

# Electric Actuator

High Performance



New



\* For details, refer to page 45.

## High Rigidity and High Precision Slider Type

Battery-less Absolute (Step Motor 24 VDC)

## Reduces cycle time

### Cycle time

Reduced by **39%** (0.57 s ← 0.93 s)  
compared with the existing model<sup>\*1</sup>

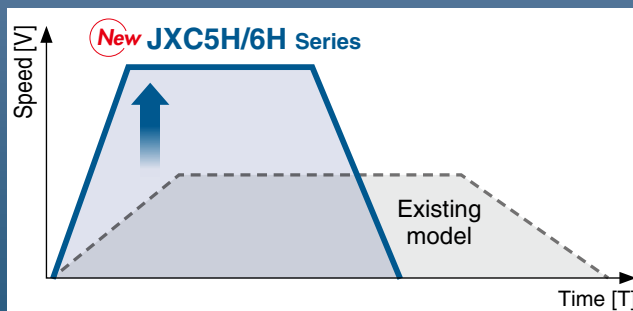
<sup>\*1</sup> When LEKFS25GH-400 is operated from 0 to 400 mm (stroke)

### Acceleration/ Deceleration

**10000 mm/s<sup>2</sup>**  
(334% increase compared with the existing model)

### Max. speed

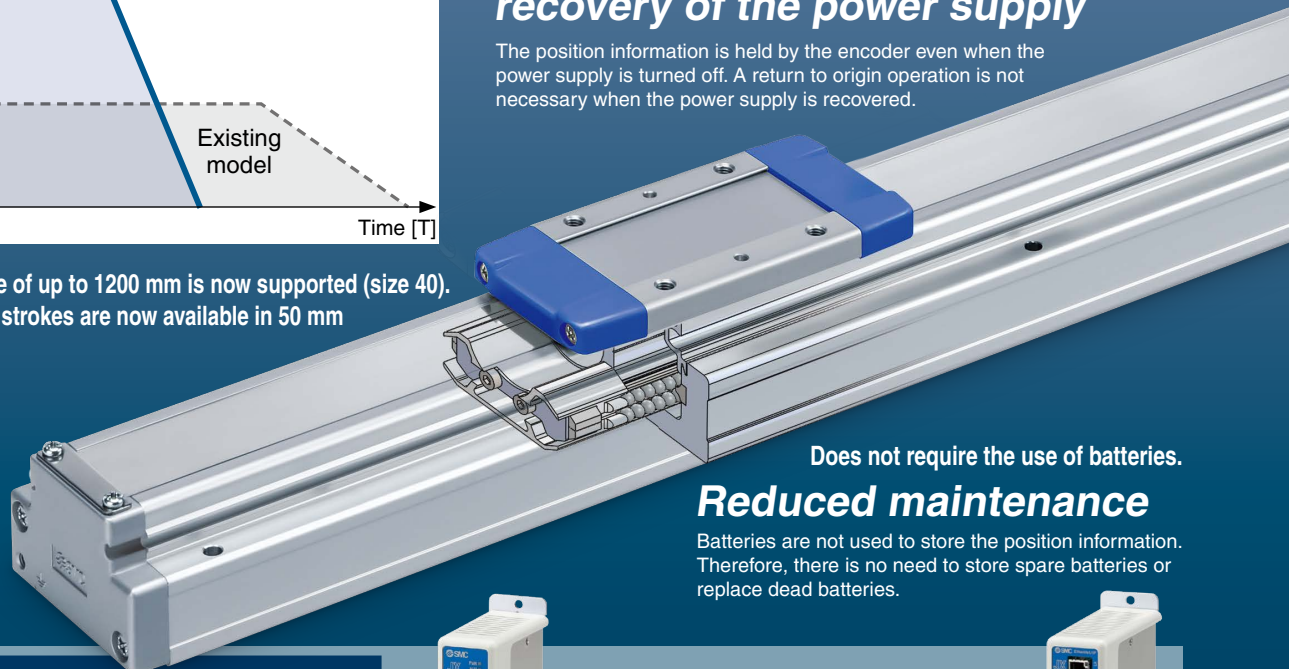
**1500 mm/s**  
(Improved by 25% compared with the existing model)



**New** A max. stroke of up to 1200 mm is now supported (size 40).  
Intermediate strokes are now available in 50 mm increments.

### Easy operation restart after recovery of the power supply

The position information is held by the encoder even when the power supply is turned off. A return to origin operation is not necessary when the power supply is recovered.



Does not require the use of batteries.

### Reduced maintenance

Batteries are not used to store the position information. Therefore, there is no need to store spare batteries or replace dead batteries.

### High Performance Step Motor Controller

Higher acceleration and maximum speed can be set with the special controller (for LEKFS□G Series).

Parallel I/O

JXC5H/6H Series p. 31



EtherCAT/EtherNet/IP™/  
PROFINET

JXCEH/9H/PH Series p. 38



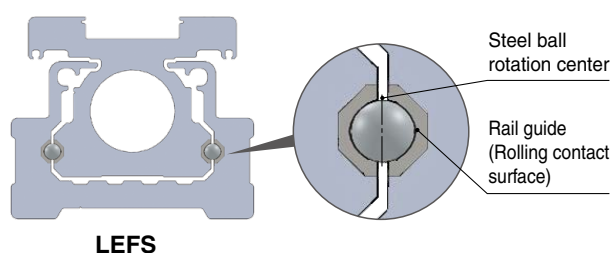
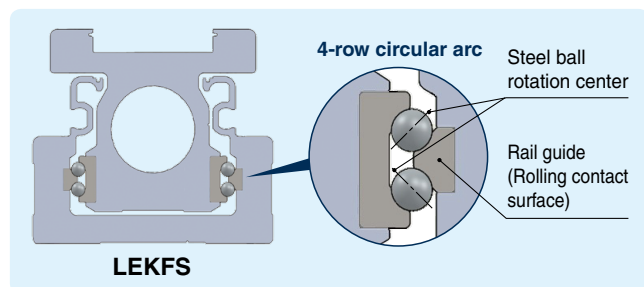
# LEKFS□G Series



CAT.ES100-151A <sup>A</sup>

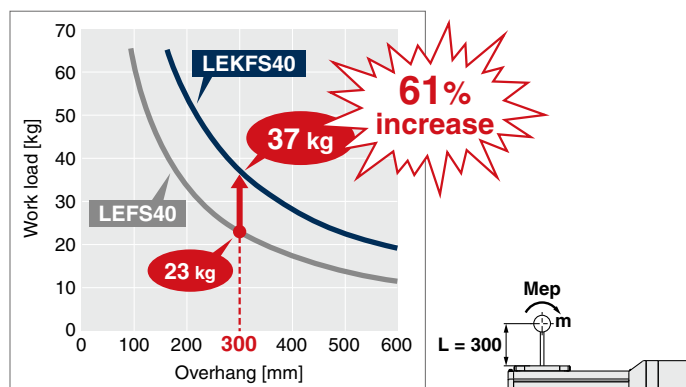
# With a 4-row circular arc on each side for high rigidity and high precision (zero clearance)

## Improved moment resistance

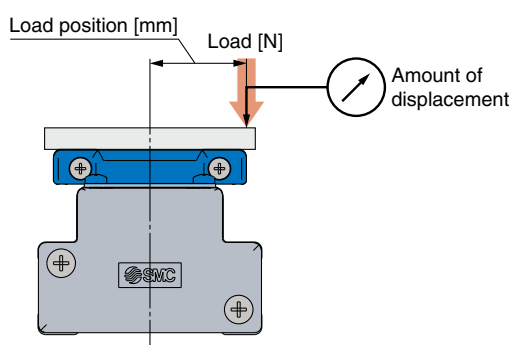


## Improved Dynamic Allowable Moment

Size	Moment direction	Work load [kg] (Overhang: 300 mm)	
		High rigidity guide LEKFS	LEFS
25	Pitching (Mep)	7.5 (10% increase)	6.8
32		18 (35% increase)	13.3
40		37 (61% increase)	23



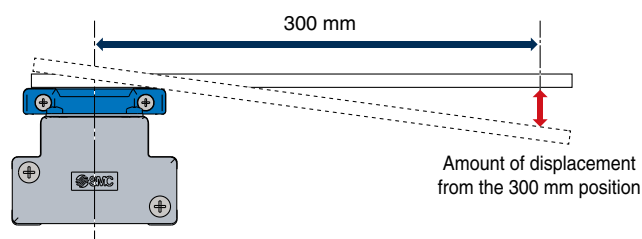
## Table displacement amount reduced to 1/2



## Table Displacement

Size	Table displacement [mm]		Load position [mm]	Load [N]
	High rigidity guide LEKFS	LEFS		
25	0.022 (50% reduction)	0.044	25	200
32	0.036 (50% reduction)	0.072	30	450
40	0.027 (50% reduction)	0.053	37	500

## Zero table clearance



## Table Clearance

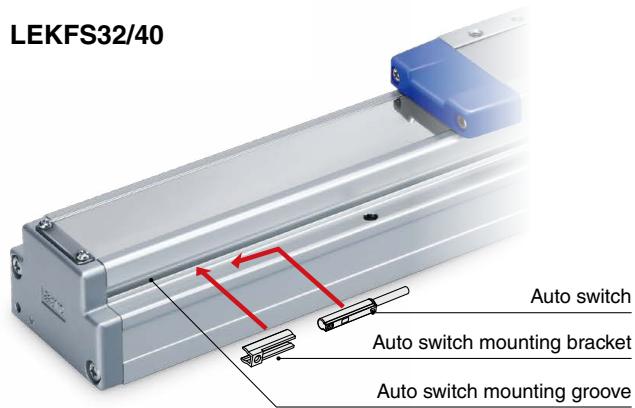
Size	Displacement due to table clearance [mm]	
	High rigidity guide LEKFS	LEFS
25	0	0.079
32	0	0.068
40	0	0.052

\* The image shows the displacement amount with zero load.

## Auto switches are mountable.

Allows for position detection of the table throughout the stroke

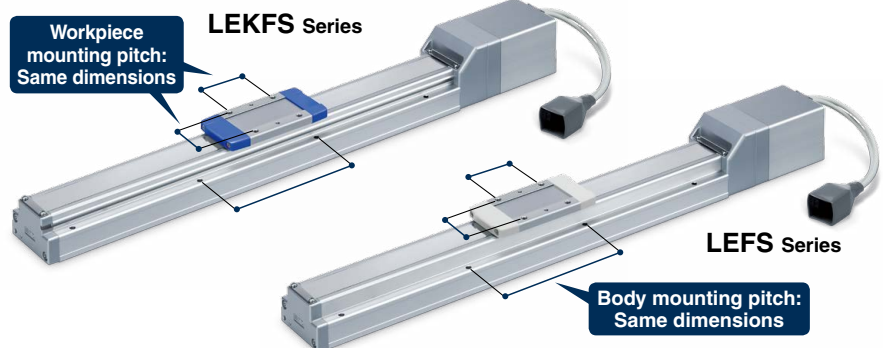
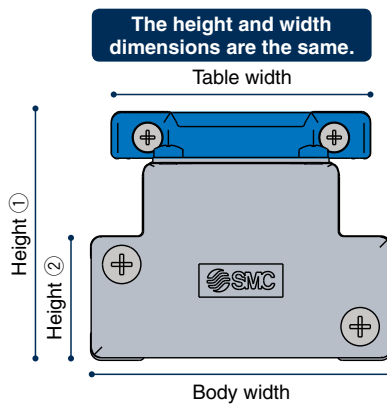
LEKFS32/40



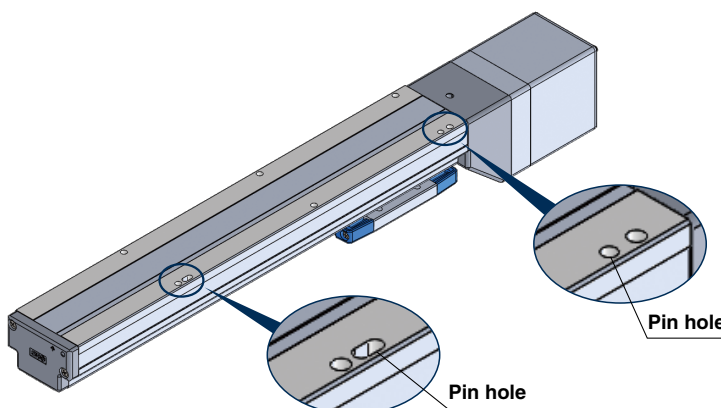
LEKFS25



## Same dimensions as the LEF/Complete mounting compatibility is ensured.

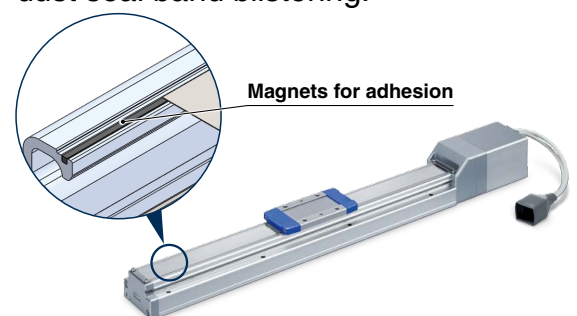


## The body bottom positioning pin holes have been standardized.



## Magnet for adhesion of the dust seal band

Improved adhesion enhances the dustproof performance and reduces dust seal band blistering.





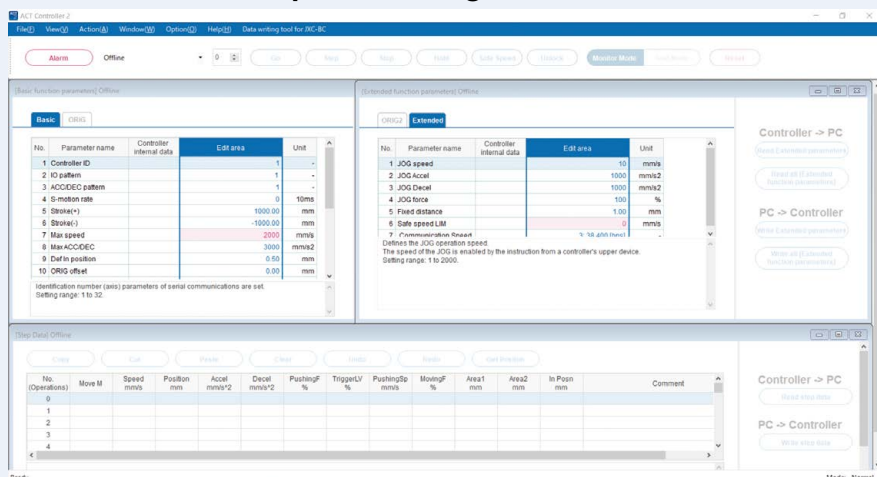
ACT  
2

### Controller Setting Software ACT Controller 2

## Easy-to-use setting software ACT Controller 2 (For PC)

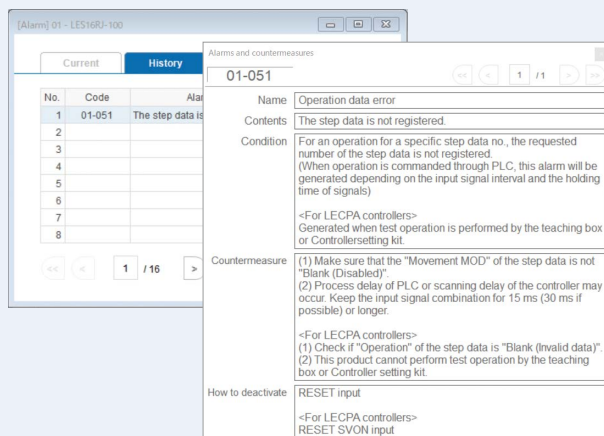
### Various functions available in normal mode (Compared with the existing ACT Controller)

#### ● Parameter and step data setting

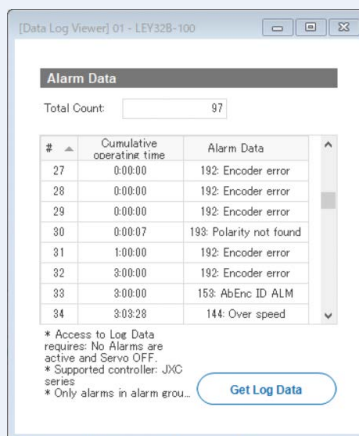


\* Customers operating computers with specifications other than Windows 10/64 bit should use the existing ACT Controller.

#### ● Alarm confirmation

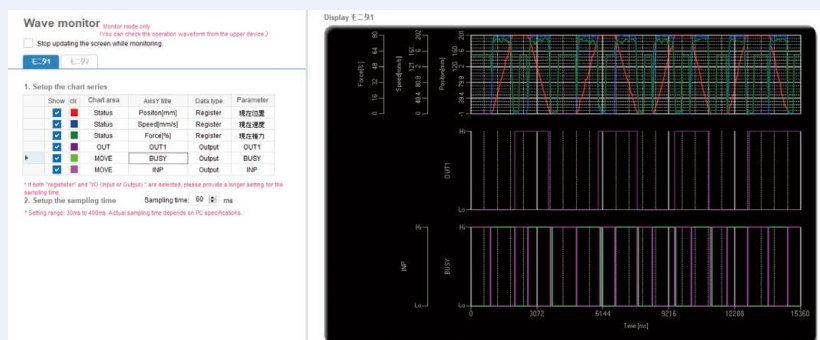


When an alarm is generated, the alarm details and countermeasures can be confirmed.



When an alarm is generated, the cumulative startup time of the controller can be confirmed.

#### ● Waveform monitoring



The position, speed, force, and input/output signals' waveform data during operation can be measured.

\* When using the ACT Controller 2 test operation function, waveform monitoring is not available.



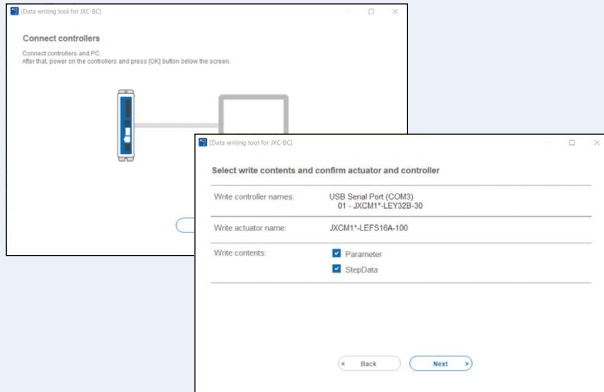
# Step Data Input Type JXC5H/6H Series p. 31



## ACT 2

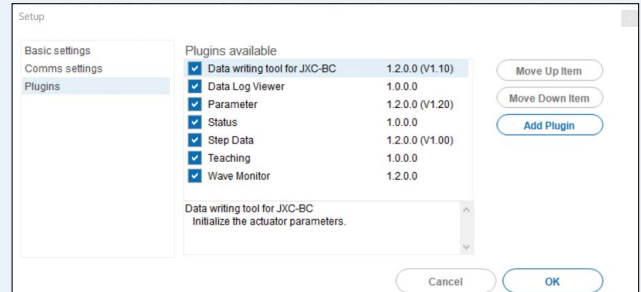
### Controller Setting Software ACT Controller 2

#### • The JXC-BC writing tool



The writing tool can be used to write the connected actuator's parameters and step data to a JXC series blank controller.

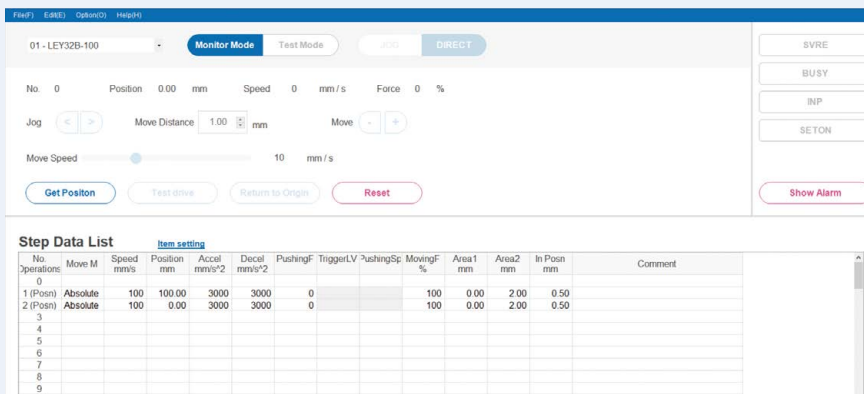
#### • Customizable plug-in functions



Which plug-in functions are displayed as well as the display order are customizable. Customers can add the functions they require.

In normal mode, various other test operation methods (program operation, jogging, moving of the constant rate, etc.), signal status monitoring, one-touch switching between Japanese and English, and other functions are available.

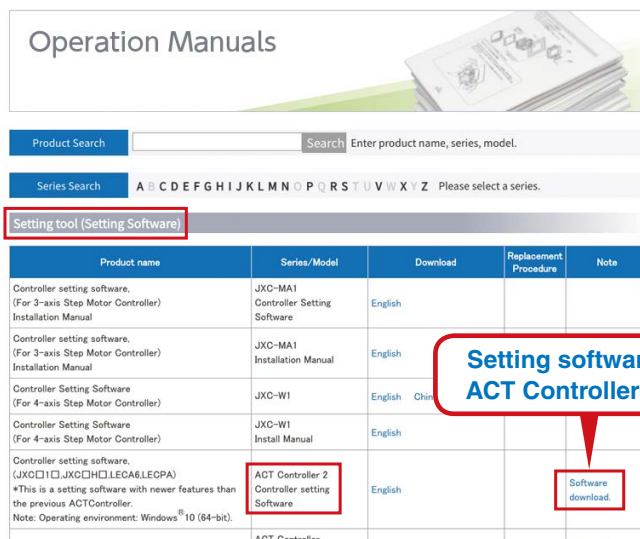
## For immediate use, operate in easy mode.



Step data setting, various test operations, and status confirmation can be done on a single screen.

## How to download the setting software

[Click here for details.](#)



### From the SMC website

Documents/Download



Operation Manuals



Electric Actuators



Setting tool (Setting Software)

**Setting software  
ACT Controller 2**

# Step Data Input Type JXC5H/6H Series p. 31

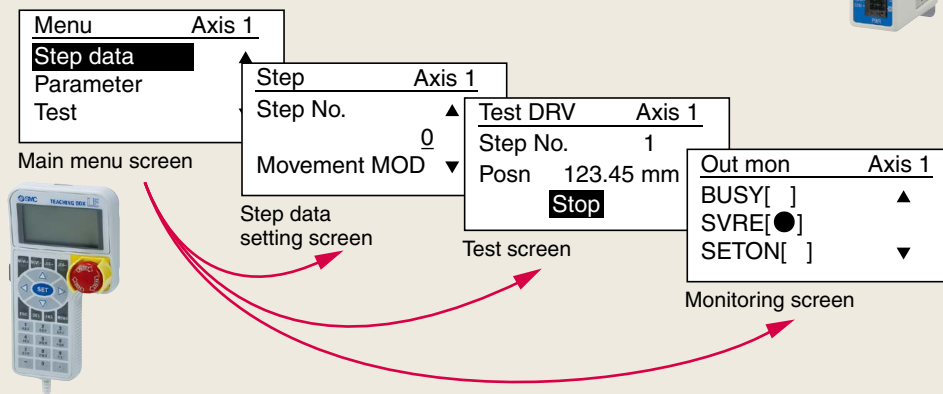
## Teaching Box

### Normal Mode

- Multiple step data can be stored in the teaching box and transferred to the controller.
- Continuous test drive by up to 5 step data

### Teaching box screen

- Each function (step data setting, test drive, monitoring, etc.) can be selected from the main menu.

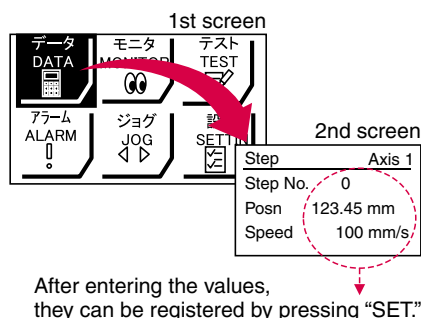


### Easy Mode

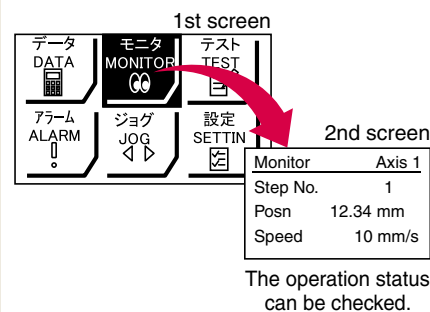
- The simple screen without scrolling promotes ease of setting and operation.
- Choose an icon from the first screen to select a function.
- Set the step data and check the monitor on the second screen.



### Example of setting the step data



### Example of checking the operation status



### Teaching box screen

- Data can be set by inputting only the position and speed. (Other conditions are preset.)

Step	Axis 1
Step No.	0
Posn	50.00 mm
Speed	200 mm/s



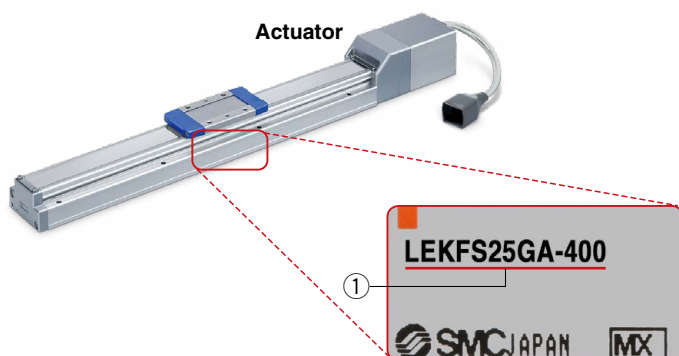
Step	Axis 1
Step No.	1
Posn	80.00 mm
Speed	100 mm/s

## The actuator and controller are provided as a set. (They can be ordered separately as well.)

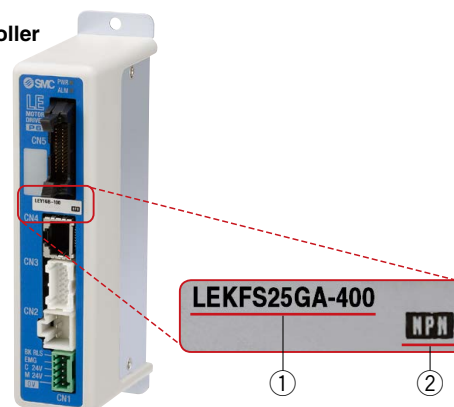
Confirm that the combination of the controller and actuator is correct.

<Check the following before use.>

- Check the actuator label for the model number. This number should match that of the controller.
- Check that the Parallel I/O configuration matches (NPN or PNP).



Controller



## Function

Item	Step data input type JXC5H/6H
Step data and parameter setting	<ul style="list-style-type: none"> <li>Input from controller setting software (PC)</li> <li>Input from teaching box</li> </ul>
Step data “position” setting	<ul style="list-style-type: none"> <li>Numerical value input from controller setting software (PC) or teaching box</li> <li>Input numerical value</li> <li>Direct teaching</li> <li>JOG teaching</li> </ul>
Number of step data	64 points
Operation command (I/O signal)	Step No. [IN <sup>+</sup> ] input ⇒ [DRIVE] input
Completion signal	[INP] output

## Setting Items

TB: Teaching box PC: Controller setting software

Item			Easy Mode		Normal Mode	Step data input type JXC5H/6H
			TB	PC	TB/PC	
Step data setting (Excerpt)	Movement MOD	Selection of “absolute position” and “relative position”	△	●	●	Set at ABS/INC
	Speed	Transfer speed	●	●	●	Set in units of 1 mm/s
	Position	[Position]: Target position [Pushing]: Pushing start position	●	●	●	Set in units of 0.01 mm
	Acceleration/Deceleration	Acceleration/deceleration during movement	●	●	●	Set in units of 1 mm/s <sup>2</sup>
	Pushing force	Rate of force during pushing operation	●	●	●	Set in units of 1%
	Trigger LV	Target force during pushing operation	△	●	●	Set in units of 1%
	Pushing speed	Speed during pushing operation	△	●	●	Set in units of 1 mm/s
	Moving force	Force during positioning operation	△	●	●	Set to 100%
	Area output	Conditions for area output signal to turn ON	△	●	●	Set in units of 0.01 mm
	In position	[Position]: Width to the target position [Pushing]: How much it moves during pushing	△	●	●	Set to 0.5 mm or more (Units: 0.01 mm)
Parameter setting (Excerpt)	Stroke (+)	+ side position limit	×	×	●	Set in units of 0.01 mm
	Stroke (–)	– side position limit	×	×	●	Set in units of 0.01 mm
	ORIG direction	Direction of the return to origin can be set.	×	×	●	Compatible
	ORIG speed	Speed during return to origin	×	×	●	Set in units of 1 mm/s
	ORIG ACC	Acceleration during return to origin	×	×	●	Set in units of 1 mm/s <sup>2</sup>
Test	JOG		●	●	●	Continuous operation at the set speed can be tested while the switch is being pressed.
	MOVE		×	●	●	Operation at the set distance and speed from the current position can be tested.
	Return to ORIG		●	●	●	Compatible
	Test drive	Operation of the specified step data	●	●	● (Continuous operation)	Compatible
	Forced output	ON/OFF of the output terminal can be tested.	×	×	●	Compatible
Monitor	DRV mon	Current position, speed, force, and the specified step data can be monitored.	●	●	●	Compatible
	In/Out mon	Current ON/OFF status of the input and output terminal can be monitored.	×	×	●	Compatible
ALM	Status	Alarm currently being generated can be confirmed.	●	●	●	Compatible
	ALM Log record	Alarms generated in the past can be confirmed.	×	×	●	Compatible
File	Save/Load	Step data and parameters can be saved, forwarded, and deleted.	×	×	●	Compatible
Other	Language	Can be changed to Japanese or English	●	●	●	Compatible

△: Can be set from TB Ver. 2.\*\* (The version information is displayed on the initial screen.)

## Fieldbus Network

# EtherCAT/EtherNet/IP™/PROFINET Direct Input Type Step Motor Controller/JXC□H Series

p. 38

### ACT 2 Controller Setting Software ACT Controller 2

EtherCAT®



JXCEH

EtherNet/IP®



JXC9H

PROFINET®



JXCPH

### Two types of operation command

**Step no. defined operation:** Operate using the preset step data in the controller.

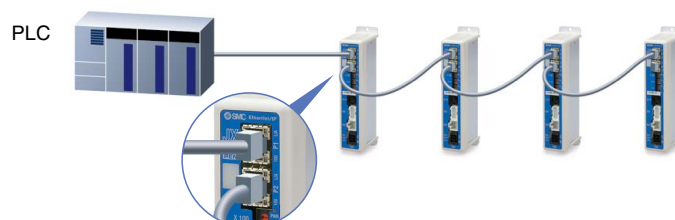
**Numerical data defined operation:** The actuator operates using values such as position and speed from the PLC.

### Numerical monitoring available

Numerical information, such as the current speed, current position, and alarm codes, can be monitored on the PLC.

### Transition wiring of communication cables

Two communication ports are provided.



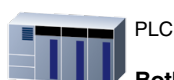
## Application

Communication protocols

EtherCAT®

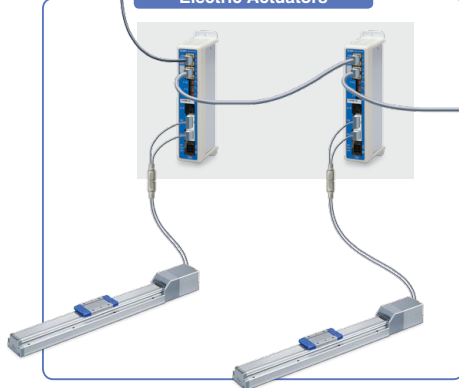
EtherNet/IP®

PROFINET®

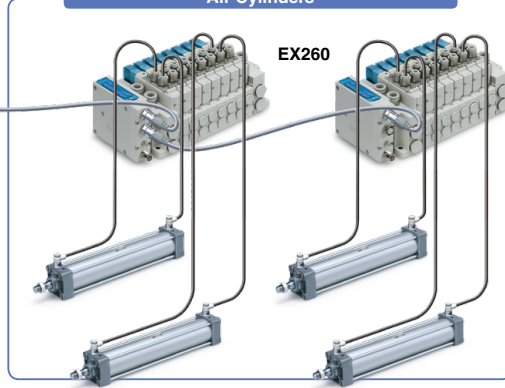


Both air and electric systems can be established under the same protocol.

Electric Actuators



Air Cylinders



### ACT 2

Controller Setting Software ACT Controller 2

From p. 3

## Easy-to-use setting software ACT Controller 2 (For PC)

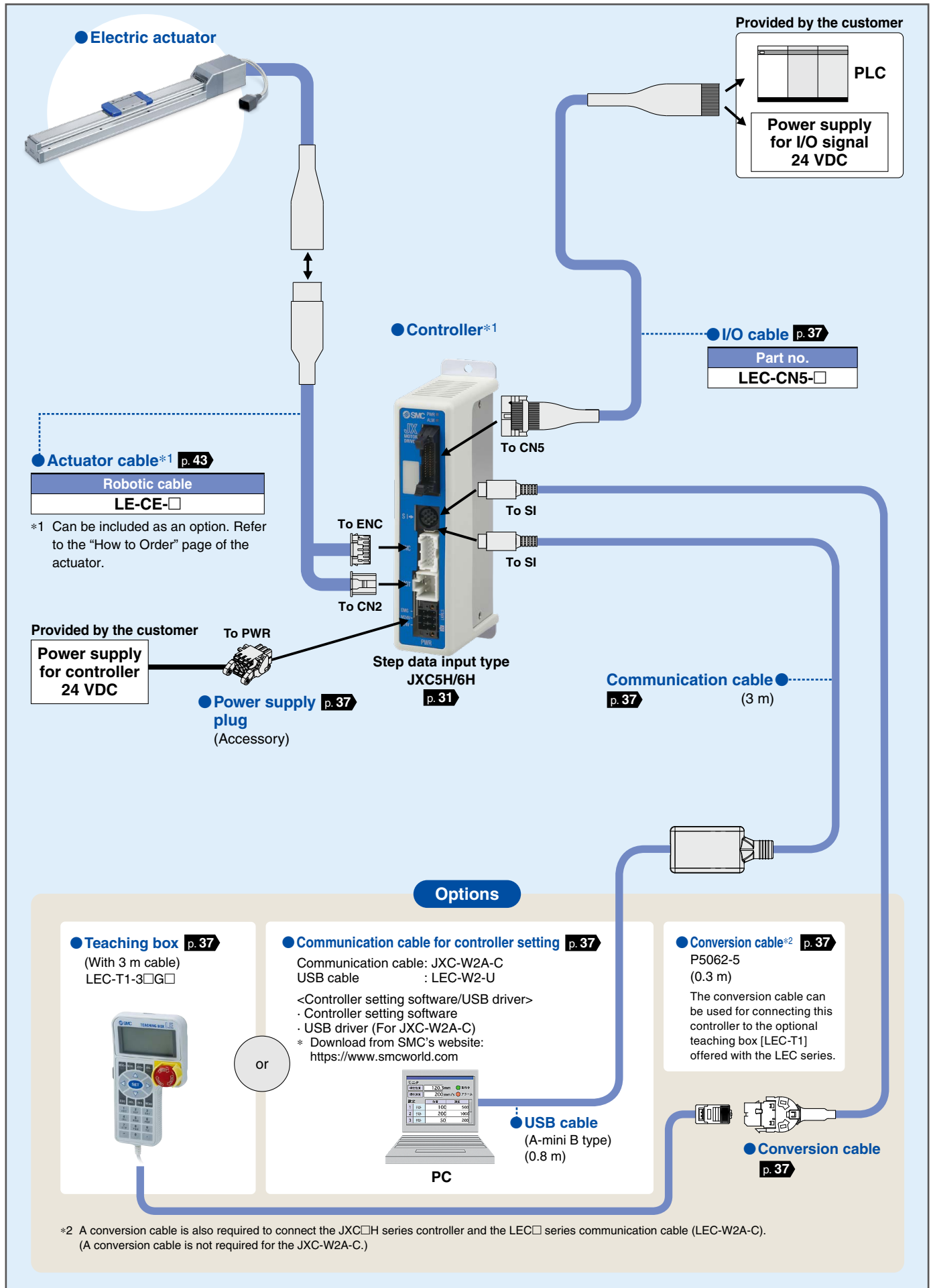
**Various functions available in normal mode** (Compared with the existing ACT Controller)

- Parameter and step data setting
- Alarm confirmation
- Waveform monitoring
- The JXC-BC writing tool
- Customizable plug-in functions

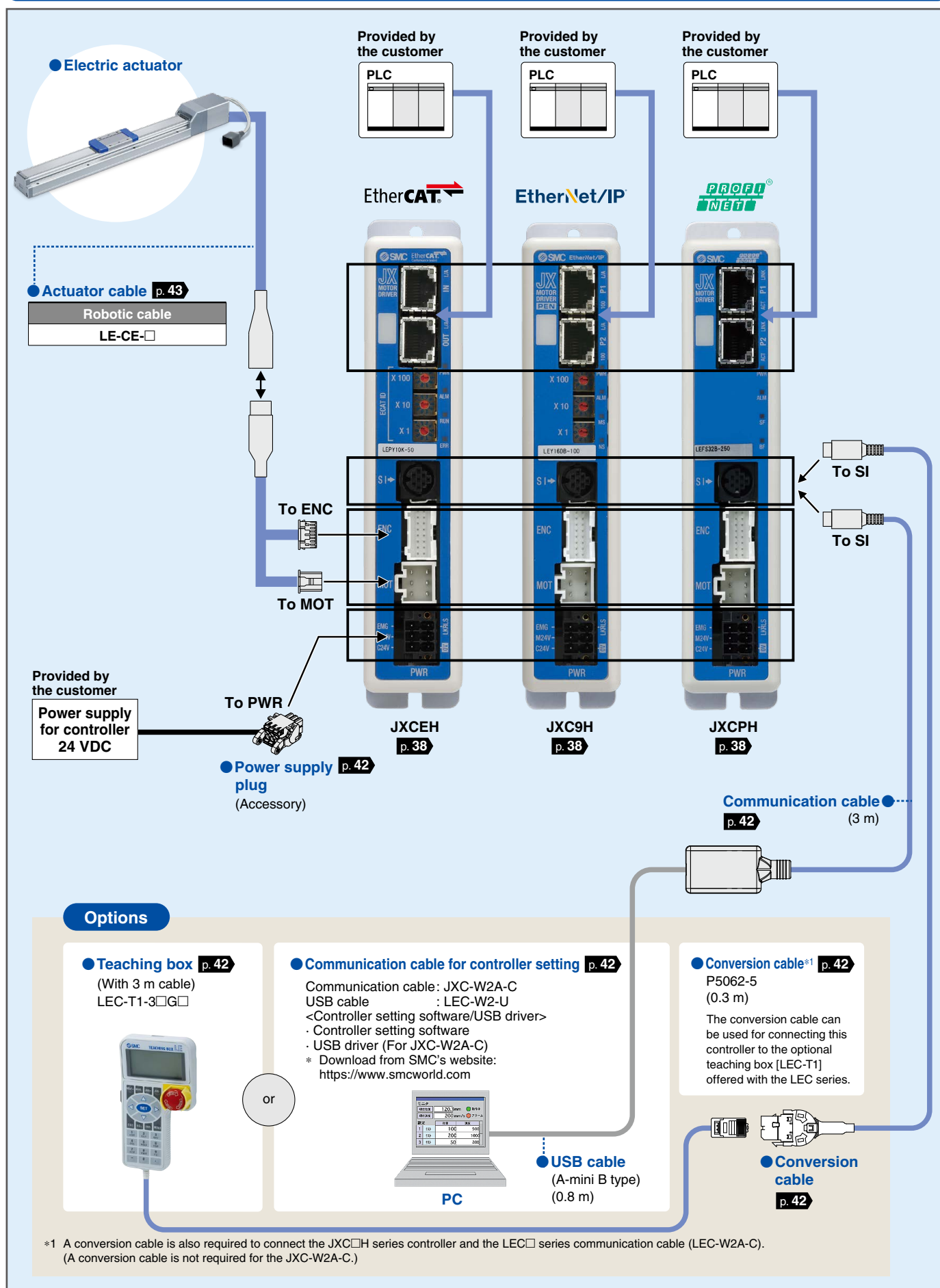
\* Customers operating computers with specifications other than Windows 10/64 bit should use the existing ACT Controller.



## System Construction/General Purpose I/O



## System Construction/Fieldbus Network (EtherCAT/EtherNet/IP™/PROFINET Direct Input Type)

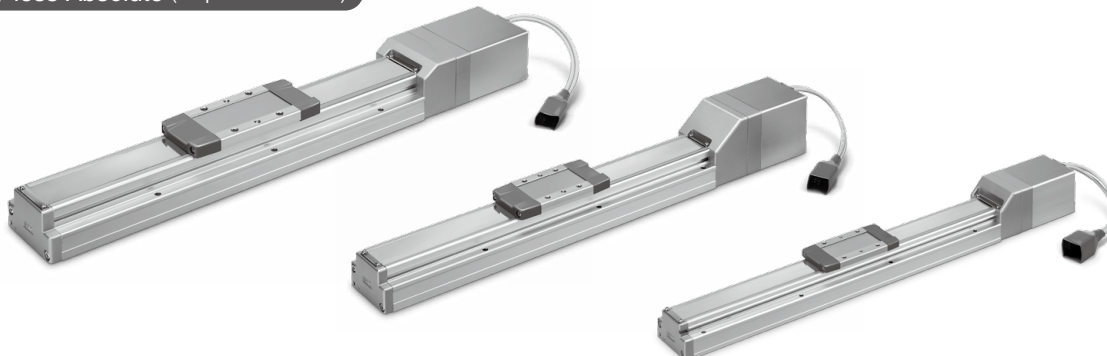


# Electric Actuator

## High Performance High Rigidity and High Precision Slider Type

### High Rigidity and High Precision Slider Type *LEKFS□G Series*

Battery-less Absolute (Step Motor 24 VDC)



Model Selection

LEKFS□G Series

Auto Switch

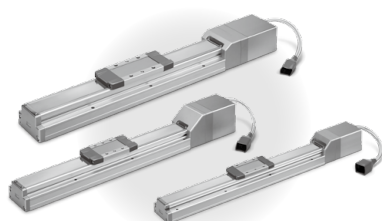
JXC5H/6H Series

JXCEH/9H/PH Series

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### High Performance High Rigidity and High Precision Slider Type *LEKFS□G Series* p. 10

Battery-less Absolute (Step Motor 24 VDC)



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### Controllers *JXC□H Series* p. 30

#### High Performance Controller (Step Data Input Type) *JXC5H/6H Series* Battery-less Absolute (Step Motor 24 VDC)



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Actuator Cable .....	p. 43

#### High Performance Step Motor Controller *JXCEH/9H/PH Series* Battery-less Absolute (Step Motor 24 VDC)

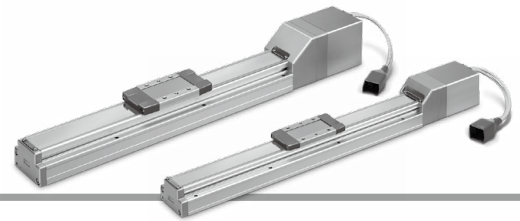


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# Model Selection



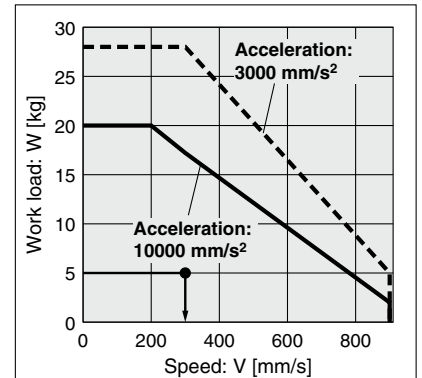
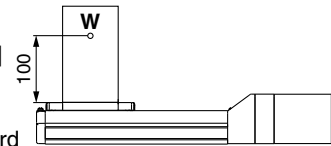
## Selection Procedure



## Selection Example

### Operating conditions

- Workpiece mass: 5 [kg]
- Speed: 300 [mm/s]
- Acceleration/Deceleration: 10000 [mm/s<sup>2</sup>]
- Stroke: 200 [mm]
- Mounting orientation: Horizontal upward



<Speed-Work load graph>  
(LEKFS25GA/Battery-less absolute)

**Step 1** Check the work load-speed. <Speed-Work load graph> (pages 12 to 14)  
Select a model based on the workpiece mass and speed while referencing the speed-work load graph.  
Selection example) The **LEKFS25GA-200** can be temporarily selected as a possible candidate based on the graph shown on the right side.

**Step 2** Check the cycle time.  
Calculate the cycle time using the following calculation method.  
**Cycle time:**  
T can be found from the following equation.

$$T = T1 + T2 + T3 + T4 \text{ [s]}$$

- T1: Acceleration time and T3: Deceleration time can be found by the following equation.

$$T1 = V/a1 \text{ [s]} \quad T3 = V/a2 \text{ [s]}$$

- T2: Constant speed time can be found from the following equation.

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} \text{ [s]}$$

- T4: Settling time varies depending on the conditions such as actuator types, load, and in position of the step data. Reference value for settling time: 0.15 [s] or less  
The following value is used for this calculation.

$$T4 = 0.15 \text{ [s]}$$

Calculation example)  
T1 to T4 can be calculated as follows.

$$T1 = V/a1 = 300/10000 = 0.03 \text{ [s]}$$

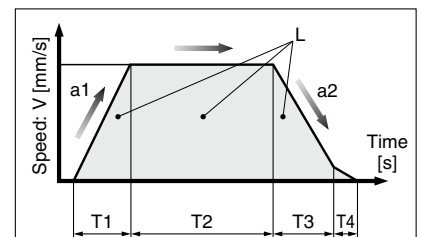
$$T3 = V/a2 = 300/10000 = 0.03 \text{ [s]}$$

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} = \frac{200 - 0.5 \cdot 300 \cdot (0.03 + 0.03)}{300} = 0.64 \text{ [s]}$$

$$T4 = 0.15 \text{ [s]}$$

The cycle time can be found as follows.

$$T = T1 + T2 + T3 + T4 = 0.03 + 0.64 + 0.03 + 0.15 = 0.85 \text{ [s]}$$

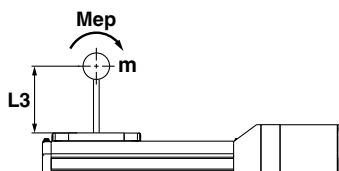


L : Stroke [mm] ... (Operating condition)  
V : Speed [mm/s] ... (Operating condition)  
a1: Acceleration [mm/s<sup>2</sup>] ... (Operating condition)  
a2: Deceleration [mm/s<sup>2</sup>] ... (Operating condition)

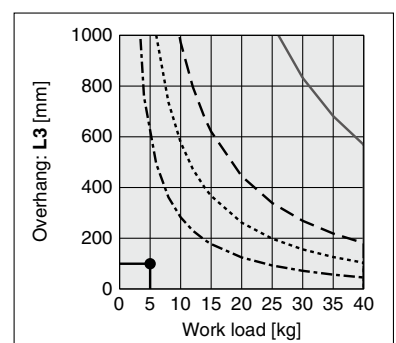
T1: Acceleration time [s]  
Time until reaching the set speed  
T2: Constant speed time [s]  
Time while the actuator is operating at a constant speed  
T3: Deceleration time [s]  
Time from the beginning of the constant speed operation to stop  
T4: Settling time [s]  
Time until positioning is completed

**Step 3** Check the allowable moment. <Static allowable moment> (page 14)  
<Dynamic allowable moment> (pages 15, 16)

Confirm the moment that applies to the actuator is within the allowable range for both static and dynamic conditions.



Based on the above calculation result, the **LEKFS25GA-200** should be selected.



\* If the step motor and servo motors do not meet your specifications, also consider the AC servo specification.

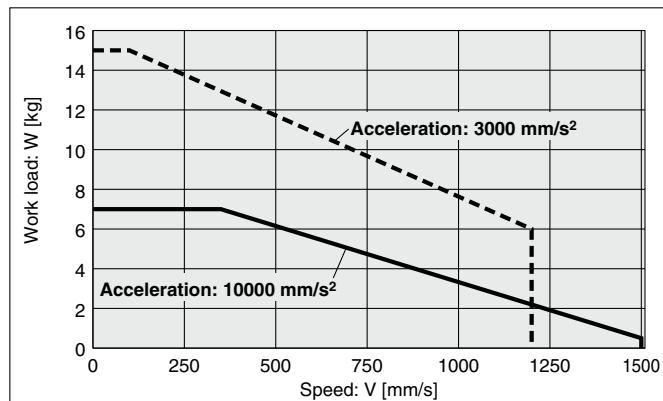


## Speed-Work Load Graph (Guide)

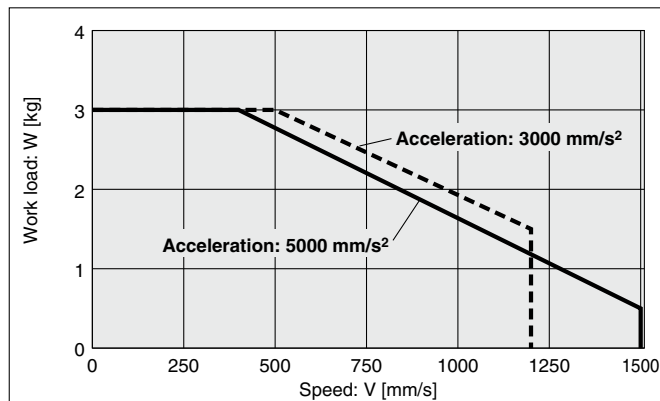
\* The following graphs show the values when the moving force is 100%.

### LEKFS25GH/Ball Screw Drive

#### Horizontal/Lead 20

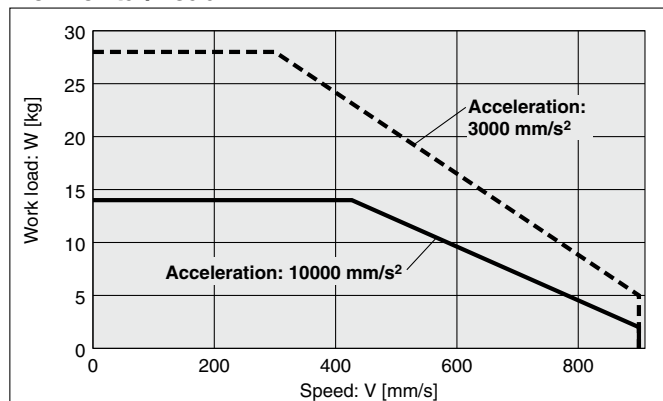


#### Vertical/Lead 20

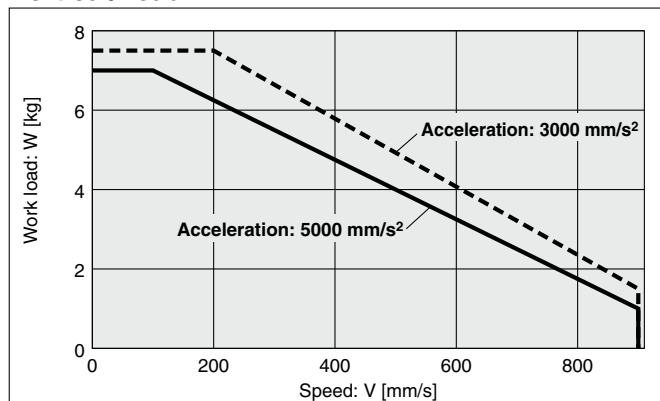


### LEKFS25GA/Ball Screw Drive

#### Horizontal/Lead 12

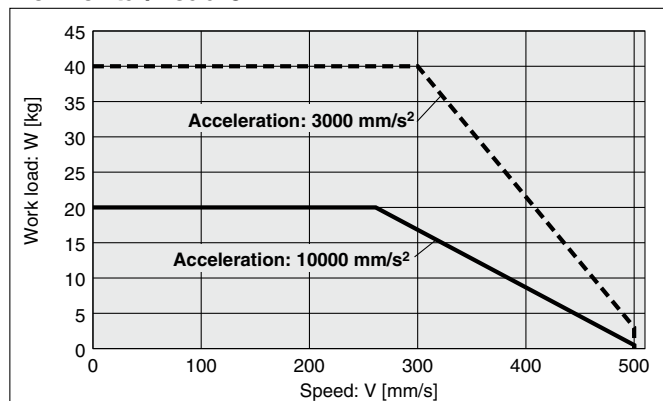


#### Vertical/Lead 12

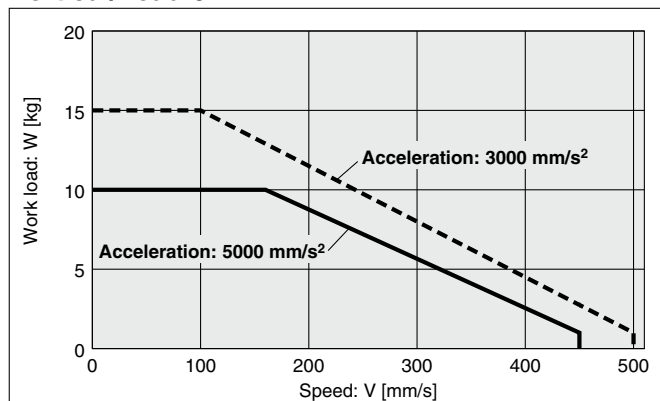


### LEKFS25GB/Ball Screw Drive

#### Horizontal/Lead 6



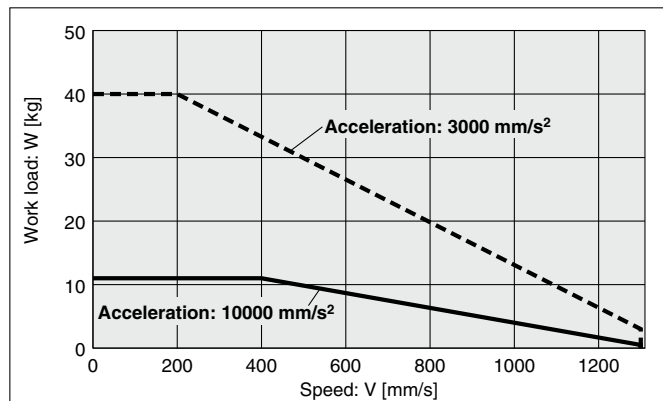
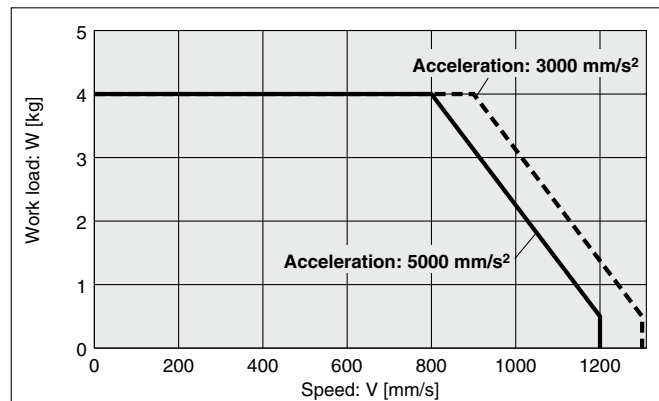
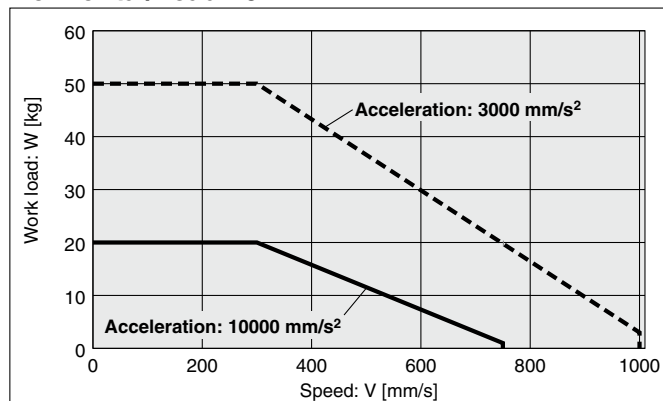
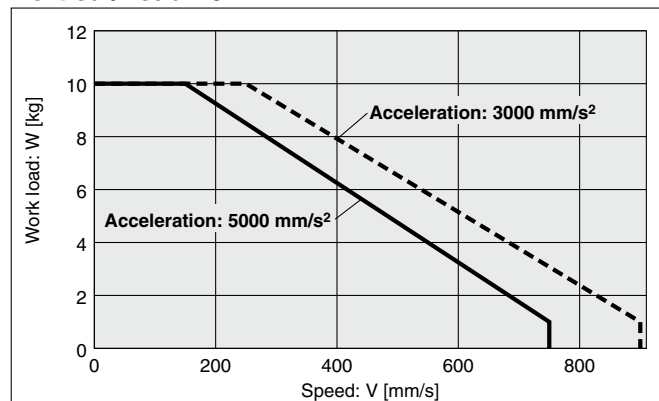
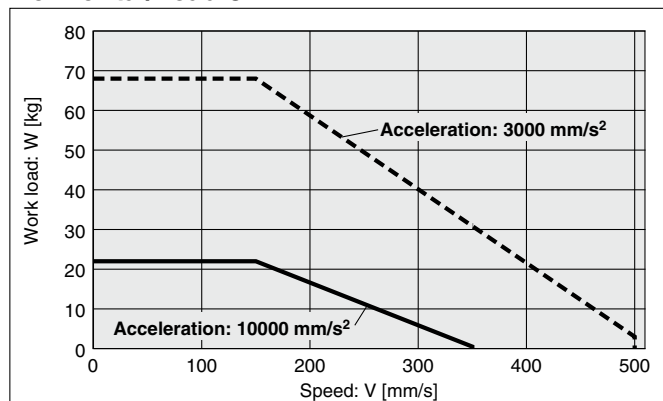
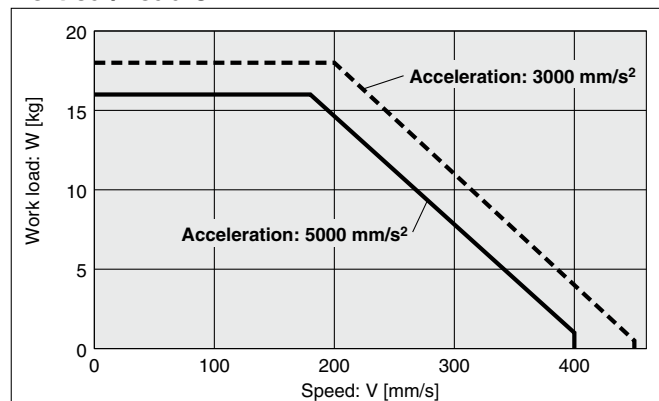
#### Vertical/Lead 6



**Operating temperature:** Use products with a duty ratio of 100% or less when the temperature is below 30°C and with a duty ratio of 35% or less when the temperature exceeds 30°C.

**Speed-Work Load Graph (Guide)**

\* The following graphs show the values when the moving force is 100%.

**LEKFS32GH/Ball Screw Drive****Horizontal/Lead 24****Vertical/Lead 24****LEKFS32GA/Ball Screw Drive****Horizontal/Lead 16****Vertical/Lead 16****LEKFS32GB/Ball Screw Drive****Horizontal/Lead 8****Vertical/Lead 8**

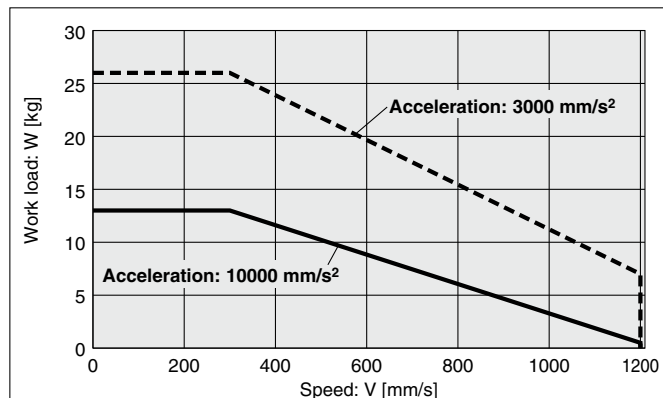
**Operating temperature:** Use products with a duty ratio of 100% or less when the temperature is below 30°C and with a duty ratio of 35% or less when the temperature exceeds 30°C.

## Speed-Work Load Graph (Guide)

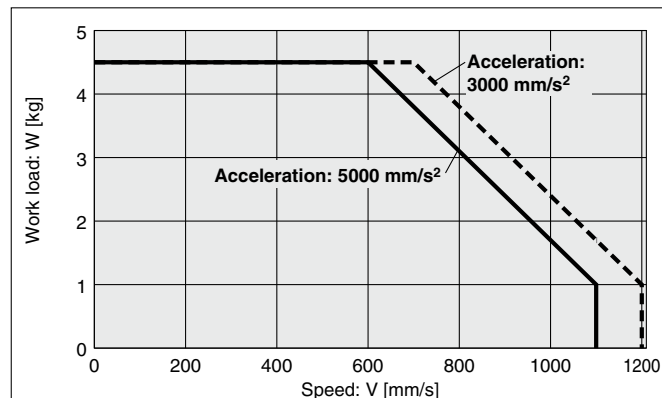
\* The following graphs show the values when the moving force is 100%.

### LEKFS40GH/Ball Screw Drive

#### Horizontal/Lead 30

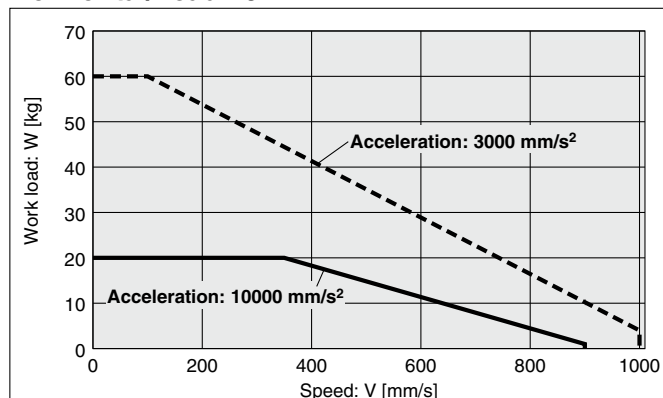


#### Vertical/Lead 30

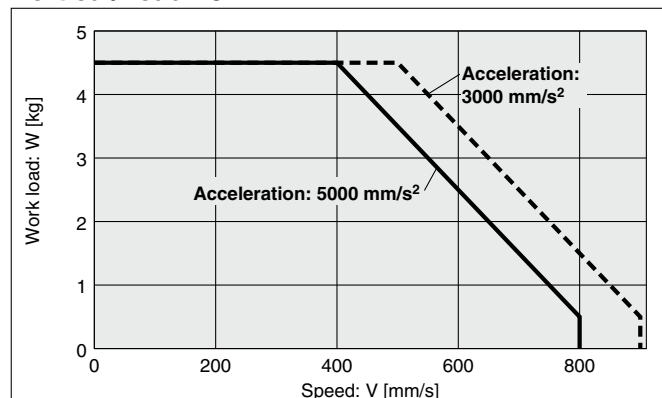


### LEKFS40GA/Ball Screw Drive

#### Horizontal/Lead 20

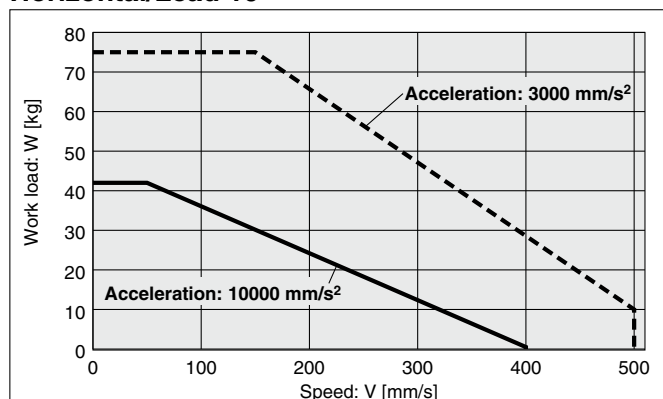


#### Vertical/Lead 20

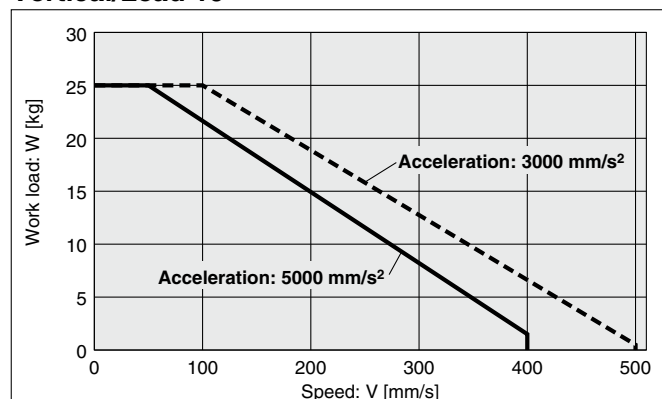


### LEKFS40GB/Ball Screw Drive

#### Horizontal/Lead 10



#### Vertical/Lead 10



Operating temperature: Use products with a duty ratio of 100% or less when the temperature is below 30°C and with a duty ratio of 35% or less when the temperature exceeds 30°C.

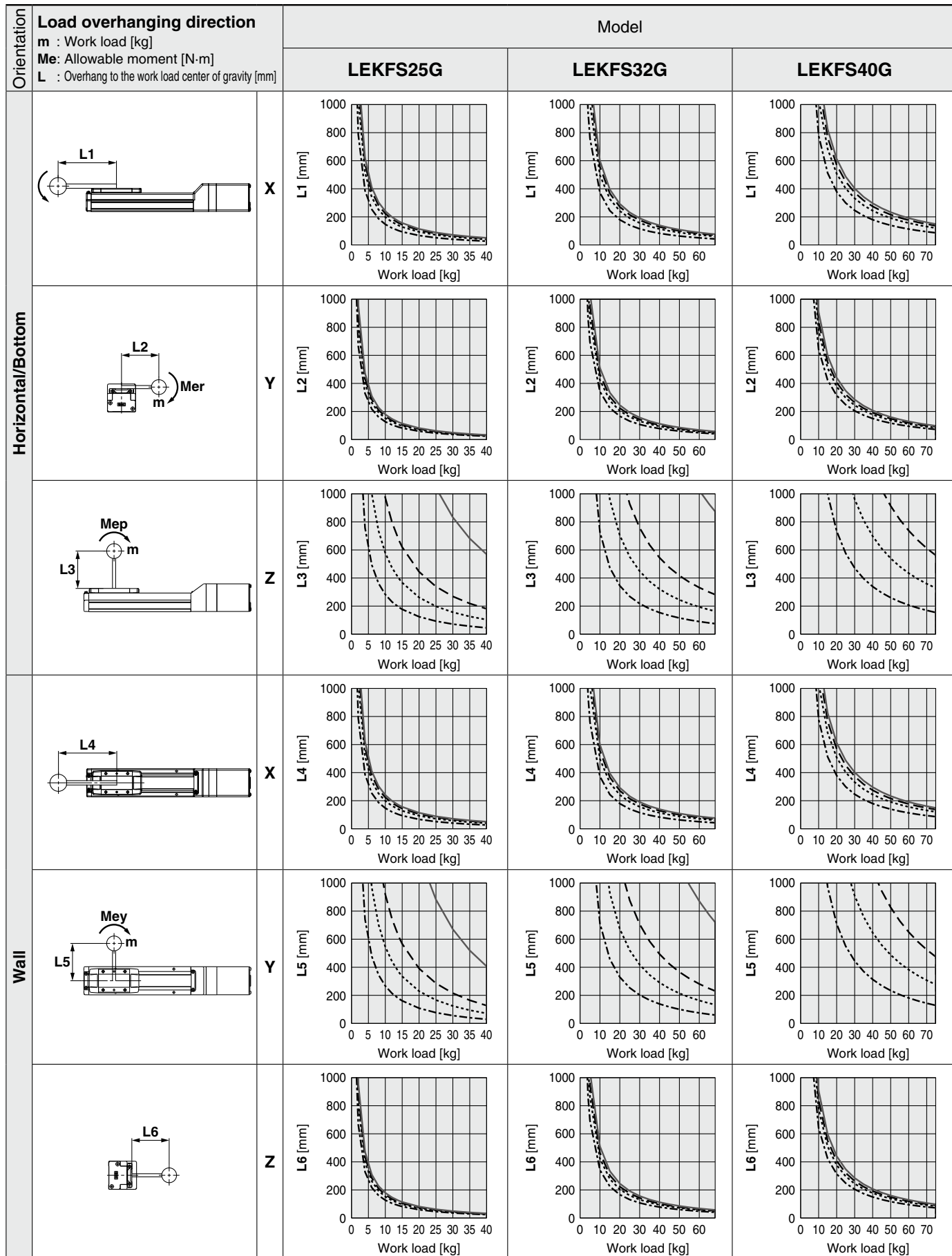
## Static Allowable Moment\*1

Model	LEKFS25	LEKFS32	LEKFS40
Pitching [N·m]	61	141	264
Yawing [N·m]	70	141	264
Rolling [N·m]	115	290	473

\*1 The static allowable moment is the amount of static moment which can be applied to the actuator when it is stopped.  
If the product is exposed to impact or repeated load, be sure to take adequate safety measures when using the product.

**Dynamic Allowable Moment**

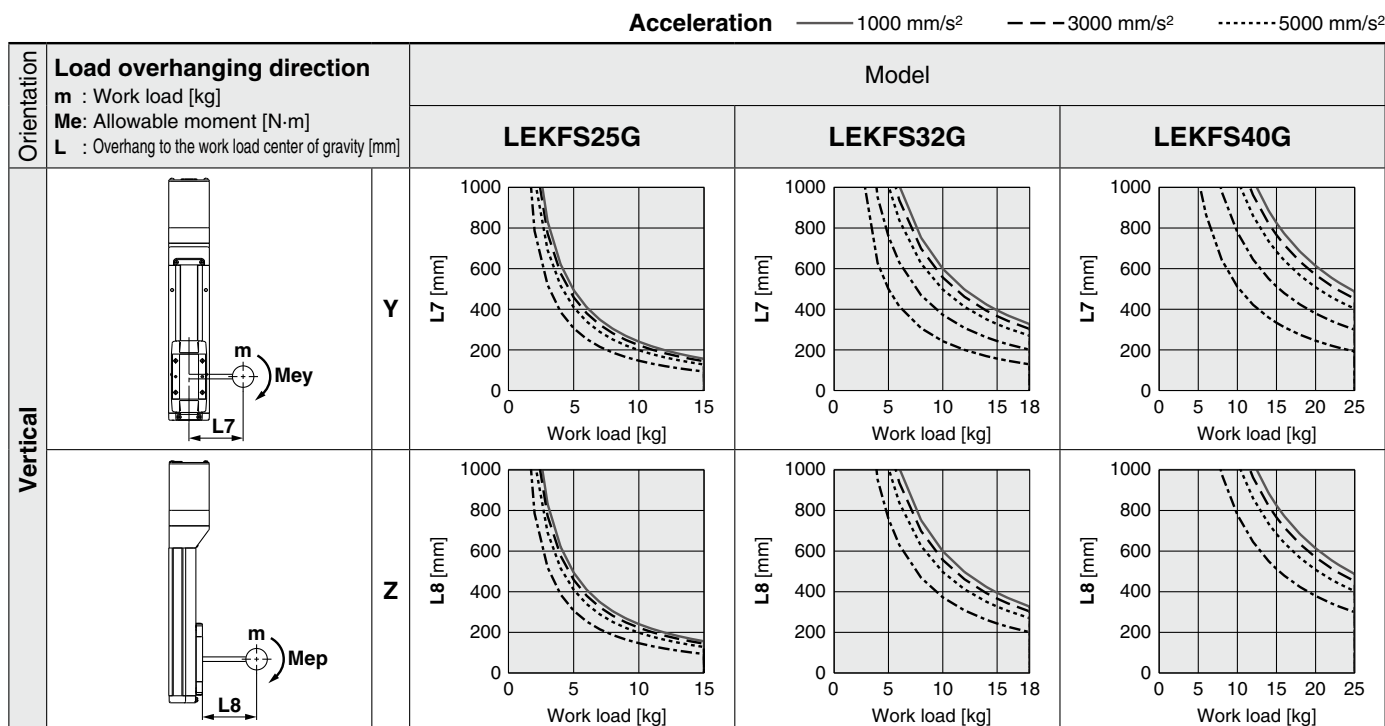
\* These graphs show the amount of allowable overhang (guide unit) when the center of gravity of the workpiece overhangs in one direction.

**Acceleration**—— 1000 mm/s<sup>2</sup>--- 3000 mm/s<sup>2</sup>.....5000 mm/s<sup>2</sup>- - - - 10000 mm/s<sup>2</sup>



## Dynamic Allowable Moment

\* These graphs show the amount of allowable overhang (guide unit) when the center of gravity of the workpiece overhangs in one direction.

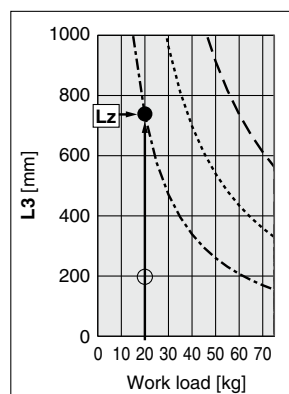
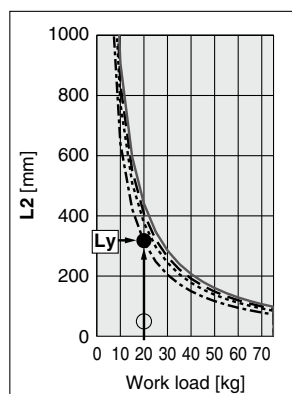
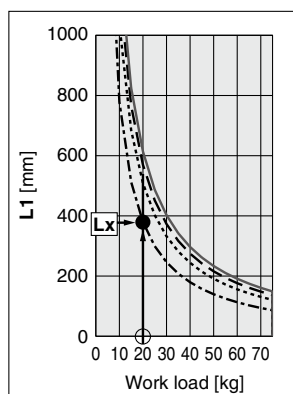


## Calculation of Guide Load Factor

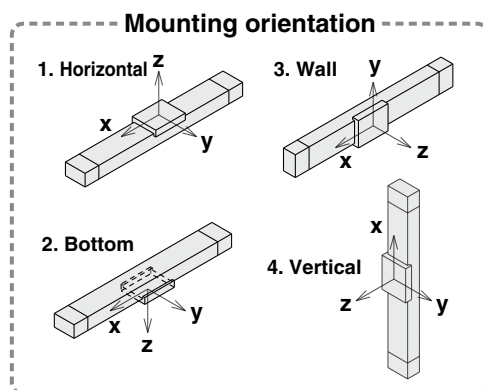
- Decide operating conditions.  
 Model: LEKFS□G  
 Size: 25/32/40  
 Mounting orientation: Horizontal/Bottom/Wall/Vertical  
 Acceleration [mm/s<sup>2</sup>]: a  
 Work load [kg]: m  
 Work load center position [mm]: Xc/Yc/Zc
- Select the target graph while referencing the model, size, and mounting orientation.
- Based on the acceleration and work load, find the overhang [mm]: Lx/Ly/Lz from the graph.
- Calculate the load factor for each direction.  
 $\alpha x = Xc/Lx$ ,  $\alpha y = Yc/Ly$ ,  $\alpha z = Zc/Lz$
- Confirm the total of  $\alpha x$ ,  $\alpha y$ , and  $\alpha z$  is 1 or less.  
 $\alpha x + \alpha y + \alpha z \leq 1$   
 When 1 is exceeded, please consider a reduction of acceleration and work load, or a change of the work load center position and series.

### Example

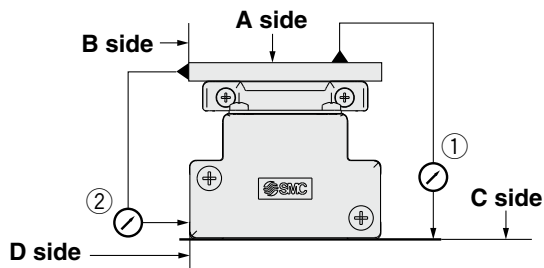
- Operating conditions  
 Model: LEKFS40G  
 Size: 40  
 Mounting orientation: Horizontal  
 Acceleration [mm/s<sup>2</sup>]: 10000  
 Work load [kg]: 20  
 Work load center position [mm]: Xc = 0, Yc = 50, Zc = 200
- Select the graphs for horizontal of the LEKFS40G on page 15.



- Lx = 380 mm, Ly = 320 mm, Lz = 740 mm
- The load factor for each direction can be found as follows.  
 $\alpha x = 0/380 = 0$   
 $\alpha y = 50/320 = 0.156$   
 $\alpha z = 200/740 = 0.270$
- $\alpha x + \alpha y + \alpha z = 0.426 \leq 1$



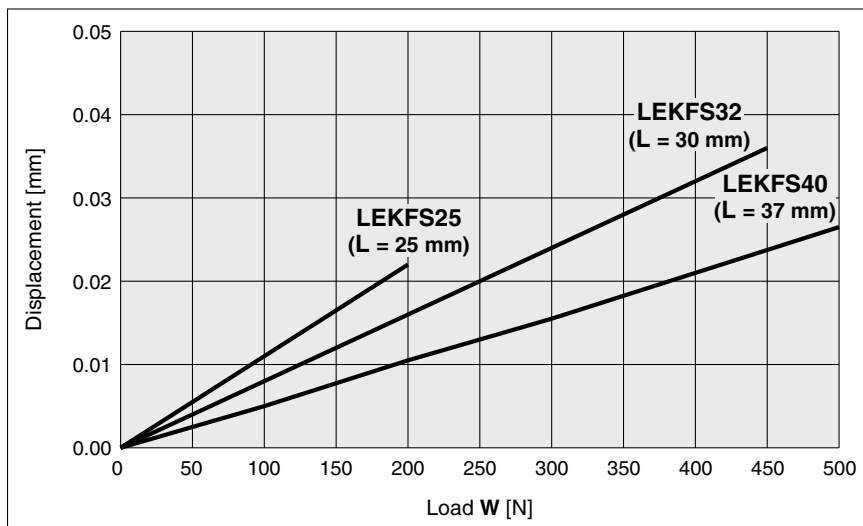
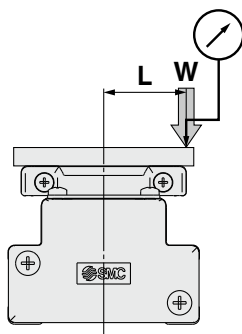
## Table Accuracy (Reference Value)



Model	Traveling parallelism [mm] (Every 300 mm)	
	① C side traveling parallelism to A side	② D side traveling parallelism to B side
<b>LEKFS25</b>	0.04	0.02
<b>LEKFS32</b>	0.04	0.02
<b>LEKFS40</b>	0.04	0.02

\* Traveling parallelism does not include the mounting surface accuracy.

## Table Displacement (Reference Value)



\* This displacement is measured when a 15 mm aluminum plate is mounted and fixed on the table.

Battery-less Absolute (Step Motor 24 VDC)

## High Performance

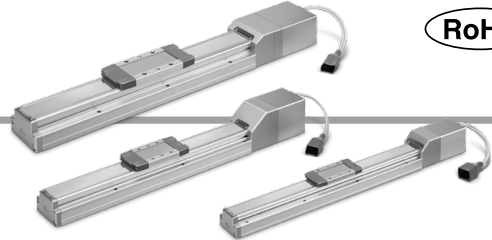
# High Rigidity and High Precision Slider Type LEKFS□G Series LEKFS25, 32, 40

CE UK  
CA

\* For details, refer to page 45.

RoHS

### How to Order



LEKFS **32** **G** **A** - **300** **R1** **C5H73**

1 2 3 4 5 6 7 8 9

#### 1 Size

25
32
40

#### 2 Motor mounting position

Nil	In-line
R	Right side parallel
L	Left side parallel

#### 3 Motor type

G	High performance Battery-less absolute (Step motor 24 VDC)
---	--

#### 4 Lead [mm]

Symbol	LEKFS25	LEKFS32	LEKFS40
H	20	24	30
A	12	16	20
B	6	8	10

#### 5 Stroke\*1

50	50
to	to
1200	1200

\* For details, refer to the applicable stroke table below.

#### 6 Motor option

Nil	Without option
B	With lock

#### 7 Grease application (Seal band part)

Nil	With
N	Without (Roller specification)

### Applicable Stroke Table

Size	Stroke																
	50	100	150	200	250	300	350	400	450	500	600	700	800	900	1000	1100	1200
25	●	●	●	●	●	●	●	●	●	●	●	●	●	—	—	—	—
32	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	—	—
40	—	—	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●

#### 8 Actuator cable type/length

Robotic cable [m]

Nil	None	R8	8*2
R1	1.5	RA	10*2
R3	3	RB	15*2
R5	5	RC	20*2

Model Selection

LEKFS□G Series

Auto Switch

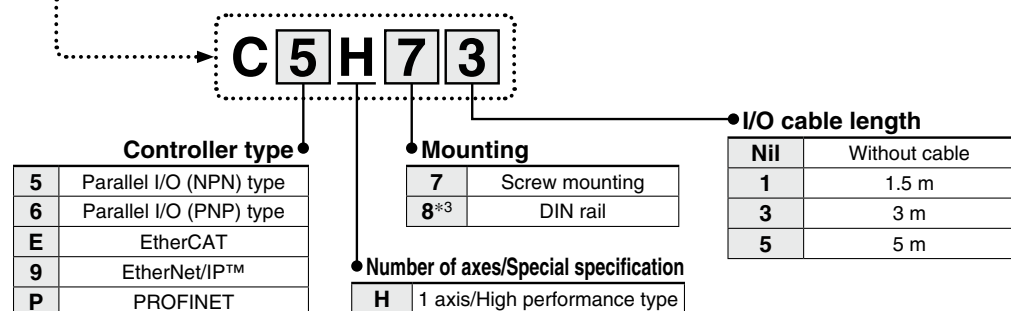
JXC5H/6H Series

JXCEH/9H/PH Series

For auto switches, refer to pages 27 to 29.

**9 Controller**

Nil	Without controller
C□H□□	With controller



\*1 Please contact SMC for non-standard strokes as they are produced as special orders.

\*2 Produced upon receipt of order

\*3 The DIN rail is not included. It must be ordered separately.

**⚠ Caution****[CE/UKCA-compliant products]**

EMC compliance was tested by combining the electric actuator LEF series and the controller JXC series.

The EMC depends on the configuration of the customer's control panel and the relationship with other electrical equipment and wiring. Therefore, compliance with the EMC directive cannot be certified for SMC components incorporated into the customer's equipment under actual operating conditions. As a result, it is necessary for the customer to verify compliance with the EMC directive for the machinery and equipment as a whole.

**■ Trademark**

EtherNet/IP® is a registered trademark of ODVA, Inc.

EtherCAT® is registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.

**The actuator and controller are sold as a package.**

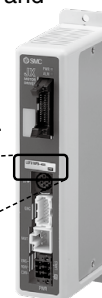
Confirm that the combination of the controller and actuator is correct.

**<Check the following before use.>**

- \*1 Check the actuator label for the model number.  
This number should match that of the controller.

**LEKFS25GA-400**

\*1



\* Refer to the Operation Manual for using the products.  
Please download it via our website: <https://www.smcworld.com>

Type	Step data input type	EtherCAT direct input type	EtherNet/IP™ direct input type	PROFINET direct input type
Series	JXC5H JXC6H	JXCEH	JXC9H	JXCPH
Features	Parallel I/O	EtherCAT direct input	EtherNet/IP™ direct input	PROFINET direct input
Compatible motor	Step motor 24 VDC			
Max. number of step data	64 points			
Power supply voltage	24 VDC			
Reference page	31	38		



## Specifications

Model			LEKFS25			LEKFS32			LEKFS40			
Actuator specifications	Stroke [mm]		50 to 800			50 to 1000			150 to 1200			
	Work load [kg]*2		Horizontal	15	28	40	40	50	68	26	60	75
			Vertical	3	7.5	15	4	10	18	4.5	4.5	25
	Speed [mm/s]	Stroke range	Up to 400	20 to 1500	12 to 900	6 to 500	24 to 1300	16 to 1000	8 to 500	30 to 1200	20 to 1000	10 to 500
			401 to 500	20 to 1100	12 to 750	6 to 400	24 to 1300	16 to 950	8 to 500	30 to 1200	20 to 1000	10 to 500
			501 to 600	20 to 900	20 to 540	20 to 270	24 to 1200	16 to 800	8 to 400	30 to 1200	20 to 1000	10 to 500
			601 to 700	20 to 630	20 to 420	20 to 230	24 to 930	16 to 620	8 to 310	30 to 1200	20 to 900	10 to 440
			701 to 800	20 to 550	20 to 330	20 to 180	24 to 750	16 to 500	8 to 250	30 to 1140	20 to 760	10 to 350
			801 to 900	—	—	—	24 to 610	16 to 410	8 to 200	30 to 930	20 to 620	10 to 280
			901 to 1000	—	—	—	24 to 500	16 to 340	8 to 170	30 to 780	20 to 520	10 to 250
			1001 to 1100	—	—	—	—	—	—	30 to 660	20 to 440	10 to 220
	1101 to 1200	—	—	—	—	—	—	30 to 570	20 to 380	10 to 190		
	Max. acceleration/deceleration [mm/s²]		10000									
			5000									
Positioning repeatability [mm]			±0.01 (Lead H: ±0.02)									
Lost motion [mm]*3			0.05									
Lead [mm]			20	12	6	24	16	8	30	20	10	
Impact/Vibration resistance [m/s²]*4			50/20									
Actuation type			Ball screw (LEKFS□), Ball screw + Belt (LEKFS□ <sup>B</sup> )									
Guide type			Linear guide									
Operating temperature range [°C]			5 to 40									
Operating humidity range [%RH]			90 or less (No condensation)									
Electric specifications	Motor size		□42			□56.4						
	Motor type		Battery-less absolute (Step motor 24 VDC)									
	Encoder		Battery-less absolute									
	Power supply voltage [V]		24 VDC ±10%									
Lock unit specifications	Power [W]*5 *7		Max. power 126			Max. power 222			Max. power 222			
	Type*6		Non-magnetizing lock									
	Holding force [N]		47	78	157	72	108	216	75	113	245	
	Power [W]*7		5			5			5			
Rated voltage [V]			24 VDC ±10%									

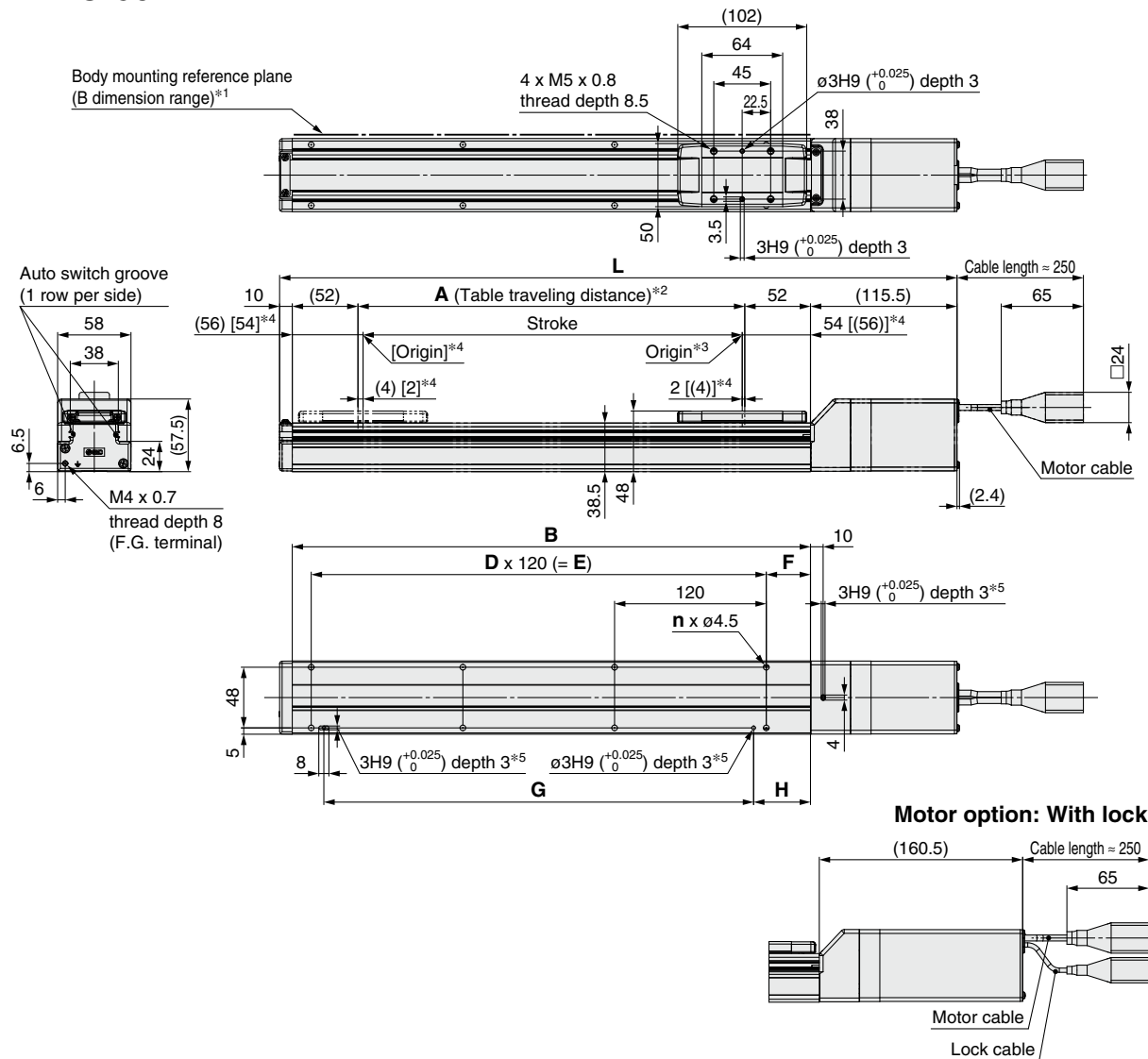
- \*1 Please contact SMC for non-standard strokes as they are produced as special orders.
- \*2 The max. work load at 3000 mm/s<sup>2</sup> acceleration and deceleration speed  
Work load varies depending on the speed and acceleration. Check the "Speed-Work Load Graph" on pages 12 to 14.  
Furthermore, if the cable length exceeds 5 m, the speed and work load specified in the "Speed-Work Load Graph" may decrease by up to 10% for each 5 m increase.
- \*3 A reference value for correcting errors in reciprocal operation
- \*4 Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (The test was performed with the actuator in the initial state.)  
Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. The test was performed in both an axial direction and a perpendicular direction to the lead screw. (The test was performed with the actuator in the initial state.)
- \*5 Indicates the max. power during operation (including the controller)  
This value can be used for the selection of the power supply.
- \*6 With lock only
- \*7 For an actuator with lock, add the power for the lock.

## Weight

Series	LEKFS25												
Stroke [mm]	50	100	150	200	250	300	350	400	450	500	600	700	800
Product weight [kg]	1.7	1.8	2.0	2.1	2.3	2.4	2.5	2.6	2.8	2.9	3.2	3.5	3.8
Additional weight with lock [kg]	0.26												

Series	LEKFS32														
Stroke [mm]	50	100	150	200	250	300	350	400	450	500	600	700	800	900	1000
Product weight [kg]	3.2	3.4	3.6	3.8	4.1	4.3	4.5	4.7	4.9	5.1	5.5	5.9	6.3	6.7	7.1
Additional weight with lock [kg]	0.53														

Series	LEKFS40														
Stroke [mm]	150	200	250	300	350	400	450	500	600	700	800	900	1000	1100	1200
Product weight [kg]	5.5	5.8	6.1	6.4	6.7	7.0	7.3	7.6	8.2	8.8	9.4	10.0	10.6	11.2	11.8
Additional weight with lock [kg]	0.53														

**Dimensions: In-line Motor****LEKFS25G**

\*1 When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height: 5 mm)

In addition, be aware that surfaces other than the body mounting reference plane (B dimension range) may slightly protrude from the body mounting reference plane. Be sure to provide a clearance of 1 mm or more to avoid interference with workpieces, facilities, etc.

\*2 This is the distance within which the table can move when it returns to origin. Make sure that workpieces mounted on the table do not interfere with other workpieces or the facilities around the table.

\*3 Position after returning to origin

\*4 [ ] for when the direction of return to origin has changed

\*5 When using the positioning pin holes on the bottom, use either the one on the body side or the one on the housing side.

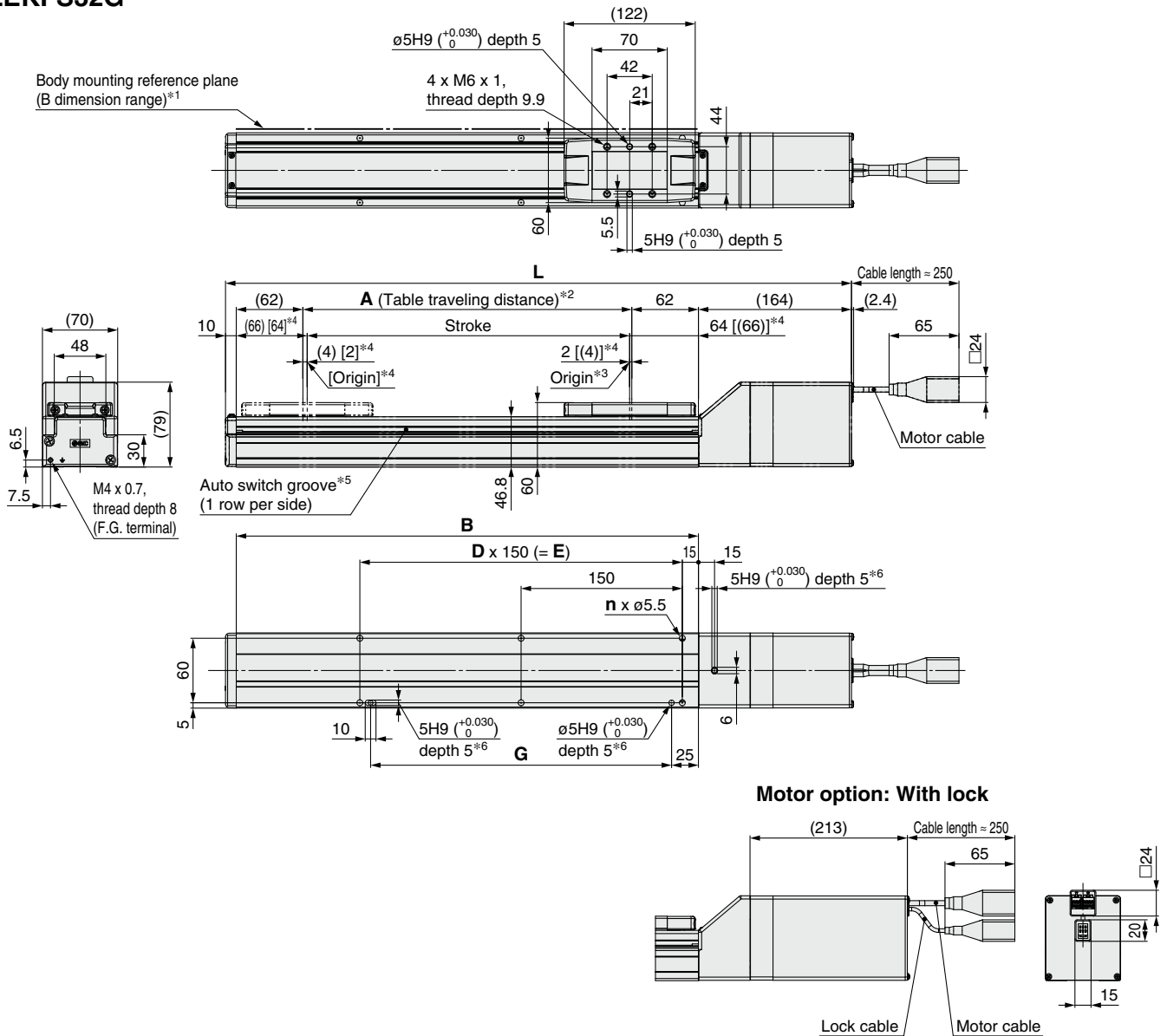
**Dimensions**

[mm]

Model	L		A	B	n	D	E	F	G	H
	Without lock	With lock								
LEKFS25G□-50□	285.5	330.5	56	160	4	—	—	20	100	30
LEKFS25G□-100□	335.5	380.5	106	210						
LEKFS25G□-150□	385.5	430.5	156	260						
LEKFS25G□-200□	435.5	480.5	206	310	6	2	240	35	220	45
LEKFS25G□-250□	485.5	530.5	256	360						
LEKFS25G□-300□	535.5	580.5	306	410						
LEKFS25G□-350□	585.5	630.5	356	460	8	3	360		340	
LEKFS25G□-400□	635.5	680.5	406	510						
LEKFS25G□-450□	685.5	730.5	456	560						
LEKFS25G□-500□	735.5	780.5	506	610	10	4	480		460	
LEKFS25G□-600□	835.5	880.5	606	710					580	
LEKFS25G□-700□	935.5	980.5	706	810					700	
LEKFS25G□-800□	1035.5	1080.5	806	910	16	7	840		820	

## Dimensions: In-line Motor

### LEKFS32G



\*1 When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height: 5 mm)

In addition, be aware that surfaces other than the body mounting reference plane (B dimension range) may slightly protrude from the body mounting reference plane. Be sure to provide a clearance of 1 mm or more to avoid interference with workpieces, facilities, etc.

\*2 This is the distance within which the table can move when it returns to origin. Make sure that workpieces mounted on the table do not interfere with other workpieces or the facilities around the table.

\*3 Position after returning to origin

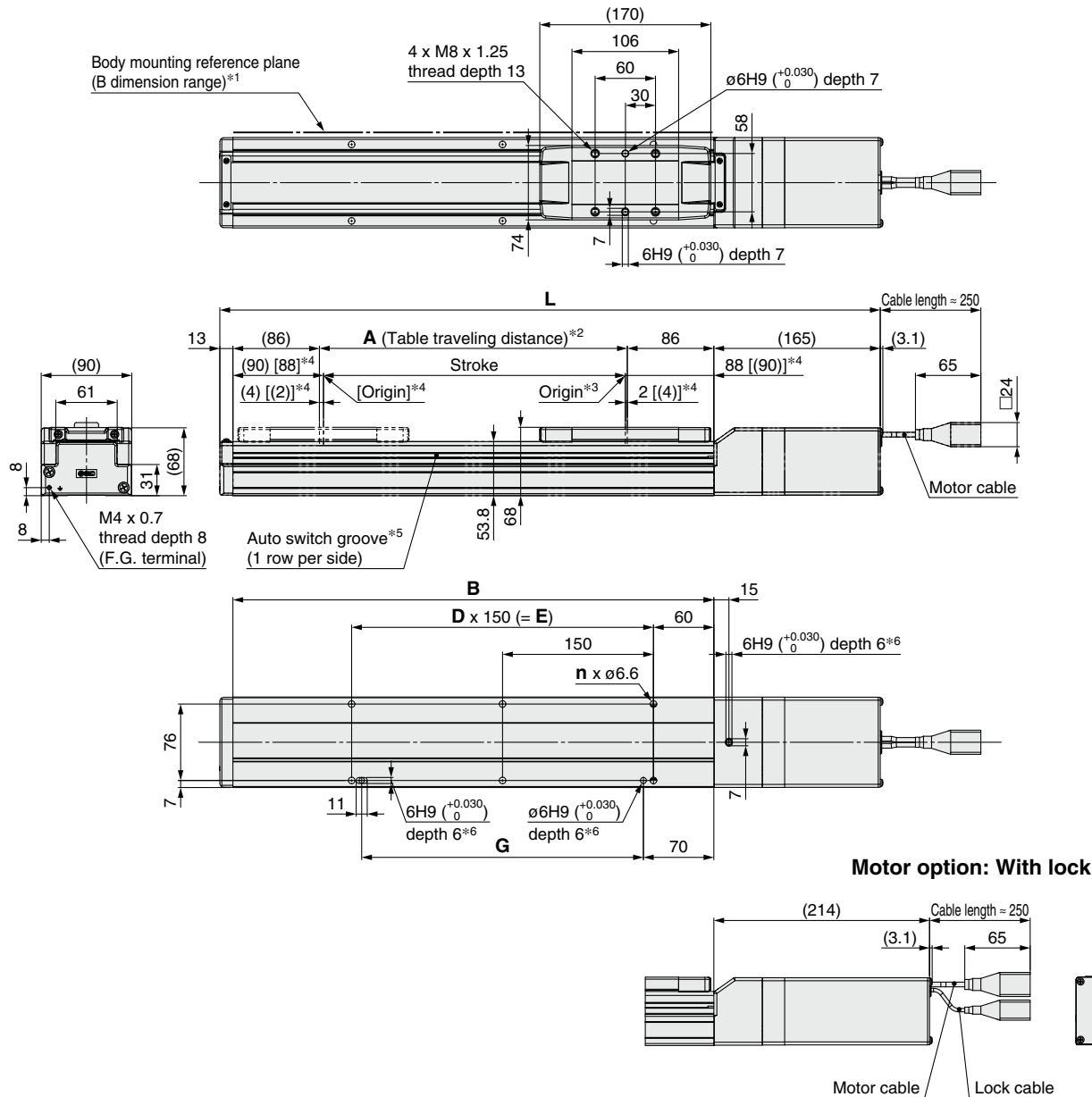
\*4 [ ] for when the direction of return to origin has changed

\*5 A switch spacer (BM3-016) is required to secure auto switches. Please order it separately.

\*6 When using the positioning pin holes on the bottom, use either the one on the body side or the one on the housing side.

## Dimensions

Dimensions								[mm]
Model	L		A	B	n	D	E	G
	Without lock	With lock						
LEKFS32G□-50□	332	384	56	180	4	—	—	130
LEKFS32G□-100□	382	434	106	230				
LEKFS32G□-150□	432	484	156	280				
LEKFS32G□-200□	482	534	206	330	6	2	300	280
LEKFS32G□-250□	532	584	256	380				
LEKFS32G□-300□	582	634	306	430				
LEKFS32G□-350□	632	684	356	480	8	3	450	430
LEKFS32G□-400□	682	734	406	530				
LEKFS32G□-450□	732	784	456	580				
LEKFS32G□-500□	782	834	506	630	10	4	600	580
LEKFS32G□-600□	882	934	606	730				
LEKFS32G□-700□	982	1034	706	830				
LEKFS32G□-800□	1082	1134	806	930	12	5	750	730
LEKFS32G□-900□	1182	1234	906	1030				
LEKFS32G□-1000□	1282	1334	1006	1130	16	7	1050	1030

**Dimensions: In-line Motor****LEKFS40G**

\*1 When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height: 5 mm)

In addition, be aware that surfaces other than the body mounting reference plane (B dimension range) may slightly protrude from the body mounting reference plane. Be sure to provide a clearance of 1 mm or more to avoid interference with workpieces, facilities, etc.

\*2 This is the distance within which the table can move when it returns to origin. Make sure that workpieces mounted on the table do not interfere with other workpieces or the facilities around the table.

\*3 Position after returning to origin

\*4 [ ] for when the direction of return to origin has changed

\*5 A switch spacer (BM Y3-016) is required to secure auto switches. Please order it separately.

\*6 When using the positioning pin holes on the bottom, use either the one on the body side or the one on the housing side.

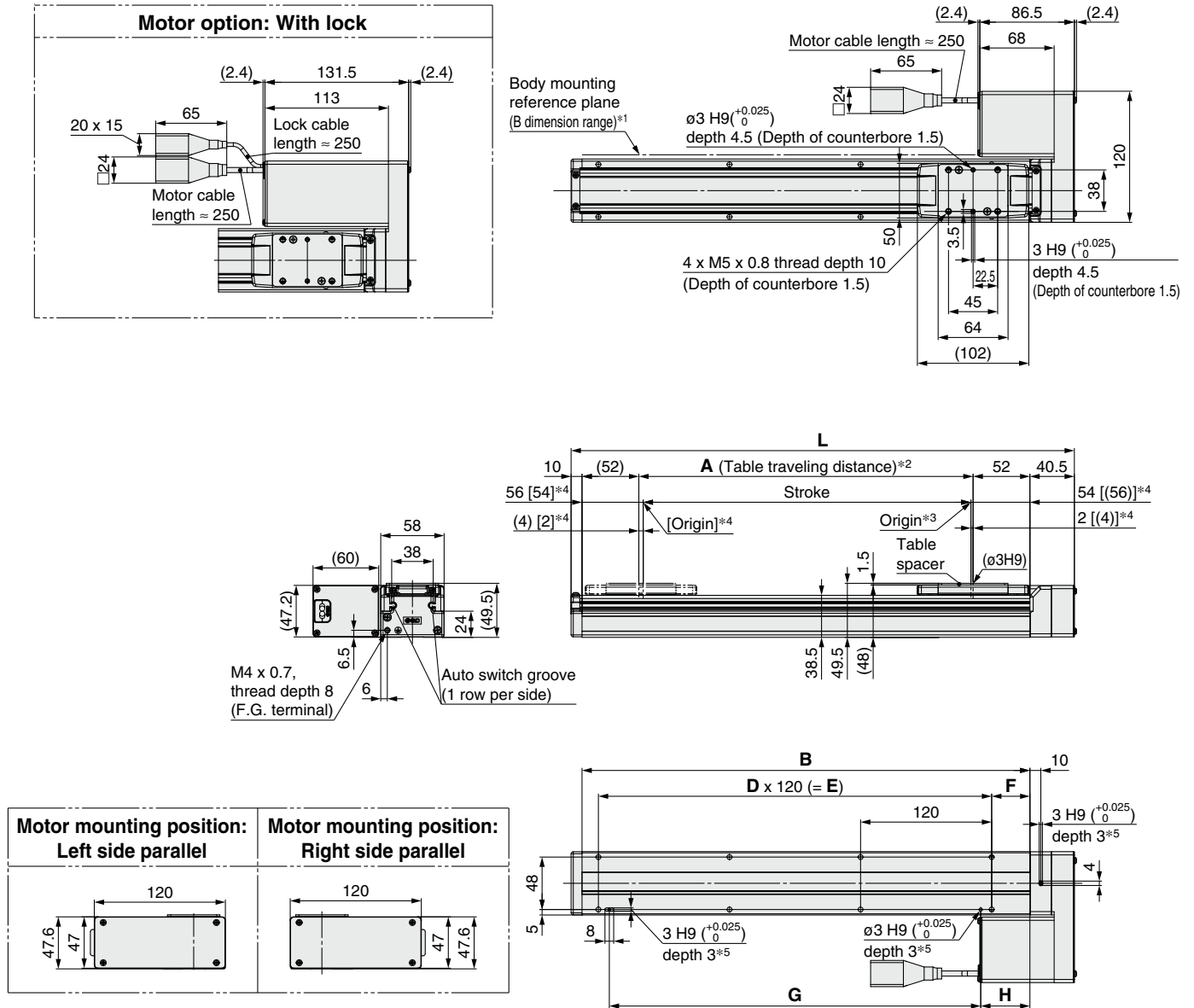
**Dimensions**

[mm]

Model	L		A	B	n	D	E	G
	Without lock	With lock						
LEKFS40G□-150□	506	555	156	328	4	—	—	130
LEKFS40G□-200□	556	605	206	378	6	2	300	280
LEKFS40G□-250□	606	655	256	428	8	3	450	430
LEKFS40G□-300□	656	705	306	478	10	4	600	580
LEKFS40G□-350□	706	755	356	528	12	5	750	730
LEKFS40G□-400□	756	805	406	578	14	6	900	880
LEKFS40G□-450□	806	855	456	628	16	7	1050	1030
LEKFS40G□-500□	856	905	506	678	18	8	1200	1180
LEKFS40G□-600□	956	1005	606	778				
LEKFS40G□-700□	1056	1105	706	878				
LEKFS40G□-800□	1156	1205	806	978				
LEKFS40G□-900□	1256	1305	906	1078				
LEKFS40G□-1000□	1356	1405	1006	1178				
LEKFS40G□-1100□	1456	1505	1106	1278				
LEKFS40G□-1200□	1556	1605	1206	1378				

## Dimensions: Right/Left Side Parallel Motor

### LEKFS25RG



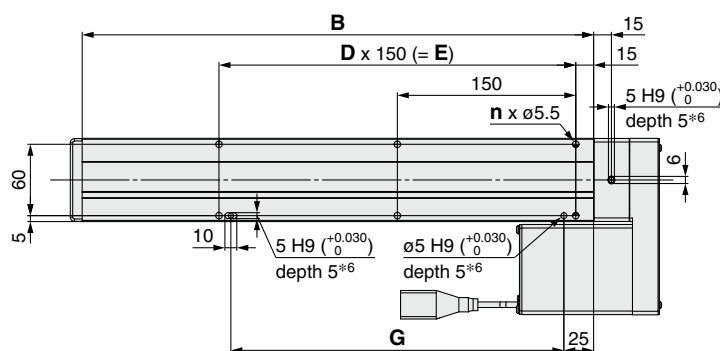
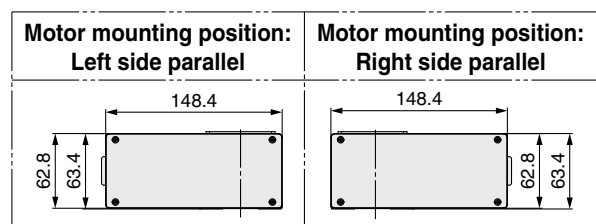
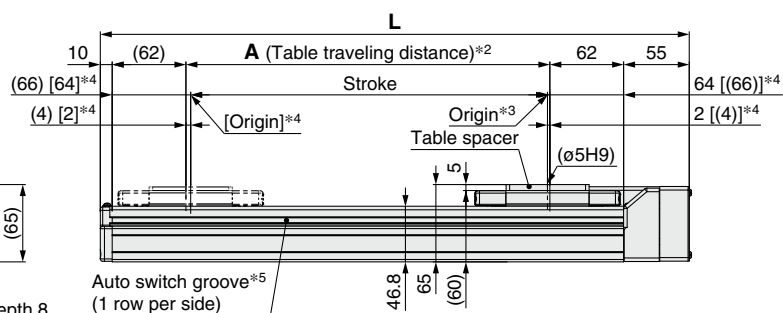
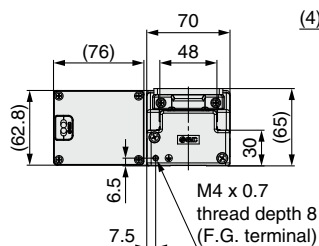
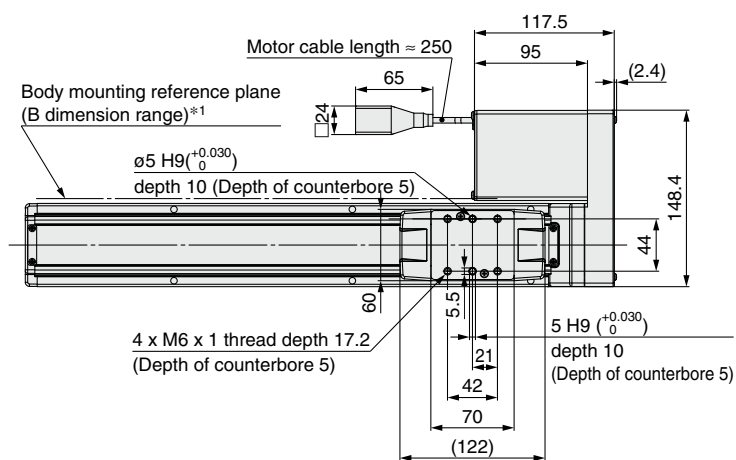
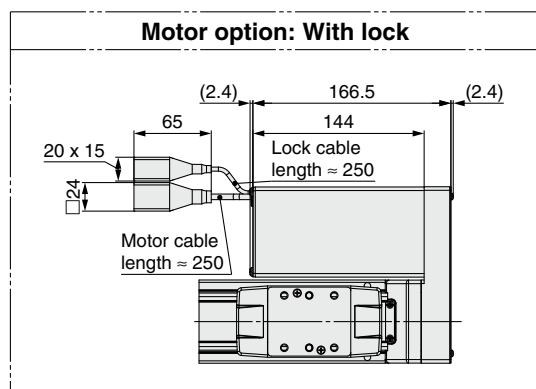
- \*1 When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height: 5 mm)  
In addition, be aware that surfaces other than the body mounting reference plane (B dimension range) may slightly protrude from the body mounting reference plane. Be sure to provide a clearance of 1 mm or more to avoid interference with workpieces, facilities, etc.
- \*2 This is the distance within which the table can move when it returns to origin. Make sure that workpieces mounted on the table do not interfere with other workpieces or the facilities around the table.
- \*3 Position after returning to origin
- \*4 [ ] for when the direction of return to origin has changed
- \*5 When using the positioning pin holes on the bottom, use either the one on the body side or the one on the housing side.
- \* This illustration shows the motor mounting position for the right side parallel type.

### Dimensions

Model	L	A	B	n	D	E	F	G	H
LEKFS25□G□-50□	210.5	56	160	4	—	—	20	100	30
LEKFS25□G□-100□	260.5	106	210						
LEKFS25□G□-150□	310.5	156	260						
LEKFS25□G□-200□	360.5	206	310	6	2	240	35	220	45
LEKFS25□G□-250□	410.5	256	360						
LEKFS25□G□-300□	460.5	306	410						
LEKFS25□G□-350□	510.5	356	460	8	3	360	35	340	45
LEKFS25□G□-400□	560.5	406	510						
LEKFS25□G□-450□	610.5	456	560						
LEKFS25□G□-500□	660.5	506	610	10	4	480	35	460	45
LEKFS25□G□-600□	760.5	606	710						
LEKFS25□G□-700□	860.5	706	810						
LEKFS25□G□-800□	960.5	806	910	16	7	840		820	

### Dimensions: Right/Left Side Parallel Motor

**LEKFS32RG**



- \*1 When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height: 5 mm)  
In addition, be aware that surfaces other than the body mounting reference plane (B dimension range) may slightly protrude from the body mounting reference plane. Be sure to provide a clearance of 1 mm or more to avoid interference with workpieces, facilities, etc.
- \*2 This is the distance within which the table can move when it returns to origin. Make sure that workpieces mounted on the table do not interfere with other workpieces or the facilities around the table.
- \*3 Position after returning to origin
- \*4 [ ] for when the direction of return to origin has changed
- \*5 A switch spacer (BMY3-016) is required to secure auto switches. Please order it separately.
- \*6 When using the positioning pin holes on the bottom, use either the one on the body side or the one on the housing side.
- \* This illustration shows the motor mounting position for the right side parallel type.

## Dimensions

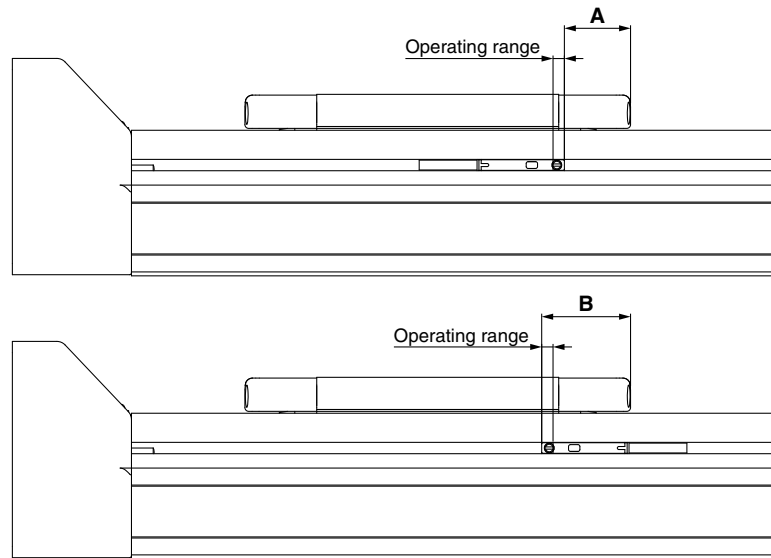
Dimensions								[mm]
Model	L	A	B	n	D	E	G	
LEKFS32□G□-50□	245	56	180	4	—	—	130	
LEKFS32□G□-100□	295	106	230					
LEKFS32□G□-150□	345	156	280					
LEKFS32□G□-200□	395	206	330	6	2	300	280	
LEKFS32□G□-250□	445	256	380					
LEKFS32□G□-300□	495	306	430					
LEKFS32□G□-350□	545	356	480	8	3	450	430	
LEKFS32□G□-400□	595	406	530					
LEKFS32□G□-450□	645	456	580					
LEKFS32□G□-500□	695	506	630	10	4	600	580	
LEKFS32□G□-600□	795	606	730					
LEKFS32□G□-700□	895	706	830					
LEKFS32□G□-800□	995	806	930	14	6	900	880	
LEKFS32□G□-900□	1095	906	1030					
LEKFS32□G□-1000□	1195	1006	1130					





# LEKFS□G Series Auto Switch Mounting

## Auto Switch Mounting Position



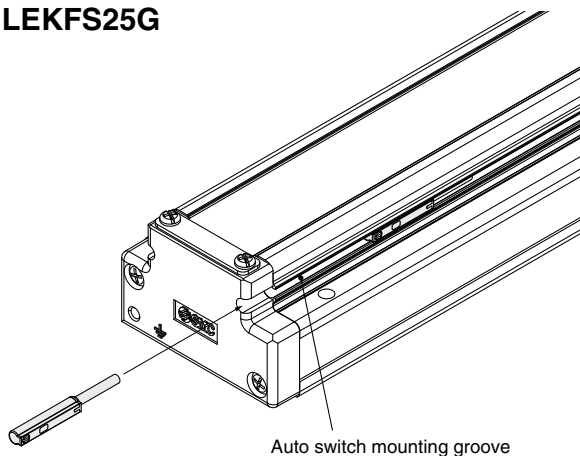
**Table 1 Auto switch mounting dimensions** [mm]

Model	Size	A	B	Operating range
LEKFS□G	25	17.5	23.5	3.0
	32	26.3	32.3	3.4
	40	32.2	38.2	3.6

- \* The applicable auto switch is D-M9 (N/P/B) (W) (M/L/Z).
- \* The operating range is a guideline including hysteresis, not meant to be guaranteed. There may be large variations depending on the ambient environment.
- \* Adjust the auto switch after confirming the operating conditions in the actual setting.

## Auto Switch Mounting

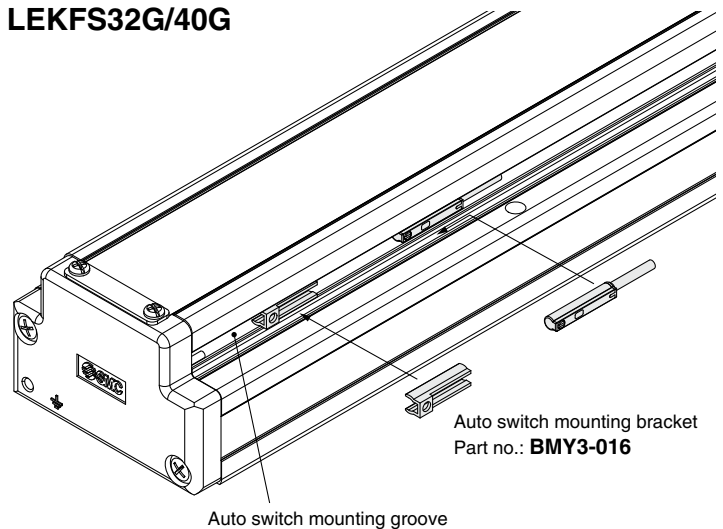
### LEKFS25G



Auto Switch Mounting Screw

Tightening torque [N·m]
0.1 to 0.15

### LEKFS32G/40G



Auto switch mounting bracket  
Part no.: **BMY3-016**

- \* The applicable auto switch is D-M9 (N/P/B) (W) (M/L/Z).
- \* When tightening the auto switch mounting screw (included with the auto switch), use a watchmaker's screwdriver with a handle diameter of 5 to 6 mm.
- \* Prepare an auto switch mounting bracket (BMY3-016) when mounting the auto switch on to the LEKFS32G/40G.

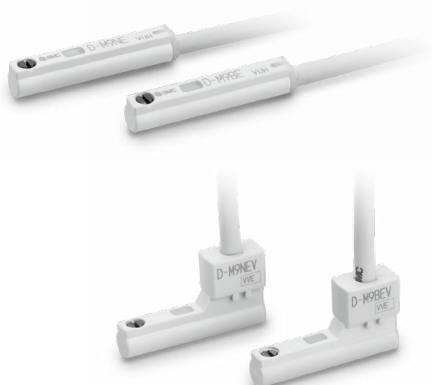
# Normally Closed Solid State Auto Switch Direct Mounting Type D-M9NE(V)/D-M9PE(V)/D-M9BE(V)

Refer to the SMC website for details on products that are compliant with international standards.

PLC: Programmable Logic Controller

## Grommet

- Output signal turns on when no magnetic force is detected.
- Can be used for the actuator adopted by the solid state auto switch D-M9 series (excluding special order products)



## Caution

### Precautions

Fix the auto switch with the existing screw installed on the auto switch body. The auto switch may be damaged if a screw other than the one supplied is used.

## Auto Switch Specifications

D-M9□E, D-M9□EV (With indicator light)						
Auto switch model	D-M9NE	D-M9NEV	D-M9PE	D-M9PEV	D-M9BE	D-M9BEV
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3-wire				2-wire	
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24 VDC relay, PLC	
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)				—	
Current consumption	10 mA or less				—	
Load voltage	28 VDC or less		—		24 VDC (10 to 28 VDC)	
Load current	40 mA or less				2.5 to 40 mA	
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)				4 V or less	
Leakage current	100 μA or less at 24 VDC				0.8 mA or less	
Indicator light	Red LED illuminates when turned ON.					
Standard	CE marking, RoHS					

## Oilproof Flexible Heavy-duty Lead Wire Specifications

Onipol® Flexible Heavy duty Lead Wire Specifications				
Auto switch model		D-M9NE(V)	D-M9PE(V)	D-M9BE(V)
Sheath	Outside diameter [mm]	2.6		
Insulator	Number of cores	3 cores (Brown/Blue/Black)		2 cores (Brown/Blue)
	Outside diameter [mm]	0.88		
Conductor	Effective area [mm²]	0.15		
	Strand diameter [mm]	0.05		
Min. bending radius [mm] (Reference values)		17		

\* Refer to the **Web Catalog** for solid state auto switch common specifications.

\* Refer to the **Web Catalog** for lead wire lengths.

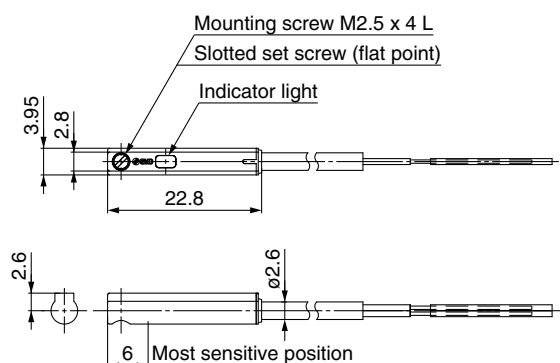
## Weight

Auto switch model	D-M9NE(V)	D-M9PE(V)	D-M9BE(V)
Lead wire length	0.5 m (Nil)	8	7
	1 m (M)*1	14	13
	3 m (L)	41	38
	5 m (Z)*1	68	63

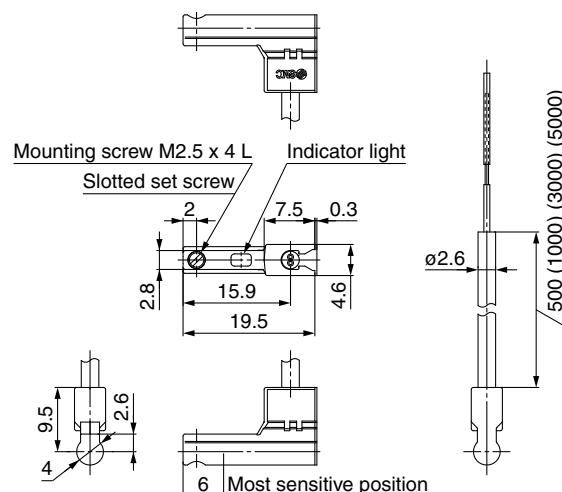
\*1 The 1 m and 5 m options are produced upon receipt of order.

## Dimensions

### D-M9□E



### D-M9□EV



# 2-Color Indicator Solid State Auto Switch Direct Mounting Type D-M9NW/D-M9PW/D-M9BW



Refer to the SMC website for details on products that are compliant with international standards.

## Grommet

- 2-wire load current is reduced (2.5 to 40 mA).
- Using flexible cable as standard spec.
- The proper operating range can be determined by the color of the light. (Red → Green ← Red)



## Caution

### Precautions

Fix the auto switch with the existing screw installed on the auto switch body. The auto switch may be damaged if a screw other than the one supplied is used.

## Auto Switch Specifications

PLC: Programmable Logic Controller

D-M9□W, D-M9□WV (With indicator light)			
Auto switch model	D-M9NW	D-M9PW	D-M9BW
Electrical entry direction	In-line		
Wiring type	3-wire		2-wire
Output type	NPN	PNP	—
Applicable load	IC circuit, Relay, PLC		24 VDC relay, PLC
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)		—
Current consumption	10 mA or less		—
Load voltage	28 VDC or less	—	24 VDC (10 to 28 VDC)
Load current	40 mA or less		2.5 to 40 mA
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)		4 V or less
Leakage current	100 μA or less at 24 VDC		0.8 mA or less
Indicator light	Operating range ..... Red LED illuminates. Proper operating range ..... Green LED illuminates.		
Standard	CE marking, RoHS		

## Oilproof Flexible Heavy-duty Lead Wire Specifications

Auto switch model	D-M9NW	D-M9PW	D-M9BW
Sheath	Outside diameter [mm]	2.6	
Insulator	Number of cores	3 cores (Brown/Blue/Black)	2 cores (Brown/Blue)
	Outside diameter [mm]	0.88	
Conductor	Effective area [mm <sup>2</sup> ]	0.15	
	Strand diameter [mm]	0.05	
Min. bending radius [mm] (Reference values)		17	

- \* Refer to the **Web Catalog** for solid state auto switch common specifications.
- \* Refer to the **Web Catalog** for lead wire lengths.

## Weight

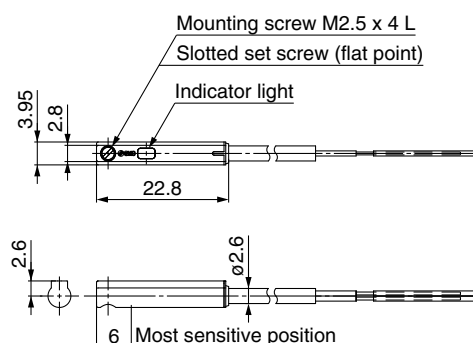
[g]

Auto switch model	D-M9NW	D-M9PW	D-M9BW
Lead wire length	0.5 m (Nil)	8	7
	1 m (M)	14	13
	3 m (L)	41	38
	5 m (Z)	68	63

## Dimensions

[mm]

### D-M9□W



# Controllers

## JXC□ Series



Step Data Input Type ..... p. 31

### High Performance

Battery-less Absolute (Step Motor 24 VDC)

JXC5H/6H Series



EtherCAT/EtherNet/IP™/PROFINET Direct Input Type ..... p. 38

### High Performance

Battery-less Absolute (Step Motor 24 VDC)

JXCEH/9H/PH Series

EtherCAT®

EtherNet/IP®

PROFI®  
NET



• Actuator Cable p. 43

Model Selection

LEKFS□G Series

Auto Switch

JXC5H/6H Series

JXCEH/9H/PH Series

# High Performance Controller (Step Data Input Type)

## JXC5H/6H Series



RoHS

### How to Order

JXC **5** H **7** **3** -

① ② ③ ④ ⑤

#### ① Controller type

5	Parallel I/O (NPN) type
6	Parallel I/O (PNP) type

#### ② Specification

H	1 axis/High performance type
---	------------------------------

#### ③ Mounting

7	Screw mounting
8	DIN rail

#### ④ I/O cable length

Nil	None
1	1.5 m
3	3 m
5	5 m

#### ⑤ Actuator part number

Without cable specifications and actuator options  
Example: Enter "LEKFS25GA-400" for the  
LEKFS25GA-400B-R1C□H□□.

BC	Blank controller*1
----	--------------------

\*1 Requires dedicated software (JXC-BCW)

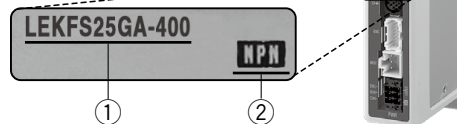


### The controller is sold as single unit after the compatible actuator is set.

Connect to an actuator (LEKFS□G) designated for a high performance controller. Confirm that the combination of the controller and actuator is correct.

#### <Check the following before use.>

- Check the actuator label for the model number. This number should match that of the controller.
- Check that the Parallel I/O configuration matches (NPN or PNP).



\* Refer to the operation manual for using the products. Please download it via our website:  
<https://www.smcworld.com>

### Precautions for blank controllers (JXC□1□□-BC)

A blank controller is a controller to which the customer can write the data of the actuator it is to be combined and used with. For data writing, use the controller setting software ACT Controller 2 or the dedicated software JXC-BCW.

- Both ACT Controller 2 and JXC-BCW can be downloaded from the SMC website.
- To use this software, order the communication cable for controller setting (JXC-W2A-C) and the USB cable (LEC-W2-U) separately.

#### Hardware Requirements

OS	Windows®10 (64 bit)	Windows®7
		Windows®8
Software	ACT Controller 2 (With JXC-BCW function)	JXC-BCW

\* Windows®7, Windows®8, and Windows®10 are registered trademarks of Microsoft Corporation in the United States.

SMC website  
<https://www.smcworld.com>

### Specifications

Model	JXC5H JXC6H
Compatible motor	Step motor (Servo/24 VDC)
Power supply	Power supply voltage: 24 VDC ±10%
Current consumption (Controller)	100 mA or less
Compatible encoder	Battery-less absolute
Parallel input	11 inputs (Photo-coupler isolation)
Parallel output	13 outputs (Photo-coupler isolation)
Serial communication	RS485 (Only for the LEC-T1 and JXC-W2)
Memory	EEPROM
LED indicator	PWR, ALM
Cable length [m]	Actuator cable: 20 or less
Cooling system	Natural air cooling
Operating temperature range [°C]	0 to 40
Operating humidity range [%RH]	90 or less (No condensation)
Insulation resistance [MΩ]	Between all external terminals and the case: 50 (500 VDC)
Weight [g]	180 (Screw mounting), 200 (DIN rail mounting)

### ⚠ Caution

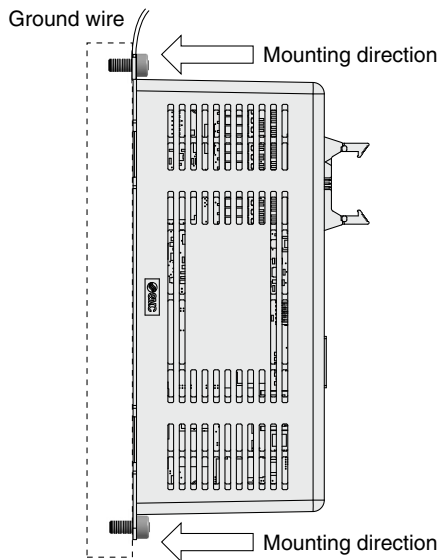
#### [CE/UKCA-compliant products]

EMC compliance was tested by combining the electric actuator LE series and the JXC5H/6H series. The EMC depends on the configuration of the customer's control panel and the relationship with other electrical equipment and wiring. Therefore, compliance with the EMC directive cannot be certified for SMC components incorporated into the customer's equipment under actual operating conditions. As a result, it is necessary for the customer to verify compliance with the EMC directive for the machinery and equipment as a whole.

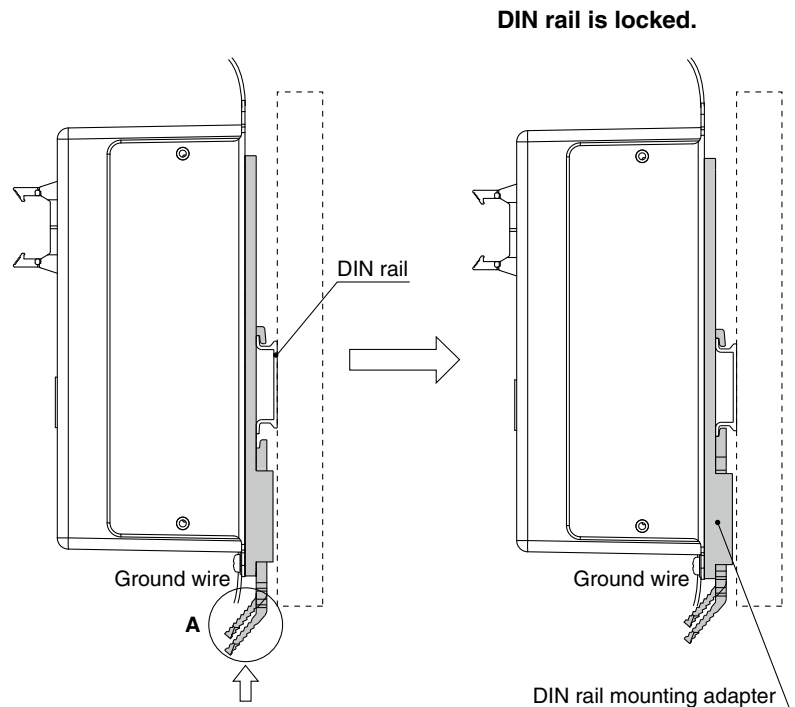


## How to Mount

### a) Screw mounting (JXC□H7□) (Installation with two M4 screws)



### b) DIN rail mounting (JXC□H8□) (Installation with the DIN rail)

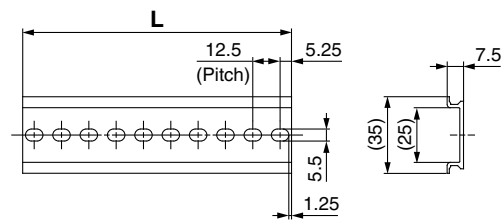


Hook the controller on the DIN rail and press the lever of section **A** in the arrow direction to lock it.

\* When size 25 or more of the LE series are used, the space between the controllers should be 10 mm or more.

### DIN rail AXT100-DR-□

\* For □, enter a number from the No. line in the table below.  
Refer to the dimension drawings on page 33 for the mounting dimensions.



#### L Dimensions [mm]

No.	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
<b>L</b>	23	35.5	48	60.5	73	85.5	98	110.5	123	135.5	148	160.5	173	185.5	198	210.5	223	235.5	248	260.5
No.	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40
<b>L</b>	273	285.5	298	310.5	323	335.5	348	360.5	373	385.5	398	410.5	423	435.5	448	460.5	473	485.5	498	510.5

### DIN rail mounting adapter LEC-3-D0 (with 2 mounting screws)

This should be used when the DIN rail mounting adapter is mounted onto a screw mounting type controller afterward.

Model Selection

LEKFS□G Series

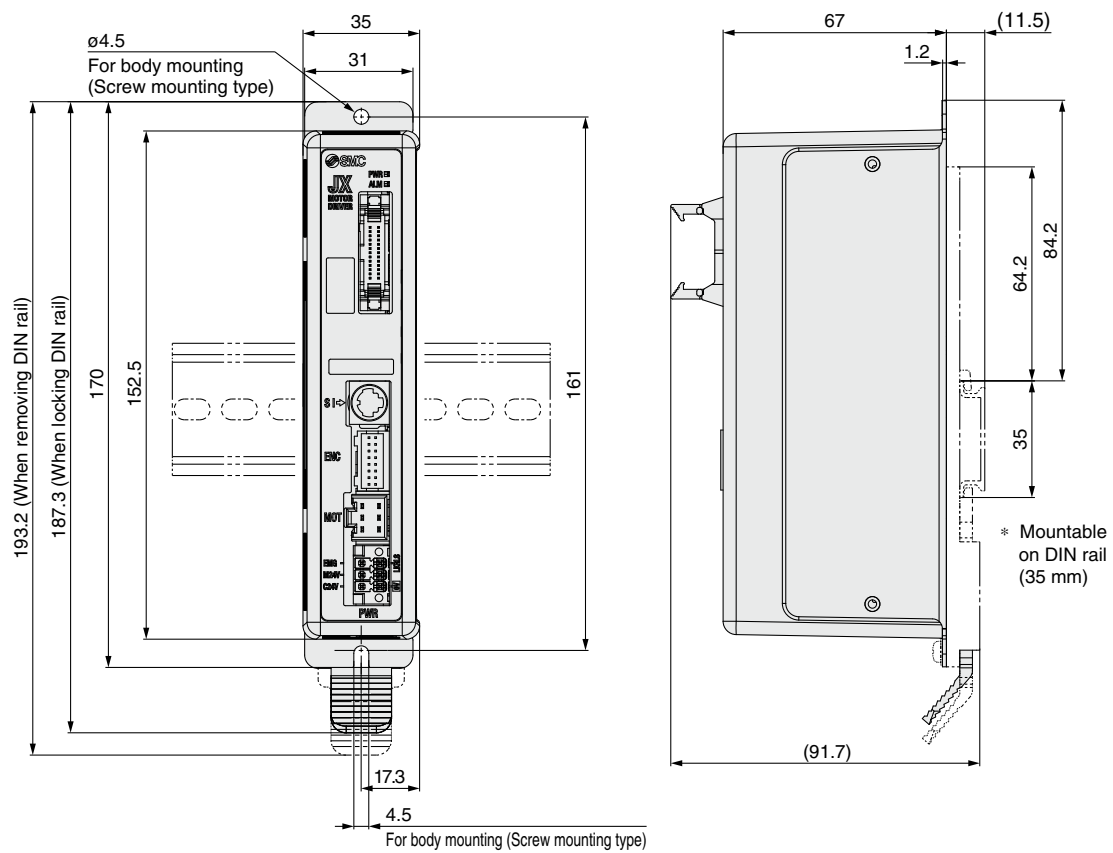
Auto Switch

JXC5H/6H Series

JXCEH/9H/PH Series

# JXC5H/6H Series

## Dimensions



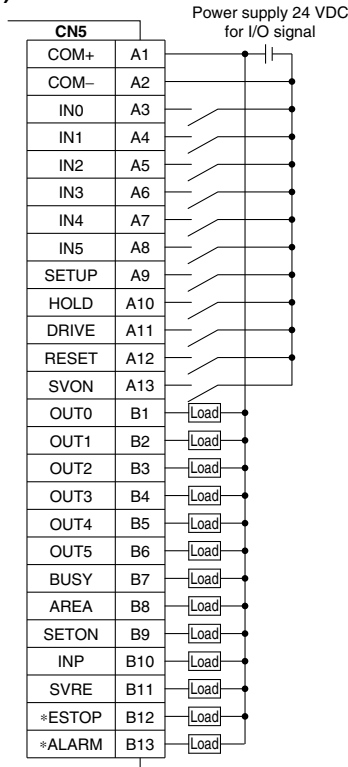
## Wiring Example 1

### Parallel I/O Connector

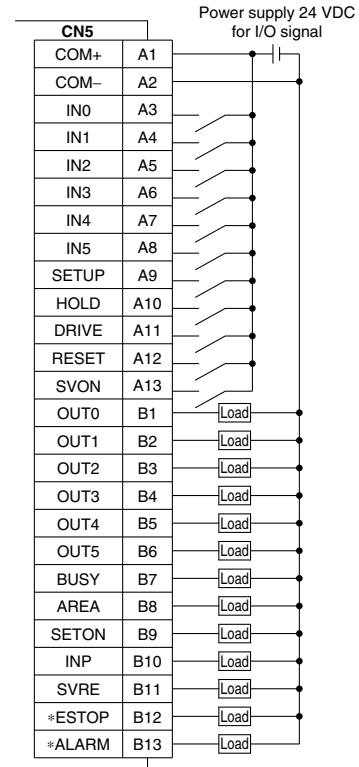
- \* When you connect a PLC to the parallel I/O connector, use the I/O cable (LEC-CN5-□).
- \* The wiring changes depending on the type of parallel I/O (NPN or PNP).

### Wiring diagram

#### JXC5H□□ (NPN)



#### JXC6H□□ (PNP)



### Input Signal

Name	Details
COM+	Connects the power supply 24 V for input/output signal
COM-	Connects the power supply 0 V for input/output signal
IN0 to IN5	Step data specified bit no. (Input is instructed by combining IN0 to 5.)
SETUP	Instruction to return to origin
HOLD	Temporarily stops operation
DRIVE	Instruction to drive
RESET	Resets alarm and interrupts operation
SVON	Servo ON instruction

### Output Signal

Name	Details
OUT0 to OUT5	Outputs the step data no. during operation
BUSY	Outputs when the actuator is moving
AREA	Outputs within the step data area output setting range
SETON	Outputs when returning to origin
INP	Outputs when target position or target force is reached (Turns on when the positioning or pushing is completed.)
SVRE	Outputs when servo is on
*ESTOP* <sup>1</sup>	OFF when EMG stop is instructed
*ALARM* <sup>1</sup>	OFF when alarm is generated

\*<sup>1</sup> Signal of negative-logic circuit (N.C.)

Model Selection

LEKFS□G Series

Auto Switch

JXC5H/6H Series

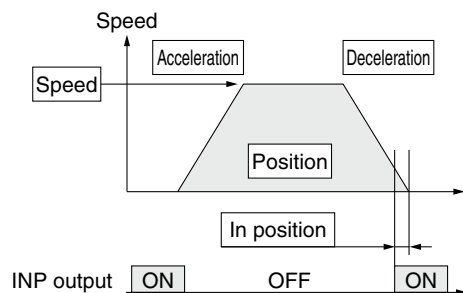
JXCEH/9H/PH Series

## Step Data Setting

### 1. Step data setting for positioning

In this setting, the actuator moves toward and stops at the target position.

The following diagram shows the setting items and operation. The setting items and set values for this operation are stated below.



◎ : Need to be set.  
○ : Need to be adjusted as required.  
— : Setting is not required.

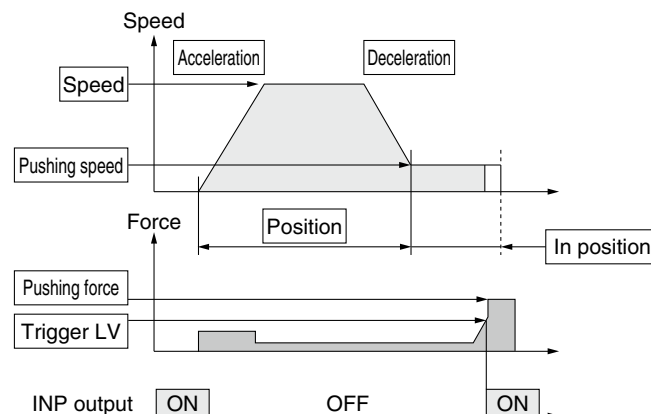
#### Step Data (Positioning)

Necessity	Item	Details
◎	Movement MOD	When the absolute position is required, set Absolute. When the relative position is required, set Relative.
◎	Speed	Transfer speed to the target position
◎	Position	Target position
○	Acceleration	Parameter which defines how rapidly the actuator reaches the speed set. The higher the set value, the faster it reaches the speed set.
○	Deceleration	Parameter which defines how rapidly the actuator comes to stop. The higher the set value, the quicker it stops.
◎	Pushing force	Set 0. (If values 1 to 100 are set, the operation will be changed to the pushing operation.)
—	Trigger LV	Setting is not required.
—	Pushing speed	Setting is not required.
○	Moving force	Max. torque during the positioning operation (No specific change is required.)
○	Area 1, Area 2	Condition that turns on the AREA output signal.
○	In position	Condition that turns on the INP output signal. When the actuator enters the range of [in position], the INP output signal turns on. (It is unnecessary to change this from the initial value.) When it is necessary to output the arrival signal before the operation is completed, make the value larger.

### 2. Step data setting for pushing

The actuator moves toward the pushing start position, and when it reaches that position, it starts pushing with the set force or less.

The following diagram shows the setting items and operation. The setting items and set values for this operation are stated below.



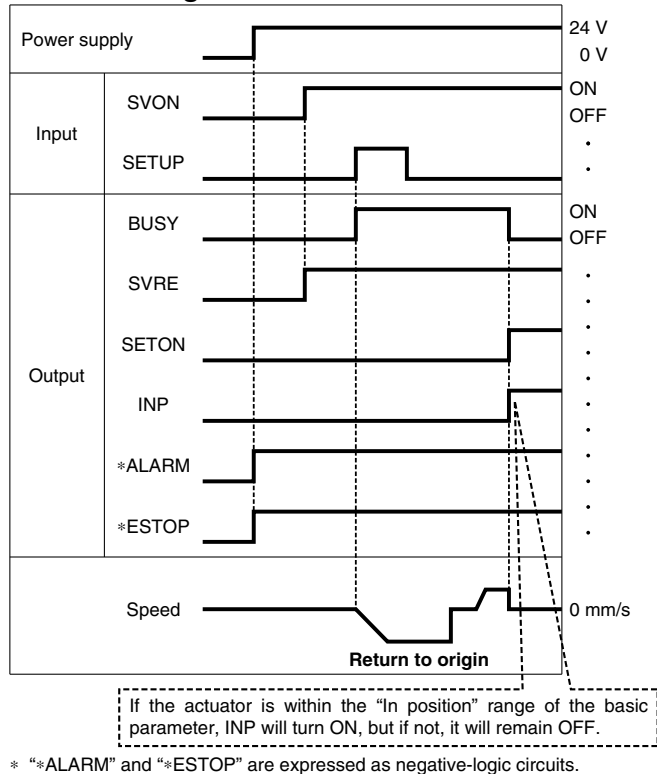
◎ : Need to be set.  
○ : Need to be adjusted as required.

#### Step Data (Pushing)

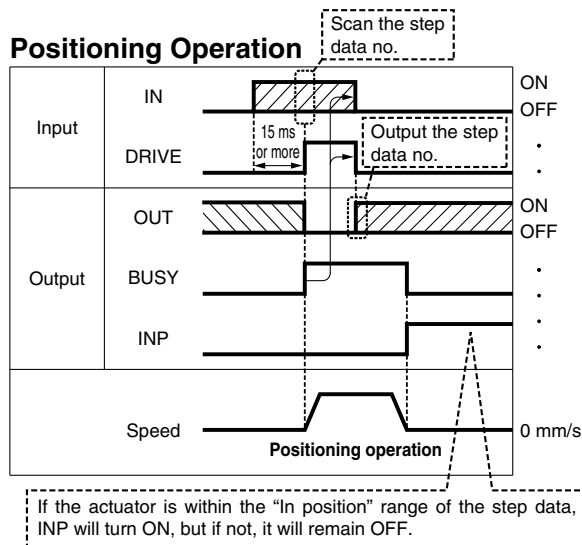
Necessity	Item	Details
◎	Movement MOD	When the absolute position is required, set Absolute. When the relative position is required, set Relative.
◎	Speed	Transfer speed to the pushing start position
◎	Position	Pushing start position
○	Acceleration	Parameter which defines how rapidly the actuator reaches the speed set. The higher the set value, the faster it reaches the speed set.
○	Deceleration	Parameter which defines how rapidly the actuator comes to stop. The higher the set value, the quicker it stops.
◎	Pushing force	Pushing force ratio is defined. The setting range differs depending on the electric actuator type. Refer to the operation manual for the electric actuator.
◎	Trigger LV	Condition that turns on the INP output signal. The INP output signal turns on when the generated force exceeds the value. Trigger level should be the pushing force or less.
○	Pushing speed	Pushing speed during pushing. When the speed is set fast, the electric actuator and workpieces might be damaged due to the impact when they hit the end, so this set value should be smaller. Refer to the operation manual for the electric actuator.
○	Moving force	Max. torque during the positioning operation (No specific change is required.)
○	Area 1, Area 2	Condition that turns on the AREA output signal.
◎	In position	Transfer distance during pushing. If the transferred distance exceeds the setting, it stops even if it is not pushing. If the transfer distance is exceeded, the INP output signal will not turn on.

## Signal Timing

### Return to Origin

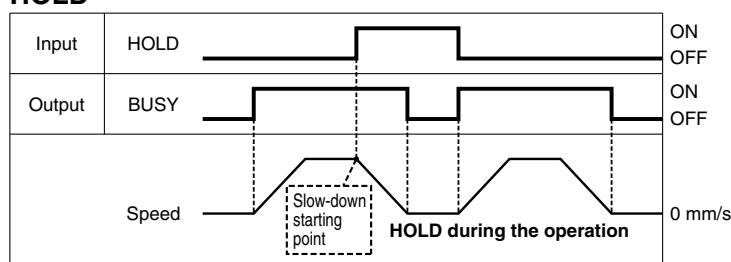


### Positioning Operation

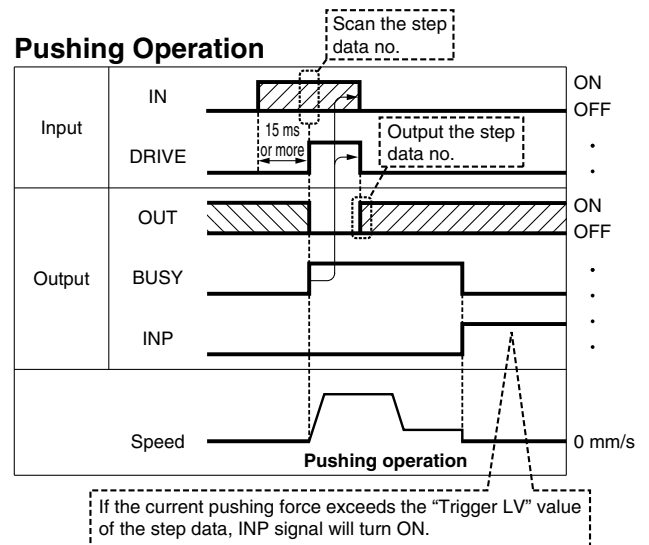


\* "OUT" is output when "DRIVE" is changed from ON to OFF.  
Refer to the operation manual for details on the controller for the LEM series.  
(When power supply is applied, "DRIVE" or "RESET" is turned ON or \*ESTOP" is turned OFF, all of the "OUT" outputs are OFF.)

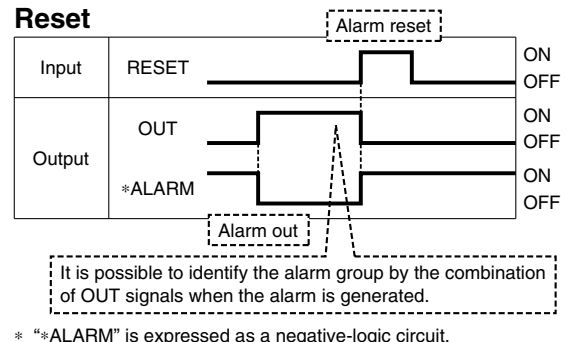
### HOLD



### Pushing Operation



### Reset

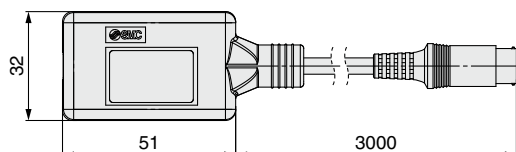


# JXC5H/6H Series

## Options

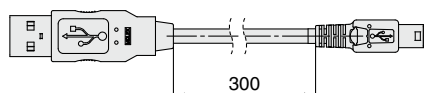
### ■ Communication cable for controller setting

#### ① Communication cable JXC-W2A-C



\* It can be connected to the controller directly.

#### ② USB cable LEC-W2-U



#### ③ Controller setting kit JXC-W2A

A set which includes a communication cable (JXC-W2A-C) and a USB cable (LEC-W2-U)

##### <Controller setting software/USB driver>

- Controller setting software
  - USB driver (For JXC-W2A-C)
- Download from SMC's website:  
<https://www.smcworld.com>

##### Hardware Requirements

OS	Windows®7, Windows®8.1, Windows®10
Communication interface	USB 1.1 or USB 2.0 ports
Display	1024 x 768 or more

\* Windows®7, Windows®8.1, and Windows®10 are registered trademarks of Microsoft Corporation in the United States.

### ■ Conversion cable P5062-5 (Cable length: 300 mm)



\* To connect the teaching box (LEC-T1-3□G□) or controller setting kit (LEC-W2□) to the controller, a conversion cable is required.

### ■ I/O cable

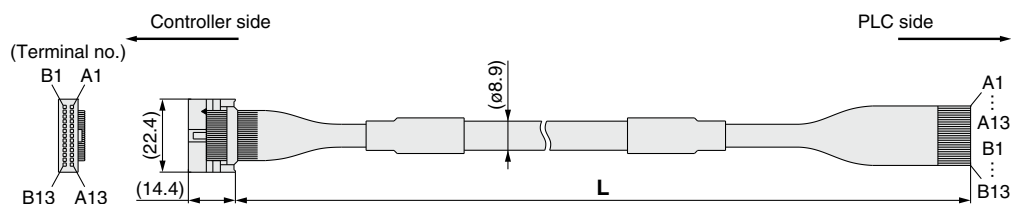
#### LEC-CN5-1

Cable length (L) [m]	
1	1.5
3	3
5	5

\* Conductor size: AWG28

##### Weight

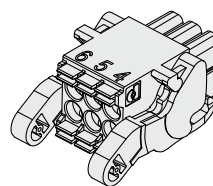
Product no.	Weight [g]
LEC-CN5-1	170
LEC-CN5-3	320
LEC-CN5-5	520



Connector pin no.	Insulation color	Dot mark	Dot color
A1	Light brown	■	Black
A2	Light brown	■	Red
A3	Yellow	■	Black
A4	Yellow	■	Red
A5	Light green	■	Black
A6	Light green	■	Red
A7	Gray	■	Black
A8	Gray	■	Red
A9	White	■	Black
A10	White	■	Red
A11	Light brown	■ ■	Black
A12	Light brown	■ ■	Red
A13	Yellow	■ ■	Black

Connector pin no.	Insulation color	Dot mark	Dot color
B1	Yellow	■ ■	Red
B2	Light green	■ ■	Black
B3	Light green	■ ■	Red
B4	Gray	■ ■	Black
B5	Gray	■ ■	Red
B6	White	■ ■	Black
B7	White	■ ■	Red
B8	Light brown	■ ■ ■	Black
B9	Light brown	■ ■ ■	Red
B10	Yellow	■ ■ ■	Black
B11	Yellow	■ ■ ■	Red
B12	Light green	■ ■ ■	Black
B13	Light green	■ ■ ■	Red
—			Shield

### ■ Power supply plug JXC-CPW



\* The power supply plug is an accessory.  
 <Applicable cable size> AWG20 (0.5 mm<sup>2</sup>), cover diameter 2.0 mm or less

① C24V	④ 0V
② M24V	⑤ N.C.
③ EMG	⑥ LK RLS

#### Power supply plug

Terminal name	Function	Details
0V	Common supply (-)	The M24V terminal, C24V terminal, EMG terminal, and LK RLS terminal are common (-).
M24V	Motor power supply (+)	Motor power supply (+) of the controller
C24V	Control power supply (+)	Control power supply (+) of the controller
EMG	Stop (+)	Connection terminal of the external stop circuit
LK RLS	Lock release (+)	Connection terminal of the lock release switch

### ■ Teaching box

LEC-T1-3□J□G□

Teaching box

Cable length [m]

Initial language

Enable switch (Option)

Stop switch

Enable switch

Stop switch

\* The displayed language can be changed to English or Japanese.

#### Specifications

Item	Description
Switch	Stop switch, Enable switch (Option)
Cable length [m]	3
Enclosure	IP64 (Except connector)
Operating temperature range [°C]	5 to 50
Operating humidity range [%RH]	90 or less (No condensation)
Weight [g]	350 (Except cable)



# High Performance Step Motor Controller

## JXCEH/9H/PH Series



RoHS

Model Selection

LEKFS□G Series

Auto Switch

JXC5H/6H Series

JXCEH/9H/PH Series

### How to Order

JXC **P** **H** **7** - □

1 2 3 4



EtherCAT

EtherNet/IP

PROFINET

#### 1 Communication protocol

E	EtherCAT
9	EtherNet/IP™
P	PROFINET

#### 2 Specifications

H	1 axis/High performance type
---	------------------------------

#### 3 Mounting

7	Screw mounting
8*1	DIN rail

\*1 The DIN rail is not included. It must be ordered separately. (Refer to page 42.)

#### 4 Actuator part number

Without cable specifications and actuator options  
Example: Enter "LEKFS25GA-400" for the LEKFS25GA-400B-R1C□H□□.

BC	Blank controller*1
----	--------------------

\*1 Requires dedicated software (JXC-BCW)

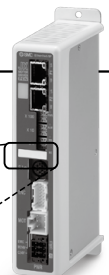
### The controller is sold as single unit after the compatible actuator is set.

Confirm that the combination of the controller and actuator is correct.

- Check the actuator label for the model number. This number should match that of the controller.

LEKFS25GA-400

1



\* Refer to the operation manual for using the products. Please download it via our website: <https://www.smcworld.com>

### Precautions for blank controllers (JXC□H□-BC)

A blank controller is a controller to which the customer can write the data of the actuator it is to be combined and used with. For data writing, use the controller setting software ACT Controller 2 or the dedicated software JXC-BCW.

- Both ACT Controller 2 and JXC-BCW can be downloaded from the SMC website.
- To use this software, order the communication cable for controller setting (JXC-W2A-C) and the USB cable (LEC-W2-U) separately.

#### Hardware Requirements

OS	Windows®10 (64 bit)	Windows®7	Windows®8	Windows®10
Software	ACT Controller 2 (With JXC-BCW function)	JXC-BCW		

\* Windows®7, Windows®8, and Windows®10 are registered trademarks of Microsoft Corporation in the United States.

SMC website: <https://www.smcworld.com>

### ⚠ Caution

#### [CE/UKCA-compliant products]

- EMC compliance was tested by combining the electric actuator LE series and the JXCEH/PH series.

The EMC depends on the configuration of the customer's control panel and the relationship with other electrical equipment and wiring. Therefore, compliance with the EMC directive cannot be certified for SMC components incorporated into the customer's equipment under actual operating conditions. As a result, it is necessary for the customer to verify compliance with the EMC directive for the machinery and equipment as a whole.

- For the JXCEH/PH series (step motor controller), EMC compliance was tested by installing a noise filter set (LEC-NFA).

Refer to page 42 for the noise filter set. Refer to the JXCEH/PH Operation Manual for installation.

# JXCEH/9H/PH Series

## Specifications

Model			JXCEH	JXC9H	JXCPH
Network			EtherCAT	EtherNet/IP™	PROFINET
Compatible motor			Step motor (Servo/24 VDC)		
Power supply			Power voltage: 24 VDC ±10%		
Current consumption (Controller)			200 mA or less	200 mA or less	200 mA or less
Compatible encoder			Battery-less absolute		
Communication specifications	Applicable system	Protocol	EtherCAT*2	EtherNet/IP™*2	PROFINET*2
		Version*1	Conformance Test Record V.1.2.6	Volume 1 (Edition 3.14) Volume 2 (Edition 1.15)	Specification Version 2.32
	Communication speed		100 Mbps*2	10/100 Mbps*2 (Automatic negotiation)	100 Mbps*2
	Configuration file*3		ESI file	EDS file	GSDML file
	I/O occupation area		Input 20 bytes Output 36 bytes	Input 36 bytes Output 36 bytes	Input 36 bytes Output 36 bytes
	Terminating resistor		Not included		
Memory			EEPROM		
LED indicator			PWR, RUN, ALM, ERR	PWR, ALM, MS, NS	PWR, ALM, SF, BF
Cable length [m]			Actuator cable: 20 or less		
Cooling system			Natural air cooling		
Operating temperature range [°C]			0 to 40 (No freezing)		
Operating humidity range [%RH]			90 or less (No condensation)		
Insulation resistance [MΩ]			Between all external terminals and the case: 50 (500 VDC)		
Weight [g]			260 (Screw mounting) 280 (DIN rail mounting)	250 (Screw mounting) 270 (DIN rail mounting)	260 (Screw mounting) 280 (DIN rail mounting)

\*1 Please note that versions are subject to change.

\*2 Use a shielded communication cable with CAT5 or higher for the PROFINET, EtherNet/IP™, and EtherCAT.

\*3 The files can be downloaded from the SMC website.

### ■Trademark

EtherNet/IP® is a registered trademark of ODVA, Inc.

EtherCAT® is registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.

## Example of Operation Command

In addition to the step data input of 64 points maximum in each communication protocol, the changing of each parameter can be performed in real time via numerical data defined operation.

\* Numerical values other than "Moving force," "Area 1," and "Area 2" can be used to perform operation under numerical instructions from JXCL1.

### <Application example> Movement between 2 points

No.	Movement mode	Speed	Position	Acceleration	Deceleration	Pushing force	Trigger LV	Pushing speed	Moving force	Area 1	Area 2	In position
0	1: Absolute	100	10	3000	3000	0	0	0	100	0	0	0.50
1	1: Absolute	100	100	3000	3000	0	0	0	100	0	0	0.50

### <Step no. defined operation>

Sequence 1: Servo ON instruction

Sequence 2: Instruction to return to origin

Sequence 3: Specify step data No. 0 to input the DRIVE signal.

Sequence 4: Specify step data No. 1 after the DRIVE signal has been temporarily turned OFF to input the DRIVE signal.

### <Numerical data defined operation>

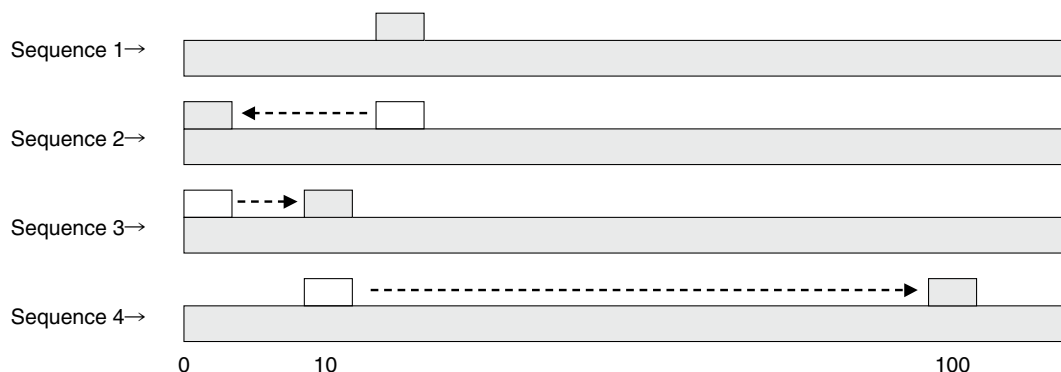
Sequence 1: Servo ON instruction

Sequence 2: Instruction to return to origin

Sequence 3: Specify step data No. 0 and turn ON the input instruction flag (position). Input 10 in the target position. Subsequently the start flag turns ON.

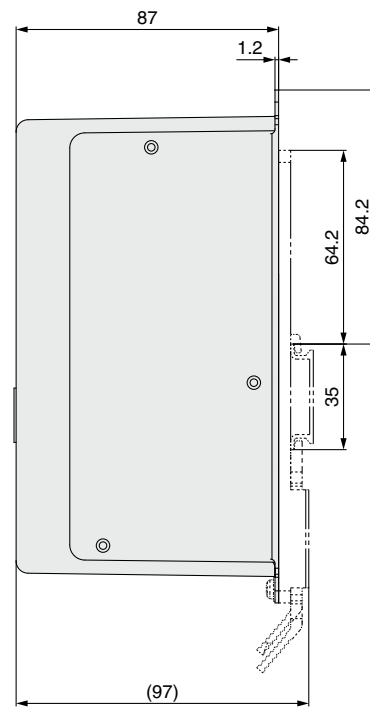
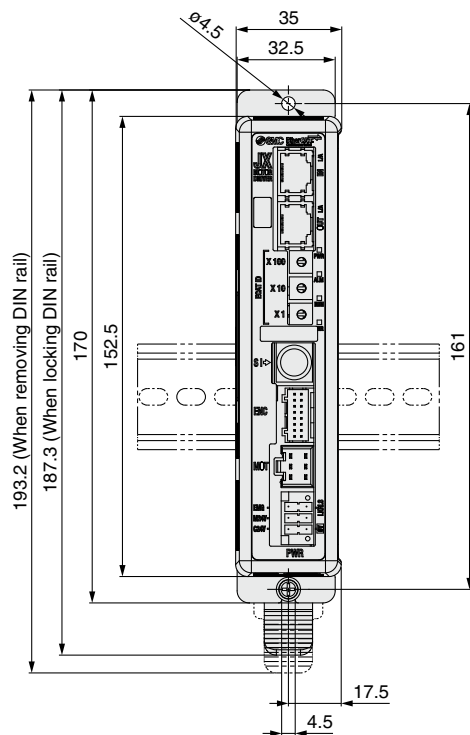
Sequence 4: Turn ON step data No. 0 and the input instruction flag (position) to change the target position to 100 while the start flag is ON.

The same operation can be performed with any operation command.

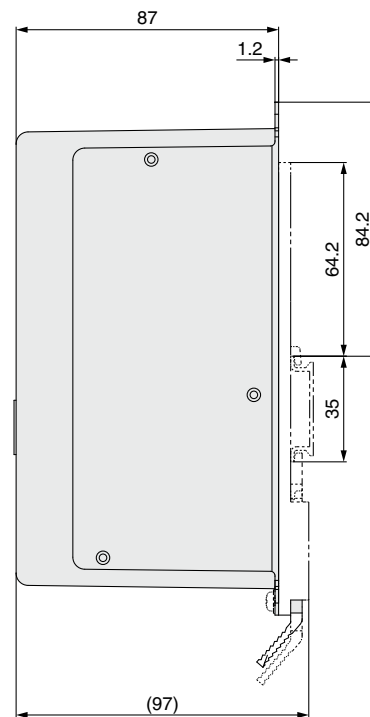
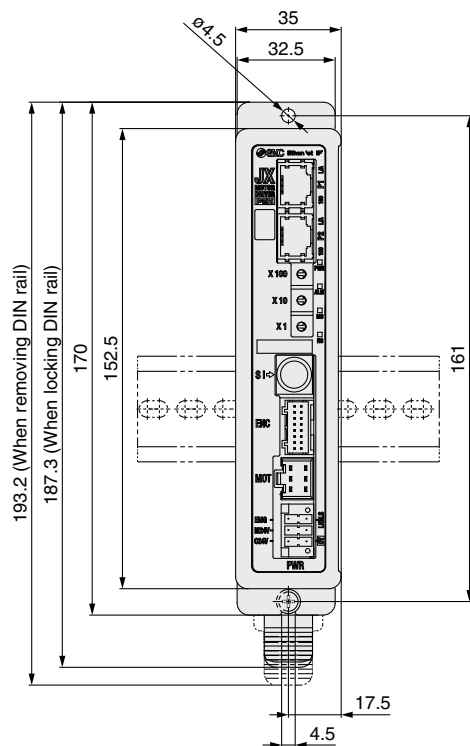


## Dimensions

### JXCEH



### JXC9H



Model Selection

LEKFS ☐ G Series

Auto Switch

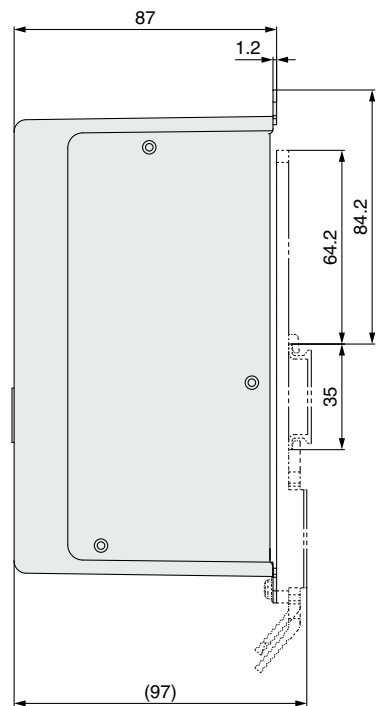
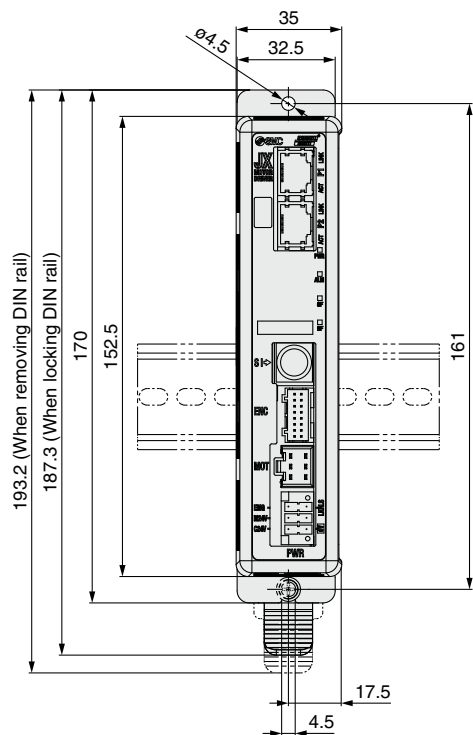
JXC5H/6H Series

JXCEH/9H/PH Series

# JXCEH/9H/PH Series

## Dimensions

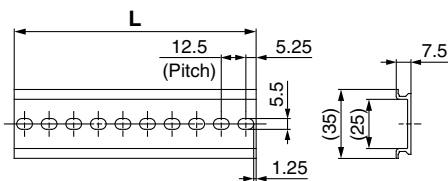
### JXCPH



### DIN rail

#### AXT100-DR-□

\* For □, enter a number from the No. line in the table below.



#### L Dimensions [mm]

No.	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
L	23	35.5	48	60.5	73	85.5	98	110.5	123	135.5	148	160.5	173	185.5	198	210.5	223	235.5	248	260.5
No.	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40
L	273	285.5	298	310.5	323	335.5	348	360.5	373	385.5	398	410.5	423	435.5	448	460.5	473	485.5	498	510.5

### DIN rail mounting adapter

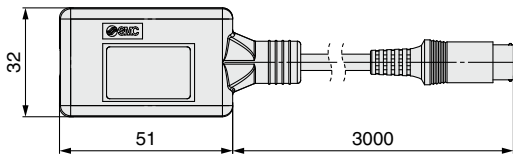
#### LEC-3-D0 (with 2 mounting screws)

This should be used when the DIN rail mounting adapter is mounted onto a screw mounting type controller afterward.

## Options

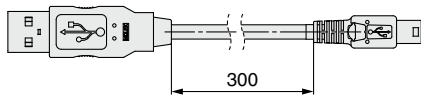
### ■ Communication cable for controller setting

#### ① Communication cable JXC-W2A-C



\* It can be connected to the controller directly.

#### ② USB cable LEC-W2-U



#### ③ Controller setting kit JXC-W2A

A set which includes a communication cable (JXC-W2A-C) and a USB cable (LEC-W2-U)

<Controller setting software/USB driver>

- Controller setting software
- USB driver (For JXC-W2A-C)

Download from SMC's website: <https://www.smcworld.com>

#### Hardware Requirements

OS	Windows®7, Windows®8.1, Windows®10
Communication interface	USB 1.1 or USB 2.0 ports
Display	1024 x 768 or more

\* Windows®7, Windows®8.1 and Windows®10 are registered trademarks of Microsoft Corporation in the United States.

### ■ DIN rail mounting adapter LEC-3-D0

\* With 2 mounting screws

This should be used when the DIN rail mounting adapter is mounted onto a screw mounting type controller afterward.

### ■ DIN rail AXT100-DR-□

\* For □, enter a number from the No. line in the table on page 41. Refer to the dimension drawings on pages 40 and 41 for the mounting dimensions.

### ■ Teaching box

**LEC-T1-3JG**

Teaching box

Cable length [m]

3	3
---	---

Initial language

J	Japanese
E	English

\* The displayed language can be changed to English or Japanese.

Enable switch (Option)

Nil	None
S	Equipped with enable switch

\* Interlock switch for jog and test function

Stop switch

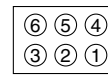
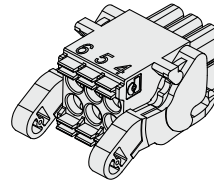
G	Equipped with stop switch
---	---------------------------

#### Specifications

Item	Description
Switch	Stop switch, Enable switch (Option)
Cable length [m]	3
Enclosure	IP64 (Except connector)
Operating temperature range [°C]	5 to 50
Operating humidity range [%RH]	90 or less (No condensation)
Weight [g]	350 (Except cable)

### ■ Power supply plug JXC-CPW

\* The power supply plug is an accessory.

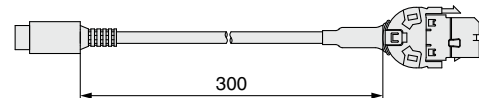


- |        |          |
|--------|----------|
| ① C24V | ④ 0V     |
| ② M24V | ⑤ N.C.   |
| ③ EMG  | ⑥ LK RLS |

#### Power supply plug

Terminal name	Function	Details
0V	Common supply (-)	The M24V terminal, C24V terminal, EMG terminal, and LK RLS terminal are common (-).
M24V	Motor power supply (+)	Motor power supply (+) of the controller
C24V	Control power supply (+)	Control power supply (+) of the controller
EMG	Stop (+)	Connection terminal of the external stop circuit
LK RLS	Lock release (+)	Connection terminal of the lock release switch

### ■ Conversion cable P5062-5 (Cable length: 300 mm)



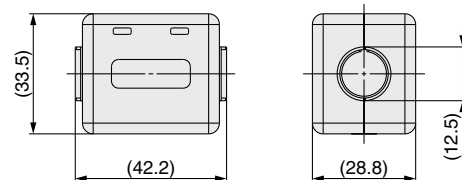
\* To connect the teaching box (LEC-T1-3□G□) or controller setting kit (LEC-W2) to the controller, a conversion cable is required.

### ■ Noise filter set

#### LEC-NFA

Contents of the set: 2 noise filters

(Manufactured by WURTH ELEKTRONIK: 74271222)



\* Refer to the JXCEH/PH series Operation Manual for installation.

**JXC5H/6H Series**  
**JXCEH/9H/PH Series**

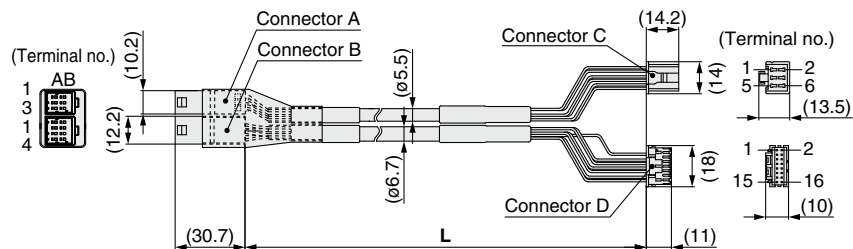
**[Robotic cable for battery-less absolute (Step motor 24 VDC)]**

## LE - CE - 1

**Cable length (L) [m]**

<b>1</b>	1.5
<b>3</b>	3
<b>5</b>	5
<b>8</b>	8*1
<b>A</b>	10*1
<b>B</b>	15*1
<b>C</b>	20*1

\*1 Produced upon receipt of order



### Weight

Product no.	Weight [g]	Note
<b>LE-CE-1</b>	190	Robotic cable
<b>LE-CE-3</b>	360	
<b>LE-CE-5</b>	570	
<b>LE-CE-8</b>	900	
<b>LE-CE-A</b>	1120	
<b>LE-CE-B</b>	1680	
<b>LE-CE-C</b>	2210	

Signal	Connector A terminal no.		Cable color	Connector C terminal no.
A	B-1		Brown	2
$\bar{A}$	A-1		Red	1
B	B-2		Orange	6
$\bar{B}$	A-2		Yellow	5
COM-A/COM	B-3		Green	3
COM-B/—	A-3		Blue	4

Signal	Connector B terminal no.		Cable color	Connector D terminal no.
Vcc	B-1		Brown	12
GND	A-1		Black	13
$\bar{A}$	B-2		Red	7
A	A-2		Black	6
$\bar{B}$	B-3		Orange	9
B	A-3		Black	8
SD+ (RX)	B-4		Yellow	11
SD- (TX)	A-4		Black	10
			Black	3

**[Robotic cable with lock for battery-less absolute (Step motor 24 VDC)]**

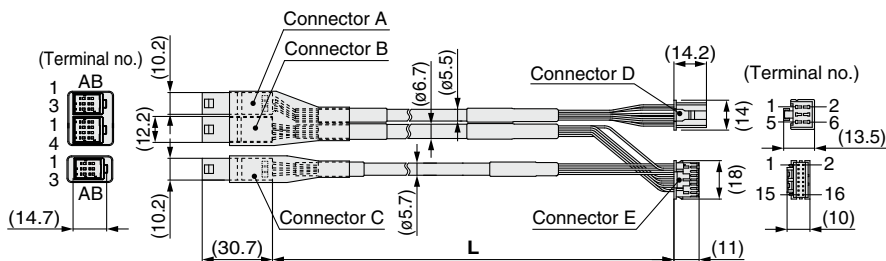
**LE-CE-1-B**

**Cable length (L) [m]**

<b>1</b>	1.5
<b>3</b>	3
<b>5</b>	5
<b>8</b>	8*1
<b>A</b>	10*1
<b>B</b>	15*1
<b>C</b>	20*1

\*1 Produced upon receipt of order

**With lock and sensor** ●



## Weight

Product no.	Weight [g]	Note
<b>LE-CE-1-B</b>	240	Robotic cable
<b>LE-CE-3-B</b>	460	
<b>LE-CE-5-B</b>	740	
<b>LE-CE-8-B</b>	1170	
<b>LE-CE-A-B</b>	1460	
<b>LE-CE-B-B</b>	2120	
<b>LE-CE-C-B</b>	2890	

Signal	Connector A terminal no.		Cable color	Connector D terminal no.
A	B-1		Brown	2
$\bar{A}$	A-1		Red	1
B	B-2		Orange	6
$\bar{B}$	A-2		Yellow	5
COM-A/COM	B-3		Green	3
COM-B/—	A-3		Blue	4
Signal	Connector B terminal no.		Cable color	Connector E terminal no.
Vcc	B-1		Brown	12
GND	A-1		Black	13
$\bar{A}$	B-2		Red	7
A	A-2		Black	6
$\bar{B}$	B-3		Orange	9
B	A-3		Black	8
SD+ (RX)	B-4		Yellow	11
SD- (TX)	A-4		Black	10
Signal	Connector C terminal no.			
Lock (+)	B-1		Red	4
Lock (-)	A-1		Black	5
Sensor (+)	B-3		Brown	1
Sensor (-)	A-3		Blue	2





# JXC□1/JXC□F/JXC□H Series

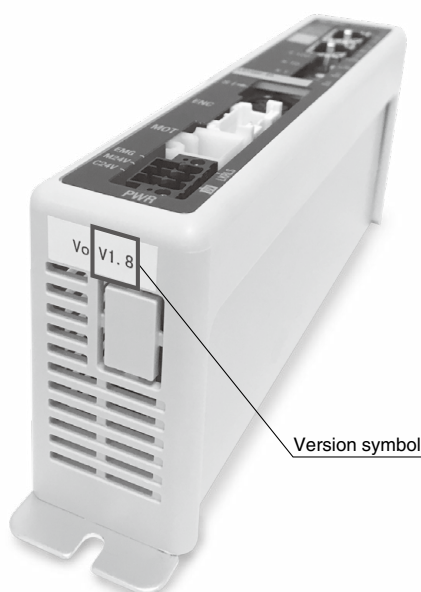
## Precautions Relating to Differences in Controller Versions

As the controller version of the JXC series differs, the internal parameters are not compatible.

- If using the JXC□1□-BC, please use the latest version of the JXC-BCW (parameter writing tool).
- There are currently 3 versions available: version 1 products (V1.□ or S1.□), version 2 products (V2.□ or S2.□), and version 3 products (V3.□ or S3.□). Keep in mind that in order to write a backup file (.bkp) to another controller with the JXC-BCW, it needs to be the same version as the controller that created the file. (For example, a backup file created by a version 1 product can only be written to another version 1 product, and so on.)

### Identifying Version Symbols

#### JXC□□ Series Version V3.□ or S3.□ Products



XR V3.0

**Applicable models**  
JXC91 Series

XR S3.0 T1.0

**Applicable models**  
JXC51 Series  
JXC61 Series  
JXCE□ Series  
JXCP1 Series  
JXCD1 Series  
JXCL□ Series  
JXCM1 Series

#### JXC□□ Series Version V2.□ or S2.□ Products

WP V2.1

**Applicable models**  
JXC91 Series

WP S2.2 T1.1

**Applicable models**  
JXCE□ Series  
JXCP1 Series  
JXCD1 Series  
JXCL□ Series

#### JXC□□ Series Version V1.□ or S1.□ Products

XR V1.0

**Applicable models**  
JXC91 Series

XR S1.0 T1.0

**Applicable models**  
JXCE□ Series  
JXCP□ Series  
JXCD1 Series  
JXCL□ Series  
JXC5H Series  
JXC6H Series

Model Selection

LEKFS□G Series

Auto Switch

JXC5H/6H Series

JXCEH/9H/PH Series

## Blank Controller Versions and Applicable Battery-less Absolute Type Electric Actuator Sizes

- The applicable battery-less absolute type electric actuator size range differs depending on the controller version.  
Be sure to confirm the controller version before using a blank controller.

### Blank Controller Versions/Applicable Electric Actuator Sizes (JXC□H Series)

Blank controller		Applicable electric actuator size				
Series	Controller version	LEFS□G	LEKF□G	LEY□G	LEG	LESYH□G
<b>JXC9H series</b> <b>JXCEH series</b> <b>JXCPH series</b>	All versions	16, 25, 32, 40	25, 32, 40	16, 25, 40	25, 32, 40	8, 16, 25
<b>JXC5H/6H series</b>	Version 1.0	25, 32, 40		25, 40		16, 25
	Version 1.1 or higher	16, 25, 32, 40		16, 25, 40		8, 16, 25



# LEKFS□G Series

## Battery-less Absolute Encoder Type Specific Product Precautions

Be sure to read this before handling the products. Refer to the back cover for safety instructions. For electric actuator precautions, refer to the "Handling Precautions for SMC Products" and the "Operation Manual" on the SMC website: <https://www.smcworld.com>

### Handling

#### ⚠ Caution

##### 1. Absolute encoder ID mismatch error at the first connection

In the following cases, an "ID mismatch error" alarm occurs after the power is turned ON. Perform a return to origin operation after resetting the alarm before use.

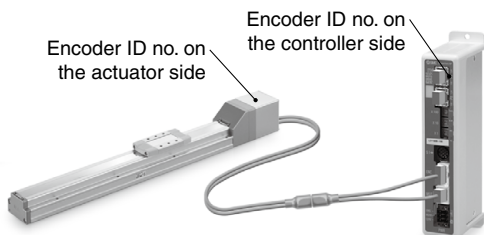
- When an electric actuator is connected and the power is turned ON for the first time after purchase\*1
- When the actuator or motor is replaced
- When the controller is replaced

\*1 If you have purchased an electric actuator and controller with the set part number, the pairing may have already been completed and the alarm may not be generated.

##### "ID mismatch error"

Operation is enabled by matching the encoder ID on the electric actuator side with the ID registered in the controller. This alarm occurs when the encoder ID is different from the registered contents of the controller. By resetting this alarm, the encoder ID is registered (paired) to the controller again.

When a controller is changed after pairing is completed				
	Encoder ID no. (* Numbers below are examples.)			
Actuator	17623	17623	17623	17623
Controller	17623	17699	17699	17623
ID mismatch error occurred?	No	Yes	Error reset ⇒	No

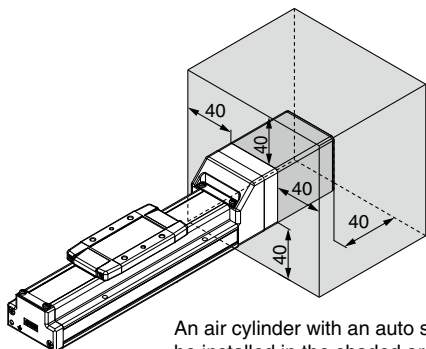


The ID number is automatically checked when the control power supply is turned ON. An error is output if the ID number does not match.

##### 2. In environments where strong magnetic fields are present, use may be limited.

A magnetic sensor is used in the encoder. Therefore, if the actuator motor is used in an environment where strong magnetic fields are present, malfunction or failure may occur. Do not expose the actuator motor to magnetic fields with a magnetic flux density of 1 mT or more.

When installing an electric actuator and an air cylinder with an auto switch (ex. CDQ2 series) or multiple electric actuators side by side, maintain a space of 40 mm or more around the motor. Refer to the construction drawing of the actuator motor.



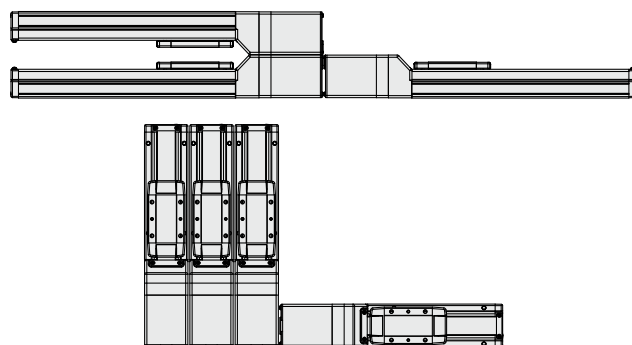
An air cylinder with an auto switch cannot be installed in the shaded area.

##### • When lining up actuators

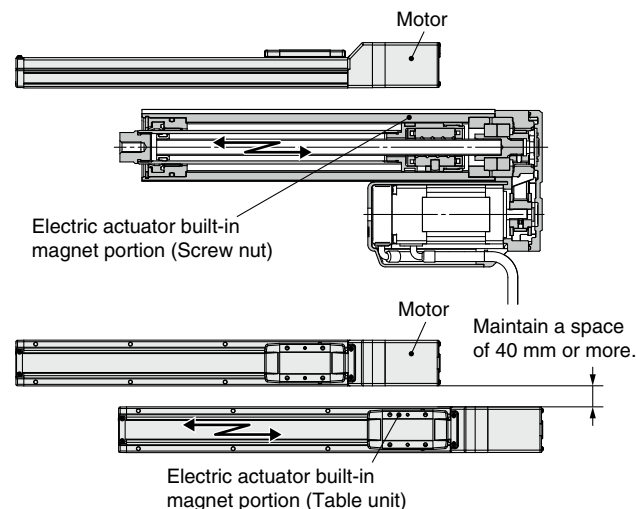
SMC actuators can be used with their motors adjacent to each other. However, for actuators with a built-in auto switch magnet, maintain a space of 40 mm or more between the motors and the position where the magnet passes.

For the LEF series, the magnet is in the middle of the table, and for the LEY series, the magnet is in the piston portion. (Refer to the construction drawings in the catalog for details.)

○ Can be used with their motors adjacent to each other

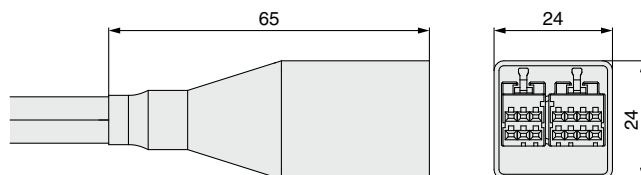


✗ Do not allow the motors to be in close proximity to the position where the magnet passes.



##### 3. The connector size of the motor cable is different from that of the electric actuator with an incremental encoder.

The motor cable connector of an electric actuator with a battery-less absolute encoder is different from that of an electric actuator with an incremental encoder. As the connector cover dimensions are different, take the dimensions below into consideration during the design process.



Battery-less absolute encoder connector cover dimensions

# CE/UKCA/UL-compliance List

\* For CE, UKCA, and UL-compliant products, refer to the tables below.

As of February 2022

## ■ Controllers “○”: Compliant “x”: Not compliant

Compatible motor	Series	CE UK CA	cUL <sup>us</sup>	
			Compliance	Certification No. (File No.)
High performance (Step motor 24 VDC)	<b>JXC5H/6H</b>	○	○	E480340
	<b>JXCEH</b>	○	○	E480340
	<b>JXC9H</b>	○	○	E480340
	<b>JXCPH</b>	○	○	E480340

## ■ Actuators “○”: Compliant “x”: Not compliant


Compatible motor	Series	CE UK CA	cUL <sup>us</sup>	
			Compliance	Certification No. (File No.)
High performance battery-less absolute (Step motor 24 VDC)	<b>LEKFS□G</b>	○	x	—


## ■ Actuators (When ordered with a controller) “○”: Compliant “x”: Not compliant “—”: Not applicable


Compatible motor	Series	JXC5H/6H			JXCEH			JXC9H			JXCPH		
		CE UK CA	cUL <sup>us</sup>		CE UK CA	cUL <sup>us</sup>		CE UK CA	cUL <sup>us</sup>		CE UK CA	cUL <sup>us</sup>	
			Compliance	Certification No. (File No.)		Compliance	Certification No. (File No.)		Compliance	Certification No. (File No.)		Compliance	Certification No. (File No.)
High performance battery-less absolute (Step motor 24 VDC)	<b>LEKFS□G</b>	○	x	—	○	x	—	○	x	—	○	x	—

## Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of “**Caution**,” “**Warning**” or “**Danger**.” They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC)\*1), and other safety regulations.

 **Caution:** **Caution** indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.

 **Warning:** **Warning** indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.

 **Danger :** **Danger** indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.

\*1) ISO 4414: Pneumatic fluid power – General rules relating to systems.  
ISO 4413: Hydraulic fluid power – General rules relating to systems.  
IEC 60204-1: Safety of machinery – Electrical equipment of machines.  
(Part 1: General requirements)  
ISO 10218-1: Manipulating industrial robots – Safety.  
etc.

### Warning

#### 1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications.

Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results. The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product. This person should also continuously review all specifications of the product referring to its latest catalog information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

#### 2. Only personnel with appropriate training should operate machinery and equipment.

The product specified here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained and experienced.

#### 3. Do not service or attempt to remove product and machinery/equipment until safety is confirmed.

1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.
2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant products carefully.
3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.

#### 4. Contact SMC beforehand and take special consideration of safety measures if the product is to be used in any of the following conditions.

1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
2. Installation on equipment in conjunction with atomic energy, railways, air navigation, space, shipping, vehicles, military, medical treatment, combustion and recreation, or equipment in contact with food and beverages, emergency stop circuits, clutch and brake circuits in press applications, safety equipment or other applications unsuitable for the standard specifications described in the product catalog.
3. An application which could have negative effects on people, property, or animals requiring special safety analysis.
4. Use in an interlock circuit, which requires the provision of double interlock for possible failure by using a mechanical protective function, and periodical checks to confirm proper operation.

### Caution

#### 1. The product is provided for use in manufacturing industries.

The product herein described is basically provided for peaceful use in manufacturing industries.  
If considering using the product in other industries, consult SMC beforehand and exchange specifications or a contract if necessary.  
If anything is unclear, contact your nearest sales branch.

## Limited warranty and Disclaimer/ Compliance Requirements

The product used is subject to the following “Limited warranty and Disclaimer” and “Compliance Requirements”.

Read and accept them before using the product.

### Limited warranty and Disclaimer

1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered, whichever is first.\*2)  
Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.
2. For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided.  
This limited warranty applies only to our product independently, and not to any other damage incurred due to the failure of the product.
3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalog for the particular products.

#### \*2) Vacuum pads are excluded from this 1 year warranty.

A vacuum pad is a consumable part, so it is warranted for a year after it is delivered.  
Also, even within the warranty period, the wear of a product due to the use of the vacuum pad or failure due to the deterioration of rubber material are not covered by the limited warranty.


### Compliance Requirements

1. The use of SMC products with production equipment for the manufacture of weapons of mass destruction (WMD) or any other weapon is strictly prohibited.
2. The exports of SMC products or technology from one country to another are governed by the relevant security laws and regulations of the countries involved in the transaction. Prior to the shipment of a SMC product to another country, assure that all local rules governing that export are known and followed.

### Caution

#### SMC products are not intended for use as instruments for legal metrology.

Measurement instruments that SMC manufactures or sells have not been qualified by type approval tests relevant to the metrology (measurement) laws of each country. Therefore, SMC products cannot be used for business or certification ordained by the metrology (measurement) laws of each country.

 **Safety Instructions** Be sure to read the “Handling Precautions for SMC Products” (M-E03-3) and “Operation Manual” before use.

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