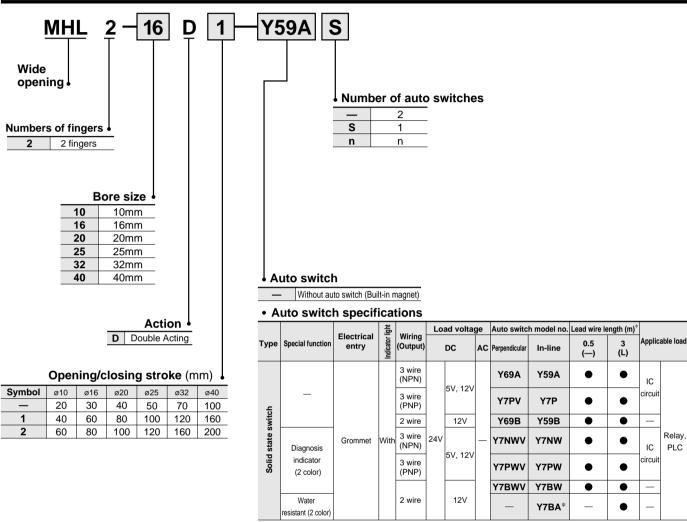


Parallel Style/ø10, ø16, ø25, ø20, ø32, ø40

How to Order



*Lead wire length symbol: 0.5m····· (Example) Y59B 3m·····L (Example) Y59BL



Refer to p.2.11-1 for auto switch specifications. *Y7BA is applicable to "-X5" oil proof type (p.2.2-6).

Wide Opening Air Gripper Series MHL2

One unit can handle workpieces with various diameters

A large amount of gripping force is provided through the use of a double piston mechanism, while maintaining a compact design

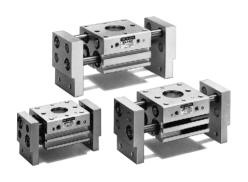
Double end type oil impregnated resin bearings with a metal backing are used for all shafts

Fingers synchronized by a rack and pinion mechanism

Built-in dust proofing mechanism

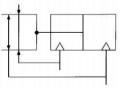
A high degree of freedom for mounting

Auto switch capable









Specifications

Bore size (mm)	10	16	20	25	32	40
Fluid			А	ir		
Action			Double	acting		
Operating pressure (MPa)	0.15 to 0.6	0.15 to 0.6				
Ambient and fluid temperature			–10 to	60°C		
Repeatability	±0.1					
Lubrication	Not required					
Effective holding force (N) at 0.5MPa ⁽¹⁾	14	45	74	131	228	396

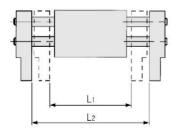
Note 1) Holding point = Bore size 10, 16, 20, 25: 40mm, Bore size 32, 40: 80mm.

Model/Stroke

Model	Bore size (mm)	Max operating frequency (c.p.m)	Opening/closing stroke (L2–L1)(mm)	Width at closing (mm) (L1)	Width at opening (mm) (L2)	Weight (g)
MHL2-10D		60	20	56	76	280
MHL2-10D1	10	40	40	78	118	345
MHL2-10D2		40	60	96	156	425
MHL2-16D		60	30	68	98	585
MHL2-16D1	16	40	60	110	170	795
MHL2-16D2		40	80	130	210	935
MHL2-20D		60	40	82	122	1025
MHL2-20D1	20	40	80	142	222	1495
MHL2-20D2		40	100	162	262	1690
MHL2-25D		60	50	100	150	1690
MHL2-25D1	25	40	100	182	282	2560
MHL2-25D2		40	120	200	320	2775
MHL2-32D		30	70	150	220	2905
MHL2-32D1	32	20	120	198	318	3820
MHL2-32D2		20	160	242	402	4655
MHL2-40D		30	100	188	288	5270
MHL2-40D1	40	20	160	246	406	6830
MHL2-40D2		20	200	286	486	7905

 \bigcirc

Note) The open and close time spans represent the value when the exterior of the workpiece is being held.



MHY2 MHW2

MRHQ

MHZ2

MHZJ2

MHQ

MHL₂

MHR

MHK

MHS

MHC₂

MHT2

Auto switch

⚠Caution

Be sure to read before handling.

Refer to p.0-20 and 0-21 for Safety Instructions and common precautions on the products mentioned in this catalog, and refer to p.2.0-3 and 2.0-4 for precautions on every series.

⚠ Warning

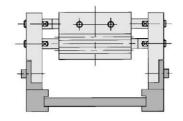
If a workpiece is hooked onto the attachment, make sure that excessive impact will not be created at the start and the end of the movement. Failure to observe this precaution may result in shifting or dropping the workpiece, which could be dangerous.

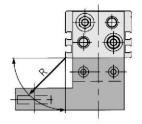
Series MHL2

Holding Point

- •Make sure that the workpiece gripping point distance is within the range of the gripping force lines indicated by each pressure in the effective gripping force graph.
- •If it is used in an area in which the workpiece gripping point distance is longer than the length indicated in the diagram, the load that will be applied to the fingers or the guide will become excessively unbalanced.

As a result, the fingers could become loosened and adversely affect the service life of the unit.



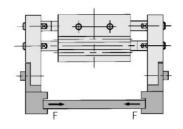


R: Holding position mm

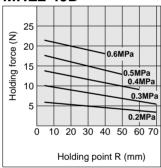
Effective Holding Force

Indication of effective holding force

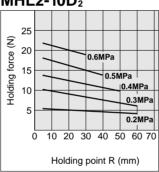
The holding force shown in the tables represents the holding force of one finger when all fingers and attachments are in contact with the work. F = one finger thrust.



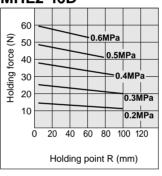
MHL2-10D



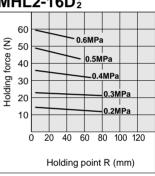
MHL2-10D₂



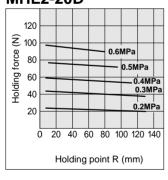
MHL2-16D



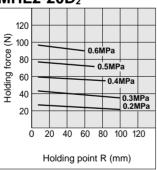
MHL2-16D₂



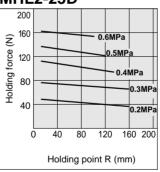
MHL2-20D

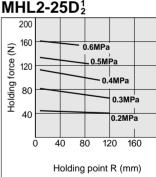


MHL2-20D₂

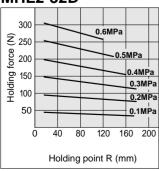


MHL2-25D

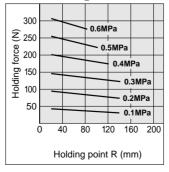




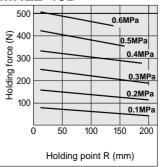
MHL2-32D



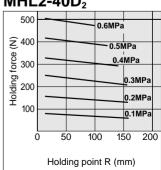
MHL2-32D3



MHL2-40D

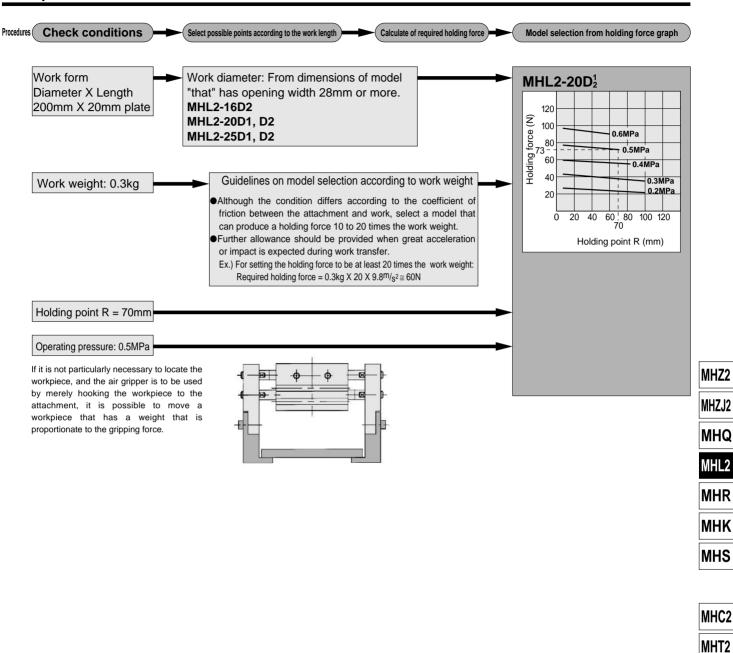


MHL2-40D¹



Wide Opening Air Gripper Series MHL2

Example of Model Selection

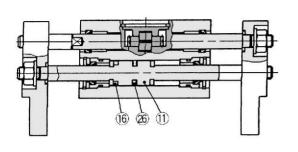


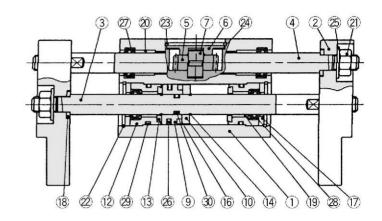
MHY2

MHW2

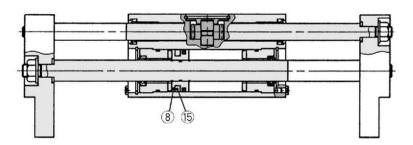
MRHQ Auto switch ø10

ø16 to ø25





ø32, ø40



Component Parts

No.	Description	Material	Note
1	Body	Aluminum alloy	Anodized
2	Finger	Aluminum alloy	Anodized
3	Piston rod	Stainless steel	
4	Rack	Sainless steel	
(5)	Pinion	Carbon steel	
6	Pinion cover	Carbon steel	Electroless nickel plated
7	Pinion axis	Stainless steel	Nitriding
8	Piston	Brass	
9	Piston A	Brass	
10	Piston B	Brass	
11)	Piston A	Stainless steel	
12	Rod cover	Aluminum alloy	Chromate treated
13	Damper	Urethane rubber	
14)	Clip	Stainless steel wire for spring	
15)	Rubber magnet	Synthetic rubber	

No.	Description	Material	Note		
16	Magnet	Magnet material	Nickel plated		
17)	Rod seal cover B	Cold-rolled steel	Electroless nickel plated		
18)	Washer	Stainless steel	Nitriding		
19	Bearing	Oil containing polyacetal with back metal			
20	Bearing	Oil containing polyacetal with back metal			
21)	U nut	Carbon steel	Nickel plated		
22	R-shape snap ring	Carbon steel	Nickel plated		
23	C-shape snap ring	Carbon steel	Nickel plated		
24)	Wave washer	Steel for spring	Phosphate coating		
25)	Conical spring washer	Carbon steel	Nickel plated		

Replacement Parts/Seal Kits

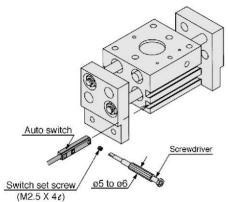
	Topiacomont i altoroda i tito									
No.	Description	Material	Kit No.							
NO.			MHL2-10D□	MHL2-16D□	MHL2-20D□	MHL2-25D□	MHL2-32D□	MHL2-40D□		
26										
27)										
28	Seal kit Note)	NBR	MHL10-PS	MHL16-PS	MHL20-PS	MHL25-PS	MHL32-PS	MHL40-PS		
29										
30										

Note) No. 36, 27, 38, 39, 30 are included.

Wide Opening Air Gripper Series MHL2

Setting Method of Auto Switch

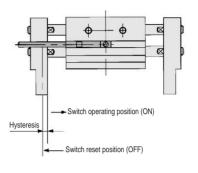
To set the auto switch, insert the auto switch into the switch groove of the air gripper from the direction indicated in the following drawing. After setting the position, tighten the attached switch mounting set screw with a straight bladed watchmakers screwdriver.



Note)Use a watchmakers screwdriver with a grip diameter of 5 to 6mm to tighten the auto switch set screw. Use a tightening torque of 0.05 to 0.1 Nm. As a rough guide, tighten the screw an additional 90° after feeling a tight resistance.

Auto Switch Hysteresis

Auto switch hysteresis is as follows. Please refer to the table as a guide when setting auto switch positions.



Unit: mm

Auto switch model	D-Y59∄ D-Y69∄	D-Y7NW	D-Y7BWV	D-Y7BA
MHL2-10D□	0.8	0.6	0.7	0.5
MHL2-16D□	0.5	0.3	0.3	0.2
MHL2-20D□	0.5	0.2	0.3	0.2
MHL2-25D□	0.2	0.2	0.2	0.1
MHL2-32D□	0.4	0.7	0.7	0.4
MHL2-40D□	0.2	0.7	0.6	0.4

MHZ2

MHZJ2

MHL2

MHR

MHK

MHS

MHC₂

MHT2

MHY2

MHW2

MRHQ Auto switch

Made to Order Specifications



MHL2 - Cylinder bore size D Stroke symbol - Solid state switch - X 5

The packing class has been revised to adopt oil-proof materials for using it in an environment with splashing of cut liquid splashing etc.

Specifications

Туре	Oil proof
Bore size	ø10, ø16, ø20 ø25, ø32, ø40
Action	Double acting
Fluid	Air
Material	Sealing, Gascket-Fluoro rubber
Applicable auto switch	D-Y7BAL

Notes) Some liquid may make the use of an air gripper or auto switch impossible Confirm the kind of the questionable liquid and consult SMC for the use. The dimensions are the same as the standard type.

Thermal proof

MHL2 - Cylinder bore size D Stroke symbol - X 4

The packing class has been revised to adopt thermal proof materials for using it at high temperature of up to 100°C.

Specifications

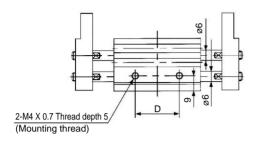
Туре	Thermal proof
Bore size	ø10, ø16, ø20, ø25, ø32, ø40
Action	Double acting
Fluid	Air
Material	Sealing, Gasket-Fluoro rubber
	•

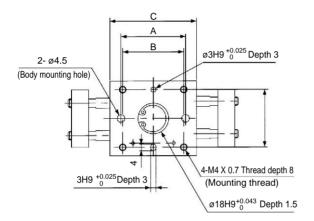
Notes) Items with auto switch can not be manufactured.

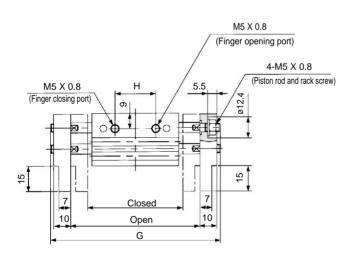
The dimensions are the same as the standard type.

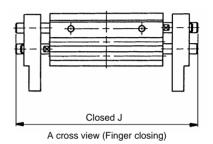


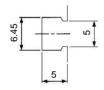
MHL2-**10**D□



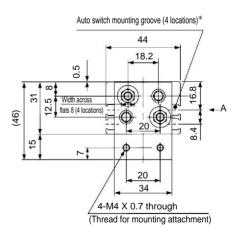




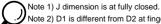




* Dimensions of auto switch mounting groove (Enlarged view)



Model	Α	В	С	D	Ε	F	G	Н	J
MHL2-10D	38	36	51	26	56	76	100	24	80
MHL2-10D1	54	52	67	42	78	118	142	39	108
MHL2-10D2	72	70	85	60	96	156	180	57	146



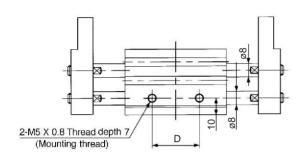
Note 2) D1 is different from D2 at finger closed because shaft is ejected from finger end. J dimension is different from the value which is subtracted stroke from G dimension.

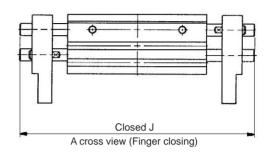


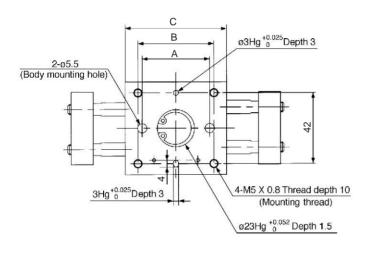
MHL2-10DSMHL. #1 MHL2-10D1.....SMHL2A, #1 MHL2-10D2.....SMHL2A, #2

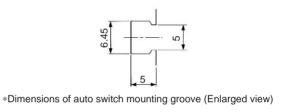


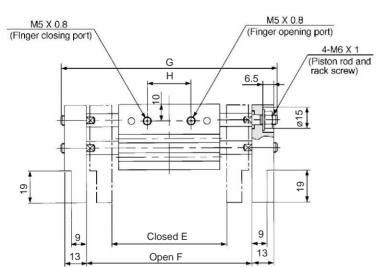
MHL2-16D□











Auto swich mounting groove (4 locations)*
55 22.6
8 Width across flats 10 (4 locations) 25
± 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
4-M5 X 0.8 through (Thread for mounting attachment)

Model	Α	В	С	D	E	F	G	Н	J
MHL2-16D	40	45	60	28	68	98	128	26	98
MHL2-16D1	70	75	90	58	110	170	200	50	152
MHL2-16D2	90	95	110	78	130	210	240	70	192
$\overline{}$									

Notes) J dimension is at fully closed position.

D1 is different from D2 at finger closed position because shaft is ejected from finger end. J dimension is different from the value which is subtracted stroke from G dimension.



MHL2

MHZ2

MHZJ2

MHQ

MHR

MHK

MHS

MHC2

MHT2

MHW2

MRHQ

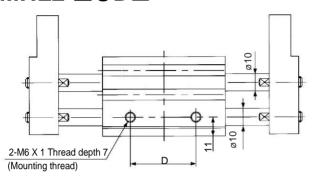
Auto switch

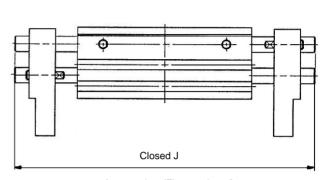
Series MHL2



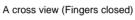


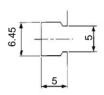
MHL2-**20**D□



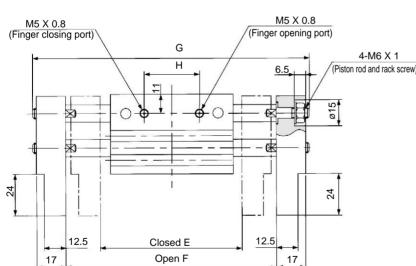


С В ø4H9 +0 030 Depth 4 Α 2-ø6.6 (Body mounting hole) 52 4-M6 X 1 Thread depth 12 (Mounting thread) 4H9 +0 030 Depth 4 ø27H9 +0 052 Depth 1.5





*Dimensions of auto switch mounting groove (Enlarged view)



		Auto sv	vitch mounting groove (4 locations)*
v)			65
	(70)	46 20 10	Width across flais 10 (4 locations)
	2	24	30
			4-M6 X 1 through (Thread for mounting attachment)

Model	Α	В	С	D	E	F	G	Н	J
MHL2-20D	54	58	71	38	82	122	160	32	120
MHL2-20D1	96	100	113	80	142	222	260	68	195
MHL2-20D2	116	120	133	100	162	262	300	88	235

Notes) J dimension is at fully closed.

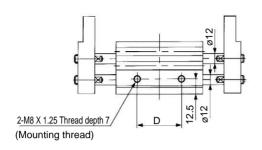
D1 is different from D2 at finger closed because shaft is ejected from finger end.

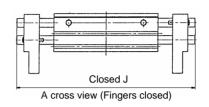
J dimension is different from the value which is subtracted stroke from G dimension.

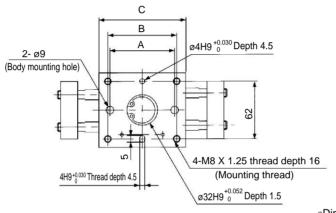
MHL2-20D SMHL, #3 MHL2-20D1 SMHL2B, #1 MHL2-20D2 SMHL2B, #2

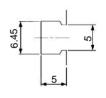


MHL2-**25**D□

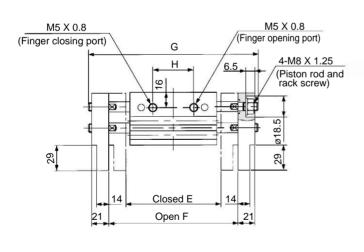


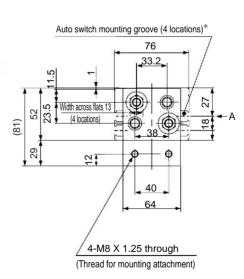






*Dimensions of auto switch mounting groove (Enlarged view)





Model		Α	В	C	D	E	F	G	Н	J
MHL2-25	5D	66	70	88	48	100	150	196	38	146
MHL2-25	5D1	120	124	142	102	182	282	328	86	244
MHL2-25	5D2	138	142	160	120	200	320	366	104	282
_										

Note 1) J dimension is at fully closed.

Note 2) D1 is different from D2 at finger closed because shaft is ejected from finger end.

J dimension is different from the value which is subtracted stroke from G dimension.



MHZ2

MHZJ2

MHQ

MHL2 MHR

MHK

MHS

MHC2

MHT2

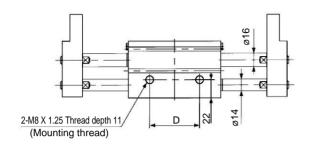
MHY2

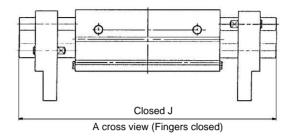
MHW2

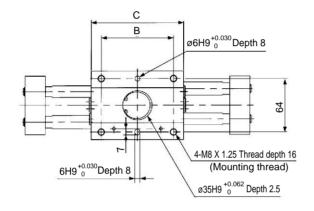
MRHQ Auto switch



MHL2-32D

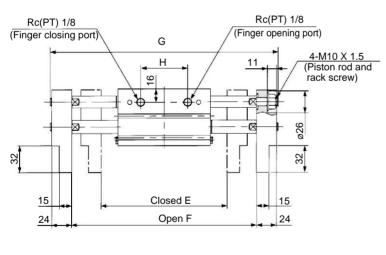


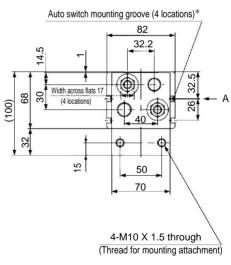






*Dimensions of auto switch mounting groove (Enlarged view)



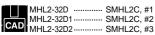


Model	В	С	D	Е	F	G	Н	J
MHL2-32D	86	110	60	150	220	272	56	202
MHL2-32D1	134	158	108	198	318	370	104	282
MHL2-32D2	178	202	152	242	402	454	148	366

Note 1) J dimension is at fully closed.

Note 2) D1 is different from D2 at finger closed because shaft is ejected from finger end.

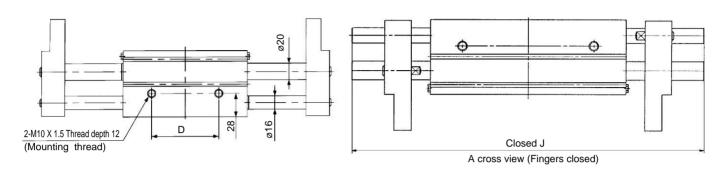
J dimension is different from the value which is subtracted stroke from G dimension.

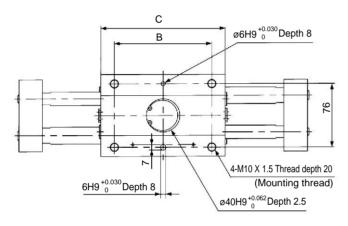






MHL2-40D







60

86

4-M12 X 1.75 through

(Thread for mounting attachment)

MHZ2

MHZJ2

MHQ

MHL2

MHW2

MRHQ

Auto

switch

*Dimensions of auto switch mounting groove (Enlarged view)

MHR Rc(PT) 1/8 Auto switch mounting groove (4 locations)* Rc(PT) 1/8 (Finger opening port) (Finger closing port) MHK G 2-M10 X 1.5 40.2 Н 11 (Rack screw) MHS 39 Width across flats 17 (2 locations) 9 MHC2 Width across flats 19 MHT2 38 (2 locations) 38 38 MHY2

18

28

2-M12 X 1.75

(Piston rod screw)

Model	В	С	D	Е	F	G	Н	J
MHL2-40D	116	148	80	188	288	348	72	252
MHL2-40D1	174	206	138	246	406	466	130	336
MHL2-40D2	214	246	178	286	486	546	170	450

Closed E

Open F

Notes) J dimension is at fully closed.

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D1 is different from D2 at finger closed because shaft is ejected from finger end.

J dimension is different from the value which is subtracted stroke from G dimension.

MHL2-40D.....SMHL2C, #4 MHL2-40D1.....SMHL2C, #5 MHL2-40D2.....SMHL2C, #6 (#6+#7)