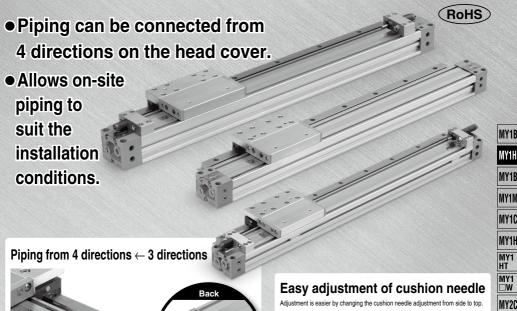
Mechanically Jointed Rodless Cylinder

MY1H Series

Linear Guide Type: Ø25, Ø32, Ø40



Piping ports



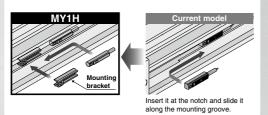
Auto switch can be mounted in any desired position. (D-M9□, D-A9□)

Bottom

Front

• The auto switch can be fixed in any desired position with a mounting bracket. This reduces man-hours for mounting.

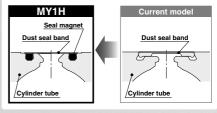
Side



New dust seal band improves life.

The current groove mounting is changed to a magnetically sealed type.

. This means the dust seal band is always in contact with the cylinder, which reduces ingress of foreign matter, improving the life of the cylinder.





MY1B

MY1H

MY1B MY1M MY1C MY1H

MY1 HT

MY2 H/HT **МҮЗА** МҮ3В MY3M



The mounting and performance are the same as before, but the weight is reduced.

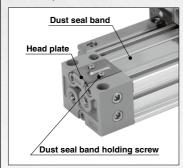
Bore size (mm) MYTH Reduction rate Current model

 Weight is reduced by the die cast head cover and removal of guide cover.

Bore size (mm)	MY1H	Reduction rate	Current model
25	2.17 kg	6%	2.31 kg
32	4.37 kg	6%	4.65 kg
40	5.84 kg	8%	6.37 kg

Maintenance of dust seal band improved

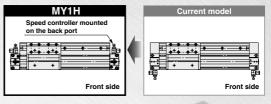
- No need to select the dust seal band from two types.
- The dust seal band can be removed by loosening two holding screws (on one side).



Space saving achieved by piping on the back

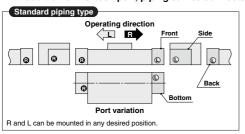
When a speed controller is mounted,

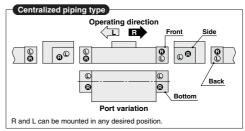
the cylinder installation area can be reduced significantly.

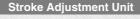


Improvement of port variations

With addition of the back port, piping can be connected to suit the installation conditions.







 With adjustment bolt • With low/high load shock absorber + adjustment bolt (L/H unit)

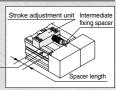






Intermediate fixing spacer as standard

Fixture can be selected to hold the stroke adjustment unit at the intermediate stroke position.



Improved shock-less characteristics when a workpiece is stopped

Soft type of shock absorber can be selected for the stroke adjustment unit.
(Made to Order: -XB22)
The cross section of the liquid passa

The cross section of the liquid passage is changed in proportion to the stroke by a unique mechanism. This allows a smooth absorption process.



MY1B

MY1H

MY1B

MY1M MY1C

MY1H

MY1 HT MY1 DW

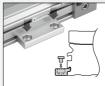
MY2

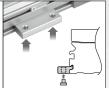
H/HT

MY3A MY3B

Side Support

Prevents deflection of the cylinder tube at a long stroke.





Improvement of positioning accuracy

Uses a linear guide to achieve high repeatability.

MY1 Series Variations

Series						Bore siz	ze (mm)					B
Series		10	16	20	25	32	40	50	63	80	100	Page
58	MY1B				0	•	•					P.1188
	MY1B	-	•	-			+	-	-	•	-	P.1233
	MY1M		•	•	•	•	-	-	-			P.1257
	MY1C		•	-	•	•	-	-	-	+		P.1277
***	МҮ1Н			+	•	•	-	-	+	+		P.1201
	MY1H End lock		_	+	-	-		-	+	+		7.1201
	МҮ1Н	-	•	-			_		_	-		
	MY1H End lock		•	-		_	+	-	+	+		P.1297
	MY1HT			+		+	+	-	-	+		P.1319
	MY1□W		•	-	-	-	-	-	-	+		P.1339

1203



D-□ -x□

MY1H Series Prior to Use

Maximum Allowable Moment/Maximum Load Mass

Model	Bore size	Maximum a	allowable mo	ment (N·m)	Maximum load mass (kg)				
Wiodei	(mm)	M1	M2	Мз	m ₁	m ₂	mз		
	25	23	26	23	27.5	27.5	27.5		
MY1H	32	39	50	39	39.2	39.2	39.2		
	40	50	50	39	50	50	50		

The above values are the maximum allowable values for moment and load mass. Refer to each graph regarding the maximum allowable moment and maximum load mass for a particular piston speed.

Load mass (kg)

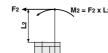


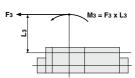




Moment (N·m)







Calculation of Guide Load Factor

- 1) Maximum load mass (1), static moment (2), and dynamic moment (3) (at the time of impact with stopper) must be examined for the selection calculations.
 - * To evaluate, use $\mathbb{U}a$ (average speed) for (1) and (2), and \mathbb{U} (collision speed $\mathbb{U}=1.4\mathbb{U}a$) for (3). Calculate m max for (1) from the maximum load mass graph (m₁, m₂, m₃) and M max for (2) and (3) from the maximum allowable moment graph (M₁, M₂, M₃).

Note 1) Moment caused by the load, etc., with cylinder in resting condition

Note 2) Moment caused by the load equivalent to impact at the stroke end (at the time of impact with stopper)

Note 3) Depending on the shape of a workpiece, multiple moments may occur. When this happens, the sum of the load factors ($\Sigma\alpha$) is the total of all such moments.

2) Reference formula [Dynamic moment at the time of impact]

Use the following formulae to calculate dynamic moment when taking stopper impact into consideration.

m : Load mass (kg)

F: Load (N)

FE : Load equivalent to impact

(at the time of impact with stopper) (N) \$\mathcal{Va}\$: Average speed (mm/s)

M : Static moment (N⋅m)

 $\upsilon = \text{1.4} \upsilon \text{a (mm/s)} \quad \begin{matrix} \text{Note 4} \\ \text{Fe} = \text{1.4} \upsilon \text{a} \cdot \delta \cdot \text{m} \cdot \text{g} \end{matrix}$

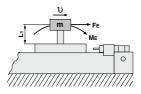
Note 5) $\therefore \mathbf{ME} = \frac{1}{3} \cdot \mathbf{FE} \cdot \mathbf{L}_1 = 4.57 \text{ } \mathbf{Da} \delta \mathbf{mL}_1 \text{ } (\text{N} \cdot \text{m})$ υ : Collision speed (mm/s)

L1 : Distance to the load center of gravity (m)

 $\textbf{Me} \colon \mathsf{Dynamic} \; \mathsf{moment} \; (\mathsf{N} {\cdot} \mathsf{m})$

 $\delta \ : \text{Bumper coefficient} \\ \text{With air cushion} = 1/100$

With shock absorber = 1/100 g : Gravitational acceleration (9.8 m/s²)

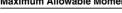


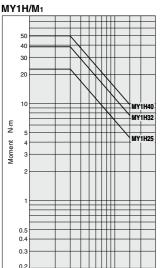
Note 4) 1.4 $va\delta$ is a dimensionless coefficient for calculating impact force.

Note 5) Average load coefficient (= $\frac{1}{3}$): For averaging the maximum load moment at the time of impact with stopper according to service life calculations.

3) For detailed selection procedures, refer to Front matter 1206 and 1207.

Maximum Allowable Moment Select the moment from within the range of operating limits shown in the graphs. Note that the maximum load mass value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the load mass for the selected conditions.

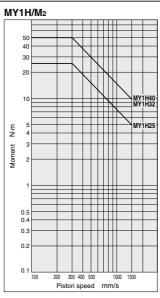


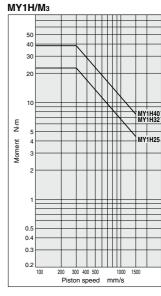


300 400 500

Piston speed

1500

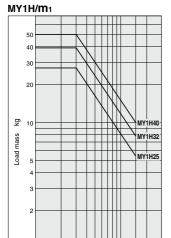




Maximum Load Mass

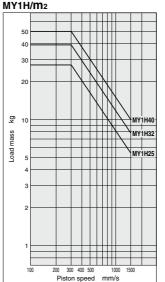
100

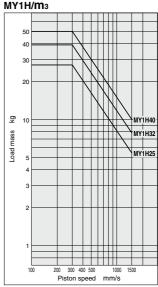
Select the load mass from within the range of limits shown in the graphs. Note that the maximum allowable moment value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the allowable moment for the selected conditions.



300 400 500

Piston speed mm/s





MY1B

MY1H

MY1B

MY1M

MY1C

MY1H

нт

MY1

 $\square W$

MY2C

MY2

H/HT

МҮ3А MY3B

MY3M

D-□ -X□ Technical Data

SMC

MY1H Series **Model Selection**

he following is the steps for selecting the most suitable MY1H series to your application.

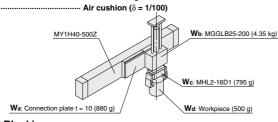
Calculation of Guide Load Factor

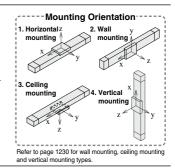
1. Operating Conditions

Cylinder MY1H40-500Z

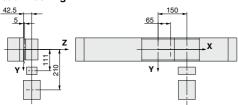
Average operating speed va - 300 mm/sMounting orientation Wall mounting

Cushion Air cushion (δ = 1/100)





2. Load Blocking



Mass and Center of Gravity for Each Workpiece

Workpiece	Mass	Center of gravity							
Wn	mn	X-axis Xn	Y-axis Yn	Z-axis Zn					
Wa	0.88 kg	65 mm	0 mm	5 mm					
Wb	4.35 kg	150 mm	0 mm	42.5 mm					
Wc	0.795 kg	150 mm	111 mm	42.5 mm					
₩d	0.5 kg	150 mm	210 mm	42.5 mm					

n = a, b, c, d

3. Calculation of Composite Center of Gravity

$$m_3 = \Sigma m_n$$

= 0.88 + 4.35 + 0.795 + 0.5 = **6.525 kg**

$$X = \frac{1}{m_3} \times \Sigma (m_n \times x_n)$$

= $\frac{1}{6.525} (0.88 \times 65 + 4.35 \times 150 + 0.795 \times 150 + 0.5 \times 150) = 138.5 \text{ mm}$

$$\mathbf{Y} = \frac{1}{\mathbf{m}_3} \times \Sigma \left(\mathbf{m}_n \times \mathbf{y}_n \right)$$

$$=\frac{1}{6.525}(0.88 \times 0 + 4.35 \times 0 + 0.795 \times 111 + 0.5 \times 210) = 29.6 \text{ mm}$$

$$\mathbf{Z} = \frac{1}{\mathbf{m}_3} \times \Sigma \left(\mathbf{m}_n \times \mathbf{z}_n \right)$$

=
$$\frac{1}{6.525}$$
 (0.88 x 5 + 4.35 x 42.5 + 0.795 x 42.5 + 0.5 x 42.5) = **37.4 mm**

4. Calculation of Load Factor for Static Load -

m3: Mass

m₃ max (from (1) of graph MY1H/m₃) = 50 (kg).....

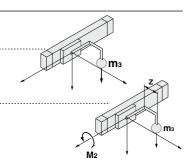
Load factor $\Omega_1 = m_3/m_3 max = 6.525/50 = 0.13$

M2: Moment

M2 max (from ② of graph MY1H/**M2**) = 50 (N·m).....

 $M_2 = M_3 \times g \times Z = 6.525 \times 9.8 \times 37.4 \times 10^{-3} = 2.39 \text{ (N·m)}$

Load factor $O(2) = M_2/M_2 \text{ max} = 2.39/50 = 0.05$

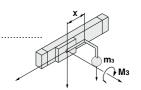


Ma: Moment

M₃ max (from ③ of graph MY1H/M₃) = 38.7 (N⋅m).....

 $M_3 = M_3 \times a \times X = 6.525 \times 9.8 \times 138.5 \times 10^{-3} = 8.86 \text{ (N·m)}$

Load factor $0.3 = M_3/M_3 max = 8.86/38.7 = 0.23$



5. Calculation of Load Factor for Dynamic Moment

Equivalent load FE at impact

$$\mathbf{F} = 1.4 \text{ } \mathbf{0} \mathbf{a} \times \mathbf{\delta} \times \mathbf{m} \times \mathbf{g} = 1.4 \times 300 \times \frac{1}{100} \times 6.525 \times 9.8 = 268.6 \text{ (N)}$$

M1E: Moment

M1E max (from 4 of graph MY1H/M1 where 1.41a = 420 mm/s) = 35.9 (N·m).......

M₁E =
$$\frac{1}{3}$$
 x Fe x **Z** = $\frac{1}{3}$ x 268.6 x 37.4 x 10⁻³ = 3.35 (N·m)

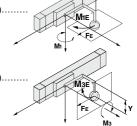
Load factor C4 = M1E/M1E max = 3.35/35.9 = 0.09

M3E: Moment

M3E max (from \odot of graph MY1H/M3 where 1.4 Ω a = 420 mm/s) = 27.6 (N·m).......

M₃E =
$$\frac{1}{3}$$
 x Fe x Y = $\frac{1}{3}$ x 268.6 x 29.6 x 10⁻³ = 2.65 (N·m)

Load factor 0.5 = M3E/M3E max = 2.65/27.6 = 0.10



6. Sum and Examination of Guide Load Factors

 $\Sigma \alpha = \Omega_1 + \Omega_2 + \Omega_3 + \Omega_4 + \Omega_5 = 0.60 \le 1$

The above calculation is within the allowable value, and therefore the selected model can be used.

Select a shock absorber separately.

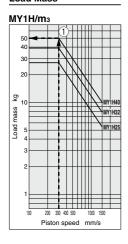
In an actual calculation, when the total sum of guide load factors $\Sigma \alpha$ in the formula above is over 1, consider either decreasing the speed, increasing the bore size, or changing the product series.

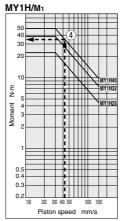
SMC

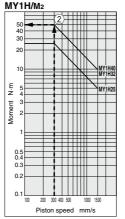
This calculation can be easily made using the "SMC Pneumatics CAD System."

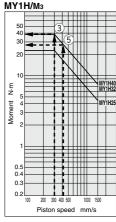
Load Mass

Allowable Moment









MY1B

MY1B

MY1M

MY1C

MY1 HT MY1

MY2C

MY2 H/HT MY3A MY3B

MY3M

D-□

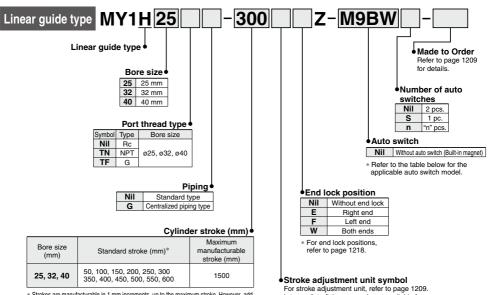
-X□

Mechanically Jointed Rodless Cylinder Linear Guide Type

MY1H Series Ø25, Ø32, Ø40



How to Order



* Strokes are manufacturable in 1 mm increments, up to the maximum stroke. However, add "-XB10" to the end of the part number for non-standard strokes from 51 to 599. Also when exceeding a 600 mm stroke, specify "-XB11" at the end of the part number. (Except ø10)

Intermediate fixing spacer is not available for end lock mounting side.

Applicable Auto Switches/Refer to pages 1575 to 1701 for further information on auto switches

			tor light	VA Cining on	L	oad volta	ge	Auto swite	ch model	Lead	d wir	e ler	ngth	(m)	D														
Type	Special function	Electrical entry	Indicator	Wiring (Output)	D	DC		Perpendicular	In-line	0.5 (Nil)	1 (M)	3 (L)	5 (Z)	Ivone	Pre-wired connector	Applicable load													
<u>_</u>				3-wire (NPN)		5 V. 12 V		M9NV	M9N	•	•	•	0	0	0	IC circuit													
switch				3-wire (PNP)		5 V, 12 V		M9PV	M9P	•	•	•	0	0	0	IC CIICUII													
			2-wire 1:	12 V	1	M9BV	M9B	•	•	•	0	0	0	_															
anto	Diagnostic indication (2-color indicator) Gromn			3-wire (NPN)		5 1/ /O 1/	5 1/ 40 1/	EV 10V	EV 10V	EV 10V	51/ 401/	51/401/	EV 10V	5 V, 12 V	EV 10V	1	M9NWV	M9NW	•	•	•	0	0	0	IC circuit	D-1			
		Grommet	Grommet	Grommet	Grommet	Grommet	Grommet	Grommet	Grommet	Grommet	Grommet	Grommet	Yes	3-wire (PNP)	24 V	5 V, 12 V	_	M9PWV	M9PW	•	•	•	0	0	0	10 circuit	Relay, PLC		
state				2-wire	12 V	1	M9BWV	M9BW	•	•	•	0	0	0	_	FLC													
1st																3-wire (NPN)		E V 10 V	1	M9NAV*1	M9NA*1	0	0	•	0	_	0	IC circuit	
Solid	Water resistant (2-color indicator)			3-wire (PNP)		5 V, 12 V	v	M9PAV*1	M9PA*1	0	0	•	0	_	0	IC circuit													
ŭ	(2-color indicator)			2-wire		12 V	1	M9BAV*1	M9BA*1	0	0	•	0	_	0	_													
Reed o switch		Grom	Grommet	Yes	3-wire (NPN equivalent)	_	5 V	_	A96V	A96	•	_	•	_	_	_	IC circuit	_											
				Grommet	Grommet		2-wire	24 V	12 V	100 V	A93V*2	A93	•	•	•	•	_	_	_	Relay,									
anto			No	Z-WIFE	24 V	12 0	100 V or less	A90V	A90	•	_	•	_	_	_	IC circuit	PLC												

- *1 Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance Please consult with SMC regarding water resistant types with the above model numbers.
- *2 1 m type lead wire is only applicable to D-A93.
- * Lead wire length symbols: 0.5 m ···· Nil (Example) M9NW 1 m M (Example) M9NWM 3 m L (Example) M9NWL 5 m Z
- * Solid state auto switches marked with "O" are produced upon receipt of order.
- * Mounting bracket (BMY3-016) is separately required to retrofit the above auto switches.
- * There are other applicable auto switches other than listed above. For details, refer to page 1220.
- * For details about auto switches with pre-wired connector, refer to pages 1648 and 1649. * Auto switches are shipped together, (but not assembled). (For details about auto switch mounting, refer to page 1220.)

(Example) M9NWZ

1208



Mechanically Jointed Rodless Cylinder MY1H Series Linear Guide Type

Specifications

specifications ————————————————————————————————————										
Bor	e size (mm)	25	32	40						
Fluid		Air								
Action			Double acting							
Operating	pressure range	C	0.1 to 0.8 MPa							
Proof pres	ssure	1.2 MPa								
Ambient ar	nd fluid temperature	5 to 60°C								
Cushion		Air cushion								
Lubricatio	n		Non-lube							
Stroke len	gth tolerance	+1.8 0								
Piping	Front/Side port	Rc	1/8	Rc1/4						
port size	Bottom port	Ø	ø6							



Lock Specifications

Bore size (mm)	25	32	40					
Lock position	One end (Selectable), Both ends							
Holding force (Max.) (N)	270	450	700					
Fine stroke adjustment range (mm)	0 to -11.5	0 to -12	0 to -16					
Backlash		1 mm or less						
Manual release	Poss	ible (Non-lock	type)					



Made to Order: Individual Specifications (For details, refer to page 1221.)

Symbol	Specifications
-X168	Helical insert thread

Made to Order

Click here for details

Symbol	Specifications
-XB10	Intermediate stroke (Using exclusive body)
-XB11	Long stroke
-XB22	Shock absorber/soft type RJ series mounted
VCEC	With knock pin bolos

Piston Speed

В	ore size (mm)	25 to 40					
Without stroke a	djustment unit	100 to 1000 mm/s					
Stroke	A unit	100 to 1000 mm/s Note 1)					
adjustment unit	L unit and H unit	100 to 1500 mm/s Note 2)					

Note 1) Be aware that when the stroke adjustment range is increased with the adjustment bolt, the air cushion capacity decreases. Also, when exceeding the air cushion stroke ranges on page 1211, the piston speed should be 100 to 200 mm/s.

Note 2) The piston speed is 100 to 1000 mm/s for centralized piping.

Note 3) Use at a speed within the absorption capacity range. Refer to page 1211.

Stroke adjustment Unit Specifications

Bore	size (mm)		25			32		40			
Unit symbol	nit symbol		L	Н	Α	L	Н	Α	L	Н	
Configuration Shock absort		With adjustment bolt	RB1007 + with adjustment bolt	RB1412 + with adjustment bolt	With adjustment bolt	RB1412 + with adjustment bolt	RB2015 + with adjustment bolt	With adjustment bolt	RB1412 + with adjustment bolt	RB2015 + with adjustment bolt	
Stroke adjust- ment range by	Without spacer		0 to -11.5			0 to -12			0 to -16		
intermediate	With short spacer		–11.5 to –23		-12 to -24			-16 to -32			
fixing spacer (mm)	With long spacer		–23 to –34.5			-24 to -36		−32 to −48			

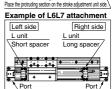
Stroke adjustment range is applicable for one side when mounted on a cylinder.

Stroke Adjustment Unit Symbol

<u>~</u>	Adjustment of the cymbol												
						Right s	side strok	e adjustn	nent unit				
			Without	A: With	adjustme	ent bolt	L: With lov + adjustme	load shock	absorber	H: With high load shock absorber + adjustment bolt			
			unit		With short spacer	With long spacer		With short spacer	With long spacer		With short spacer	With long spacer	
unit	Wit	hout unit	Nil	SA	SA6	SA7	SL	SL6	SL7	SH	SH6	SH7	
μ	A: With adjustment bolt		AS	Α	AA6	AA7	AL	AL6	AL7	AH	AH6	AH7	
ner	A: With a	With short spacer	A6S	A6A	A6	A6A7	A6L	A6L6	A6L7	A6H	A6H6	A6H7	
nst		With long spacer	A7S	A7A	A7A6	A7	A7L	A7L6	A7L7	A7H	A7H6	A7H7	
adj	L: With low lo	ad shock absorber +	LS	LA	LA6	LA7	L	LL6	LL7	LH	LH6	LH7	
ke	adjustment bolt	With short spacer	L6S	L6A	L6A6	L6A7	L6L	L6	L6L7	L6H	L6H6	L6H7	
strc	DOIL	With long spacer	L7S	L7A	L7A6	L7A7	L7L	L7L6	L7	L7H	L7H6	L7H7	
de	H: With high	load shock absorber +	HS	HA	HA6	HA7	HL	HL6	HL7	Н	HH6	HH7	
#s	adjustment	With short spacer	H6S	H6A	H6A6	H6A7	H6L	H6L6	H6L7	Н6Н	H6	Н6Н7	
٩		With long spacer	H7S	H7A	H7A6	H7A7	H7L	H7L6	H7L7	H7H	H7H6	H7	

Stroke adjustment unit mounting diagram

Stroke adjustment unit Intermediate fixing spacer



- * Intermediate fixing spacer is not available for end lock mounting side.
- * Spacers are used to fix the stroke adjustment unit at an intermediate stroke position.

Shock Absorber Model for L and H Units

Time	Stroke		Bore size (mm)	
Туре	adjustment unit	25	32	40
Standard	L	RB1007	RB1	412
(Shock absorber/RB series)	Н	RB1412	RB2	2015
Shock absorber/soft type	L	RJ1007H	RJ14	112H
RJ series mounted (-XB22)	Н	RJ1412H	_	_

- * The shock absorber service life is different from that of the MY1H cylinder depending on operating conditions. Refer to the RB/RJ series Specific Product Precautions for the replacement period.
- * Shock absorber/soft type RJ series mounted (-XB22) is made to order. For details, refer to page 1752.

Shock Absorber Specifications

SHOCK AD	SUIDEI S	pecifications					
Mod	del	RB RB RB 1007 1412 201					
Max. absorbe	d energy (J)	5.9	19.6	58.8			
Stroke absor	rption (mm)	7	12	15			
Max. collision	speed (mm/s)	1500	1500	1500			
Max. operating frequency	uency (cycle/min)	70	45	25			
Spring	Extended	4.22	6.86	8.34			
force (N)	Retracted	6.86	15.98	20.50			
Operating temper	ature range (ºC)		5 to 60				

*The shock absorber service life is different from that of the MY1H cylinder depending on operating conditions. Refer to the RB series Specific Product Precautions for the replacement period.



D-□ -X□ Technical

MY1B

MY1H

MY1B

MY1M

MY1C MY1H MY1 MY1 $\square W$ MY2C

MY2

H/HT

MY3A MY3B MY3M

Theoretical Output

								Unit: N				
Bore	Piston	Operating pressure (MPa)										
size (mm)	area (mm²)	0.2	0.3	0.4	0.5	0.6	0.7	0.8				
25	490	98	147	196	245	294	343	392				
32	804	161	241	322	402	483	563	643				
40	1256	251	377	502	628	754	879	1005				

Note) Theoretical output (N) = Pressure (MPa) x Piston area (mm²)

Weight

							Unit: kg
	Bore	Basic	weight	Side support bracket weight (per set)	Stroke ad	justment u (per unit)	nit weight
	(mm)	weight per each 50 mm of stroke	50 mm	A/B type weight	A unit weight	L unit weight	H unit weight
ĺ	25	2.17	0.30	0.02	0.04	0.07	0.11
	32	4.37	0.46	0.04	0.08	0.14	0.23
	40	5.84	0.55	0.08	0.12	0.19	0.28

Calculation: (Example) MY1H25-300AZ

 Basic weight
 2.17 kg

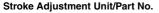
 Cylinder stroke
 300 mm stroke

 Additional weight
 0.30 kg/50 mm stroke

 A unit weight
 0.04 kg

2.17 + 0.30 x 300 ÷ 50 + 0.04 x 2 ≈ 4.05 kg

Options



MYH-A 25 L2-6N

Unit tuno

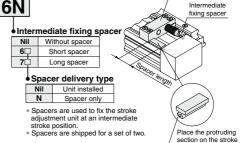
Stroke adjustment unit

Bore size ●

25	25 mm
32	32 mm
40	40 mm

	OI.	ııı type ●
Symbol	Stroke adjustment unit	Mounting position
A1	A unit	Left
A2	A unit	Right
L1	L unit	Left
L2	L unit	Right
H1	H unit	Left
H2	ri ufilt	Right

Note) For details about adjustment range, refer to page 1209.

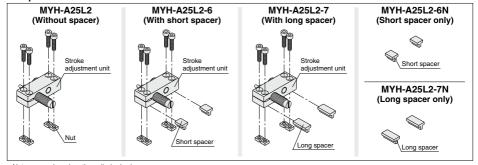


Stroke adjustment unit

adjustment unit side.

* When ordering the intermediate fixing spacer for the stroke adjustment unit, the intermediate fixing spacer is shipped together.

Component Parts



^{*} Nuts are equipped on the cylinder body.

Side Support/Part No.

Bore size (mm)		32	40
Side support A	MY-S25A	MY-S32A	MY-S40A
Side support B	MY-S25B	MY-S32B	MY-S40B

For details about dimensions, etc., refer to page 1219. Side supports consist of a set of right and left support.

Cushion Capacity

Cushion Selection

<Air cushion>

Air cushions are a standard feature on mechanically jointed rodless cylinders.

The air cushion mechanism is incorporated to prevent excessive impact of the piston with high kinetic energy at the stroke end. The purpose of air cushion, thus, is not to decelerate the piston near the stroke end.

The ranges of load and speed that air cushions can absorb are within the air cushion limit lines shown in the graphs.

<Stroke adjustment unit with shock absorber> Use this unit when operating with a load and speed exceeding the air cushion limit line, or when cushioning is required outside of the effective air cushion stroke range due to stroke adjustment

L unit

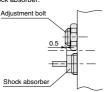
Use this unit when cushioning is necessary outside of the effective air cushion range even if the load and speed are within the air cushion limit line, or when the cylinder is operated in a load and speed range above the air cushion limit line and below the L unit limit line.

Hunit

Use this unit when the cylinder is operated in a load and speed range above the L unit limit line and below the H unit limit line.

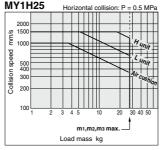
∕!\ Caution

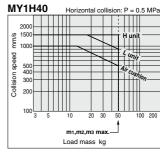
1. Refer to the below figure when using the adjustment bolt to perform stroke adjustment. When the effective stroke of the shock absorber decreases as a result of stroke adjustment, the absorption capacity decreases dramatically. Secure the adjustment bolt at the position where it protrudes approximately 0.5 mm from the shock absorber



2. Do not use a shock absorber together with air cushion.

Absorption Capacity of Air Cushion and Stroke Adjustment Units





Unit: mm

Air Cushion Stroke Bore size (mm) Cushion stroke 25 15 32 19 40 24

s/ww peeds uc	500 500 500 500 400					_				4	4	ini	ļ			
isi	300		П	T	t	t			П	Г	Г	Ϊ	"(77	_	
ပိ	100															
	100	3	5	r		۱,۱	0 m2,m ad m	nax.		. 5	i0			10	10	

Horizontal collision: P = 0.5 MPa

MY1H32

Calculation of Absorbed Energy for Stroke

Adjustment Unit with Shock Absorber Unit: N.m.										
	Horizontal collision	Vertical collision (Downward)	Vertical collision (Upward)							
Type of impact	<u>m</u> <u>s</u>	0 m	<u>a</u>							
Kinetic energy E1		$\frac{1}{2}$ m· \mathbb{U}^2								
Thrust energy E2	F⋅s	F·s + m·g·s	F·s – m·g·s							
Absorbed energy		E1 + E2								

Symbols

υ: Speed of impact object (m/s)

F: Cylinder thrust (N)

s: Shock absorber stroke (m)

m: Mass of impact object (kg)

g: Gravitational acceleration (9.8 m/s2)

Note) The speed of the impact object is measured at the time of impact with the shock absorber. MY3M

MY1B

MY1H

MY1B

MY1M

MY1C

MY1H

MY1

MY1

 $\square W$

MY2C

MY2

H/HT

MY3A

MY3B

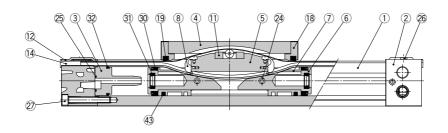
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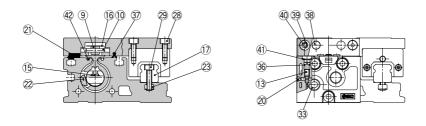
D-□ -X□ Technical



Construction

Standard type







Mechanically Jointed Rodless Cylinder Linear Guide Type MY1H Series

Component Parts

	ipolielii rai is		
No.	Description	Material	Note
1	Cylinder tube	Aluminum alloy	Hard anodized
2	Head cover	Aluminum alloy	Painted
3	Cushion boss	Special resin	
4	Slide table	Aluminum alloy	Hard anodized
5	Piston yoke	Aluminum alloy	Chromated
6	Piston	Aluminum alloy	Chromated
7	Wear ring	Special resin	
8	Belt separator	Special resin	
9	Guide roller	Special resin	
10	Parallel pin	Stainless steel	
11	Coupler	Sintered iron material	
12	Head plate	Stainless steel	
13	Cushion needle	Rolled steel	Nickel plated
14	Belt clamp	Special resin	
17	Guide	_	
18	End cover	Special resin	
20	Steel ball	Carbon tool steel	
21	Bearing	Special resin	
22	Magnet	Rare earth magnet	
23	Square nut	Carbon steel	Chromated
24	Spring pin	Bearing steel	
26	Thin head screw	Chromium molybdenum steel	Chromated
27	Hexagon socket head cap screw	Chromium molybdenum steel	Chromated
28	Hexagon socket head cap screw	Chromium molybdenum steel	Chromated
29	Hexagon socket head cap screw	Chromium molybdenum steel	Chromated
33	Hexagon socket head taper plug	Carbon steel	Chromated (Centralized piping: 10 pcs.)
34	Hexagon socket head taper plug	Carbon steel	Chromated (Centralized piping: 4 pcs.)
38	Stopper	Carbon steel	
39	Spacer	Stainless steel	
40	Hexagon socket button head screw	Chromium molybdenum steel	Chromated
41	CR retaining ring	Spring steel	
42	Seal magnet	Rubber magnet	
43	Lube retainer	Special resin	

Renlacement Parte: Seal Kit

nep	Replacement Parts: Sear Kit									
No.	Description	Material	Qty.	MY1H25	MY1H32	MY1H40				
15	Seal belt	Urethane	1	MY25-16C-Stroke	MY32-16C-Stroke	MY40-16C-Stroke				
16	Dust seal band	Stainless steel	1	MY1B25-16B-Stroke	MY1B32-16B-Stroke	MY1B40-16B-Stroke				
25	Cushion boss gasket	NBR	2	MYB25-16GA5900	MYB32-16GA5901	MYB40-16GA5902				
36	O-ring	NBR	2	KA00311	KA00320	KA00320				
30	O-ring	INDI	-	(ø5.1 x ø3 x ø1.05)	(ø7.15 x ø3.75 x ø1.7)	(ø7.15 x ø3.75 x ø1.7)				
37	Side scraper	Special resin	2	MYH25-15BK2902B	MYH32-15BK2903B	MYH40-15BK2904B				
19	Scraper	NBR	2							
30	Piston seal	NBR	2							
31	Cushion seal	NBR	2	MY1H25-PS	MY1H32-PS	MY1H40-PS				
32	Tube gasket	NBR	2							
35	O-ring	NBR	2							

^{*} Seal kit includes 19, 30, 31, 32 and 35. Order the seal kit based on each bore size.

MY1 HT MY1 □W MY2C MY2 H/HT МҮ3А MY3B MY3M

MY1B MY1H MY1B MY1M MY1C MY1H

-X□ Technical Data

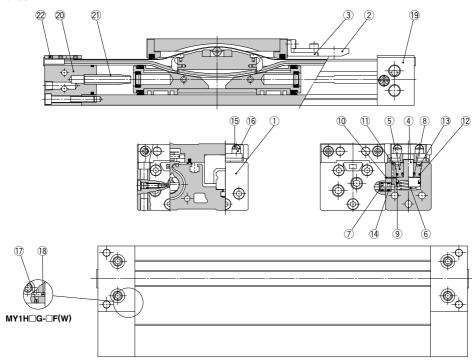
D-□



^{*} Seal kit includes a grease pack (10 g). When (5) or (6) is shipped independently, a grease pack (20 g) is included. Order with the following part number when only the grease pack is needed. Grease pack part number: GR-S-010 (10 g), GR-S-020 (20 g)

Construction

End lock



Component Parts

Description	Material	Note
Locking body	Aluminum alloy	Painted
Lock finger	Carbon steel	After quenching, nickel plated
Lock finger bracket	Rolled steel	Nickel plated
Lock piston	Carbon tool steel	After quenching, electroless nickel plated
Rod cover	Aluminum alloy	Hard anodized
Return spring	Spring steel	Zinc chromated
Bypass pipe	Aluminum alloy	Hard anodized
Steel ball	High carbon chromium bearing steel	
Steel ball	High carbon chromium bearing steel	
Inverted internal retaining ring	Carbon tool steel	Nickel plated
Hexagon socket head cap screw	Chromium molybdenum steel	Chromated
Hexagon socket head cap screw	Chromium molybdenum steel	Chromated
Steel ball	High carbon chromium bearing steel	
Steel ball	High carbon chromium bearing steel	
Head cover WR	Aluminum alloy	Painted
Head cover WL	Aluminum alloy	Painted
Cushion ring	Aluminum alloy	
Hexagon socket head set screw	Chromium molybdenum steel	Chromated
	Locking body Lock finger Lock finger bracket Lock piston Rod cover Return spring Bypass pipe Steel ball Inverted internal retaining ring Hexagon socket head cap screw Hexagon socket head cap screw Steel ball Steel ball Head cover WR Head cover WR Lead cover WL Loushion ring	Locking body Lock finger Lock finger Lock finger bracket Lock piston Rod cover Return spring Bypass pipe Bypass pipe Steel ball High carbon chromium bearing steel High carbon chromium bearing steel Hexagon socket head cap screw Hagon carbon chromium bearing steel Head cover WR High carbon chromium bearing steel Head cover WL Aluminum alloy Aluminum alloy Aluminum alloy

Replacement Parts: Seal Kit

No.	Description	Material	Qty.	MY1H25	MY1H32	MY1H40
8	Rod seal	NBR	1	KB00267	KB00267	KB00267
9	Piston seal	NBR	1	KB00217	KB00217	KB00217
12	O-ring	NBR	1	KB00037	KB00037	KB00037
14	O-ring	NBR	2	KA00048	KA00048	KA00048

 $[\]ast$ Since the seal kit does not include a grease pack, order it separately. Grease pack part no.: GR-S-010 (10 g)

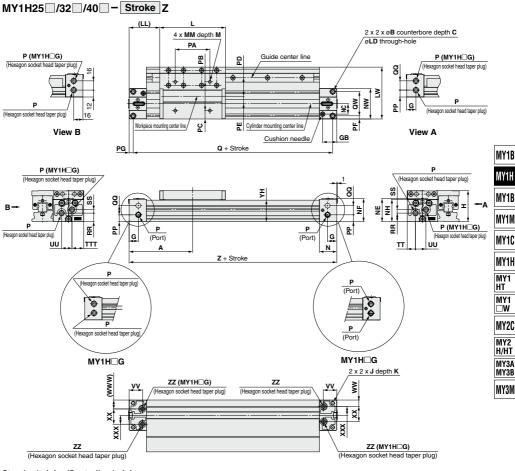




Mechanically Jointed Rodless Cylinder Linear Guide Type MY1H Series

Standard Type/Centralized Piping Type

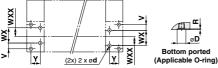
Regarding centralized piping port variations, refer to page 1222.



Standard piping/Centralized piping A B C G GB H N NC NE NF NH NW PA PB PC MY1H25 110 9 5.5 16 24.5 54 M6 x 1 9.5 114 5.6 53 90 9 M5 x 0.8 30 18 40.2 40.5 39 53 60 50 14.5 Rc1/8 MY1H32 140 11 6.6 19 28.5 68 M8 x 1.25 16 140 6.8 70 110 13 M6 x 1 37 22 50.2 50 49 64 Rc1/8 80 60 15 MY1H40 170 14 8.5 23 35 84 M10 x 1.5 15 170 8.6 85 121 13 M6 x 1 45 26.5 62.7 62 61.5 75 Rc1/4 100 80 20.5

Model	PD	PE	PF	PG	PP	Q	QW	RR	TT	TTT	٧٧	ww	www	XXX	YH	Z	ZZ
MY1H25	32	13	5.5	7	12	206	42	15	14.5	20.5	23.3	11	15.5	15.5	37.5	220	Rc1/16
MY1H32	42	13	6.5	8	16	264	51	16	16	16	28.5	12	12	20	47	280	Rc1/16
MY1H40	37.5	23	8	9	18.5	322	59	23.5	20	20	35	14	14	23.5	59.5	340	Rc1/8

Centralize	d pi	ping		(mm)
Model	QQ	SS	UU	XX
MY1H25	16	6	18	26.5
MY1H32	16	11	32	40
MY1H40	24	12	35	47



* This figure shows the recommended machining dimensions of
the mounting surface when viewed from the cylinder side.

the mount	ıng surface	when vie	ewed from	the cy	lınder	SIC
Values inc	ida tha nar	anthonon	ara thaaa	for BAY	/1 U 🗆 /	•

Hole Size for Centralized Piping on the Bottom	1 (Machine the mounting side to the dimensions below.)
--	--

Standard	pipiii	g/CE	entra	lizec	ı bib	ilig (mm)
Model	WXX	Υ	d	D	R	Applicable O-ring
MY1H25	15.5	16.2	6	11.4	1.1	C9
MY1H32	20	20.4	6	11.4	1.1	Cs
MY1H40	23.5	25.9	8	13.4	1.1	C11.2

Centralize	d pipin	g (mm)
Model	WX	V
MY1H25	26.5	10
MY1H32	40	5.5
MY1H40	47	6

SMC

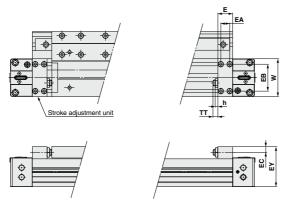
D-□

-X□

Technical

Stroke Adjustment Unit

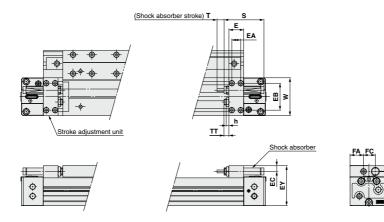
With adjustment bolt MY1H Bore size - Stroke AZ





Applicable cylinder	Е	EA	EB	EC	EY	FA	FC	h	TT	W
MY1H25	18	9	40	7.5	53.5	16	21	3.5	5 (Max.16.5)	53
MY1H32	25	14	45.6	9.5	67.5	23	20	4.5	8 (Max.20)	64
MY1H40	31	19	55	11	82	24.5	26	4.5	9 (Max.25)	75

With low load shock absorber + adjustment bolt MY1H Bore size — Stroke LZ

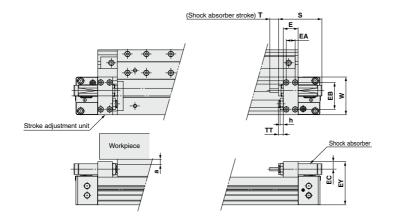


														(mm)
Applicable cylinder	E	EA	EB	EC	EY	F	FA	FC	h	S	Т	TT	W	Shock absorber model
MY1H25	18	9	40	7.5	53.5		16	21	3.5	46.7	7	5 (Max.16.5)	53	RB1007
MY1H32	25	14	45.6	9.5	67.5	_	23	20	4.5	67.3	12	8 (Max.20)	64	RB1412
MY1H40	31	19	55	11	82	_	24.5	26	4.5	67.3	12	9 (Max.25)	75	RB1412

Mechanically Jointed Rodless Cylinder MY1H Series

Stroke Adjustment Unit

With high load shock absorber + adjustment bolt MY1H Bore size Stroke HZ





* Since the EY dimension of H unit is greater than the table top height (H dimension), when a workpiece exceeding the overall length (L dimension) of the slide table is mounted, allow a clearance of size "a" or larger at the workpiece side.

Applicable cylinder	E	EA	EB	EC	EY	F	FA	FC	h	S	Т	TT	W	Shock absorber model	а
MY1H25	18	9	40	9	57	_	18	17.5	4.5	67.3	12	5 (Max.16.5)	53	RB1412	3.5
MY1H32	25	14	45.6	12.4	73	_	18.5	22.5	5.5	73.2	15	8 (Max.20)	64	RB2015	5.5
MY1H40	31	19	55	12.4	86		26.5	22	5.5	73.2	15	9 (Max.25)	75	BB2015	2.5

MY1B

MY1B MY1M

MY1C

MY1H MY1 HT

MY1 □W

MY2C MY2 H/HT

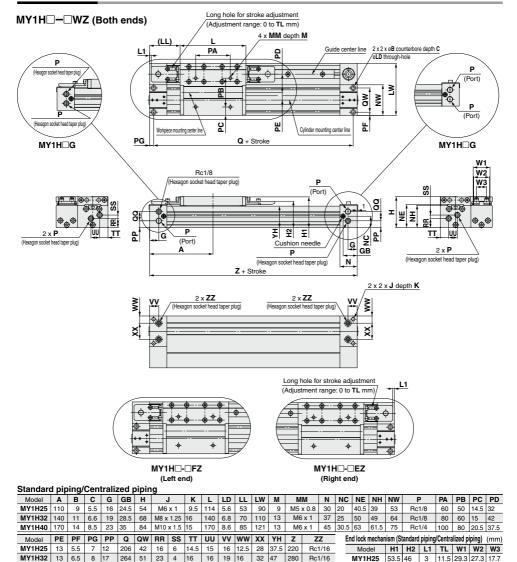
MY3A MY3B

D-□ -X□

Technical Data



With End Lock





9 8.5 322 59 27 10.5 20



22 | 23 | 19.5 | 36 | 59.5 | 340

Rc1/8

Bottom ported (Applicable O-ring)



6.5 12

MY1H40 83 68.5 10.5 16 38 35 24.4

29.3 27.3 17.7

Standard	pipin	ıg/C	entra	alize	d pip	oing	
Model	WV	v	9	7	ח	ь	Γ

MY1H32 67 56

Model	WX	Υ	S	d	D	R	Applicable O-ring
MY1H25	28	9	7	6	11.4	1.1	C9
MY1H32	32	11	9.5	6	11.4	1.1	C9
MY1H40	36	14	11.5	8	13.4	1.1	C11.2



MY1H40 23

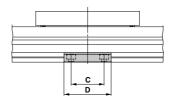
R

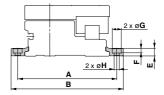
^{*} This figure shows the recommended machining dimensions of the mounting surface when viewed from the cylinder side.

Mechanically Jointed Rodless Cylinder Linear Guide Type MY1H Series

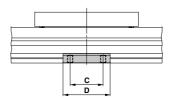
Side Support

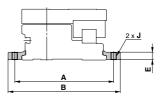
Side support A MY-S□A





Side support B MY-S□B





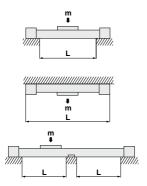
										(mm)
Part no.	Applicable cylinder	Α	В	С	D	E	F	G	Н	J
MY-S25A	MY1H25	105	119	35	50	8	5	9.5	5.5	M6 x 1
MY-S32A	MY1H32	130	148	45	64	11.7	6	11	6.6	M8 x 1.25
MY-S40 ^A _B	MY1H40	145	167	55	80	14.8	8.5	14	9	M10 x 1.5

* Side supports consist of a set of right and left supports.

Guide to Side Support Application

For long stroke operation, the cylinder tube may be deflected depending on its own weight and the load. In such a case, use a side support in the middle section. The spacing (L) of the support must be no more than the values shown in the below graph.

SMC



(800) 50 (600) 40 (550) Mass m (kg) 10 1500 Support spacing L (mm)

- 1. If the cylinder mounting surfaces are not measured accurately, using a side support may cause poor operation. Therefore, be sure to level the cylinder tube when mounting it. Also, for long stroke operation involving vibration and impact, use of a side support is recommended.
- 2. Support brackets are not for mounting; use them solely for providing support.

-X□ Technical Data

D-□

MY1B MY1H MY1B MY1M

MY1C MY1H MY1 нт

MY1 $\square W$

MY2C

MY2

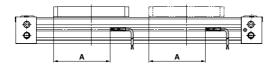
H/HT MY3A MY3B

MY3M

1219

MY1H Series Auto Switch Mounting

Auto Switch Proper Mounting Position



Auto Switch Proper Mounting Position (mm)

Auto switch model	D-M9 D-M9 V D-M9 W D-M9 WV D-M9 AL D-M9 AV	D-A9□ D-A9□V
Bore size	Α	Α
25	85	81
32	116.5	112.5
40	137.5	133.5

Note) Adjust the auto switch after confirming the operating conditions in the actual setting.

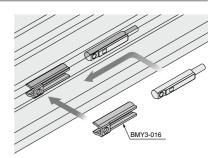
Operating Range

			(mm)			
Auto switch model	Bore size					
Auto switch model	25	32	40			
D-M9□/M9□V						
D-M9□W/M9□WV	5.0	5.5	5.5			
D-M9□A/M9□AV						
D-A9□/A9□V	7.0	10.0	9.0			

Note) Values which include hysteresis are for guideline purposes only, they are not a guarantee (assuming approximately ±30% dispersion) and may change substantially depending on the ambient environment.

Auto Switch Mounting Bracket/Part No.

Auto switch model	Bore size (mm)
Auto switch model	ø25 to ø40
D-M9□/M9□V D-M9□W/M9□WV D-M9□A/M9□AV D-A9□/A9□V	BMY3-016



Other than the applicable auto switches listed in "How to Order", the following auto switches are mountable.

- * Normally closed (NC = b contact) solid state auto switches (D-F9G/F9H) are also available. For details, refer to page 1593.
- * With pre-wired connector is also available for solid state auto switches. For details, refer to pages 1648 and 1649.

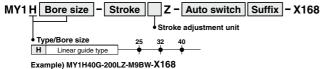
Made to Order: Individual Specifications

Please contact SMC for detailed dimensions, specifications and lead times.





Helical insert thread is used for the slide table mounting thread, the thread size is the same as the standard model.



Specifications: Same as standard type

MY1H
MY1B
MY1M
MY1C
MY1H
MY1
HT
MY1
HT
MY2
H/HT
MY2
H/HT
MY3A
MY3A

MY3M

MY1B







MY1H Series **Specific Product Precautions 1**

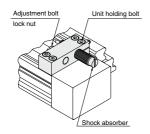
Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

Operating Precautions

. Caution

Use caution not to get your hands caught in the unit.

· When using a product with stroke adjustment unit, the space between the slide table (slider) and the stroke adjustment unit becomes narrow at the stroke end, causing a danger of hands getting caught. Install a protective cover to prevent direct contact with the human body.



<Fastening of unit>

The unit can be secured by evenly tightening the four unit holding bolts.

Tightening Torque for Stroke

Adjustment Unit Holding Bolts Unit: N-m

Bore size (mm)	Tightening torque
25	1.8
32	3.5
40	5.8

^Caution

Do not operate with the stroke adjustment unit fixed in an intermediate position.

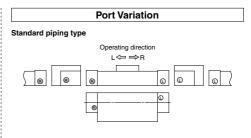
When the stroke adjustment unit is fixed in an intermediate position, slippage can occur depending on the amount of energy released at the time of an impact. In that case, use a short spacer or a long spacer. For other lengths, please consult with SMC. (Refer to "Tightening Torque for Stroke Adjustment Unit Holding Bolts.")

<Adjustment bolt stroke adjustment>

Loosen the adjustment bolt lock nut, and adjust the stroke from the lock cover side using a hexagon wrench. Then, retighten the lock nut.

<Shock absorber stroke adjustment>

Loosen the two unit holding bolts at the shock absorber side, turn the shock absorber and adjust the stroke. Then, uniformly retighten the unit holding bolts to secure the shock absorber.



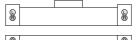
Centralized piping type

Operating direction L⇔⇔R ®

End lock

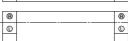
®D

L⇔ ⇒R



Operating direction







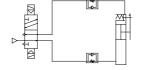
MY1H Series Specific Product Precautions 2

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

With End Lock

Recommended Pneumatic Circuit

This is necessary for the correct locking and unlocking actions.



Operating Precautions

1. Do not use 3-position solenoid valves.

Avoid use in combination with 3-position solenoid valves (especially closed center metal seal types). If pressure is trapped in the port on the lock mechanism side, the cylinder cannot be locked

Furthermore, even after being locked, the lock may be released after some time due to air leaking from the solenoid valve and entering the cylinder.

2. Back pressure is required when releasing the lock.

Before starting operation, be sure to control the system so that air is supplied to the side without the lock mechanism (in case of locks on both ends, the side where the slide table is not locked) as shown in the figure above. There is a possibility that the lock may not be released. (Refer to "Lock Release.")

- Release the lock when mounting or adjusting the cylinder. If mounting or other work is performed when the cylinder is locked, the lock unit may be damaged.
- 4. Operate at 50% or less of the theoretical output.

If the load exceeds 50% of the theoretical output, this may cause problems such as failure of the lock to release, or damage to the lock unit.

- 5. Do not operate multiple cylinders in synchronization. Avoid applications in which two or more end lock cylinders are synchronized to move one workpiece, as one of the cylinder locks may not be able to release when required.
- 6. Use a speed controller with meter-out control.
 - Lock cannot be released occasionally by meter-in control.

7. Be sure to operate completely to the cylinder stroke end on the side with the lock.

If the cylinder piston does not reach the end of the stroke, locking and unlocking may not be possible. (Refer to "End Lock Mechanism Adjustment.")

Operating Pressure

⚠ Caution

 Supply air pressure of 0.15 MPa or higher to the port on the side that has the lock mechanism, as it is necessary for disengaging the lock

Exhaust Speed

∧ Caution

1. Locking will occur automatically if the pressure applied to the port on the lock mechanism side falls to 0.05 MPa or less. In the cases where the piping on the lock mechanism side is long and thin, or the speed controller is separated at some distance from the cylinder port, the exhaust speed will be reduced. Take note that some time may be required for the lock to engage. In addition, clogging of a silencer mounted on the solenoid valve exhaust port can produce the same effect.

Relation to Cushion

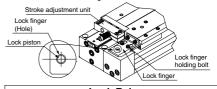
⚠ Caution

 When the air cushion on the lock mechanism side is in a fully closed or nearly closed state, there is a possibility that the slide table will not reach the stroke end, in which case locking will not occur.

End Lock Mechanism Adjustment

∕**.**∖ Caution

- The end lock mechanism is adjusted at the time of shipping.
 Therefore, adjustment for operation at the stroke end is unnecessary.
- 2. Adjust the end lock mechanism after the stroke adjustment unit has been adjusted. The adjustment bolt and shock absorber of the stroke adjustment unit must be adjusted and secured first. Locking and unlocking may not occur otherwise.
- Perform fine adjustment of the end lock mechanism as follows. Loosen the lock finger holding bolts, and then adjust by aligning the center of the lock piston with the center of the lock finger hole. Secure the lock finger.



Lock Release

⚠ Warning

1. Before releasing the lock, be sure to supply air to the side without the lock mechanism, so that there is no load applied to the lock mechanism when it is released. (Refer to "Recommended Pneumatic Circuit.") If the lock is released when the port on the side without the lock is in an exhaust state, and with a load applied to the lock unit, the lock unit may be subjected to an excessive force and be damaged.

Furthermore, sudden movement of the slide table is very

Manual Release

. Caution

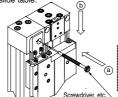
dangerous.

 When manually releasing the end lock, be sure to release the pressure.

If it is unlocked while the air pressure still remains, it will lead to damage a workpiece, etc. due to unexpected lurching.

2. Perform manual release of the end lock mechanism as follows.

Push the lock piston down with a screwdriver, etc., and move the slide table.



Other handling precautions regarding mounting, piping and environment are the same as the standard series

D-U
-XU
Technical

MY1B

MY1H

MY1B

MY1C

MY1H

MY1

MY1

 $\square W$

MY2C

MY2

H/HT

MY3A

MY3B

MY3M

нт

