

Operation Manual

PRODUCT NAME

Fieldbus system
EtherNet/IPTM compatible SI Unit
(For Ford Motor Company)

MODEL / Series / Product Number

EX600-SEN5-X16 EX600-ED3-X16 EX600-DXPD-X16 EX600-DYPB-X16

SMC Corporation

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Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of "Caution", "Warning" or "Danger". They are all important notes for safety and must be followed in addition to International standards (ISO/IEC) *1) and other safety regulations.

*1) ISO 4414: Pneumatic fluid power -- General rules relating to systems. ISO 4413: Hydraulic fluid power -- General rules relating to systems. IEC 60204-1: Safety of machinery -- Electrical equipment of machines. (Part 1: General requirements) ISO 10218-1992: Manipulating industrial robots -Safety.

⚠Caution :

CAUTION indicates a hazard with a low level of risk which, if not avoided,

could result in minor or moderate injury.

⚠Warning :

WARNING indicates a hazard with a medium level of risk which, if not

avoided, could result in death or serious injury.

▲ Danger :

DANGER indicates a hazard with a high level of risk which, if not avoided,

will result in death or serious injury.

Warning

1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications.

Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results. The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product. This person should also continuously review all specifications of the product referring to its latest catalogue information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

- 2. Only personnel with appropriate training should operate machinery and equipment. The product specified here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained and experienced.
- 3. Do not service or attempt to remove product and machinery/equipment until safety is confirmed.
 - 1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.
 - 2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant products carefully.
 - 3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.
- 4. Contact SMC beforehand and take special consideration of safety measures if the product is to be used in any of the following conditions.
- 1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
- 2. Installation on equipment in conjunction with atomic energy, railways, air navigation, space, shipping, vehicles, military, medical treatment, combustion and recreation, or equipment in contact with food and beverages, emergency stop circuits, clutch and brake circuits in press applications, safety equipment or other applications unsuitable for the standard specifications described in the product catalogue.
- 3. An application which could have negative effects on people, property, or animals requiring special safety analysis.
- 4. Use in an interlock circuit, which requires the provision of double interlock for possible failure by using a mechanical protective function, and periodical checks to confirm proper operation.



The product is provided for use in manufacturing industries.

The product herein described is basically provided for peaceful use in manufacturing industries. If considering using the product in other industries, consult SMC beforehand and exchange specifications or a contract if necessary.

If anything is unclear, contact your nearest sales branch.

Limited warranty and Disclaimer/Compliance Requirements

The product used is subject to the following "Limited warranty and Disclaimer" and "Compliance Requirements".

Read and accept them before using the product.

Limited warranty and Disclaimer

- 1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered, whichever is first. *2)
 - Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.
- 2. For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided.
 - This limited warranty applies only to our product independently, and not to any other damage incurred due to the failure of the product.
- 3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalogue for the particular products.
 - *2) Vacuum pads are excluded from this 1 year warranty.

 A vacuum pad is a consumable part, so it is warranted for a year after it is delivered.

 Also, even within the warranty period, the wear of a product due to the use of the vacuum pad or failure due to the deterioration of rubber material are not covered by the limited warranty.

Compliance Requirements

- 1. The use of SMC products with production equipment for the manufacture of weapons of mass destruction (WMD) or any other weapon is strictly prohibited.
- The exports of SMC products or technology from one country to another are governed by the relevant security laws and regulation of the countries involved in the transaction. Prior to the shipment of a SMC product to another country, assure that all local rules governing that export are known and followed.



Operator

- ♦ This operation manual is intended for those who have knowledge of machinery using pneumatic equipment, and have sufficient knowledge of assembly, operation and maintenance of such equipment. Only those persons are allowed to perform assembly, operation and maintenance.
- ♦ Read and understand this operation manual carefully before assembling, operating or providing maintenance to the product.

■Safety Instructions



- ■Do not disassemble, modify (including changing the printed circuit board) or repair. An injury or failure can result.
- ■Do not operate or set with wet hands.

This may lead to an electric shock.

■Do not operate the product outside of the specifications.

Do not use for flammable or harmful fluids.

Fire, malfunction, or damage to the product can result.

Verify the specifications before use.

■Do not operate in an atmosphere containing flammable or explosive gases.

Fire or an explosion can result.

This product is not designed to be explosion proof.

- If using the product in an interlocking circuit:
- •Provide a double interlocking system, for example a mechanical system.
- •Check the product regularly for proper operation.

Otherwise malfunction can result, causing an accident.

- ■The following instructions must be followed during maintenance:
- •Turn off the power supply.
- •Stop the air supply, exhaust the residual pressure and verify that the air is released before performing maintenance.

Otherwise an injury can result.





- ■When handling the unit or assembling/replacing units:
- •Do not touch the sharp metal parts of the connector or plug for connecting units.
- •Take care not to hit your hand when disassembling the unit.
- The connecting portions of the unit are firmly joined with seals.
- •When joining units, take care not to get fingers caught between units.

An injury can result.

After maintenance is complete, perform appropriate functional inspections.

Stop operation if the equipment does not function properly.

Safety cannot be assured in the case of unexpected malfunction.

■ Provide grounding to assure the noise resistance of the Fieldbus system. Individual grounding should be provided close to the product with a short cable.

■NOTE

- oFollow the instructions given below when designing, selecting and handling the product.
- The instructions on design and selection (installation, wiring, environment, adjustment, operation, maintenance, etc.) described below must also be followed.
- *Product specifications
- •The direct current power supply to combine should be UL1310 Class 2 power supply when conformity to UL is necessary.
- •Use the specified voltage.
- Otherwise failure or malfunction can result.
- •Reserve a space for maintenance.
- Allow sufficient space for maintenance when designing the system.
- Do not remove any nameplates or labels.
- This can lead to incorrect maintenance, or misreading of the operation manual, which could cause damage or malfunction to the product.
- It may also result in non-conformity to safety standards.
- •Beware of inrush current when the power supply is turned on.
- Some connected loads can apply an initial charge current which will activate the over current protection function, causing the unit to malfunction.

Product handling

- *Installation
- •Do not drop, hit or apply excessive shock to the SI unit.

Otherwise damage to the product can result, causing malfunction.

•Tighten to the specified tightening torque.

If the tightening torque is exceeded the mounting screws may be broken.

IP67 protection cannot be guaranteed if the screws are not tightened to the specified torque.

•If a large manifold valve is mounted, lift the unit so that stress is not applied to the connecting part while transporting.

The stress may cause breakage of the connecting part. The unit may become very heavy depending on the combination. Transportation/installation shall be performed by multiple operators.

•Never mount a product in a location that will be used as a foothold.

The product may be damaged if excessive force is applied by stepping or climbing onto it.

*Wiring

•Avoid repeatedly bending or stretching the cables, or placing heavy load on them.

Repetitive bending stress or tensile stress can cause breakage of the cable.

•Wire correctly.

Incorrect wiring can break the product.

•Do not perform wiring while the power is on.

Otherwise damage to the SI unit and/or input or output device can result, causing malfunction.

•Do not route wires and cables together with power or high voltage cables.

Otherwise the SI unit and/or input or output device can malfunction due to interference of noise and surge voltage from power and high voltage cables to the signal line.

Route the wires (piping) of the SI unit and/or input or output device separately from power or high voltage cables.

Confirm proper insulation of wiring.

Poor insulation (interference from another circuit, poor insulation between terminals, etc.) can lead to excess voltage or current being applied to the product, causing damage.

•Take appropriate measures against noise, such as using a noise filter, when the Fieldbus system is incorporated into equipment.

Otherwise noise can cause malfunction.

*Environment

•Select the proper type of protection according to the environment of operation.

IP67 protection is achieved when the following conditions are met.

- (1) The units are connected properly with fieldbus cable with M12 connector and power cable with M12 (M8) connector.
- (2) Suitable mounting of each unit and manifold valve.
- (3) Be sure to fit a waterproof cap on any unused connectors.

If using in an environment that is exposed to water splashes, please take measures such as using a cover.

Do not use in an environment where moisture or water vapor are present. Otherwise failure and malfunction can result.

•Do not use in a place where the product could be splashed by oil or chemicals.

If the product is to be used in an environment containing oils or chemicals such as coolant or cleaning solvent, even for a short time, it may be adversely affected (damage, malfunction etc.).

- •Do not use the product in an environment where corrosive gases or fluids could be splashed. Otherwise damage to the product and malfunction can result.
- Do not use in an area where surges are generated.

If there is equipment generating large surge near the unit (magnetic type lifter, high frequency inductive furnace, welding machine, motor, etc.), this can cause deterioration of the internal circuitry element of the unit or result in damage. Take measures against the surge sources, and prevent the lines from coming into close contact.



•When a surge-generating load such as a relay, valve or lamp is driven directly, use a product with a built-in surge absorbing element.

Direct drive of a load generating surge voltage can damage the unit.

- •The product is CE marked, but not immune to lightning strikes. Take measures against lightning strikes in the system.
- •Prevent foreign matter such as dust or wire debris from getting inside the product.
- •Mount the product in a place that is not exposed to vibration or impact.

Otherwise failure or malfunction can result.

Do not use the product in an environment that is exposed to temperature cycle.

Heat cycles other than ordinary changes in temperature can adversely affect the inside of the product.

•Do not expose the product to direct sunlight.

If using in a location directly exposed to sunlight, shade the product from the sunlight.

Otherwise failure or malfunction can result.

•Keep within the specified ambient temperature range.

Otherwise malfunction can result.

•Do not operate close to a heat source, or in a location exposed to radiant heat.

Otherwise malfunction can result.

*Adjustment and Operation

•Set the switches by using a sharp-pointed screwdriver etc. When setting the switch, do not touch other unrelated parts.

This can cause parts damage or malfunction due to a short circuit.

Perform settings suitable for the operating conditions.

Incorrect setting can cause operation failure.

•Please refer to the PLC manufacturer's manual etc. for details of programming and addresses.

For the PLC protocol and programming refer to the relevant manufacturer's documentation.

*Maintenance

•Turn off the power supply, stop the supplied air, exhaust the residual pressure and verify the release of air before performing maintenance.

There is a risk of unexpected malfunction.

•Perform regular maintenance and inspections.

There is a risk of unexpected malfunction.

•After maintenance is complete, perform appropriate functional inspections.

Stop operation if the equipment does not function properly.

Otherwise safety is not assured due to an unexpected malfunction or incorrect operation.

•Do not use solvents such as benzene, thinner etc. to clean each unit.

They could damage the surface of the body and erase the markings on the body.

Use a soft cloth to remove stains.

For heavy stains, use a cloth soaked with diluted neutral detergent and fully squeezed, then wipe up the stains again with a dry cloth.

System Outline

System configuration

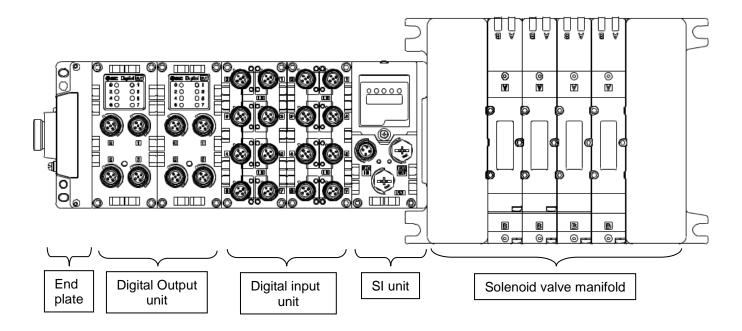
The EX600-SEN5-X16(SI unit) can communicated to EtherNet/IP.

SI unit has the following features.

Number of valve outputs : Max.32 outputs

Number of Digital input units: Max.3 units (EX600-DXPD-X16)

Number of Digital output units: Max.3 units (EX600-DYPB-X16)



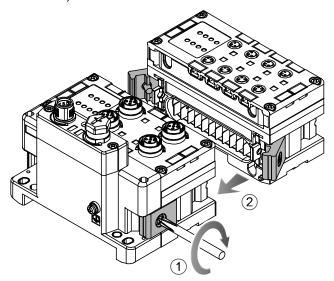
Name	Function
SI unit (EX600-SEN5-X16)	Performs fieldbus communication and solenoid valve manifold ON/OFF output.
Digital input unit (EX600-DXPD-X16)	For connecting sensors with switch output capability.
Digital Output unit (EX600-DYPB-X16)	For connecting output device such as solenoid valves, lamps, buzzers, etc.
End plate (EX600-ED3-X16)	Connected at EX600 Manifold's D side, incorporating the power supply connection.
Solenoid valve manifold	An assembly of solenoid valves. One connector is used as the electric connection to all connected valves.

Assembly

Composing the unit as a manifold

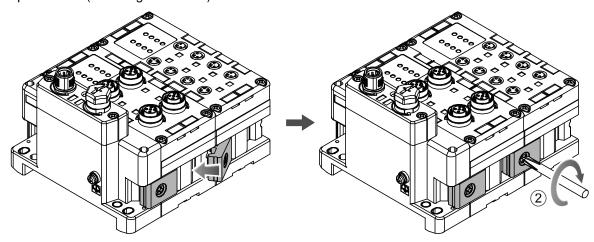
- *: If the unit was purchased as a manifold, the work described in this section is not necessary.
- (1) Connect the unit to the end plate.

The Digital unit, Analogue unit can be connected in any order. (Tightening torque: 1.5 to 1.6Nm)



(2) Add more units.

Up to 4 units (including the SI unit) can be connected to one manifold.



(3) Connecting the SI unit.

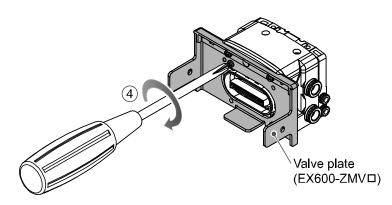
After connecting the necessary units, connect the SI unit. Connecting method is the same as above (1), (2).



(4) Mounting the valve plate.

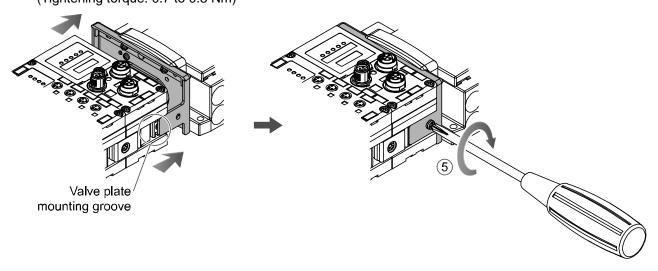
Mount the valve plate (EX600-ZMV $_{\square}$) to the valve manifold using the valve set screws. (M3 x 8) (Tightening torque: 0.6 to 0.7 Nm)

Screw mounting place SV : 2 places S0700 : 2 places VQC1000: 2 places VQC2000: 3 places VQC4000: 4 places SY : 2 places



(5) Connect the SI unit and the valve manifold.

Insert the valve plate to the valve plate set groove on the side of SI unit. Then, tighten it with the valve plate set screws (M4 \times 6) to fix the plate. (Tightening torque: 0.7 to 0.8 Nm)



Precautions for handling

- •Please do not connect the unit while the power supply is active. It will cause equipment damage.
- •Take care not to drop the nuts of Joint bracket.
- •Tighten the screws to the specified torque.

 Insufficient tightening may lead to equipment malfunction, injury or equipment damage.

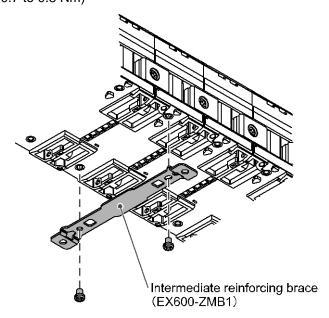
Mounting and Installation

■Installation

Direct mounting

(1) Direct mounting

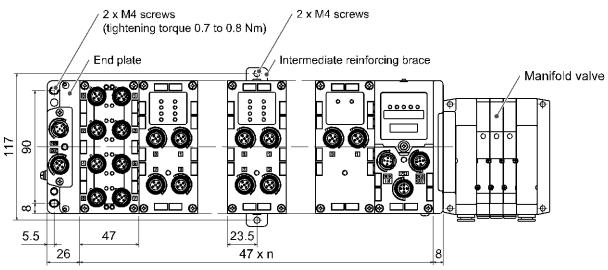
When joining six or more units, fix the middle part of the complete EX600 unit with an intermediate reinforcing brace (EX600-ZMB1) before mounting using 2-M4 x 5 screws. (Tightening torque: 0.7 to 0.8 Nm)



(2) Fix and tighten the end plates at one end of the unit. (M4) $\,$

(Tightening torque: 0.7 to 0.8 Nm)

Fix the end plate at the valve side while referring to the operation manual of the corresponding valve manifold.



n (Number of connected Units) ≤ 4

Precautions for handling

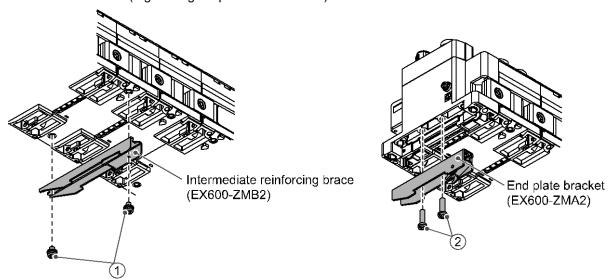
•When joining six or more units, fix the middle part of the complete unit with an intermediate reinforcing brace to prevent incorrect connection between the units due to deflection.



DIN rail mounting

(Not available for SY series valves. Refer to the SY catalog.)

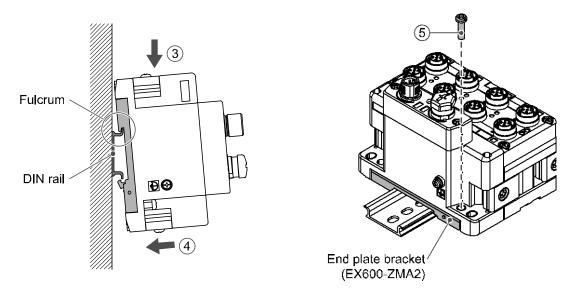
- (1) When joining six or more units, fix the middle part of the complete EX600 unit with an intermediate reinforcing brace (EX600-ZMB2) before mounting, using 2-M4 x 6 screws. (Tightening torque: 0.7 to 0.8 Nm)
- (2) Mount the end plate bracket (EX600-ZMA2) to the end plate at the opposite end to the valves, using 2-M4 x 14 screws. (Tightening torque: 0.7 to 0.8 Nm)



- (3) Hook the DIN rail mounting groove to the DIN rail.
- (4) Press the manifold using its side hooked to the DIN rail as a fulcrum until the manifold is locked.
- (5) Fix the manifold by tightening the DIN rail fixing screws of the EX600-ZMA2. (M4 x 20) (Tightening torque: 0.7 to 0.8 Nm)

The tightening torque at the valve side depends on the valve type.

Refer to the operation manual of the corresponding valve manifold.



- Precautions for handling
- •When joining six or more units, fix the middle part of the complete unit with an intermediate reinforcing brace to prevent incorrect connection between the units due to deflection.

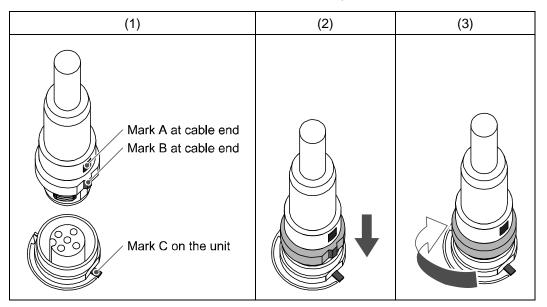


■Wiring

•Connect the M12 or M8 connector cable.

M12 connector is applicable for SPEEDCON connector. SPEEDCON connector wiring method is explained below.

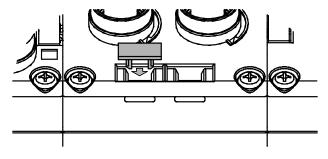
- (1) Align the mark B on the metal bracket of the cable side connector (plug/socket) with the mark A.
- (2) Align the mark C on the unit and insert the connector into the unit vertically. If they are not aligned, the connector cannot be joined properly.
- (3) When the mark B of the connector has been turned 180 degrees (1/2 turn), wiring is completed. Confirm that the connection is not loose. If turned too far, it will become hard to remove the connector.



Mounting the marker

Signal name of the input or output devices and unit address can be written to the marker, and it can be installed to each unit.

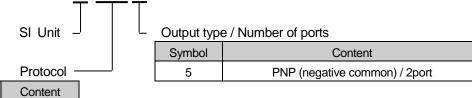
Mount the marker (EX600-ZT1) into the marker groove as required.



SI Unit

Model Indication and How to Order



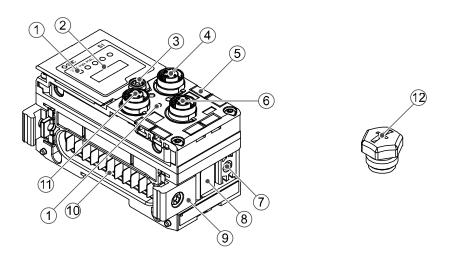


Summary of Product parts

EtherNet/IPTM

Symbol

ΕN



No.	Description	Function
1	Status display LED	Displays the status of the unit.
2	Display cover	Open at the switch configuration.
3	Display cover tightening screw	Loosen to open the display cover.
4	Connector (BUS OUT)	Connects the cable for fieldbus outputs. (M12, 5 pin, socket: SPEEDCON)
5	Marker groove	Groove to mount a marker.
6	Connector (PCI)	Connects the cable of the handheld terminal. (M12, 5 pin, socket: SPEEDCON)
7	Valve plate mounting screw hole	Fixes the valve plate.
8	Valve plate mounting groove	Groove to insert the valve plate into.
9	Joint bracket	Bracket for joining to adjacent units.
10	Unit connector (plug)	Transmits signals and power supplies to adjacent units.
11	Connector (BUS IN)	Connects the cable for fieldbus inputs. (M12, 5 pin, socket: SPEEDCON)
12	Seal cap (2 pcs.)	Mounted on to unused connectors (BUS OUT and PCI).

Mounting and Installation

■Wiring

Connector pin assignment

Configuration	Dia Na	0:	
BUS IN / BUS OUT	Pin No.	Signal name	
1/ 2	1	TX+	
	2	RX+	
(0 05)	3	TX-	
4 3	4	RX-	

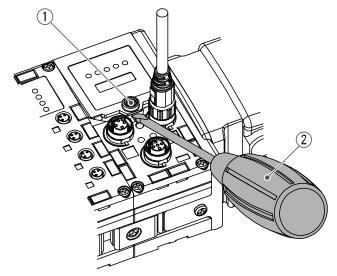
Precautions for handling

Be sure to fit a seal cap on any unused connectors. Proper use of the seal cap enables the enclosure to achieve IP67 specification.

Setting and Adjustment

Switch operation

- (1) Loosen the display cover screw (indicated by arrow).
- (2) Open the display cover using a flat head screwdriver, etc.

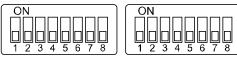


- (3) Set the switch using a small watchmaker's screwdriver with a thin blade, referring to the setting of switch on the following pages.
- (4) After setting the switch, tighten the display cover tightening screw in the reverse order of the above procedure. (Tightening torque: 0.3 to 0.4 Nm)

Precautions for handling

- •Turn off the power supply whilst setting the switch.
- •If there is foreign matter or water droplets around the display cover, clean it off before opening the cover.
- •When setting the switch, do not touch other unrelated parts. This can cause parts damage or malfunction due to a short circuit.
- •All default settings are OFF. Perform the setting of the switch before using this product.
- •When introducing power supply, switch setting will become effective.

Switch setting



Settings1 Settings2

	Settings1	Settings2		
1	Hold/Clear setting	1		
2		2		
3		3		
4		4	•IP address byte 4 setting	
5	Reserved	5	•DHCP mode setting	
6		6		
7		7		
8		8		

- Precautions for handling
- •Handle the switch with care. Excessive force can break the switch.
- •2 to 8 of the Settings1 switch are not used. (Never turn it ON.)

•HOLD/CLEAR switch: Sets the output status when the fieldbus has a communication error or is in idling state.

Settings1	Content
1	Content
OFF	Output is OFF. (default setting)
ON	Holds the output.

^{*:} This switch can be enabled and disabled by parameter.

•IP address setting switch

Settings2							ID address	Culturat manale	
1	2	3	4	5	6	7	8	IP address	Subnet mask
ON	OFF	136.129.2.1							
OFF	ON	OFF	OFF	OFF	OFF	OFF	OFF	136.129.2.2	
:		:	:	:	:	:		:	255.255.0.0
ON	OFF	ON	ON	ON	ON	ON	ON	136.129.2.253	
OFF	ON	136.129.2.254							
ON	ON	ON	ON	ON	ON	ON	ON	DHCP mode *1	
OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	Remote Cor	ntrol mode *2

^{*1:} The mode to obtain IP address from DHCP server. Obtained IP address etc. is lost when the power supply is cut.

Enable DHCP: IP address etc. can be obtained from BOOTP/DHCP Server.

If the power is supplied again in this state, information including IP address is obtained again.

Disable DHCP: IP address etc. cannot be obtained from BOOTP/DHCP Server.

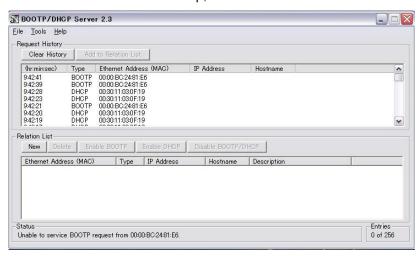
If the power is supplied again with this condition, previous setting can be held.



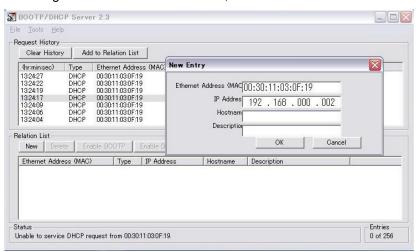
^{*2:} The mode to respond to the commands below of BOOTP/DHCP Server provided by Rockwell Automation.

Setting method of IP address by BOOTP/DHCP Server

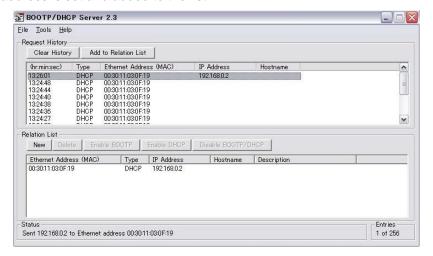
•When BOOTP/DHCP Server starts up, the Server scans the devices connected to the network.



•After selecting the MAC address of EX600, IP address is set.

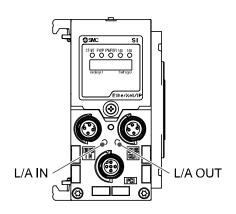


•IP address is set and added to the list.



LED Display

LED display shows the power supply and communication status.



Display	Content
ST(M)	Displays the diagnosis status of the unit.
PWR	Displays the status of the power supply voltage for control and input.
PWR(V)	Displays the status of the power supply voltage for output.
MS	Displays the module status.
NS	Displays the network status.

Display	Content
L/A IN	Displays the communication status of the BUS IN side.
L/A OUT	Displays the communication status of the BUS OUT side.

•ST(M)-LED

LED display	Content
ST(M) O OFF	The power supply for control and input is OFF.
ST(M) Green ON	Normal operation.
Green flashing	Diagnostic error of I/O unit is detected.
ST(M) Red flashing	Either of the following diagnostic error is detected. (When diagnostic parameter is enabled) •Valve ON/OFF counter has exceeded the set value. •Valve is short circuited or disconnected.
Red/green flashing alternately	Detect a communication error between SI unit and I/O unit.
ST(M) Red ON	SI unit has failed.

•PWR-LED

LED display	Content	
PWR Green ON	The power supply voltage for control and input is 18VDC or more.	
PWR • Red ON	The power supply voltage for control and input is less than 18VDC. (When diagnostic parameter is enabled)	

•PWR(V)-LED

LED display	Content
PWR(V) O OFF	The power supply voltage for output is less than 18VDC. (When diagnostic parameter is disabled)
PWR(V) Green ON	The power supply for output is 18VDC or more
PWR(V) Red ON	The power supply voltage for output is less than 18VDC. (When diagnostic parameter is enabled)

•MS-LED

LED display	Content	
MS Green flashing	Either of the following conditions are detected: •The unit has not been configured correctly. •The master is idle state.	
MS Green ON	The unit is in normal operation.	
M6 Red flashing	Diagnostic error is detected.	
MS Red ON	The element in SI unit is broken.	

•NS-LED

LED display	Content	
NS O OFF	IP address is not set.	
NS Green flashing	EtherNet/IP™ communication is not established.	
NS Green ON	EtherNet/IP™ communication is established.	
N8 Red flashing	EtherNet/IP TM communication is time-out.	
NS Red ON	IP address is duplicated.	

•Communication status

LED display		Content	
	OFF	Bus IN side :No Link, No Activity	
1 /A INI	Green ON	Bus IN side: Link, No Activity (100 Mbps)	
L/A IN	Green flashing	Bus IN side: Link, Activity (100 Mbps)	
	Yellow ON	Bus IN side: Link, No Activity (10 Mbps)	
	Yellow flashing	Bus IN side: Link, Activity (10 Mbps)	
	OFF	Bus OUT side :No Link, No Activity	
L /A OLIT	Green ON	Bus OUT side: Link, No Activity (100 Mbps)	
L/A OUT	Green flashing	Bus OUT side: Link, Activity (100 Mbps)	
	Yellow ON	Bus OUT side: Link, No Activity (10 Mbps)	
	Yellow flashing	Bus OUT side: Link, Activity (10 Mbps)	

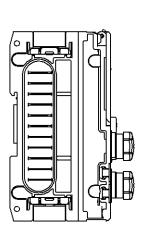
Specifications

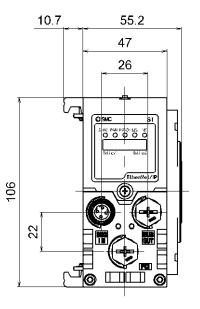
Model		EX600-SEN5-X16	
	Protocol	EtherNet/IP™	
	Transmission medium	Standard EtherNet cable (CAT5 or more, 100BASE-TX)	
	Transmission speed	10 / 100 Mbps (Auto negotiation)	
L.	Transmission type	Full duplex / Half duplex	
icatic	IP address setting range	Setting by SI unit switch :136.129.2.1 to 254	
unc	ii address setting range	Via DHCP server : Arbitrary address	
Communication	Device information	Vendor ID: 7 (SMC Corporation) Device type: 12 (Communication Adapter) Product code: 182	
	Network topology	Star: Supported Linear Bus: Supported Ring (including DLR): Supported	
	EtherNet/IP QuickConnect TM	Supported	
	Web server	Supported	
Current consumption		120 mA or less	
	Output type	Source / PNP(negative common)	
=	Number of solenoid valves	32 outputs	
Valve output	Applicable valve series	Solenoid valve with surge voltage suppressor of 24 VDC and 1.0 W or lead (manufactured by SMC)	
Valv	Output setting during communication fault	HOLD / CLEAR / Force ON	
	Protection	Short circuit protection	
	Enclosure	IP67 (manifold assembly) *1	
	Operating temperature range	-10 to 50 °C	
	Storage temperature range	-20 to 60 °C	
	Operating humidity range	35 to 85% RH (no dew condition)	
ent	Withstand voltage	500 VAC for 1 minute between external terminals and FE	
muc	Insulation resistance	500 VDC, 10 M Ω or more between external terminals and FE	
Environment	Vibration resistance	10 to 57 Hz: constant amplitude 0.75 mm p-p 57 to 150 Hz: constant acceleration 49 m/s² for 2 hours in each direction X, Y and Z respectively (De-energized)	
	Impact resistance	147 m/s ² 3 times in each directions of X, Y and Z respectively (De-energized)	
Wei	ght	300 g	

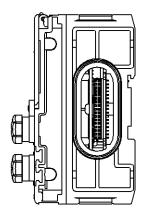
^{*1:} All unused connectors must have a seal cap fitted.

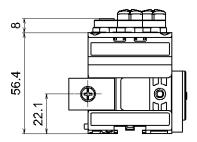


■Dimensions









End plate Model Indication and How to Order

EX600-ED3-X16

End plate at D side

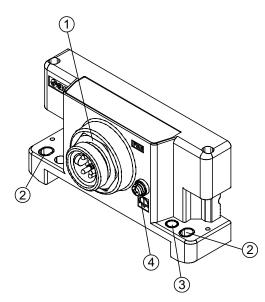
-Special specifications

Connector -

Symbol	Content
3	7/8 inch Connector

Symbol	Content	
X16	•With 7/8 inch connector (4pins) for power supply	
	Applicable pulse test	

Summary of Product parts



No.	Description	Function	
1 Power connector Supplies power for each unit and input/output device		Supplies power for each unit and input/output device	
2	Fixing hole for direct mounting	e for direct mounting Holes used for direct mounting	
3	DIN rail fixing hole	Holes used to fix DIN rail	
4	4 FE terminal FE terminal to grounding		

Mounting and Installation

■Wiring

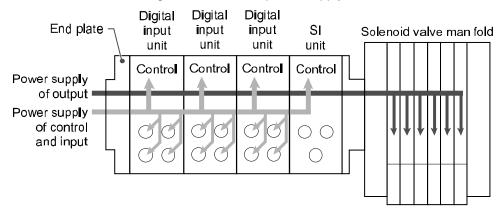
Connector pin assignment

Pin No.	Signal name	Configuration
1	24V(Output)	4 / 2
2	24V(Control and Input)	~ (O O\ -
3	0V(Control and Input)	
4	0V(Output)	3 1

Regarding the 2 types of power supply

The power supply consists of two power supply systems as follows:

- •Power supply for control and input: Supplying power for control of each unit's power supply for control and also for device connected to input port of Digital and Analogue unit.
- •Power supply for output: Supplying power for equipment connected to output port of Digital and Analogue unit, and also power supply for solenoid valve manifold.



Precautions for handling

Be sure to fit a seal cap on any unused connectors. Proper use of the seal cap enables the enclosure to achieve IP67 specification.

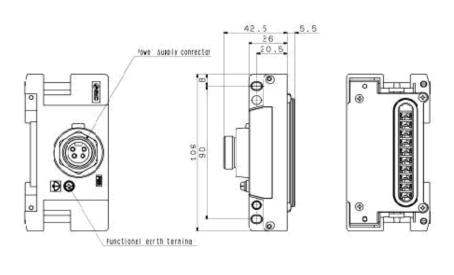
Specifications

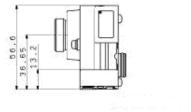
■Specifications

Model		EX600-ED3-X16	
suc	Power connector	7/8 inch (4 pins) Plug	
Power ecifications	Power supply (control and input)	24 VDC ±10%, 2 A	
eds	Power supply (output)	24 VDC +10/-5%, 2 A	
	Enclosure	IP67 (with manifold assembled) *1	
	Operating temperature range	-10 to 50 °C	
	Storage temperature range	-20 to 60 °C	
	Operating humidity range	35 to 85%RH (no condensation)	
nen	Withstand voltage	500 VAC for 1 minute between external terminals and FE	
uuo.	Insulation resistance	500 VDC, 10 M Ω or more between external terminals and FE	
Environment	Vibration resistance	10 to 57 Hz: constant amplitude 0.75 mm p-p 57 to 150 Hz: constant acceleration 49 m/s ² for 2 hours in each direction X, Y and Z respectively (De-energized)	
	Impact resistance	147 m/s ² 3 times in each directions of X, Y and Z respectively (De-energized)	
Weigh	Weight 175 g		

^{*1:} All unused connectors must have a seal cap fitted.

■Dimensions





Digital input unit Model Indication and How to Order



Digital input

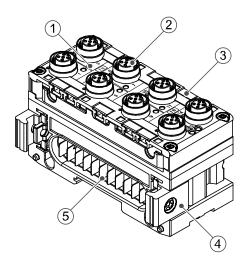
Number of Inputs and Connector

Symbol	Content
D	16 inputs / M12 connector (5pins)

Input type

Description Symbol **PNP**

Summary of Product parts



No.	Description	Function	
1	Status display LED	Displays the status of the unit.	
2	Connector (Input)	Connector for input device.	
3	Marker groove	Groove to mount a marker.	
4	Joint bracket	Bracket for joining to adjacent units.	
5	Unit connector (Plug)	Transmits signals and power supplies to adjacent units.	

Mounting and Installation

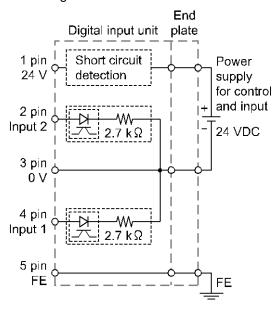
■Wiring

oConnector pin assignment

Configuration	Pin number	Signal name
1 ~ ~ 2	1	24 V (Control and input)
\(\sigma_0\)	2	Input 2
(50)	3	0 V (Control and input)
0 0/	4	Input 1
4 3	5	FE

^{*:} An M12 connector (4 pin) can also be connected.

•Circuit diagram

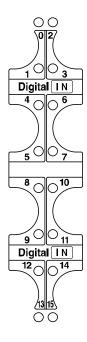


Precautions for handling

Be sure to fit a seal cap on any unused connectors. Proper use of the seal cap enables the enclosure to achieve IP67 specification.

LED Display

The status display LED shows the following unit state. Various kinds of status can be checked as follows:



Display	Content		
O OFF	The power supply for control and input, or the input device, is OFF.		
Green LED is ON	The input device is ON.		
0 2 0 2 Red LEDs are ON	The power supply of either input device of adjoined up and down LED has a short circuit.		
Red LED is flashing	The input device ON/OFF count has exceeded the set value.		

Specifications

■Specifications

Model		EX600-DXPD-X16		
specifications	Input type	PNP		
	Input connector	M12 (5 pin) socket *1		
	Number of inputs	16 inputs (2 inputs/connector)		
	Powor supply voltage (Control and input)	24 VDC Class2, 2 A		
	Max. sensor supply current	0.5 A/ connector 2 A/unit		
Input	Protective function	Short circuit protection		
드	Input resistance	2.7 kΩ		
	Rated input current	9 mA or less		
	ON voltage /ON current	17 V or more/5 mA or more		
	OFF voltage /OFF current	5 V or less/1 mA or less		
Сι	rrent consumption	70 mA or less		
	Enclosure	IP67 (With manifold assembled) *2		
	Operating temperature range	-10 to 50 °C		
	Storage temperature range	-20 to 60 °C		
ju t	Operating humidity range	35 to 85%RH (No condensation)		
Environment	Withstand voltage	500 VAC for 1 minute between external terminals and FE		
virol	Insulation resistance	500 VDC, 10 $M\Omega$ or more between external terminals and FE		
En	Vibration resistance	10 to 57 Hz: constant amplitude 0.75 mm p-p 57 to 150 Hz: constant acceleration 49 m/s² for 2 hours each in direction X, Y and Z respectively (De-energized)		
	Impact resistance	147 m/s ² 3 times each in directions of X, Y and Z respectively (De-energized)		
W	eight	340 g		

^{*1:} An M12 connector (4 pin) can also be connected.

^{*2:} All unused connectors must have a seal cap fitted.

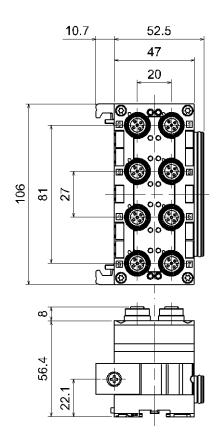
oDigital input data

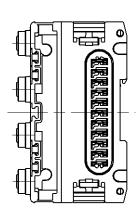
The relationship between the connector position and the input data assignment is as shown below.

•Input signal assignment (EX600-DXPD-X16)

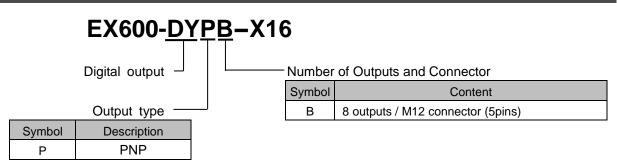
Connector nu	umber	0	1	2	3	4	5	6	7
Connector position		0000	0000	0000	0000	0000	0000	0000	0000
lanut sissal	Pin 2	Input 1	Input 3	Input 5	Input 7	Input 9	Input 11	Input 13	Input 15
Input signal	Pin 4	Input 0	Input 2	Input 4	Input 6	Input 8	Input 10	Input 12	Input 14

■Dimensions



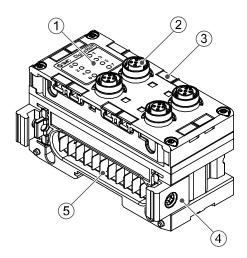


Digital output unit Model Indication and How to Order



Summary of Product parts

•EX600-DYPB-X16



No.	Description	Function		
1	Status display LED Displays the status of the unit.			
2	Connector (Output)	Connector for output device.		
3	Marker groove	Groove to mount a marker.		
4	Joint bracket	Bracket for joining to adjacent units.		
5	Unit connector (Plug) Transmits signals and power supplies to adjacent units.			

Mounting and Installation

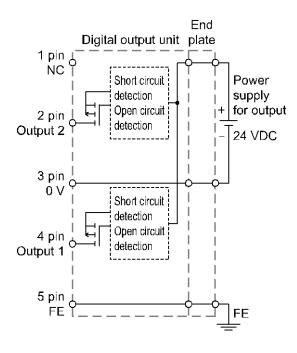
■Wiring

oConnector pin assignment

Configuration	Pin number	Signal name		
1 1 2	1	NC	24 V (Output)	
\(\sigma \)	2	Output 2	Output 2	
(50)	3	0 V (Output)	NC	
	4	Output 1	Output 1	
4 3	5	FE	FE	

^{*:} An M12 connector (4 pin) can also be connected.

Circuit diagram



Precautions for handling

Be sure to fit a seal cap on any unused connectors. Proper use of the seal cap enables the enclosure to achieve IP67 specification.

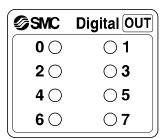
Note the following points when using the open circuit detection:

•This function detects open circuit only when the output is OFF. Therefore if output is turned ON, open circuit can not be detected.



LED Display

The status display LED shows the following unit state. Various kinds of status can be checked as follows:



Display	Content
O OFF	The power supply for control and input, or the output device, is OFF.
Green LED is ON	The output device is ON.
Red LED is ON	The output device has a short circuit.
Red LED is flashing	Either of the following conditions: •The output device ON/OFF count has exceeded the set value. •The output device is open circuit.

^{*:} Refer to troubleshooting (SI unit Operation Manual of protocol used) for the further details of countermeasures.

Specification

■Specifications

М	odel	EX600-DYPB-X16
	Output type	PNP
	Output connector	M12 (5 pin) socket *1
ions	Number of outputs	8 outputs (2 outputs/connector)
Output specifications	Power supply voltage (Control and input)	24 VDC Class2, 2 A
Output	Power supply voltage (Output)	24 VDC Class2, 2 A
	Max. load current	0.5 A/output 2 A/unit
	Protective function	Short circuit protection
Cı	urrent consumption	50 mA or less
	Enclosure	IP67 (With manifold assembled) *2
	Operating temperature range	-10 to 50 °C (Max. surrounding air temperature rating: 50 °C) *3
	Storage temperature range	-20 to 60 °C
ment	Operating humidity range	35 to 85%RH (No condensation)
Environment	Withstand voltage	500 VAC for 1 minute between external terminals and FE
ш	Insulation resistance	500 VDC, 10 M Ω or more between external terminals and FE
	Vibration resistance	10 to 57 Hz: constant amplitude 0.75 mm p-p 57 to 150 Hz: constant acceleration 49 m/s ² for 2 hours each in direction X, Y and Z respectively (De-energized)
	Impact resistance	147 m/s ² 3 times each in directions of X, Y and Z respectively (De-energized)
W	eight	300 g

^{*1:} An M12 connector (4 pin) can also be connected.

^{*2:} All unused connectors must have a seal cap fitted.

o Digital Output data

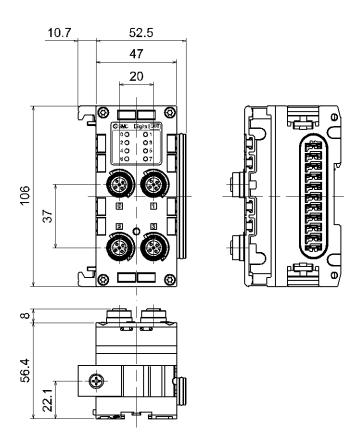
The relationship between the connector position and the output data assignment is as shown below.

•Output signal assignment (EX600-DYPB-X16)

Connector num	Connector number		1	2	3
Connector pos	ition	00	00	00	00
Output signal	Pin 2	Output 1	Output 3	Output 5	Output 7
Output signal	Pin 4	Output 0	Output 2	Output 4	Output 6

■Dimensions

•EX600-DY□B



Maintenance

Turn OFF the power supply, stop the supplied air, exhaust the residual pressure and verify the release of air before performing maintenance.

Cleaning method

Use a soft cloth to remove stains.

For heavy stains, use a cloth soaked with diluted neutral detergent and fully squeezed, then wipe up the stains again with a dry cloth.

Do not use solvents such as benzene, thinner etc. to clean each unit.

Inspection item	Content of inspection
Connector/Electric wiring	Connect properly if the connection is loose.
Seal cap	Tighten properly if the connection is loose.
Thread for mounting and installation	If the thread is loose, re-tighten it to the specified torque.
Connection cables	If the cable is broken or any other abnormality is confirmed by appearance, replace the cable with a new one.
Supply source voltage	Check if source voltage within the specification range (24 VDC ±10%) is supplied.

How to reset the product for power cut or forcible de-energizing

Supply power to the product.

The output status just before the power failure is not maintained when power supply is recovered. Start operation after confirming safety of the entire equipment.



Parameter Setting

The EX600 parameters can be configured for the system, each unit and each channel. Parameters can be changed by Web server.

■Parameter definition and setting

With EX600 series, parameters can be set for each unit.

The table below shows settable parameters for the SI unit and input/output units.

•SI unit parameters (1)

No.	Parameter	Definition	Item	Content	Default setting	Parameter setting range	
	Hold/Clear	Switch the setting of the output during communication error or	Via switch	Setting by SI unit switch becomes valid. OFF/Hold can be set output of all.	0		
1	priority setting	communication idling to follow the setting of the SI unit or the parameters.	Via software	Setting by EtherNet/IP TM object or the Web server becomes valid. OFF/Hold/Forced ON can be set per channel.		System	
2	Short Circuit	Generates error when the short	Enable	Generates an error.	0	Unit	
2	Detection	circuit of the valve is detected.	Disable	Does not generate an error.		Offic	
	Restart after	Restore the setting of short circuit		Error is automatically cleared when the short circuit is fixed.	0		
3	short circuit	detection error after the valve short circuit is cleared.	Manual	Even when the short circuit is fixed, error is not cleared until the power is supplied again.		Unit	
	Open Circuit	Generates error when the	Enable	Generates an error.		Channel	
4	Detection	disconnection of the valve is detected.	Disable	Does not generate an error.	0	Channel	
	Output setting		Clear	Turn off the output	0		
5	during communication	Sets output when communication	Hold	Hold the output		Channel	
	fault *1	error is occurred.	ForceON	Turn on the output forcefully			
	Output setting	Output setting at	Clear	Turn off the output	0		
6	during communication	the time of communication	Hold	Hold the output		Channel	
	idling *1 *2	idling	ForceON	Turn on the output forcefully			



•SI unit parameters (2)

-01	unii parameters	5 (2)				
No.	Parameter	Definition	Item	Content	Default setting	Parameter setting range
	Valve	Generates error when the operation	Enable	Generates an error. Val: 1 to 65000 *4		Channel
6	ON/OFF counter	count exceeds the set value. *3	Disable	Does not generate an error.	0	Channel
7	Valve ON/OFF counter clear	Clears the valve ON/OFF counter to 0.	-	-	-	-

- *1: This function is valid only when "Hold/Clear priority" of the SI unit parameter is set to "Via software".
- *2: Some PLC does not support an idle mode.
- *3: The count is memorized every hour. When the power supply is turned on again, counting starts from the last value memorized.
- *4: Times for setting is set value x1000 times.

•Digital input unit parameters

No.	Parameter	Definition	Item	Content	Default setting	Parameter setting range
4	The power supply short circuit	Generates error when the short	Enable	Generates an error.	0	Unit
1	detection for control and input	circuit of the power supply for the input device is detected.	Disable	Does not generate an error.		Offic
	Inrush current	Selects the over current detection	Enable	Ignores inrush current.		l lait
2	filter	for 100 msec after supplying power.	Disable	Does not ignore inrush current.	0	Unit
			0.1 ms			
_	Input filtering	Sets the time to	1.0 ms	Selects the time for	4.0	Unit
3	time	ignore the input signal change.	10 ms	filtering.	1.0 ms	Orint
			20 ms			
			1.0ms		15 ms	Unit
4	Input extension	Sets the time to hold the input	15 ms	Selects the time to hold		
-	time	signal.	100 ms	the input signal.		
		<u> </u>	200 ms			
_	Input	Generates error when the operation	Enable	Generates an error. Val: 1 to 65000 *2		Channel
5	ON/OFF counter	count exceeds the set value. *1	Disable	Does not generate an error.	0	Chame
6	Input ON/OFF counter clear	Clears the Input ON/OFF counter to 0.	-	_	-	_

^{*1:} The count is memorized every hour. When the power supply is turned on again, counting starts from the last value memorized.

^{*2:} Times for setting is set value x1000 times.

•Digital output unit parameters

No.	Parameter	Definition	Item	Content	Default setting	Parameter setting range	
	Output load	Generates error when the short	Enable	Generates an error.	0	Unit	
1	short circuit detection	circuit of the output device is detected.	Disable	Does not generate an error.		Offic	
	Restart after	Restore the setting of short circuit detection error	Auto	Error is automatically cleared when the short circuit is fixed.	0		
2	output load short circuit	after the output device short circuit is cleared.	Manual	Even when the short circuit is fixed, error is not cleared until the power is supplied again.		Unit	
	Open circuit	Generates error when the	Enable	Generates an error.		Channel	
3	detection disconnection the output do detected.		Disable	Does not generate an error.	0	Charmer	
	Output setting		Clear	Turn off the output	0		
,	during	Sets output when	Hold	Hold the output		Channal	
4	communication fault *2	communication error is occurred.	ForceON	Turn on the output forcefully		Channel	
	Output setting		Clear	Turn off the output	0		
5	during	Sets output during communication	Hold	Hold the output		Channel	
5	communication idling *2 *3	idling.	ForceON	Turn on the output forcefully		Charmer	
6	Output ON/OFF	Generates error when the operation	Enable	Generates an error. Val: 1 to 65000 *5		Channel	
0	6 ON/OFF counter	count exceeds the set value. *4	Disable	Does not generate an error.	0	Chambel	
7	Output ON/OFF counter clear	Clears the Output ON/OFF counter to 0.	-	-	-	-	

^{*1:} Could be incorrectly recognized as short circuit depending on used load (ex.: lamp load). If detection is incorrect, disable the parameter setting.



^{*2:} This function is valid only when "Hold/Clear priority" of the SI unit parameter is set to "Via software".

^{*3:} Some PLC does not support an idle mode.

^{*4:} The count is memorized every hour. When the power supply is turned on again, counting starts from the last value memorized.

^{*5:} Times for setting is set value x1000 times.

I/O Map

I/O mapping

The I/O mapping is shown with the following unit configuration as an example.

	Unit 0	Unit 1	Unit 2	Unit 3	Unit 4	
	DXPD-X16	DXPD-X16	DYPB-X16	DYPB-X16	SEN5-X16	
End plate	Digital input unit	Digital input unit	Digital output unit	Digital output unit	SI unit	Valve
·	2byte input	2byte input				
			1 byte output	1 byte output	4 byte output	

•Input data

Digital Input Unit (Unit 0, EX600-DXPD-X16) :2byte Digital Input Unit (Unit 1, EX600-DXPD-X16) :2byte

Output data

SI Unit (Unit4, EX600-SEN5-X16) :4byte
Digital Output Unit (Unit2, EX600-DYPB-X16) :1byte
Digital Output Unit (Unit3, EX600-DYPB-X16) :1byte

Input map: 8bytes fixed (Assembly instance 101)

Пристар	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0		
Byte 0	Power Status (Out) *1		Reserved							
Byte 1			Reser	ved			Power Status (C/I) *2	Reserved		
Byte 2	Unit 0 Input 7	Unit 0 Input 6	Unit 0 Input 5	Unit 0 Input 4	Unit 0 Input 3	Unit 0 Input 2	Unit 0 Input 1	Unit 0 Input 0		
Byte 3	Unit 0 Input 15	Unit 0 Input 14	Unit 0 Input 13	Unit 0 Input 12	Unit 0 Input 11	Unit 0 Input 10	Unit 0 Input 9	Unit 0 Input 8		
Byte 4	Unit 1 Input 7	Unit 1 Input 6	Unit 1 Input 5	Unit 1 Input 4	Unit 1 Input 3	Unit 1 Input 2	Unit 1 Input 1	Unit 1 Input 0		
Byte 5	Unit 1 Input 15	Unit 1 Input 14	Unit 1 Input 13	Unit 1 Input 12	Unit 1 Input 11	Unit 1 Input 10	Unit 1 Input 9	Unit 1 Input 8		
Byte 6	0	0	0	0	0	0	0	0		
Byte 7	0	0	0	0	0	0	0	0		

^{*1:} Byte 0 Bit 7 is ON -> Power supply voltage for output is less than approx. 18VDC.

Output map: 12bytes fixed (Assembly instance 102)

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Byte 0				Rese	erved			
Byte 1				Rese	erved			
Byte 2	Unit4							
Dyto 2	Coil7	Coil6	Coil5	Coil4	Coil3	Coil2	Coil1	Coil0
Byte 3	Unit4							
Dyte 3	Coil15	Coil14	Coil13	Coil12	Coil11	Coil10	Coil9	Coil8
Byte 4	Unit4							
byte 4	Coil23	Coil22	Coil21	Coil20	Coil19	Coil18	Coil17	Coil16
Duto 5	Unit4							
Byte 5	Coil31	Coil30	Coil29	Coil28	Coil27	Coil26	Coil25	Coil24
Byte 6	Unit 2							
Dyte 0	Output 7	Output 6	Output 5	Output 4	Output 3	Output 2	Output 1	Output 0
Byte 7				Rese	erved			
Byte 8	Unit 3							
Dyte 0	Output 7	Output 6	Output 5	Output 4	Output 3	Output 2	Output 1	Output 0
Byte 9		Reserved						
Byte 10		Reserved						
Byte 11				Rese	erved			

^{*2:} Byte 1 Bit 1 is ON -> Power supply voltage for control and input is less than approx. 18VDC.

Configuration map : 16bytes fixed(Assembly instance 103)

	To similar map is to by to a mitour, to be m							
	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Byte 0				Rese	erved			
• • •				Rese	erved			
Byte 9				Rese	erved			QC *1
• • •		Reserved						
Byte 15				Rese	erved			

^{*1:} Quick Connect mode(0:Normal mode 1:Quick Connect mode) It is necessary to reenter the power supply to reflect the setting.

EX600-SEN5-X16(SI unit) Boot Modes:

SI unit shall have 2 modes: Normal and Quick Connect.

SI unit shall utilize Configuration Byte 9 Bit 0 as a single value to manipulate the Quick Connect configuration.

Byte 9 Bit 0 Options:

(1) A value of 0 shall return the SI unit to Normal mode:

Bus IN port	Bus OUT port	QuickConnect [™] setting
Auto-negotiation	Auto-negotiation	Disable

If SI unit fail Auto Negotiation, Bus IN port should default to 100 Full Duplex Auto-MDIX. Bus OUT port should default to 100 Full Duplex Auto-MDIX.

(2) A value of 1 shall set the SI unit to Quick Connect mode:

Bus IN port	Bus OUT port	QuickConnect [™] setting	
100Mbps/Full duplex	100Mbps/Full duplex	Enable	
MDI	MDIX		

Hardware Configuration

■EDS file and icon

EDS file is required to configure the EX600. Furthermore, icons are necessary for the display icon of the EX600 on the configure.

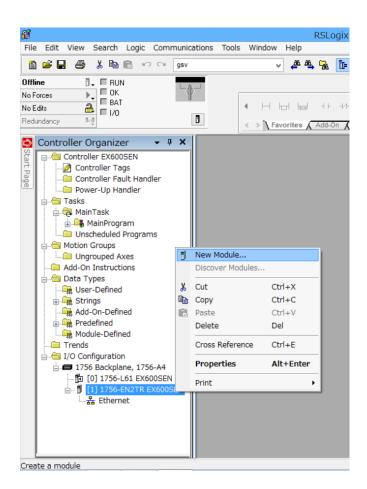
EDS file: ex600_sen5_x16_v11.eds

Icon: ex600_1.ico

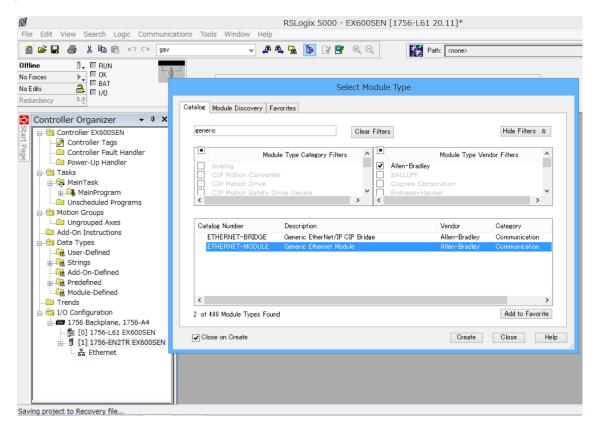
■Setting using RSLogix5000TM

When connecting EX600 series, use RSLogix5000TM software by Rockwell Automation. Refer to the manual of RSLogix5000TM for a detailed manner of operation.

- *: The screen data shown here is the English version of RSLogix5000TM.
- •Select [EtherNet/IPTM module] in [I/O Configuration] folder. Select [New Module].



•[Select Module] window is displayed. Select [ETHERNET-MODULE Generic Ethernet Module], and click on [OK].



- •[Module Properties] window is displayed. Perform each setting.
- (1)Name: Input the description of specific unit.
- (2)Comm Format: Select the data format of Connection Parameters.
- (3)IP Address: Input IP Address which is set in SI unit.

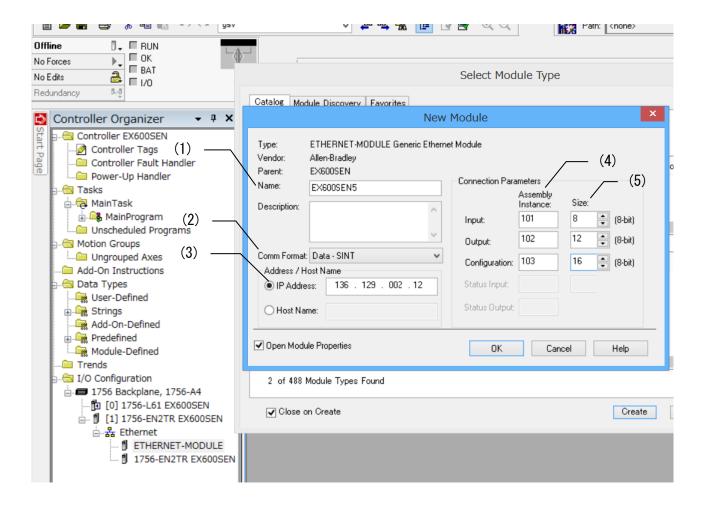
(4) Assembly Instance: Set as below.

Description	Decimal		
Common Format	"Data-INT" "Data-SINT"		
Input	101	101	
Output	102	102	
Configuration Note)	103	103	

Note) Configuration other than 103 is possible when Configuration Assembly is not used

(5)Size: Set as below.

(0)0:20: 00: 00:0:::			
Description	Decimal		
Common Format	"Data-INT" "Data-SINT"		
Input	4 word	8 byte	
Output	6 word	12 byte	
Configuration	8 word	16 byte	



Web Server

EX600 Web server functional overview

The Web server function is provided by the EX600-SEN5-X16.

The functions available vary depending on the mode.

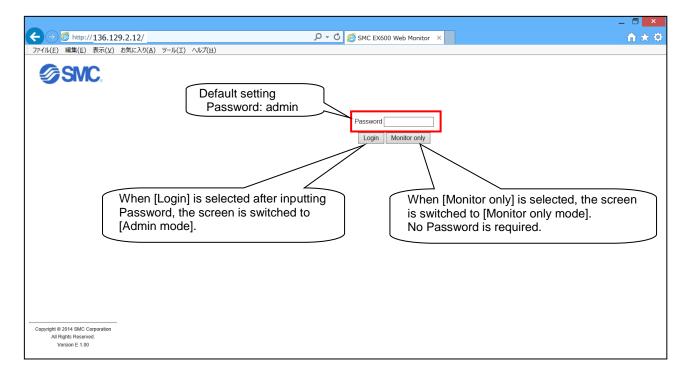
Function	Admin mode	Monitor only mode	
I/O Monitor	Available	Available	
Diagnostic status monitor	Available	Available	
Parameter setting	Available	Not available	
Force I/O setting	Available	Not available	

Note

This software operates correctly using Internet Explorer 6 to 11. If the functions do not operate correctly with Internet Explorer 10 or later versions, then use Internet Explorer in compatibility mode.

Connecting to a EX600-SEN5-X16 (Ex. Windows 8)

- (1) Open a web browser on the PC.
- (2) Type the IP address of EX600-SEN5-X16. (Ex. http://136.129.2.12)
- (3) The EX600 webpage should load after several seconds.

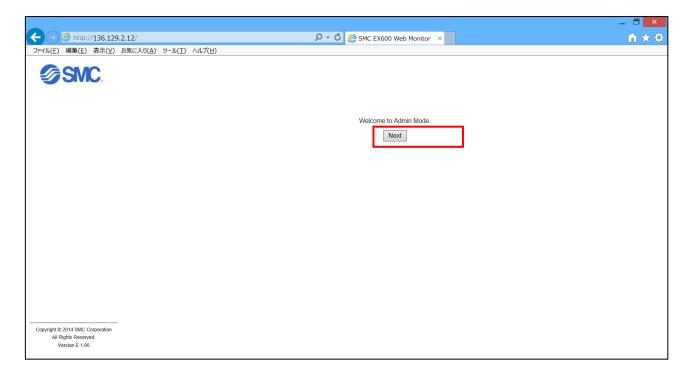


Note

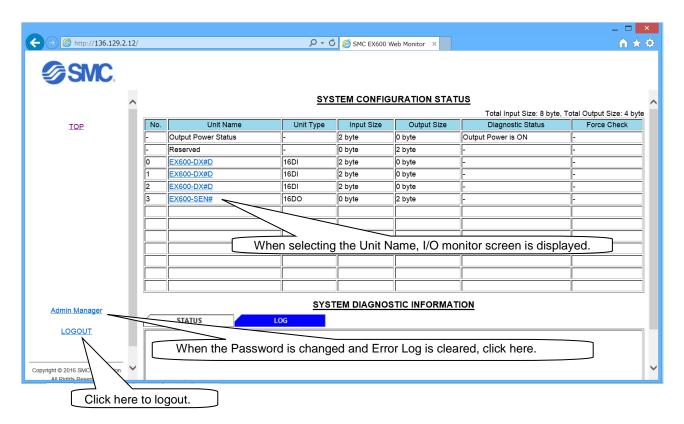
Connect one SI unit to one PC.



(4) When [Login] is selected after inputting Password, the screen below is displayed. Press the [Next] button.



(5) After pressing the [Next] button, the [SYSTEM CONFIGURATION STATUS] screen is displayed. This screen will be the TOP screen.

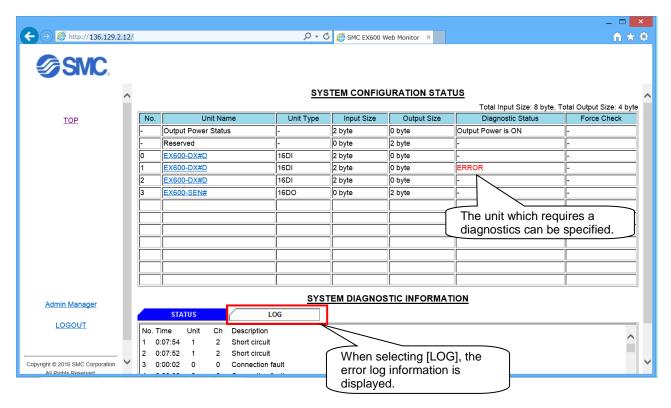


Caution

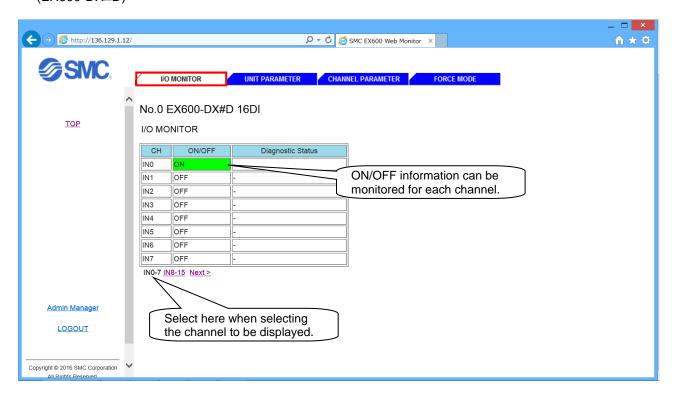
The screen above shows the case when the unit is connected as shown below.

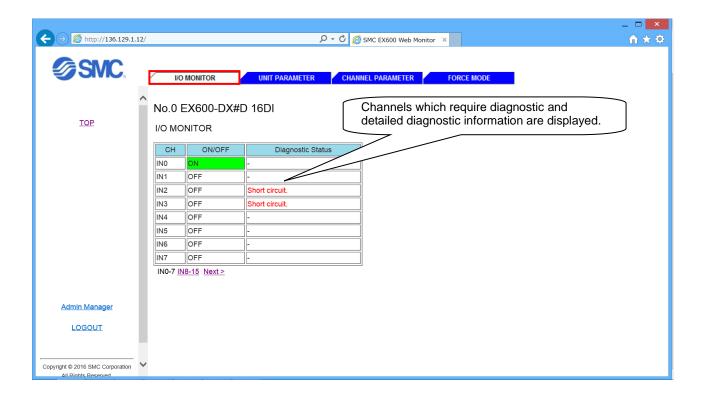
	No.0	No.1	No.2	No.3
End plate	DX#D	DX#D	DX#D	SEN

(6) When unit diagnostics is generated, the diagnostic information is displayed on the [SYSTEM CONFIGURATION STATUS] screen.

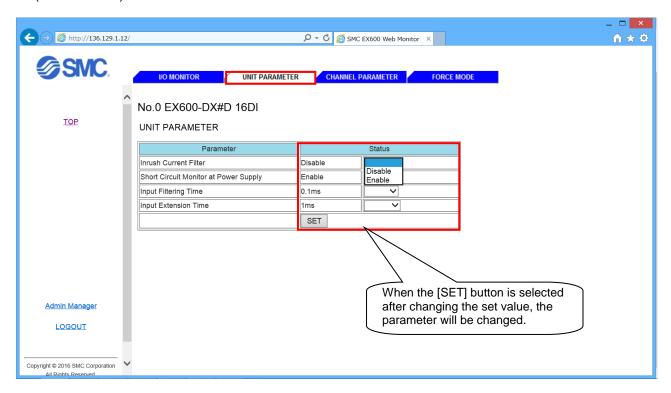


(7) When [Unit Name] is selected on the [SYSTEM CONFIGURATION STATUS] screen, the [I/O MONITOR] screen is displayed. (EX600-DX□D)

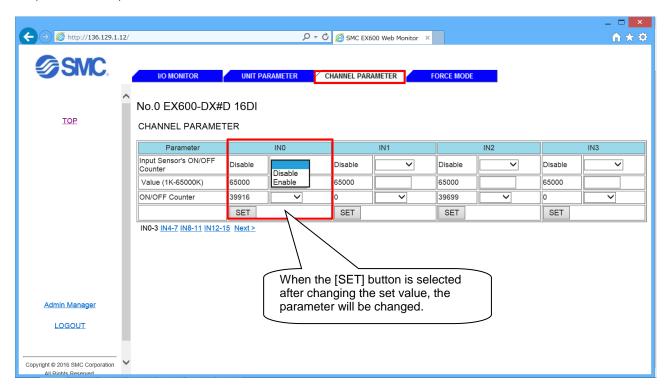




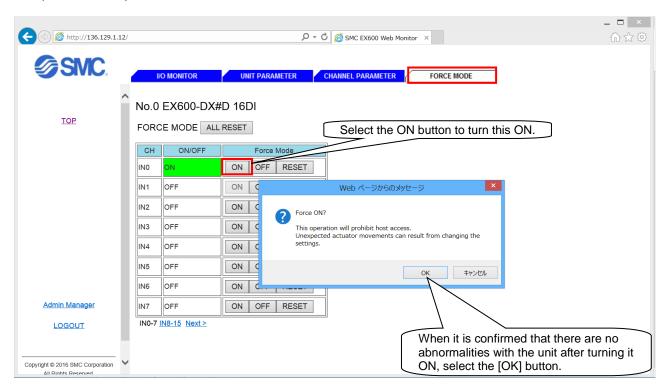
(8) Select the [UNIT PARAMETER] tab to display the [UNIT PARAMETER] screen. (EX600-DX \square D)



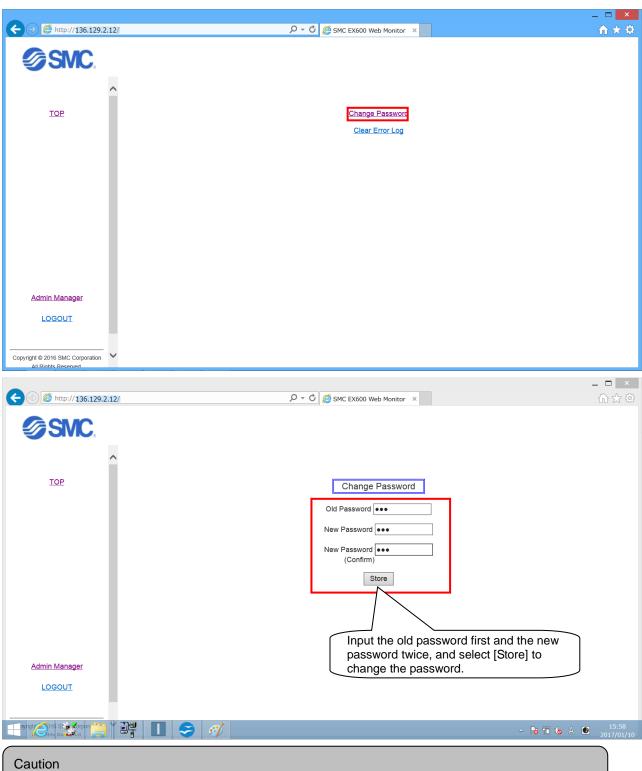
(9) Select the [CHANNEL PARAMETER] tab to display the [CHANNEL PARAMETER] screen. (EX600-DX□D)



(10) Select the [FORCE MODE] tab to display the [FORCE MODE] screen. (EX600-DX□D)



(11) To change the Password, select [Admin Manager] and select [Change Password].



Do not logout using the [x] button shown at the upper right of the screen.

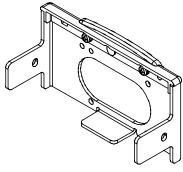
Accessories

For the selection of accessories, refer to the catalog.

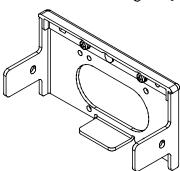
(1)Valve plate

EX600-ZMV1

Enclosed parts: Round head screw (M4 x 6), 2 pcs. Round head screw (M3 x 8), 4 pcs.



EX600-ZMV2 (Specified for SY series)
Enclosed parts: Round head screw (M4 x 6), 2 pcs.
Round head screw (M3 x 8), 4 pcs.



(2)End plate bracket

EX600-ZMA2

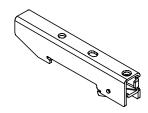
Enclosed parts: Round head screw (M4 x 20), 1 pc.

P tight screw (4 x 14), 2 pcs.

EX600-ZMA3 (Specified for SY series)

Enclosed parts: Round head screw (M4x20) with washer, 1 pc.

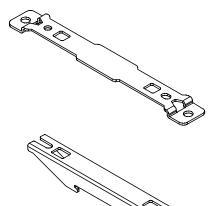
P tight screw (4 x 14), 2 pcs.



(3)Intermediate support bracket

EX600-ZMB1: For direct mounting

Enclosed parts: Round head screw (M4 x 5), 2 pcs.



EX600-ZMB2: For DIN rail mounting

Enclosed parts: Round head screw (M4 x 6), 2 pcs.



(4)Seal cap (10 pcs.)

EX9-AWES: For M8 EX9-AWTS: For M12





(5)Marker (1 sheet, 88 pcs.) EX600-ZT1



(6)EtherNet/IP™ communication cable

PCA-1446566: Cable with M12 connector, D code, Plug, Straight 5 m, SPEEDCON compatible

EX9-AC010EN-PSRJ: Cable with M12 connector, D code-RJ45, Plug, Straight 1 m EX9-AC020EN-PSRJ: Cable with M12 connector, D code-RJ45, Plug, Straight 2 m EX9-AC030EN-PSRJ: Cable with M12 connector, D code-RJ45, Plug, Straight 3 m EX9-AC100EN-PSRJ: Cable with M12 connector, D code-RJ45, Plug, Straight 5 m EX9-AC100EN-PSRJ: Cable with M12 connector, D code-RJ45, Plug, Straight 10 m



Revision history

Edition A

- EX600-DYPB-X16 added.
- I/O map and hardware configuration are changed.

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