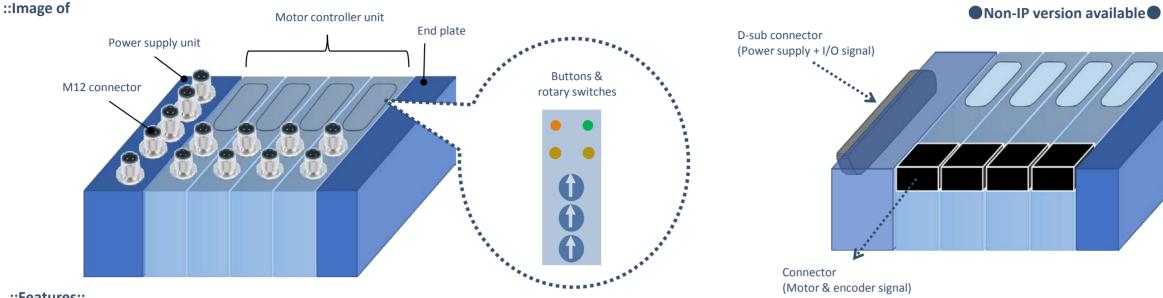
# ::Description:

Manifoldable End-to-End Operation Controllers for **Electric Actuators** 

A controller for end-to-end operation of electric actuators, which can control EAs in a similar way as that of pneumatic cylinders • Space-saving controllers by manifolding them like pneumatic valves



## ::Features::

1) EA controls with system configurations silmilar to those for pneumatic system Electric operation of a machine can be achieved easily by simple wiring, handling and signals of the controller, which are similar to those of valves for pneumatic cylinders.

## 2) Possible to have smaller controller according to the motor size

The manifold can have up to 4 controllers as needed basis. The controller has 2 body sizes depending on the size of the motor. If the smaller size controller (Size 1) is used, the manifold footprint (with 4 stations) becomes smaller than the existing LEC or JXC series controllers.

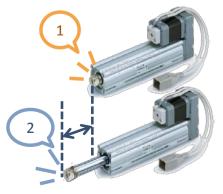
## The controllers can be operated by input signals similar to those for pneumatic valves (ON/OFF)



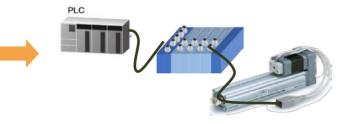
System configurations with pneumatic <u>components</u>

### Simple operation between 2 positions

End-to-end control or 2-position control by learning stroke length



Note) Homing is necessary when power is supplied.



System configurations with manifold type controller

## Simple actuator control with rotary switch

Force and speed of an electric actuator can be set and adjusted with rotary switches, that is done with a regulator and a flow controller in a pneumatic system.

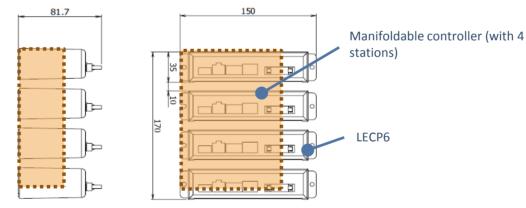
### Rotary switches

Alarm /INP



- Manual override (equivalent to that on solenoid valves)
- Speed to move forward/ backward
- Force adjustment

## Size comparison of Size 1 with LECP6 (with clearance of 10mm)



### 2 controller sizes according to motor sizes

