



# Air Gripper for Collaborative Robots

Compliant with the CRX Series

**FANUC CORPORATION**

collaborative robot

## Plug and Play

configuration for immediate use

**FANUC CRX plug-in software** Easy programming



# JMhZ2-X7400B-CRX



P-EU20-26-UK

# Plug and Play

## Air Gripper for Collaborative Robots

FANUC CORPORATION

CRX-10 iA, 10 iA/L compliant



■ Compact, lightweight product with high gripping force due to air operation

■ An air gripper that realises high rigidity and high precision due to its guide-integrated construction

With high-precision linear guide

**Repeatability:  $\pm 0.01$  mm**

Linear guide of the higher rigidity and precision is used.

**Higher rigidity** (Compared with the same size of the existing MHZ2)

■ Operate by simply connecting 1 air supply tube and an electrical wiring M8 connector.

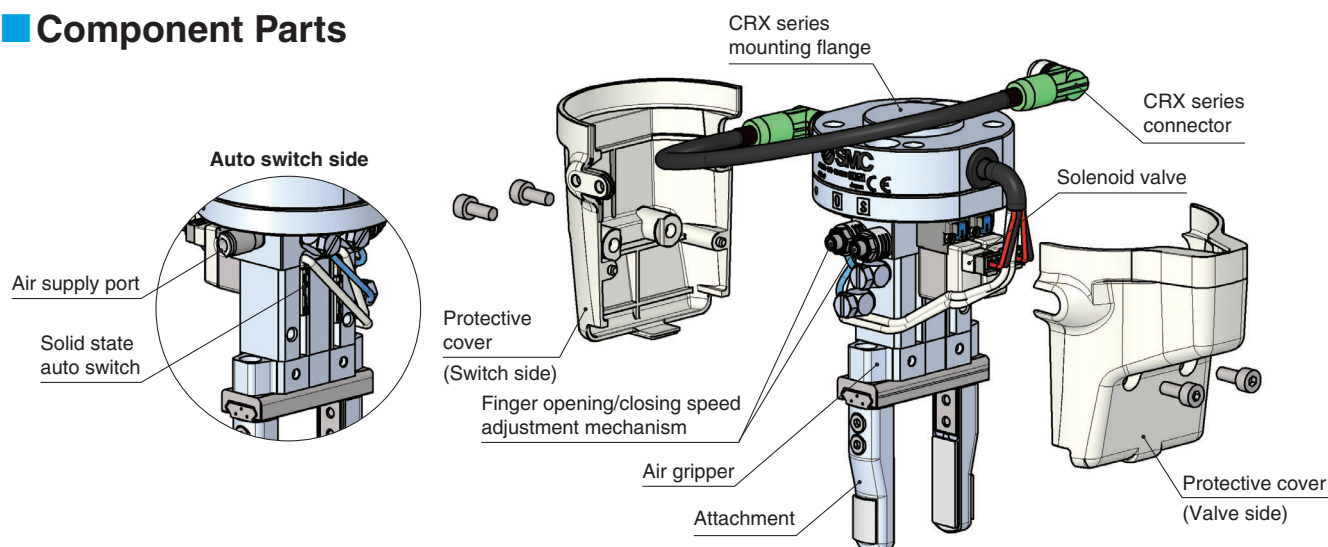
■ Integrated solenoid valve, speed adjustment mechanism, and auto switch

■ FANUC CRX plug-in software

■ A split protective cover for easy air gripper maintenance

Allows you to maintain the air gripper without removing the user-specific attachment

### Component Parts



### How to Order



RoHS

**JMHZ2-16D-X7400B-CRX**

### Specifications

Bore size [mm]		16
Fluid		Air
Action		Double acting
Operating pressure [MPa]		0.1 to 0.7
Repeatability [mm]		±0.01
Gripping force	External	32.7
Effective value per finger [N]	Internal	43.5
Opening/Closing stroke (Both sides) [mm]		10
Weight [g]		430
Standards		ISO9409-1-50-4-M6
Auto switch model		D-M9P-5
Connector type		M8 8-pin connector (Socket)

■ Included parts: Piping tube ( $\varnothing 4 \times 2$  m), Mounting bolt, Positioning pin

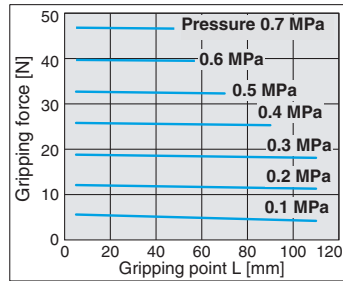
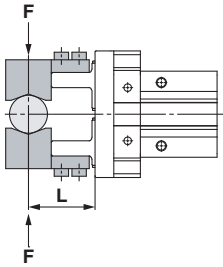
## Characteristics

### Gripping force

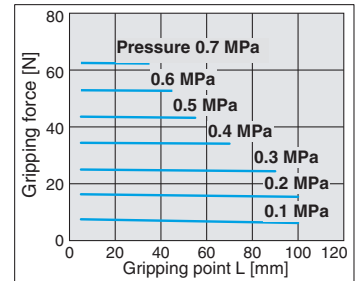
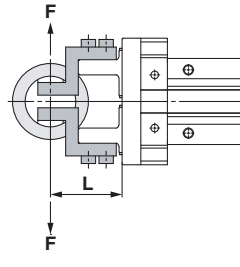
#### ● Indication of effective gripping force

The gripping force shown in the graphs below represents the gripping force of one finger when all fingers and attachments are in contact with the workpiece. F = One finger thrust

#### External gripping force



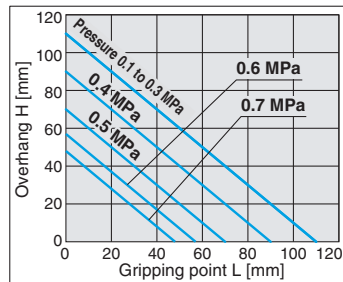
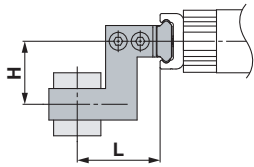
#### Internal gripping force



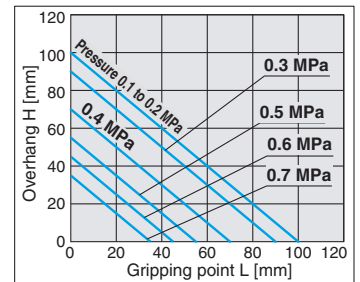
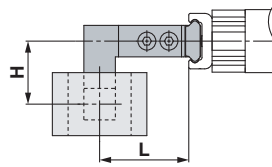
### Gripping point

- The air gripper should be operated so that the workpiece gripping point "L" and the amount of overhang "H" stay within the range shown for each operating pressure given in the graphs below.
- If the workpiece gripping point goes beyond the range limits, this will have an adverse effect on the life of the air gripper.

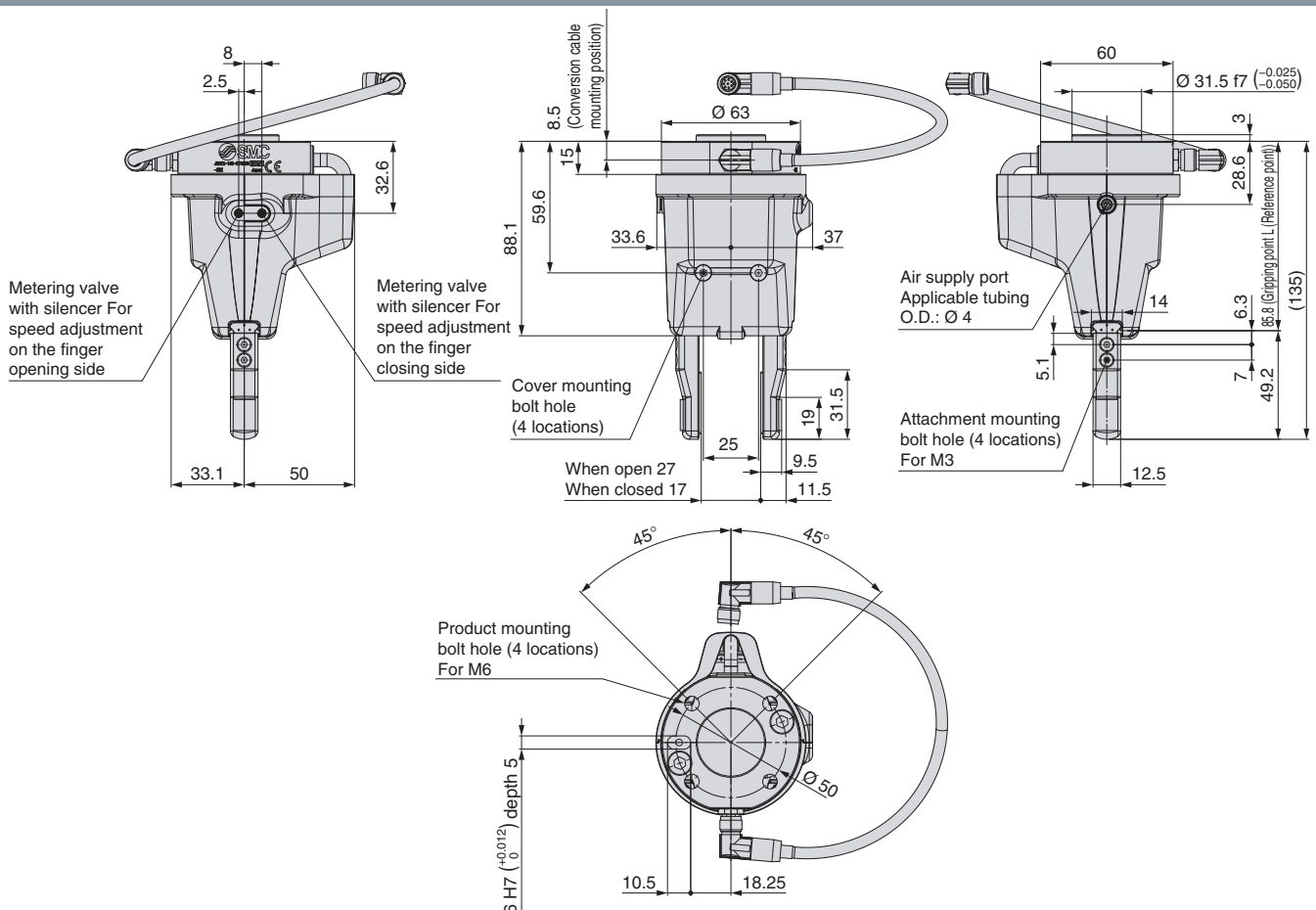
#### External grip



#### Internal grip



## Dimensions



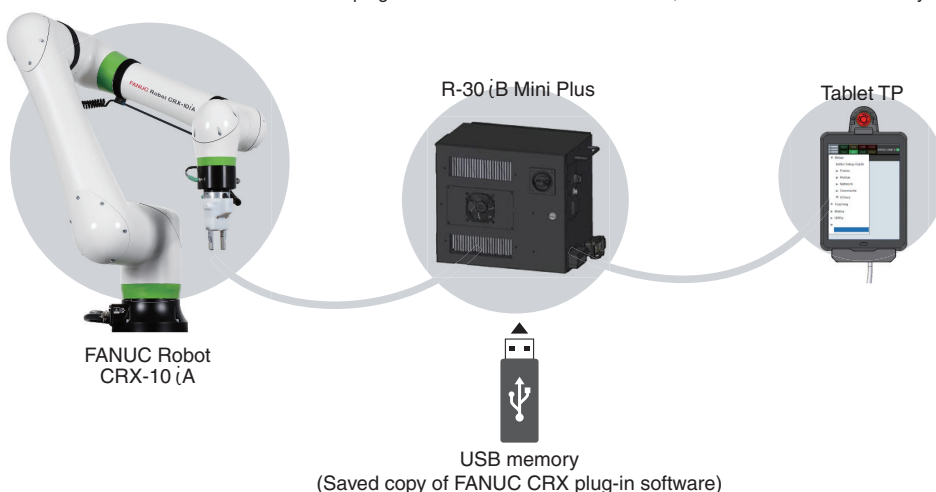
# FANUC CRX Plug-in Software

## Easy programming

By using SMC's air gripper unit plug-in software, the dedicated setting window can be displayed and dedicated instructions can be executed.

The CRX plug-in software can be easily installed by inserting a USB stick containing the software (provided by SMC) into the control device.

\* Please download the CRX plug-in software from the SMC website, and save it to a USB memory.



## SMC Corporation

SMC CORPORATION  
Akihabara UDX 15F, 4-14-1, Sotokanda, Chiyoda-ku, Tokyo 101-0021, JAPAN  
Phone: 03-5207-8249 FAX: 03-5298-5362  
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## European Marketing Centre (EMC)

Zuazobidea 14, 01015 Vitoria  
Tel: +34 945-184 100 Fax: +34 945-184 124  
URL <http://www.smc.eu>