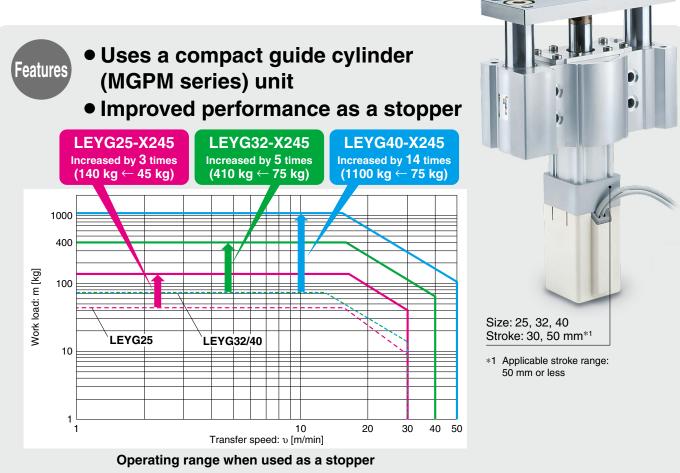
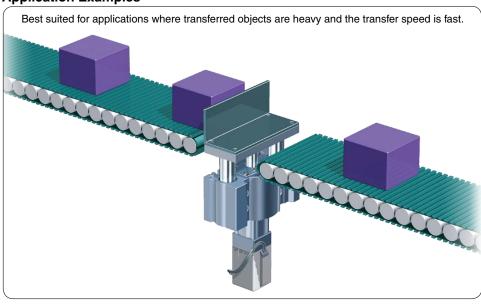
# **Electric Actuator: Guide Rod Type**

LEYG-X245



## **Application Examples**

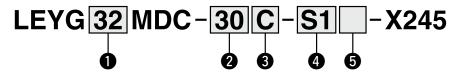


Caution

To ensure the safest possible operation of this product, please be sure to thoroughly read the "Safety Instructions" in our "Best Pneumatics" catalog before use.



#### **How to Order**



Without cable

Standard cable 1.5 m

Standard cable 3 m Standard cable 5 m Robotic cable (Flexible cable) 1.5 m

Robotic cable (Flexible cable) 3 m

Robotic cable (Flexible cable) 5 m

Robotic cable (Flexible cable) 8 m\*1

Robotic cable (Flexible cable) 10 m\*1

Robotic cable (Flexible cable) 15 m\*1

#### 1 Size 25 32

40



With motor cover

With lock/motor cover

_	4 Act	tuator cable type/length
1	Nil	Without o
	S1	Standard cab
_	S3	Standard ca
	S5	Standard ca
	R1	Robotic cable (Flexit
	R3	Robotic cable (Flex
	R5	Robotic cable (Flex
	R8	Robotic cable (Flexit

RA

RB

RC

- Robotic cable (Flexible cable) 20 m\*1 \*1 Produced upon receipt of order (Robotic cable only)
- \*2 The standard cable should only be used on fixed parts. For use on moving parts, select the robotic cable.

## 6 Controller/Driver type\*1

• • • • • • • • • • • • • • • • • • • •					
Nil	Without controller/driver				
6N	LECP6	NPN			
6P	6P (Step data input type) 1N LECP1				
1N					
1P	(Programless type)	PNP			
MJ	LECPMJ*2	_			
	(CC-Link direct input type)	NPN			
AN	AN LECPA*3				
AP	AP (Pulse input type)				

- \*1 For details on controllers/drivers and compatible motors, refer to the Web Catalog.
- \*2 Not applicable to CE
- \*3 When pulse signals are open collector, order the current limiting resistor (LEC-PA-R-□) separately. (Refer to the Web Catalog.)

## **Specifications**

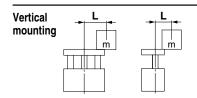
Motor option

					LEVOSENDO VOAS	LEVOCALDO VOAS	LEVO 40MBO VO4E			
	Model L Stroke [mm]				LEYG25MDC-X245 LEYG32MDC-X245 LEYG40MDC-X245					
	*				30, 50					
		Ial	LECP6 LECP1	(3000 [mm/s <sup>2</sup> ])	60	60	80			
	Work load	Horizontal	LECPMJ	(2000 [mm/s <sup>2</sup> ])	70	80	90			
	[kg]*1	힏	LECPA	(3000 [mm/s <sup>2</sup> ])	30	40	60			
		-		(2000 [mm/s <sup>2</sup> ])	50	60	_			
ရ				(3000 [mm/s <sup>2</sup> ])	30	43	53			
ē	Pushing	fo	rce [N]		232 to 452	296 to 707	562 to 1058			
ca	Speed	LE	CP6/LE	CP1/LECPMJ	5 to 125	6 to 150	6 to 175			
뺼	[mm/s]	LE	СРА		5 to 125	6 to 125	6 to 75			
be	Max. acce	lera	tion/dece	leration [mm/s <sup>2</sup> ]		3000				
Actuator specifications	Pushing	sp	eed [mn	n/s]	35 or less	30 or less	30 or less			
	Positioning repeatability [mm]			bility [mm]		±0.02				
	Lost motion [mm]					0.15 or less				
Ă	Screw le	ad	[mm]		3	3 4				
	Impact/Vibration resistance [m/s <sup>2</sup> ]			stance [m/s <sup>2</sup> ]	50/20					
	Actuation type				Ball screw					
	Guide type				Sliding bearing					
	Operating temperature range [°C]			ure range [°C]		5 to 40				
	Operating humidity range [%RH]			range [%RH]	90 or less (No condensation)					
	Motor size				□42	□56.4	□56.4			
ations	Motor type				Step motor (Servo/24 VDC)					
Electric specifications	Encoder				Incremental A/B phase (800 pulse/rotation)					
<u>:</u>	Rated vo	Rated voltage [V]			DC24 ±10%					
支	Power consumption [W]			n [W]	40	50	50			
Ee	Standby power consumption when operating [W]			when operating [W]	15	48	48			
	Max. instantaneous power consumption [W]			r consumption [W]	48 104 106					
it ons	Туре				Non-magnetizing lock					
Lock unit	Holding force [N]				294	519				
충블	Power consumption [W]			n [W]	5					
as	Rated voltage [V]				DC24 ±10%					
Inte	rnational	sta	ndards			CE marking				

- \*1 The maximum value of the work load when the acceleration/deceleration in brackets ( ) is applied
- \*2 The guide weight is not considered in the vertical work load. Add [Guide weight] to the vertical work load, and then refer to the "Speed - Vertical Work Load Graph" of the LEY series in the Web Catalog.
- \*3 For other precautions, refer to the LEY series in the Web Catalog.

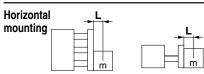
### Weight of Guide Drive

Size	Weight [kg]				
Stroke	25	35	40		
30	0.9	1.6	3.1		
50	1	1.8	3.3		

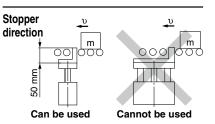


Size	Eccentric distance: L [mm]	10	50	100	200
25	1	30	30	21.9	10.9
32	Load mass [kg]	43	43	36	18
40	[kg]	53	53	49.2	25

For the load mass, subtract the guide weight according to the stroke.

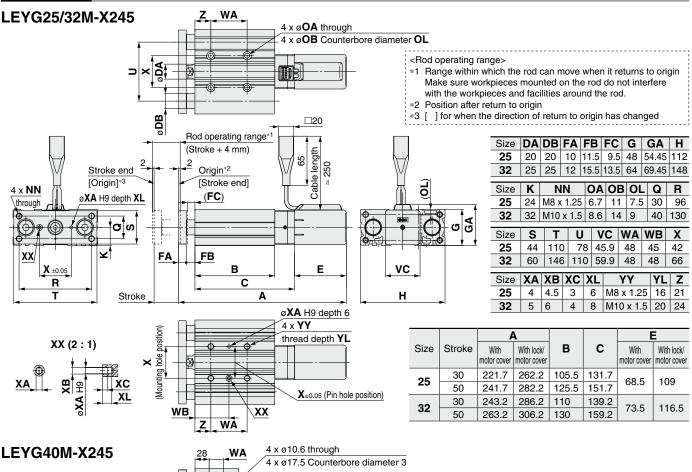


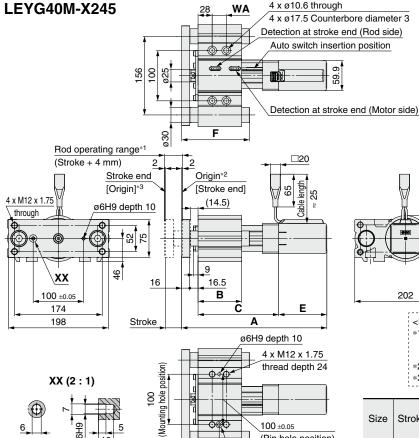
Size	Stroke [mm]	Load mass [kg]			
Size	Stroke [mm]	30	50		
25	L = 50 mm	12.7	11.1		
25	L = 100 mm	9.5	8.5		
32	L = 50 mm	19.1	16.7		
32	L = 100 mm	14.4	12.9		
40	L = 50 mm	22.5	19.9		
40	L = 100 mm	17.2	15.5		

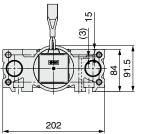




## **Dimensions**







- <Rod operating range>
- \*1 Range within which the rod can move when it returns to origin Make sure workpieces mounted on the rod do not interfere with the workpieces and facilities around the rod.
- \*2 Position after return to origin
- \*3 [ ] for when the direction of return to origin has changed

			Α					E		
	Size	Stroke	With motor cover	With lock/ motor cover	В	С	WA	With motor cover	With lock/ motor cover	F
	40	30	288	331	86.5	160	28	95.5	138.5	134.5
40	40	50	308	351	106.5	180	52			154.5

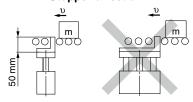


(Pin hole position)

# Caution

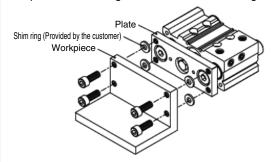
1. Workpiece collision in series with the guide cannot be permitted.

#### Stopper direction



- 2. The manufacturable stroke range is 30 to 300 mm. Please contact SMC for strokes other than 30 and 50. When using as a stopper, select a model with a stroke of 50 mm or less.
- 3. Make sure that the cylinder mounting surface has a flatness of 0.02 mm or less.

If the flatness of the workpieces and brackets mounted on the plate are not appropriate, sliding resistance may increase. If it is difficult to maintain a flatness of 0.02 mm or less, put a thin shim ring (provided by the customer) between the plate and the workpiece mounting surface to prevent the sliding resistance from increasing.



4. Do not scratch or gouge the sliding portion of the piston rod and the guide rod.

Doing so may cause a malfunction.

5. Do not dent or scratch the mounting surface of the body and the plate.

This may cause a decrease in the flatness of the mounting surface, which will cause an increase in sliding resistance.

6. Do not operate the actuator in a state where lateral loads are applied.

The actuator may not operate due to the friction force generated between the conveyor and the transferred object.

Regarding this product, unless otherwise noted along with a separate contract or agreement within the Product Specifications, the safety instructions specified in the catalog are applied.

Please contact your local SMC Sales office for further de-

