4.5	4.5	4.5	4.5	4.5			

* Since this is a guideline including hysteresis, not meant to be guaranteed. (Assuming approximately ±30% dispersion)

There may be the case it will vary substantially depending on an ambient environment.

Other than the models listed in "How to Order", the following auto switches are applicable. For detailed specifications, refer to page 8-30-1.

er detailed openineations, refer to page 6 66 11								
Model	Electrical entry (Fetching direction)	Features						
D-A80	Grommet (Perpendicular)							
D-A80H	Grommet (In-line)	Without indicator light						
D-A80C	Connector (Perpendicular)							
D-F7NTL	Grommet (In-line)	With timer						
	Model D-A80 D-A80H D-A80C	Model Electrical entry (Fetching direction) D-A80 Grommet (Perpendicular) D-A80H Grommet (In-line) D-A80C (Perpendicular) Grommet (Perpendicular)						

^{*} With pre-wire connector is available for D-F7NTL type, too. For details, refer to page 8-30-52.

MX□

MTS

MY□

CY■ MG□

CX□

D-

-X

20-

Data