

# **Shock Absorber: Short Type** Series RBQ

#### Allowable eccentric angle is 5°

Ideal for absorption of rotating energy

#### **Specifications**

Model	Basic type	RBQ1604	RBQ2007 RBQ2508		RBQ3009	RBQ3213
Specifications	With bumper	RBQC1604	BQC1604 RBQC2007 RBQC2508		RBQC3009	RBQC3213
Max. energy abso	rption (J)	1.96	11.8	19.6	33.3	49.0
Stroke absorption	(mm)	4	7	8	8.5	13
Collision speed (n	n/s)			0.05 to 3		
Max. operating frequency * (cycle/min)		60	60	45	45	30
Max. allowable thrust (N)		294	490	686	981	1177
Ambient temperat	ure (C°)			-10 to 80		
Coning force (NI)	Extended	6.08	12.75	15.69	21.57	24.52
Spring force (N)	Retracted	13.45	27.75	37.85	44.23	54.23
Weight (g)	Weight (g)		60	110	182	240
Option/Stopper nu	ıt	RBQ16S	RB20S	RBQ25S	RBQ30S	RBQ32S

<sup>\*</sup>It denotes the values at the maximum energy absorption per one cycle. Therefore, the operating frequency can be increased according to the energy absorption.

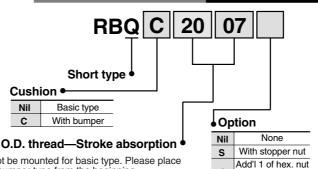


With bumper Series RBQC

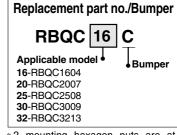
Basic type Series RBQ



(Total: 3 pcs.\*)

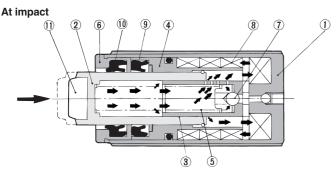


Bumper cannot be mounted for basic type. Please place an order with bumper type from the beginning.



2 mounting hexagon nuts are attached as standard.

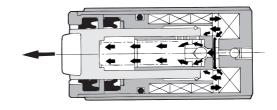
#### Construction



An impact object that strikes against the piston rod end pressurizes oil inside the piston. Thus, pressurized oil jets out through the orifice inside the piston, thereby generating hydraulic resistance to absorb the energy of the impacting object.

The oil jetted out through the orifice is collected inside the outer tube by means of the stretching action of the accumulator.

#### At returning



When the impact object is removed, the return spring pushes out the piston rod, and negative pressure, generated at the same time, opens the check ball to permit oil to return to the shock absorber ready for the next impact.

#### **Component Parts**

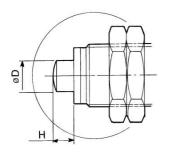
No.	Description	Material	Treatment
1	Outer tube	Rolled steel Black nickel plated	
2	Piston rod	Special steel Heat treated, Hard chrome	
3	Piston	Special steel Heat treated	
4	Bearing	Special bearing material	
(5)	Return spring	Piano wire	Zinc chromated
6	Stopper	Carbon steel Zinc chromated	

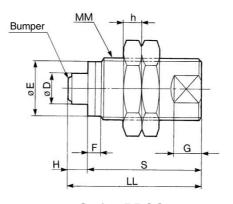
No.	Description	Material	Treatment
7	Check ball	Bearing steel	
8	Accumulator	Fluoro rubber	Foam rubber
9	Rod seal	NBR	
10	Scraper	NBR	
11)	Bumper	Polyurethane	Only with bumper

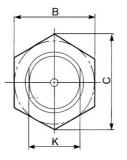


# Shock Absorber: Short Type Series RBQ

#### **Dimensions**







**Series RBQ Basic type** 

With bumper

**RBQC1604** 

**RBQC2007** 

**RBQC2508** 

**RBQC3009** 

**RBQC3213** 

MM

M16 x 1.5

M20 x 1.5

M25 x 1.5

M30 x 1.5

M32 x 1.5 6

Note 1) In the case of RB20J, RB and RBQ are

D

6

10

12

18

Ε

14.2

18.2

23.2

28.2

30.2

(mm)

С

25.4

31.2

47.3

47.3

37

В

22

27

32

41

41

h

6

6

6

6

Model

Basic type

**RBQ1604** 

**RBQ2007** 

**RBQ2508** 

**RBQ3009** 

**RBQ3213** 

**Hexagon Nut** 

Part no.

RBQ16J

**RB20J** (1)

RBQ25J

RBQ30J

RBQ32J

(2 pcs. standard equipment)

**Series RBQC** With bumper

Κ

14

18

23

28

30

Shock absorber

G

9

10

12

13

(mm)

6

6

6

6

6

Hexagon nut

С

25.4

31.2

47.3

47.3

37

В

22

27

32

41

41

MK(2)

RE A

**REC** 

**C**□X

CUY

MQ M

**RHC** 

RS G RSA A

**RZQ** 

MIS

CEP1

CE1

CE<sub>2</sub>

ML2B

C<sub>G</sub>5-S

CV

MVGQ

CC

RB

D-

-X 20-

Data

**SMC** 

# **Option**

3.5

4

4

5

#### Stopper nut



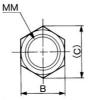
н

4

8

13

8.5



LL

31

52

76

44.5

61.5

B

Material: Carbo	(mm)			
Part no.	В	С	h1	ММ
RBQ16S	22	25.4	12	M16 x 1.5
RB20S (2)	27	31.2	16	M20 x 1.5
RBQ25S	32	37	18	M25 x 1.5
RBQ30S	41	47.3	20	M30 x 1.5
RBQ32S	41	47.3	25	M32 x 1.5

Note 2) In the case of RB20S, RB and RBQ are

#### **Replacement Parts**

s

27

44

53

63

37.5

#### **Bumper**

ММ

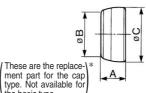
M16 x 1.5

M20 x 1.5

M25 x 1.5

M30 x 1.5

M32 x 1.5



tine basic	type. I
Material:	Polyurethane

Part no.	Α	В	С
RBQC16C	3.5	4	4.7
RBQC20C	4.5	8	8.3
RBQC25C	5	8.3	9.3
RBQC30C	6	11.3	12.4
RBQC32C	6.6	13.1	14.4

# Series RBQ/Shock Absorber: Short Type **Technical Data:**

#### **Model Selection**

#### **Model Selection Step**

#### 1. Type of impact

- Cylinder stroke at load (Horizontal)
- Cylinder stroke at load (Downward)
- Cylinder stroke at load (Upward)
- Conveyor stroke at load (Horizontal)
- Free dropping impact
- Rotating impact (With torque)

#### 2. Enumeration of operating conditions

Symbol	Operating conditions	Unit
m	Impacting object weight	kg
υ	Collision speed	m/sec
h	Dropping height	m
ω	Angle speed	rad/sec
r	Distance between axis of cylinder and impact point	m
d	Bore size	mm
р	Cylinder operation pressure	MPa
F	Thrust	Ν
Т	Torque	
n	Operation cycle	cycle/min
t	t Ambient temperature	
μ	Friction coefficient	

#### 3. Specifications and operational instructions

Ensure that the collision speed, thrust, operation cycle, the ambient temperature and atmosphere fall within the specifications.

\* Be aware of the min. installation radius in

the case of rotating impacts.

## Calculation of kinetic energy E<sub>1</sub>

Using the equation suitable for the classification of impact.

In the case of cylinder stroke at load and free horizontal impact, substitute respective figures for Data A in order to calculate E1.

#### Calculation of thrust energy E2 Select any shock absorber as a provisional

In the case of thrust energy of cylinder E2, substitute respective figures for Data B or Data C.

#### Calculation of corresponding weight of impacting object Me Absorbed energy $E = E_1 + E_2$

Corresponding weight of impacting object  $Me = \frac{2}{v^2} \cdot E$ 

Substitute both absorbed energy E and collision speed  $\upsilon$  for Data A in order to calculate the corresponding weight of the impacting object.

#### 7. Selection of applicable model

Taking into consideration the corresponding weight of the impacting object Me, calculated using Data D and collision speed υ, check provisional model compatibility with the condition of application. If this is satisfactory, then the said provisional model will be the applicable one

#### Caution on Selection

In order for the shock absorbers to operate accurately for long hours, it is necessary to select a model that is well-suited to your operating conditions. If the impact energy is smaller than 5% of the maximum energy absorption, select a model that is one class

#### Selection Example

#### Cylinder stroke at load (Horizontal) Shock absorber **Type** of impact Collision speed (1) Kinetic energy ·m∙υ² Εı Thrust energy F<sub>1</sub>·S E2 Absorbed energy E<sub>1</sub> + E<sub>2</sub> Corresponding (2 <u>2</u>.E weight of impacting object Me m = 20 kg $\upsilon = 0.7 \text{ m/s}$ d = 40 mmOperating p = 0.5 MPaconditions n = 20 cycle/min t = 25°C Confirmation of specifications

### **Specifications** and operational

instructions

υ ··· 0.7 < 3 (max.) t ··· -10 (min.) < 25 < 80 (max.) F ··· F1 ··628 < 686 (max.)

#### YES

### Calculation of kinetic energy E<sub>1</sub>

 Kinetic energy E1 Use Formula to calculate E1. Suitable 20 for m and 0.7 for  $\upsilon$ 

#### E<sub>1</sub> ≅ 4.9 J

### Calculation of thrust energy E2

 Thrust energy E2 Provisionally select a model RBQ2508 and make the use of Data B. According to d = 40, E2

#### $E_2 \cong 5.0 J$

#### Calculation of corresponding weight of impacting object Me

Selection of

applicable

model

Corresponding weight of impacting object Me

Use the formula "Absorbed energy E = E1 + E2 = 4.9 + 5.0 = 9.9J" to calculate Me. Substitute 9.9 J for E and 0.7 for  $\nu$ .

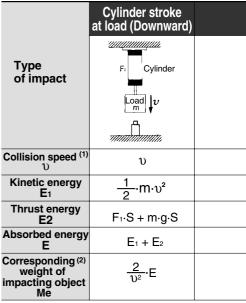
#### Me ≅ 40 kg

#### Selection of applicable model

According to Data D, the tentatively selected RBQ2508 satisfies Me = 40 kg < 60 kg at v = 0.7. Ultimately, it will result in an operating frequency of n...30 < 45, without causing a problem.



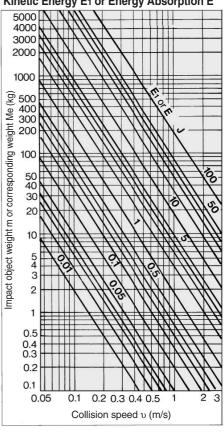
#### 1. Type of Impact



Note 1) Collision speed is momentary velocity at which object is impacting against shock absorber.

#### Data A

#### Kinetic Energy E<sub>1</sub> or Energy Absorption E



# Shock Absorber: Short Type Series RBQ

Cylinder stroke at load (Upward) at load (Horizontal)		Free dropping impact	Rotating impact (Weight torque)
v Load m Cylinder	Load d	Load v	7 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
υ	υ	$\sqrt{2 \text{ gh}}$	ω·R
$\frac{1}{2}$ ·m· $v^2$	$\frac{1}{2}$ ·m· $v^2$	m⋅g⋅h	$\frac{1}{2}$ ·I· $\omega^2$
F₁⋅S – m⋅g⋅S	m⋅g⋅μ⋅S	m⋅g⋅S	T. <u>S</u>
E <sub>1</sub> + E <sub>2</sub>	E <sub>1</sub> + E <sub>2</sub>	E <sub>1</sub> + E <sub>2</sub>	E <sub>1</sub> + E <sub>2</sub>
<u>2</u> .∙E	<u>2</u> .∙E	$\frac{2}{v^2}$ E	<u>2</u> , E

Note 2) An "Impact body equivalent weight" is the weight of an impact object without involving thrust, into which an object's total energy has been converted.), refer to the catalog of rotary actuator. Hence,  $E=\frac{1}{2}$ -Me· $0^2$ 

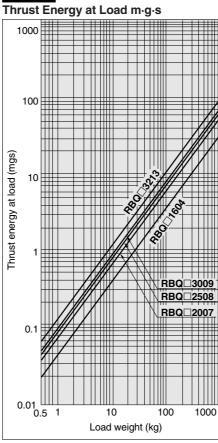
Note 3) For the formula of moment of inertia I (kg·m²), refer to the catalog of rotary actuator.

#### (Operating pressure 0.5 MPa) Data B v of Cylinder F1.S

Ih	I hrust Energy of Cylinder F1.S (J)							
Model		RBQ□ 1604	RBQ□ 2007	RBQ□ 2058	RBQ□ 3009	RBQ□ 3213		
Stro	oke absorption (mm)	4	7	8	8.5	13		
	6	0.057	0.099	0.113	0.120	0.184		
	10	0.157	0.274	0.314	0.334	0.511		
	15	0.353	0.619	0.707	0.751	1.15		
	20	0.628	1.10	1.26	1.34	2.04		
	25	0.982	1.72	1.96	2.09	3.19		
	30	1.41	2.47	2.83	3.00	4.59		
<del>-</del>	40	2.51	4.40	5.03	5.34	8.17		
Bore size d (mm	50	3.93	6.87	7.85	8.34	12.8		
þ	63	6.23	10.9	12.5	13.2	20.3		
Size	80	10.1	17.6	20.1	21.4	32.7		
ore	100	15.7	27.5	31.4	33.4	51.1		
Ď	125	24.5	43.0	49.1	52.2	79.8		
	140	30.8	53.9	61.6	65.4	100		
	160	40.2	70.4	80.4	85.5	131		
	180	50.9	89.1	102	108	165		
	200	62.8	110	126	134	204		
	250	98.2	172	196	209	319		
	300	141	247	283	300	459		

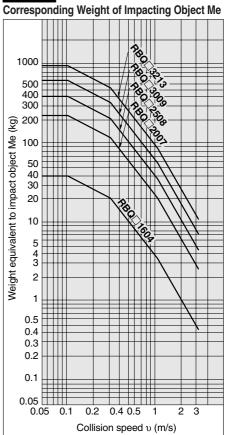
#### ■ Operating pressure other than 0.5 MPa: Multiply by the following coefficient.

Operating pressure (MPa)	1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9
Coefficient	0.2	0.4	0.6	0.8	1.0	1.2	1.4	1.6	1.8



#### **Symbol**

Syllii	JOI		
Symbol	Specifications	Unit	
d	Bore size	mm	
E	Absorbed energy	J	
E <sub>1</sub>	Kinetic energy	J	
E <sub>2</sub>	Thrust energy	J	
F1	Cylinder thrust	N	
g	Acceleration of gravity (9.8)	m/s²	
h	Dropping height	m	
I (3)	Moment of inertia around the center of gravity	kg⋅m²	
n	Operating frequency	cycle/min	
р	Cylinder operation pressure	MPa	
R	Distance between axis of cylinder and impact point	m	
S	Shock absorber stroke	m	
Т	Torque	N⋅m	
t	Ambient temperature	°C	
υ	Collision speed	m/s	
m	Impact object weight	kg	
Ме	Me Corresponding weight of impact object kg		
ω	Angle speed	rad/s	
μ	Friction coefficient	_	



**REC** 

RE A

**C**□X

**C**□Y

MQM

**RHC** 

MK(2)

RS<sub>G</sub>

RSA A

**RZQ** 

MIS

CEP1 CE1

CE<sub>2</sub>

ML2B

C<sub>G</sub>5-S CV

MVGQ

CC RB

D-

-X 20-

Data

# Precautions

Be sure to read before handling. Refer to pages 10-24-3 to 10-24-6 for Safety Instructions and Actuator Precautions.

#### Selection

# <u>/!\</u> Danger

1. Energy absorption

Select a model so that the aggregated energy of impact object should not exceed the maximum absorption energy. Otherwise, it could cause changes in properties or result in damaging the shock absorber.

2. Corresponding weight of impacting object

Make a model selection, so that the corresponding weight of impacting object does not exceed the allowable range. Pulsation will occur in buffer and deceleration force, thus making it difficult to absorb shock smoothly.

3. Collision speed

Use it in the conditions that collision speed is within the specified range. It could cause the changes in buffer characteristics or lead to damage a

# ∕!\ Warning

Design the system, so that any other forces than the buffer capacity or impacts should not be applied to the piston rod which is stopped at the retracted state.

# **∕!∖** Caution

Maximum operating frequency
Design the system in the conditions under which it is not used at the frequency exceeding the specified maximum operating frequency. (But, the maximum operating frequency will vary depending on the absorbed

2. Stroke

The maximum absorption energy in the specifications cannot be exerted unless the full stroke is used

3. Work surface of an impact object

The contact surface of the impact object with which the piston rod comes into contact must be highly rigid.

In the case without a cap, a high surface compression load is applied to the contact surface of the impact body with which the piston rod comes into contact. Therefore, the contact surface must be highly rigid (hardness of HRC35 or more)

4. Be aware of the return force of the impact object.

If used in a conveyor drive, after the shock absorber has absorbed energy, it could be pushed back by the spring that is built-in. For the spring force in the specifications, refer to the column (page 10-18-10).

5. Selection of size

As the number of operation proceeds, the maximum absorption energy of shock absorbers will be decreased by the following reasons such as abrasion, or deterioration, etc. of the internal working fluid. Taking this into consideration, selecting a size which is 20 to 40% affordable against the amount of absorption energy is recommended.

6. Drag characteristics

In general, the values of drag (reactive force generated during operation) generated by the operating speed will vary in hydraulic shock absorber. And then, by adopting "Porous orifice construction", the RB series can adapt to such this fast/slow speed and can absorb shock smoothly in a wide range of speed.

But, the speed reduction (speed reduction G) would be larger around the stroke terminal, depending upon the operating conditions. Please note that it might be encountered that stroke time is long, motion is not smooth, etc. If this would be a problem, we recommend that stroke amount should be restricted by using our optional component like "Stopper nut", etc.

Including this case, if the data on operational status (stroke time, reactive force, deceleration, etc.) are required, please consult with SMC

#### **Operating Environment**

## 🗥 Danger

- 1. Operation in an environment which requires explosion-proof
  - · When mounting in places where static electricity is accumulated, implement a distribution of electrical energy by grounding.

    • Do not use the materials for buffer face which might cause to spark by
  - collision.

# 🗥 Warning

Do not use it in the vacuum state, which is substantially different from the atmospheric pressure (above sea level) and in the atmosphere under being pressurized.

#### 2. Using inside a clean room

Do not use the shock absorber in a clean room, as it could contaminate

### ∕!\ Caution

1. Temperature range

Do not use it, exceeding the specified allowable temperature range. Seal could be softened or hardened or worn out, or leading to leak a working fluid, deterioration, or impact characteristic changes.

2. Deterioration by atmosphere

Do not use in an atmosphere such as salt damage, sulfurous acid gas which makes the metal corroded, or having solvent, etc. which makes seal deteriorated.

3. Deterioration by ozone

Do not use it under the direct sunlight on the beach, or by the mercury lamp, or the ozone generator, because the rubber material will be deteriorated by ozone.

4. Cutting oil, water, blown dust

Do not use the product under the condition, where the liquid such as cutting oil, water, blown dust, solvent, etc. is exposed either directly or in atomized form to the piston rod, or where blown dust could be adhered around the piston rod. This could cause malfunction.

When vibrations are applied on impact objects, implement a secure guide on impact objects.

#### Mounting

# ∕!\ Warning

1. Before performing installation, removal, or stroke adjustment, make sure to cut the power supply to the equipment and verify that the equipment has stopped.

2. Installation of protective cover

We recommend the protective cover should be installed in the case workers might be getting close during the operation.

3. The rigidity of the mounting frame must be taken into consideration If the mounting frame lacks strength, the shock absorber will vibrate after an impact, causing bearing wear and damage. Load on mounting plate can be calculated as follows.

Load on mounting plate  $N \cong 2$  E (Absorbed energy J)

# Warning

Tightening torque of mounting nut should be as follows.

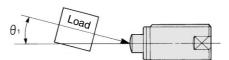
When threading on a mounting frame in order to mount a shock absorber directly, prepared hole dimensions are referred to the table below. For tightening torque of a nut for shock absorber, kindly abide by the table

If the tightening torque that is applied to the nut exceeds the value given below, the shock absorber itself could become damaged.

Model	RBQ(C)1604	RBQ(C)2007	RBQ(C)2508	RBQ(C)3009	RBQ(C)3213
O.D. thread (mm)	M16 x 1.5	M20 x 1.5	M25 x 1.5	M30 x 1.5	M32 x 1.5
Thread prepared bore (mm)	ø14.7 <sup>+ 0.1</sup>	ø18.7 <sup>+ 0.1</sup>	ø23.7 <sup>+ 0.1</sup>	ø28.7 <sup>+ 0.1</sup>	ø30.7 + 0.1
Tightening torque (N·m)	14.7	23.5	34.3	78.5	88.3

#### 2. Deviation of impact

The installation must be designed so that the impact body is perpendicular to the shock absorber's axial center. An angle of deviation that exceeds 5 will place an excessive load on the bearings, leading to oil leaks within a short period of operation.



Allowable eccentric angle  $\theta_1 < 5^{\circ}$ 

# **A**Precautions

Be sure to read before handling. Refer to pages 10-24-3 to 10-24-6 for Safety Instructions and Actuator Precautions.

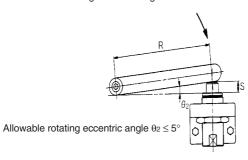
(mm)

#### Mounting

#### 3. Rotating angle

If rotating impacts are involved, the installation must be designed so that the direction in which the load is applied is perpendicular to the shock absorber's axial center.

The allowable rotating eccentric angle until the stroke end must be  $\theta_2 \le 5^\circ$ .



#### **Installation Conditions for Rotating Impact**

Model	S (Stroke)	θ <sub>2</sub> (Allowable rotating angle)	R (Min. installation radius)
RBQ□1604	4	0 0 7	46
RBQ□2007	7		80
RBQ□2508	8	5°	92
RBQ□3009	8.5		98
RBQ□3213	13		149

Do not scratch the sliding portion of the piston rod or the outside threads of the outer tube.

Failure to observe this precaution could scratch or gouge the sliding potion of the piston rod, or damage the seals, which could lead to oil leakage and malfunction. Furthermore, damage to outside threaded portion of the outer tube could prevent the shock absorber from being mounted onto the frame, or its internal components could deform, leading to a malfunction.

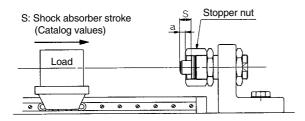
5. Never turn the screw on the bottom of the body.

This is not an adjusting screw. Turning it could result in oil leakage.



Adjust the stopping time through the use of the stopper nut, as follows:

Control the stopping time of the impact object by turning the stopper nut in or out (thus changing length "a"). After establishing the stopper nut position, use a hexagon nut to secure the stopper nut in place.



#### **Maintenance**

### **⚠** Caution

1. Check the mounting nut is not loosen.

The shock absorber could become damaged if it is used in a loose state.

2. Pay attention to any abnormal impact sounds or vibrations. If the impact sounds or vibrations have become abnormally high, the shock absorber may have reached the end of its service life. If this is the case, replace the shock absorber. If use is continued in this state, it could lead to equipment damage.

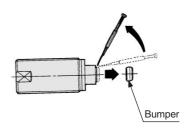
3. Confirm that abnormality, oil leakage, etc. in the outward surface. When a large amount of oil is leaking, replace the product, because it is believed to be happening something wrong with it. If it keeps on using, it may cause to break the equipment which is mounted by this product.

4. Inspect the bumper for any cracks or wear.

If the shock absorber comes with a bumper, the damper could wear first. To prevent bumper to the impact object, replace the bumper often.

5. How to replace bumper

The bumper inserted into the piston rod can be removed easily by a small screwdriver. When reassembling, push the smaller end of the bumper inside the piston.



RE A

REC

C□X C□Y

MQ Q

DUC

RHC

MK(2)

RS<sup>Q</sup><sub>G</sub>

RS<sup>H</sup>

RZQ

MI s

CE1

CE2

ML2B

C<sub>G</sub>5-S

CV

MVGQ

CC RB

J

D-

-X

20-Data