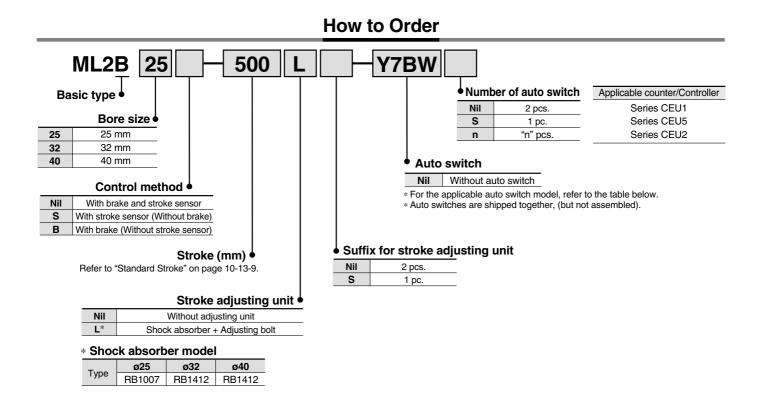
Stroke Reading Rodless Cylinder with Brake Series ML2B

ø25, ø32, ø40



Applicable Auto Switch/Refer to page 10-20-1 for further information on auto switches.

			Indicator light			Load volta	age	Auto switch model		Lead wire le	ngth	(m)*								
Туре	Special function	Electrical	ator	Wiring		2	AC	Auto Swite	Shimodel	0.5	3	5	Pre-wire	Applic	able load					
		entry	lidi Di	(Output)		DC	AC	Perpendicular	In-line	(Nil)	(L)	(Z)	connector							
고등			l o	3-wire		5 V			Z76											
Reed switch	-	Grommet	×	(NPN equivalent)	_	50	_		2/0	•	•	_	_		_					
шS			ļ -	2-wire	24 V	12 V	100 V	—	Z73		۲	\bullet	_	—	Relay, PLC					
				3-wire (NPN)		5 V. 12 V		Y69A	Y59A	•										
te	_			3-wire (PNP)))	-	24 V	-		5 V, 12 V		Y7PV	Y7P	•	۲	0	0		
tch		Grommet	es	2-wire							24 V 12 V	_	Y69B	Y59B	•	\bullet	0	0	—	Relay,
swi	Graden indication Graden indication Graden indication	0	⊁	3-wire (NPN)	<u> </u>		534 4034	Y7NWV	Y7NW	•	۲	0	0		PLC					
S,	(2-color indication)			3-wire (PNP)		5 V, 12 V		Y7PWV	Y7PW	•	\bullet	0	0		C circuit C circuit C circuit C circuit					
				2-wire		12 V		Y7BWV	Y7BW			0	0	—						
* Lead v	* Lead wire length symbols: 0.5 mNil (Example) Y59A * Solid state switches marked with "O" are produced upon receipt of order.																			

* Lead wire length symbols. 0.5 m

3 m ······· L (Example) Y59AL 5 m ······ Z (Example) Y59AZ

• Since there are other applicable auto switches than listed, refer to page 10-13-17 for details.

• For details about auto switches with pre-wire connector, refer to page 10-20-66.

Stroke Reading Rodless Cylinder with Brake Series ML2B



Bore siz	e (mm)	25	32	40		
Fluid		Air				
Cylinder		Double acting				
Action	Brake	S	Spring and pneumatic	;		
Operating	Cylinder		0.1 to 0.8 MPa			
pressure range	Brake		0.3 to 0.5 MPa			
Proof pressure	Cylinder	1.2 MPa				
FIOOI pressure	Brake	0.75 MPa				
Ambient and fluid t	emperature	5 to 60°C (No freezing)				
Piston speed		100 to 1500 mm/s (During the positioning 100 to 500 mm/s)				
Cushion		Air cushion on both sides				
Lubrication		Non-lube				
Stroke tolerance (mm)		0 to 1.8				
Dising part size	Front/Side ported	Rc	1/8	Rc 1/4		
Piping port size	Bottom ported	ø5	ø6	ø8		

Sensor Specifications

Cylinder Specifications

Maximum transmission distance	20 m (In the case of using our cable as well as our controller or counter.)
Position detection method	Incremental type
Magnetic field resistance	14.5 mT
Power supply	10.8 to 13.2 VDC (Ripple less than 1%)
Current consumption	40 mA
Resolution	0.1 mm/pulse
Accuracy	±0.2 mm ^{Note)} (at 20°C)
Output type	NPN open collector (35 VDC, 80 mA)
Output signal	A/B phase difference output
Insulation resistance	500 VDC, 50 M Ω or more (between case and 12E)
Vibration resistance	33.3 Hz, 2 hours at X, Y and 4 hours at Z JIS D 1601 as standard
Impact resistance	30 G, 3 times at X, Y, Z
Enclosure	IP50 (IEC standard)
Extension cable (Option)	5 m, 10 m, 15 m, 20 m Cable: ø7, 6 core twisted pair shielded wire, oil, heat and frame resistant cable

Made to Order Specifications Order (For details, refer to page 10-21-1.) Specifications Symbol -X416 Holder mounting bracket I

-X417	Holder mounting bracket I

Theoretical Output

Made to

Theo	Theoretical Output (N)							
Bore size	Piston area		Oper	ating	pres	sure	(MPa	a)
(mm)	(mm²)	0.2	0.3	0.4	0.5	0.6	0.7	0.8
25	490	98	147	196	245	294	343	392
32	804	161	241	322	402	483	563	643
40	1256	251	377	502	628	754	879	1005
Note) T	Note) Theoretical output (N) = Pressure (MPa) x							

х Piston area (mm²)

Standard Stroke

Bore size (mm)	Series	Standard stroke (mm)
25		100, 200, 300, 400, 500,
32	ML2B	600, 700, 800, 900, 1000, 1200, 1400, 1600, 1800,
40		2000

It is possible to make 100 stroke up to 2000 by the 1 mm interval.

Stroke Adjusting Unit Part No.

Bore size (mm) Unit no.	25	32	40	
Туре	MY-A25L	MY-A32L	MY-A40L	

Side Support Part No.

Bore size (mm) Type	25	32	40
Side support A	MY-S	S25A	MY-S32A
Side support B	MY-S	S25B	MY-S32B

Note) Digital error under Controller (CEU2), Counter (CEU1 or CEU5) is included. Besides, the whole accuracy after mounting on an equipment may be varied depending on the mounting condition and surroundings. As an equipment, calibration should be done by customer.

Stroke Adjusting Unit Specifications

Applicable bore size (mm)		25	32	40
Shock absorber r	nodel	RB1007	RB1412	RB1412
Maximum energy absorption (J)		5.9	19.6	19.6
Stroke absorption (mm)		7	12	12
Maximum collision speed (mm/s)		1500	1500	1500
Maximum operating frequency (cycle/min)		70	45	45
Spring force (NI)	Extended	4.22	6.86	6.86
Spring force (N)	Retracted	6.86	15.98	15.98
Operating temperature range (°C)			5 to 60	

Weight

						(K <u></u>
Poro oizo			Additional weight	Side support w	veight (per set)	Stroke adjusting unit
Bore size (mm)	Series	Basic weight	per each 50 mm of stroke	Туре А	Туре В	weight (per unit)
25		2.89	0.142	0.015	0.016	0.10
32	ML2B	4.75	0.199	0.015	0.016	0.21
40		6.87	0.290	0.040	0.041	0.32

As for 3 point preset counter and multi counter, it will be common to CEP1 and CE1 series. For details, refer to 3 point preset counter/CEU1 on page 10-12-30, and Multi counter/CEU5 on page 10-12-27 respectively. Regarding controller, since it will be common to CE2 series, refer to Controller/CEU2 on page 10-12-54 for details.

(ka)

Brake Capacity

Holding Force of Spring Locking (Maximum static load)

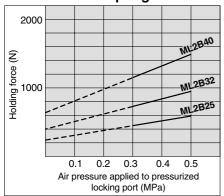
-			
Bore size (mm)	25	32	40
Holding force	245 N	400 N	628 N

Note) The holding force is the lock's ability to hold a static load that does not involve vibrations or impacts, when it is locked without a load

Therefore, when normally using the cylinder near the upper limit of the holding force, be aware of the points described below.

- Select the cylinder bore size so that the load is less than 80% of the holding force.
- If the piston rod slips because the lock's holding force has been exceeded, the brake shoe could be damaged, resulting in a reduced holding force or shortened life.

Holding Force of Locking for Pneumatic and Spring



Stopping Accuracy

When the cylinder is stopped at intermediate strokes by PLC and erratic stopping positions appear. Check piston speed, load, piping conditions, control method, etc. Use values on the table below as reference.

1. ML2B + CEU2

Piston speed	100 to 500 mm/s
Stopping accuracy	±0.5 mm

2. ML2B + PLC

Piston speed (mm/s)	100	300	500	800	1000
Stopping accuracy (mm)	±0.5	±1.0	±2.0	±3.0	±4.0
Condition/Driving p	ressure	e:	0.	5 MPa	

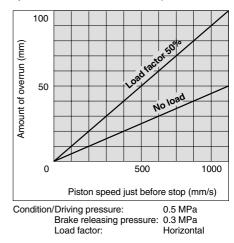
Brake releasing pressure: 0.3 MPa Load factor: 25% (Solenoid valve for brake releasing is connected to the cylinder directly and the dispersion of control system is not included.)

Overrun (ML2B + PLC)

When cylinder is stopped at intermediate strokes, "idle running distance" is from the detection of stop signal to beginning of brake operation and "braking distance" is from beginning of brake operation to stop of slider.



The graph below shows the relation between piston speed and overrun. (The length of overrun is changed dependent on piston speed, load, piping condition and control method. Be sure to adjust the stop signal position, etc. by trial operation with the actual machine.)



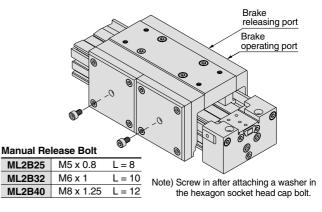
Manual Operation

[Brake releasing]

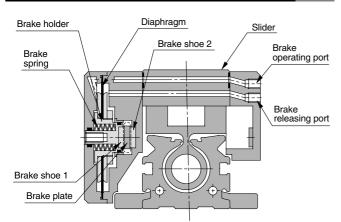
- Supply brake releasing pressure of 0.3 to 0.5 MPa to brake releasing port on slider side.
- Screw on appropriate hexagon socket head bolt into manual port on slide side.

3. Exhaust brake releasing air.

- [Brake operation]
- Supply brake releasing pressure of 0.3 to 0.5 MPa to brake releasing port on slider side.
- 2. Remove the bolt threaded into manual port.
- 3. Exhaust brake releasing air.



Working Principle of Brake Mechanism



Anatomy of brake operation

Spring force generated by the brake spring and the air pressure supplied to brake operating port work on brake shoe 1 fixed to the brake holder, bend brake plate fixed on head cover on both sides, and stop slider by putting brake plate between brake shoe 1 and brake shoe 2 fixed on the slider side.

Brake release

The air pressure supplied to the brake releasing port acts on a diaphragm, extending the brake spring, and canceling the brake.



Cushion Capacity

Cushion Selection

<Air cushion>

Stroke reading hy-rodless cylinder with brake is equipped with a standard air cushion.

The air cushion mechanism is incorporated to prevent excessive impact of the piston at the stroke end during high speed operation. The purpose of air cushion, thus, is not to decelerate the piston near the stroke end.

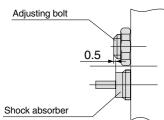
The weight and speed ranges that the air cushion can absorb are shown within the limit lines on the graph.

<Stroke adjusting unit with shock absorber>

Use this unit to decelerate the cylinder when weight and speed are beyond the air cushion limit lines or when the stroke adjustment causes limited or no cushion engagement.

A Caution

 The absorption capacity of each unit shown here is given for the mounted shock absorber when used at full stroke. When the effective stroke of the absorber decreases as a result of stroke adjustment, the absorption capacity becomes extremely small. Fix the adjusting bolt to around 0.5 mm projection from the shock absorber as shown below.

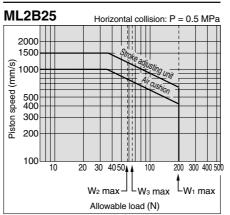


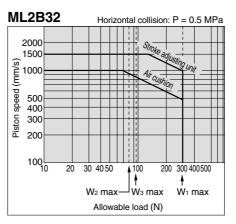
 When the shock absorber is used within the air cushion stroke range, almost open the air cushion needle (about 1 turn from the fully closed position).

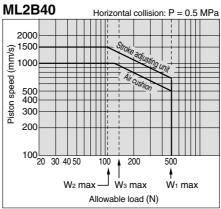
Air Cushion Stroke

Bore size (mm)	Cushion stroke
25	15
32	19
40	24

Absorption Capacity of the Air Cushion and Stroke Adjusting Unit







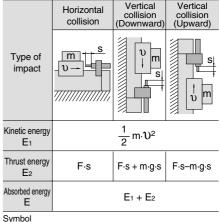
Tightening Torque for Stroke Adjusting Unit Holding Bolts (N·m)

onit holding boits	(N·m)
Bore size (mm)	Tightening torque
25	3
32	5
40	10

Tightening Torque for Stroke Adjusting Unit Lock Plate Holding Bolts (N·m)

	- ()
Bore size (mm)	Tightening torque
25	1.2
32	3.3
40	3.3

Calculation of Absorbed Energy for Stroke Adjusting Unit with Shock Absorber (N·m)



 Symbol

 D: Speed of impact object (m/s)

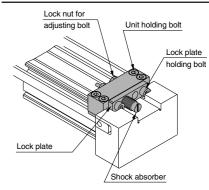
 F: Cylinder thrust (N)

 g: Gravitational acceleration (9.8 m/s²)

 s: Shock absorber stroke (m)

Note) The speed of the impact object is measured at the time of impact with the shock absorber.

Adjusting Procedure



<Movement and location of stroke adjustment> The unit body can be moved after the four unit holding bolts are loosened and can be fixed at any position by uniformly tightening the four unit holding bolts. However, there is a possibility that the adjustment mechanism will be tilted due to high impact energy.

Since the holder mounting bracket for adjustment is available as an option for -X416, -X417, we recommend that you use it. If any other length is desired, please consult with SMC. (Refer to "Tightening Torque for Stroke Adjusting Unit Holding Bolts".)

<Stroke adjustment of the adjusting bolt>

Loosen the lock nut of the adjusting bolt, adjust the stroke from the lock plate side using a wrench, then re-tighten it.

<Adjustment of shock absorber>

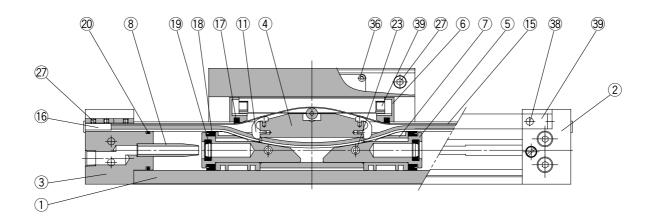
Loosen the two lock plate holding bolts, turn the shock absorber and adjust the stroke. Then, uniformly tighten the lock plate holding bolts and secure the shock absorber. Take care not to over-tighten the holding bolts.

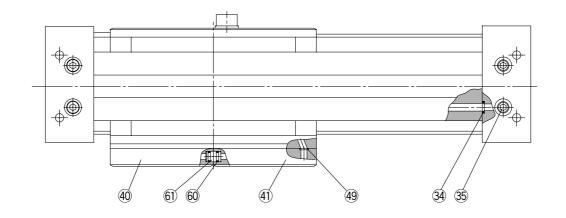
(Refer to "Tightening Torque for Stroke Adjusting Unit Lock Plate Holding Bolts".)

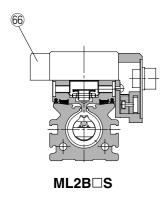
Note) Although the lock plate may slightly bend due to tightening of the lock plate holding bolt, this does not affect the shock absorber and locking function.

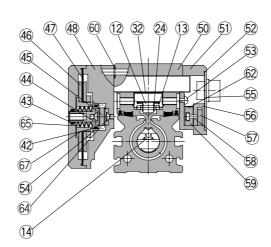
Series ML2B

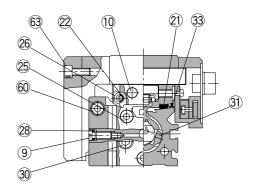
Construction











Stroke Reading Rodless Cylinder with Brake Series ML2B

Component Parts

No.	Description	Material	Qty.	Note
(1)	Cylinder tube	Aluminum alloy	1	Hard anodized
2)	Head cover WR	Aluminum alloy	1	Glossy, self-coloring
3	Head cover WL	Aluminum alloy	1	Glossy, self-coloring
<u>4</u>	Piston yoke	Aluminum alloy	1	Hard anodized
5	Piston	Aluminum alloy	2	Hard anodized
6	End cover	Special resin	2	
<u>)</u>	Wear ring	Special resin	2	
<u>/</u> 8)	Cushion ring	Stainless steel	2	Nickel plated
<u> </u>	Cushion needle	Rolled steel		Nickel plated
<u>9</u>			2	
10	Stopper	Carbon steel		
	Belt separator Guide roller	Special resin	2	
12		Special resin	1	
13	Guide roller shaft	Stainless steel	1	
16	Belt clamp	Special resin	2	
20	Bearing	Special resin	2	
22	Spacer	Stainless steel	4	
23	Spring pin	Carbon tool steel	2	Black zinc chromated
24)	Type E snap ring	Cold rolled special steel strip	2	
25)	Hexagon socket head cap screw	Chromium molybdenum steel	6	Nickel plated
26)	Hexagon socket button head screw	Chromium molybdenum steel	4	Nickel plated
27)	Hexagon socket head set screw	Chromium molybdenum steel	8	Nickel plated
29	Double round parallel key	Carbon steel	2	
30)	Hexagon socket head taper plug	Carbon steel	6	Nickel plated
31)	Magnet	Rare earth magnet	2	•
32)	Top cover	Stainless steel	1	
33	Side scraper	Special resin	2	
35)	Hexagon socket head taper plug	Carbon steel	4	Nickel plated
36)	Round head Phillips screw	Carbon steel	4	Nickel plated
<u>37)</u>	Hexagon socket head cap screw	Carbon steel	3	Nickel plated
<u>38</u>	Parallel pin	Carbon steel	4	Nieker plated
<u>39</u>	Tension plate	Carbon steel	4	Nickel plated
40)	Side cover L			Hard anodized, Urban whit
<u> </u>		Aluminum alloy	1	,
<u>41)</u>	Side cover R	Aluminum alloy	1	Hard anodized, Urban whit
14)	Brake shoe	Special abrasion material	4	
45	Brake plate	Stainless steel	1	
46)	Diaphragm shell	Stainless steel	4	
17)	Diaphragm	NBR	2	
18)	Brake guide	Aluminum alloy	1	Hard anodized, white
50	Slide table	Aluminum alloy	1	Hard anodized
51)	Sensor body	Aluminum alloy	1	Hard anodized, white
53	Round head Phillips screw	Carbon steel	2	Nickel plated
54)	Brake guide	Carbon steel	2	Gas soft treated
55	Connector cover	Carbon steel	1	Nickel plated
6	Sensor guide	Special abrasion material	1	
57)	Scale plate	Carbon steel	1	Nickel plated
58)	Hexagon socket head cap screw	Carbon steel	2	Nickel plated
59	Sensor unit	_	1	
61)	Air joint	Stainless steel	1	
62)	Sensor holder	Carbon steel	1	
-				
63) CA	Hexagon socket head cap screw	Carbon steel	8	
<u>64)</u>	Cross recessed countersunk head screw	Carbon steel	4	
<u>65</u>	Brake spring	—	2	
6	Side plate	Aluminum alloy	1	Hard anodized, white
	Hexagon socket head cap screw	Chromium molybdenum steel	6	Nickel plated

* There are two dust seal bands, and part no. is different according to color of the treated "Hexagon socket head set screw" of 2. Please contact SMC.

B: Nickel color: MYDD-16BW-Stroke

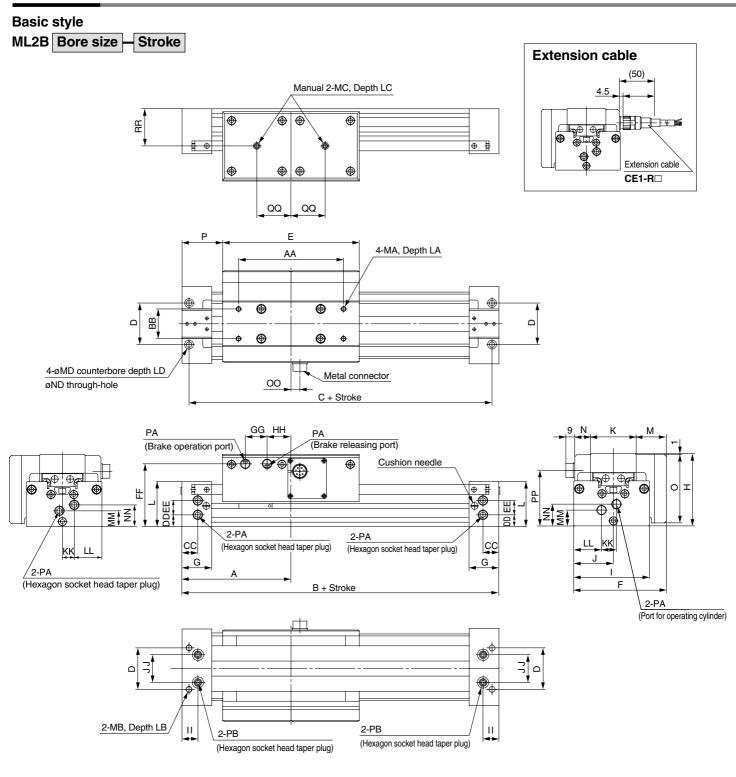
٧o.	Description	Material	Qty.	ML2B25	ML2B32	ML2B40
14	Seal belt	Special resin	1	MY25-16A-stroke	MY32-16A-stroke	MY40-16A-stroke
15	Dust seal band	Stainless steel	1	MY25-16B-stroke	MY32-16B-stroke	MY40-16B-stroke
\bigcirc	Scraper	NBR	2	MYB25-15AA5900	MYB32-15AA5901	MYB40-15AA5902
18	Piston seal	NBR	2	GMY25	GMY32	GMY40
19	Cushion seal	NBR	2	RCS-8	RCS-10	RCS-12
20	Tube gasket	NBR	2	NLP-25-19A	NLP-32A	NLP-40A
28	O-ring	NBR	2	ø7.15 x ø3.75 x ø1.7	ø8.3 x ø4.5 x ø1.9	C-4
34)	O-ring	NBR	4	P-5	P-6	C-9
42	O-ring	NBR	2	SO-015-16	SO-016-9	SO-015-20
43	O-ring	NBR	2	P-7	P-9	P-11
(49)	O-ring	NBR	1	SO-010-16	SO-010-21	SO-010-24
52	Connector guide	NBR	1	M2L025-07B82106	M2L032-07B82107	M2L040-07B82108
60	O-ring	NBR	6	SO-010-20	SO-010-21	SO-010-24
67	O-ring	NBR	2	ø17.6 x ø19.4 x ø0.9	ø22.2 x ø24 x ø0.9	ø28 x ø30 x ø1

ct SMC regarding the replacement of seals.

REB

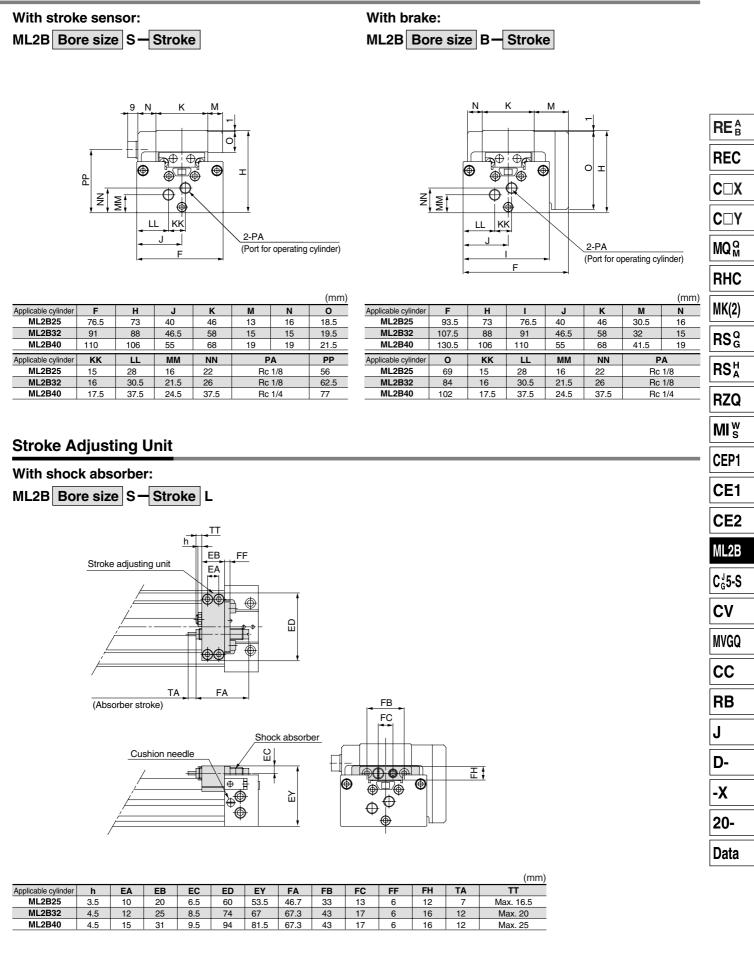
Series ML2B

Dimensions



Model	Α	В	С	D	E	F	G	н	I	J	Κ	L	М	Ν	0	Ρ	AA	BB	CC	DD	EE	FF	GG	HH	Ш	JJ
ML2B25	110	220	206	42	138	93.5	30	73	76.5	40	46	45.5	30.9	16	69	41	106	30	16	11	14.5	63.5	22	24	16	28
ML2B32	140	280	264	51	168	107.5	37	88	91	46.5	58	54	32.4	15	84	56	133	35	19	15	16	77.5	27	32	19	32
ML2B40	170	340	322	59	204	130.5	45	106	110	55	68	64	41.4	19	102	68	164	40	23	16.5	22	95	35	37	23	36
Model	КК	LL	MM	NN	00	PP	QQ	RR	М	A	LA	М	B	LB	M	С	LC	MD	LD	ND		PA			PB	
Model ML2B25	KK 15	LL 28	MM 16	NN 22				RR 37.5			LA 11	M M6		LB 9.5	M5 x	-	LC 9.5		LD 5.5	ND 5.6		PA Rc 1/8	3	F	PB Rc 1/1	6
	15	28		22	9		34.5			(0.8	11		x 1	9.5		(0.8										-

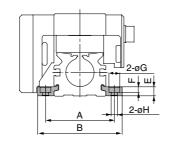
SMC

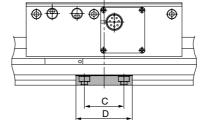


Series ML2B

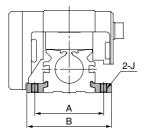
Dimensions

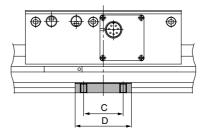
Side support A MY-S□A





Side support B MY-S□B





										(mm)
Part no.	Applicable cylinder	Α	В	С	D	ш	F	G	Н	J
MY-S25A	ML2B25	61	75	35	50	8	5	9.5	5.5	M6 x 1
W1-525B	ML2B32	70	84	35	50	0	5	9.5	5.5	
MY-S32 ^A	ML2B40	87	105	45	64	11.7	6	11	6.6	M8 x 1.25

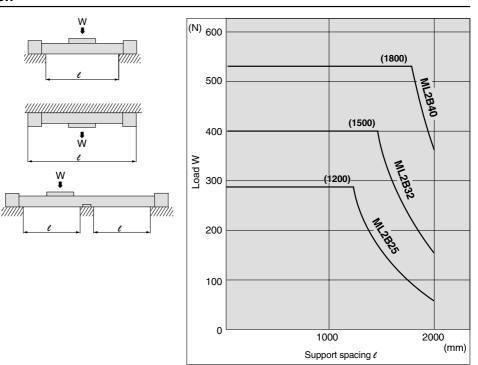
Guide for Side Support Application

For long stroke operation, the cylinder tube may be deflected depending on its own weight and the load weight. In such a case, use a side support in the middle section. The spacing (*l*) of the support must be no more than the values shown in the graph on the right.

A Caution

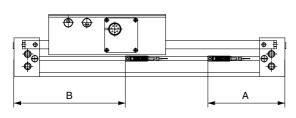
If the cylinder mounting surfaces are not measured accurately, using a side support may cause poor operation. Therefore, be sure to level the cylinder tube when mounting. If there is vibration, impact, etc. at long stroke, we recommend adoption of side support even if it is

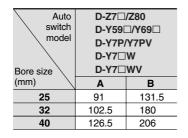
within the allowable value shown in the graph.





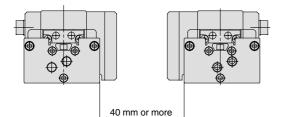
Proper Auto Switch Mounting Position (Detection at stroke end)





▲ Caution on Handling Auto Switch

- 1. Always connect the auto switch to the power supply after the load has been connected.
- 2. Use caution not to apply excessive impact forces by dropping and bumping when handling.
- **3.** When more than 2 pcs cylinders with auto switches are juxtaposed, leave the distance of 40 mm or more between the cylinder tubes as shown in the below.



- 4. Avoid wiring patterns in which bending stress and pulling force are repeatedly applied to the lead wires.
- 5. Please consult with SMC when using in locations where water or coolant liquid, etc is splashing constantly.
- 6. Avoid the use in locations where the large amount of magnetism is occurring.

Operating Range

Auto switch model	Bore size (mm)							
Auto switch model	25	32	40					
D-Z7□/Z80	12	12	12					
D-Y59□/Y69□								
D-Y7P/Y7PV	6	6	6					

* Since this is a guideline including hysteresis, not meant to be guaranteed. (assuming approximately ±30% dispersion.)

There may be the case it will vary substantially depending on an ambient environment.

Mounting of Auto Switch

When mounting and securing auto switches, they should be inserted into the cylinder's switch mounting rail from the direction shown in the drawing below. After setting in the mounting position, use a flat head watchmakers' screwdriver to tighten the set screw that is included.

M2.5 x 4*t* (Included with the auto switch)

Note) When tightening an auto switch mounting screw, use a watchmakers' screwdriver with a handle of approximately 5 to 6 mm in diameter.

Also, tighten with a torque of about 0.05 to 0.1 N·m. As a guide, turn about 90° past the point at which tightening can first be felt.

 Other than the applicable auto switches listed in "How to Order", the following auto switches can be mounted. For detailed specifications, refer to page 10-20-1.

 Type
 Model
 Electrical entry (Fetching direction)

 Features

Type	model	(Fetching direction)	1 outdroo	
Reed switch	D-Z80	Grommet (In-line)	Without indicator light	
* Normally closed (NC = b	contact), solid sta	ate switch (D-Y7G/Y7H type)) are also available. For detai	ils, refe

* Normally closed (NC = b contact), solid state switch (D-Y7G/Y7H type) are also available. For details, refer to page 10-20-41.

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