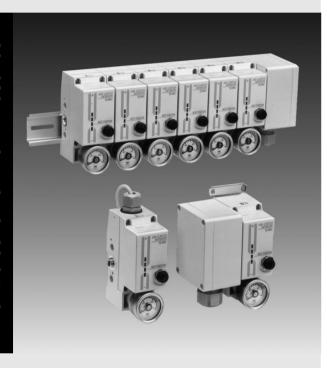
# Air Catch Sensor Series ISA

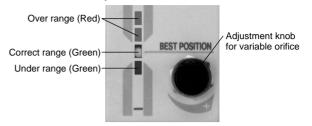


Due to the construction of the sensor, fluctuations in the supply pressure do not influence operations.

Non contact style sensor for applications requiring confirmation of work present for machining operations.

#### LED Bar graph for easy calibration

The LED bar graph indicator in conjunction with the adjustment knob for the variable orifice allows for easy and correct calibrations.



#### Reliable detection of a 10 µm gap

The operation of the Air-Catch Sensor is stable during supply pressure fluctuations due to the internal air bridge circuit and solid state sensors.

Up to 6 Air-Catch Sensors can be manifold mounted for centralized wiring and piping.

#### **Mounting orientation**

Due to the use of a pressure sensor, stable detection is guaranteed regardless of mounting orientation.

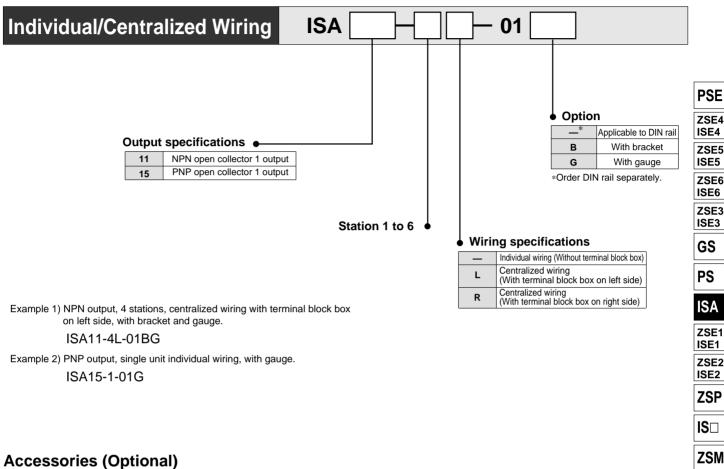
#### Wide detection range

Applicable to 10 to 300 µm

#### **Enclosure IP66**

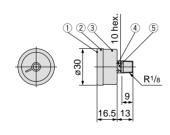
Dust proof and drip proof

#### **How to Order**



- · Bracket ISA-1-A
- · Gauge G33-3-01
- · DIN rail ISA-2-1 to 7

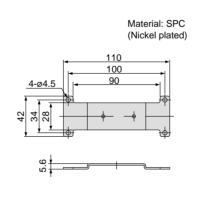
#### - Gauge/G33-3-01



#### Description

No.	Description	Material
1	Cover	Glass
2	Front rim	Stainless steel
3	Retaining rim	Stainless steel
4	Cross recessed round head screw	Stainless steel
(5)	Stub	Brass

#### · Bracket/ISA-1-A



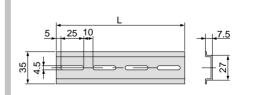
\* Part no. includes M3 X 8 tapping screws (2 pcs.)

#### - DIN rail/ISA-2-1 to 7

Material: Aluminum

PF□

 $\mathsf{IF}\Box$ 

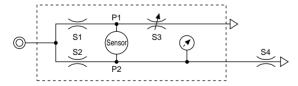


Part No.	L	Applicable model		
ISA-2-1	105	ISA□-1		
ISA-2-2	140	ISA□-2/ISA□-1 <sup>L</sup> <sub>R</sub>		
ISA-2-3	175	ISA□-3/ISA□-2 <sup>L</sup> <sub>R</sub>		
ISA-2-4	210	ISA□-4/ISA□-3 <sup>L</sup> <sub>R</sub>		
ISA-2-5	245	ISA□-5/ISA□-4 <sup>L</sup> <sub>R</sub>		
ISA-2-6	280	ISA□-6/ISA□-5 <sup>L</sup> <sub>R</sub>		
ISA-2-7	315	ISA□-6 <sup>L</sup> <sub>R</sub>		

#### **Specifications**

Fluid		Dry air (Filtered through a 5μm filter)		
Operating pressure range		0.05 to 0.2MPa		
Recommended pressure range		0.1 to 0.2MPa		
Detection zone		10 to 300 μm		
Repeatability including temperature characteristics		±10μm (for 0 to 60°C on the basis of 25°C)		
Hysteresis		Less than 10 μm (Detection distance 10 to 150 μm)		
Detection nozzle size		ø1.0 standard (Refer to p.3.8-7 when nozzle size is changed)		
Indicator light		Operation indicator light (lighting under ON condition) Deflection level indicator light		
Power supply voltage		12 to 24 V DC (Ripple less than ±10%)		
Current consumption		Less than 30 mA (Output ON, LED ON)		
	ISA11	NPN open collector less than 30V 80mA		
Output	ISA15	PNP open collector less than 80mA		
Operating temperature range		0 to 60°C (No condensation)		
Operating humidity range		35 to 85% RH		
Noise resistance		1000 Vp-p Pulse width 1μS, Standing 1ns pulse		
Voltage resistance		1000V AC 50/60Hz for one minute between external terminals and case		
Insulation resistance		$2 \mathrm{M}\Omega$ or more (at 500VDC megameter) between external terminals and case		
Vibration resistance		10 to 500Hz vibration width 1.5mm or 9.8m/s² to X, Y, Z directions 2 hours for each direction		
Impact resistance		980 m/s <sup>2</sup> X, Y, Z direction, 3 times for each direction		
Cable		Oil-proof chloroethylene cable (ø3.4, 0.2mm², 5m)		
Weight		250g (Including gauge, 5m lead wire)		
Port size		Rc 1/8		
Enclosure		IP66 (Dust proof and drip proof)		
Flow consumption	Supply	16d/min at 0.10 MPa		
	pressure	21d/min at 0.15 MPa		
	pressure	25t/min at 0.20 MPa		

#### **Operation Principles**



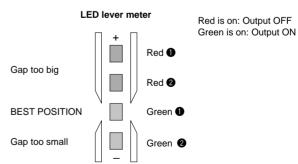
- S1, S2: Fixed orifice
  - S3: Variable orifice (Set via adjustment knob)
  - S4: Detection nozzle

The bridge circuit is constructed as shown in the diagram. Position the work piece in front of the nozzle (S4).

With a gap gauge adjust the distance between work piece and the nozzle. Remove the gauge and balance the bridge circuit (P1 = P2) by adjusting the variable orifice (S3) via the adjustment knob. By moving the work piece away from the nozzle (S4) a pressure differential (P1  $\geq$  P2) is created. As soon as the work piece is moved within the detection range of the Air-Catch Sensor the back pressure P2 increases. If P2 is equal or greater than P1, the switch output is 'ON'. As soon as the work piece is outside of the detection zone the switch output is 'OFF'.

### **Method of Calibration**

The Air-Catch Sensor is adjusted using the LED bar graph and the adjustment knob.

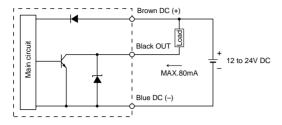


- (1) Place the gap gauge on the detection nozzle for precise adjustment.
- (2) Confirm applied air pressure. If the variable orifice is closed (turn the adjustment knob counterclockwise), all LED's are off.
- (3) When opening the variable orifice (turn the adjustment knob clockwise) the LED's will light up in the following order: Red 1, Red 2, Green 1, Green 2
- (4) When the LED Green is on, the output is energized. This should conclude the calibration.
- (5) Confirm calibration setting by removing the gap gauge from the nozzle. The LED Green should go off. Place the gap gauge on to the detection nozzle again, the Green LED should light up again.
- (6) Secure the setting of the adjustment knob with the spanner nut.

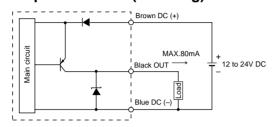
### **Internal Circuit/Wiring**

The lead wire colors indicated inside "( )" are old colors prior to compliance with the IEC standard.

#### **NPN Open Collector (Sinking)**

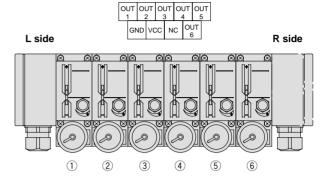


#### **PNP Open Collector (Sourcing)**



#### **Centralized Wiring Style**

Relation between terminal block wiring in terminal box and switch is shown below.



PSE

ZSE4 ISE4 ZSE5

ZSE6 ISE6

ZSE3 ISE3

GS

PS

ISA

ZSE1 ISE1

ZSE2 ISE2

ZSP

IS□

ZSM

PF□

IF□

## **⚠** Precautions

Be sure to read before handling. Refer to p.0-26 and 0-27 for Safety Instruction and common precaution of the products mentioned in this catalog, and refer to p.3.0-7 to 3.0-9 for precautions on every series.

#### Installation

#### 

①Do not allow water, cutting oil, etc. to flow back from the detection nozzle to the switch body. Always mount switch body higher than detection nozzle if possible.

#### **Piping**

#### **⚠** Caution

#### **1** Piping materials

Do not mount any equipment or fittings between the switch body and the detection nozzle in order to avoid leaks and pressure drops. Do not use one-touch fittings in applications where these fittings might be exposed to liquid being sprayed onto them.

#### **Supply Pressure**

#### **⚠** Caution

#### 1 Supply air

Be careful not to allow any foreign materials into the supply of the Air Catch Sensor. Contamination of the sensor will decrease the sensor's accuracy.

Especially important when measuring small bore orifices. Use dry and filtered ( $5\mu m$ ) supply air.

**2**Operating pressure

Do not exceed the max. operating pressure of 0.2 MPa. Damage to the solid state pressure sensor may occur.

## Environment

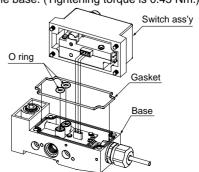
#### **⚠**Caution

- ①If the Air Catch Sensor is mounted in an enclosure, make sure that the exhaust port is open to atmospheric pressure to avoid malfunction due to possible pressure build-up inside the enclosure.
- ②Connect the tubing via the M5 fittings to the Air Catch Sensor. Place the tubing in such a way that no water, oil, etc. can enter the sensor. The Air Catch Sensor is rated IP66. However in order to achieve this rating the gauge has to be removed from the sensor screw a fitting into the gauge port and run tubing to the gauge. When remove mounting the gauge keep the tubing as short as possible otherwise the response time will increase.

#### Maintenance

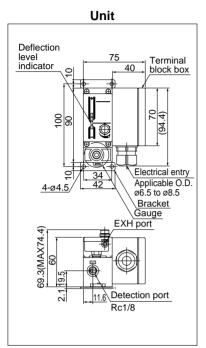
#### **∧**Caution

- ①After removing the 4 mounting screws (M4 X 8) pull the switch body off vertically.
  - If the switch body is pulled off in an angle the connector pins may be bent.
- When mounting the switch body onto the base, be careful that the body is lowered vertically onto the base and the connector pins are not bent. Tighten the 4 mounting screws equally (M4 X 8)
- Note) Do not forget to insert the seals prior to mounting the body onto the base. (Tightening torque is 0.45 Nm.)



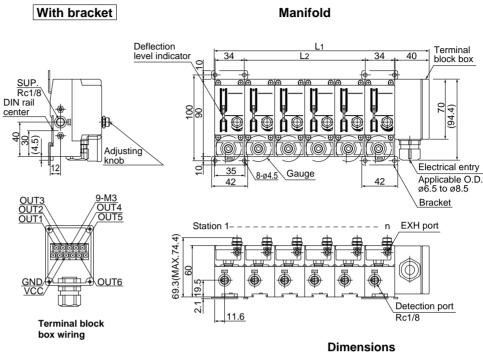


#### **Dimensions/Centralized Wiring (Terminal Block Box Style)**



2 station manifold, if the terminal block is located on the right side of the manifold assembly, the mounting bracket is located on the second Air-Catch Sensor. If the terminal block is located on the left side of the manifold assembly, the mounting bracket is located on the first Air-Catch Sensor.

For manifolds with more than 2 stations, the mounting brackets are located on the first and last Air-Catch Sensor.



Station 2 3

L1

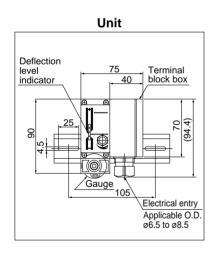
L2

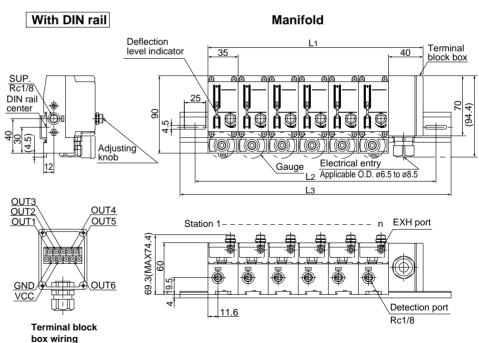
110 145 180 215 250

4 5

36 71 106 141

6





#### **Dimensions/With DIN rail** Station 2 3 4 5 L1 110 145 180 215 250 L2 140 175 210 245 280

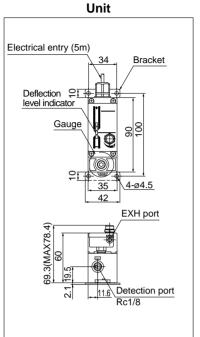
210 | 245 | 280 | 315

L3

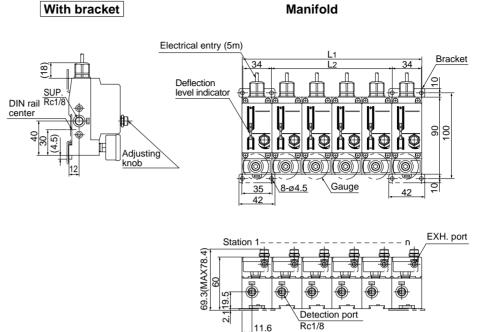
175

# Air Catch Sensor ISA

## **Dimensions/Individual Wiring (Lead Wire Style)**



For 2 station manifold, the mounting bracket is located on the first Air-Catch Sensor. For manfolds with more than 2 stations, the mounting brackets are located on the first and last Air-Catch Sensor.



Dimensions					
Station	2	3	4	5	6
L1	70	105	140	175	210
L2	_	36	71	106	141

**PSE** 

ZSE4 ISE4

ZSE5 ISE5

ZSE6 ISE6

ZSE3

ISE3

GS

PS

ISA

ZSE1

ISE1

ZSE2

ISE2

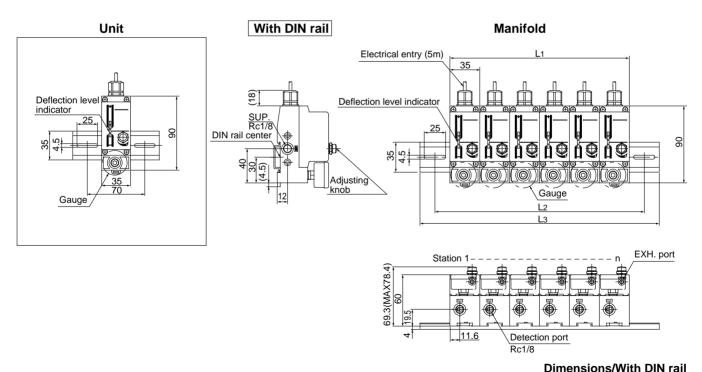
**ZSP** 

IS□

**ZSM** 

PF□

 $\mathsf{IF}\Box$ 



Difficusions/With Difficult					
Station	2	3	4	5	6
L1	70	105	140	175	210
L2	105	140	175	210	245
L3	140	175	210	245	280

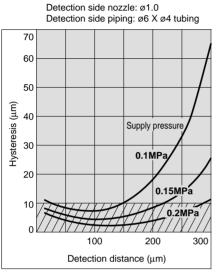
#### **Guide for Use/Design Data**

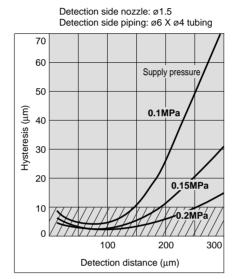
When designing a pneumatic circuit with an Air-Catch Sensor, please refer to the data below. The detection distance for the Air-Catch Sensor is between 10 to  $300\mu m$ . When the supply pressure of the nozzle diameter changes reliable detection is not possible.

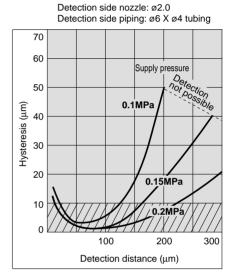
#### **Nozzel Diameter and Detection Distance**

The graphs below show the hysteresis in relationship to the detection distance. When high accuracy is required, design the system so the hysteresis is within the  $10\mu m$  detection distance. When the Hysteresis exceeds  $10\mu m$  use the Air-Catch Sensor as a confirmation of position of work piece.

[///]: Stable adjustment range





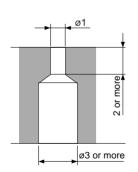


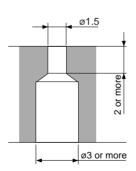
Example 1) When requiring  $300\mu m$  detection, select the detection nozzle of ø1.0 with supply pressure 0.2MPa. Example 2) When requiring  $10\mu m$  detection, select the detection nozzle of ø1.5.

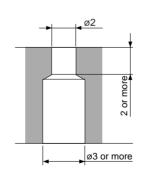
#### **Nozzle Shape**

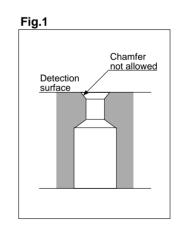
Nozzle shape should be designed as follows.

Pay attention to detection surface and the chamfer of nozzle hole as shown in Fig.1 since they can affect performance.









#### **Response Time**

The response time is dependent on the detection distance and the piping length. The supply pressure and the nozzle diameter do not influence the response time. Table 2 shows the response time for different detection distance settings and a constant piping length. Table 3 shows the response time when the detection distance is constant but the piping length changes. As can be seen from the graphs below, if the piping length is kept short and the detection distance is small, the response time is faster.

Piping: Ø6 X Ø4 tubing 5m Supply pressure: 0.2MPa

2.5
2.0
Set value 50μm 100μm 200μm 300μm
300μm
1.5
98 0.5

150

Detection distance (µm)

200

250

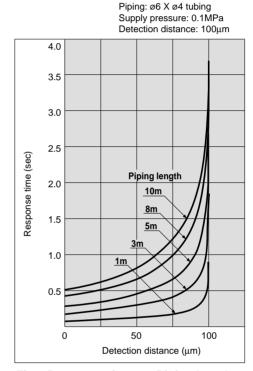
300 350

Detection nozzle: ø1.0

Fig.2 Detection distance vs. Response time

100

50

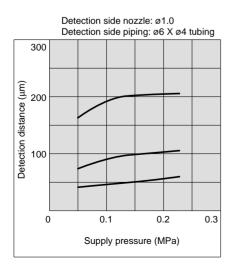


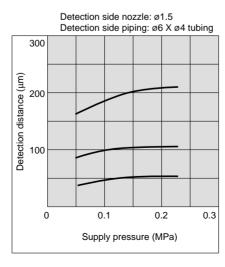
Detection nozzle: ø1.0

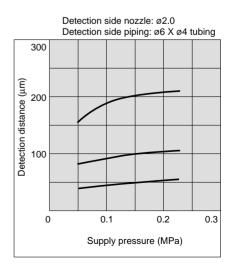
Fig.3 Response time vs. Piping length

#### **Supply Pressure vs. Detection Distance**

The graphs below show the detection distance for different supply pressure setting.







**PSE** 

ZSE4 ISE4

ZSE5 ISE5 ZSE6

ISE6 ZSE3 ISE3

GS

GS

PS

ISA

ZSE1 ISE1 ZSE2 ISE2

ZSP

IS IZSM

PF□

IF□