

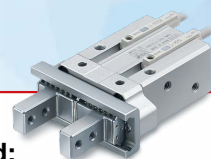
# Compact Type Parallel Style Air Gripper

ø8, ø12, ø16, ø20

RoHS

New

- A single acting type has been added.
- Made-to-order options have been added:
  - ① With positioning pins on the lateral mounting surface
  - ② Lateral auto switch mounting



Downsizing is possible without changes to the gripping point range. (ø20→ø16)

Overall length

Max. **21.7** mm shorter

102.7 mm → 81 mm

Thickness

Max. **7.6** mm shorter

33.6 mm → 26 mm

Weight

Max. **180** g lighter

420 g → 240 g



\* When comparing the ø25 of the MHZ2 and the ø20 of the JMHZ2

High rigidity and precision are achieved by integrating the guide and finger.

With high-precision linear guide

Repeatability: **±0.01 mm**

A linear guide of higher rigidity and precision is used.

**Higher rigidity**

(Compared with the same size of the existing MHZ2)



**JMHZ2 Series**

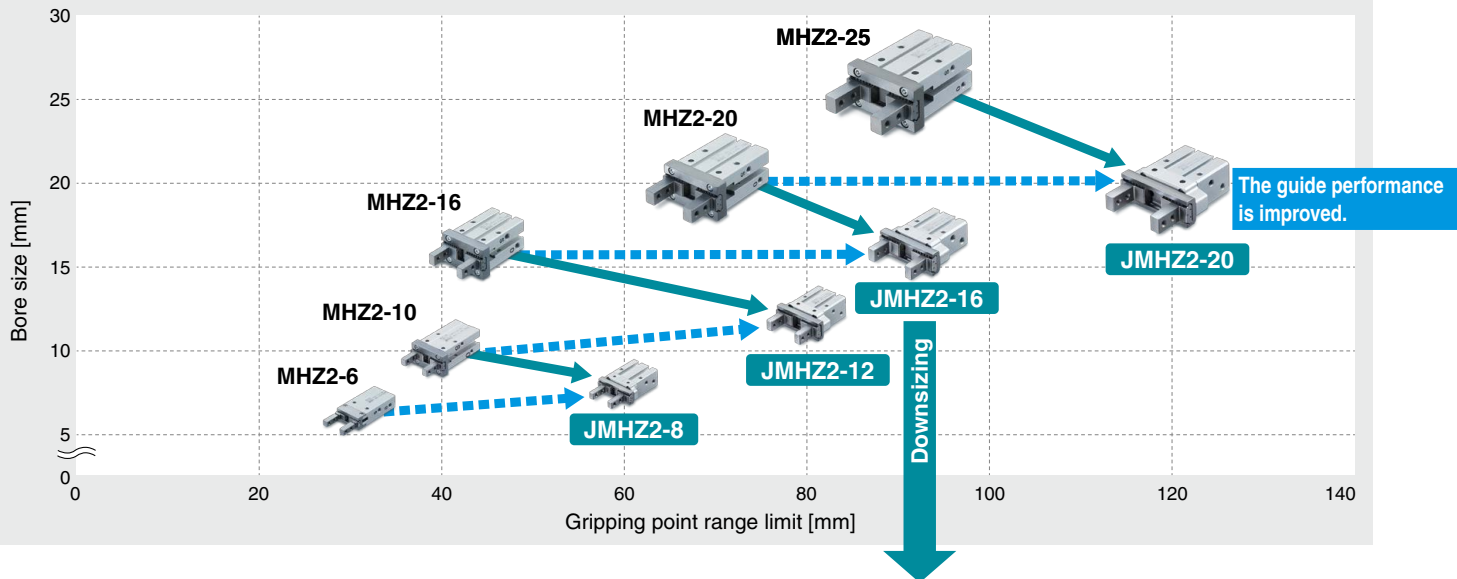


**SVC**

CAT.ES20-262B

# Compact Type Parallel Style Air Gripper *JMHZ2 Series*

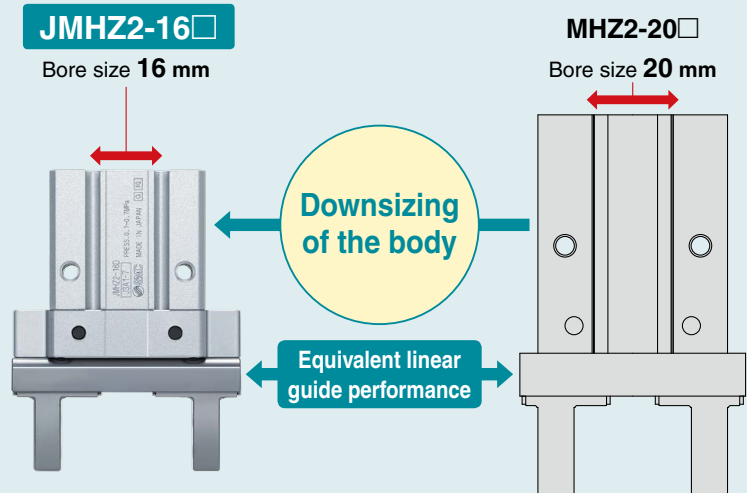
## Series Map



## Downsizing

The cylinder can be downsized by one bore size without reducing the linear guide performance.

Bore size [mm]	
JMHZ2	MHZ2
8	10
12	16
16	20
20	25



## Compact and lightweight

### Overall length reduction [mm]

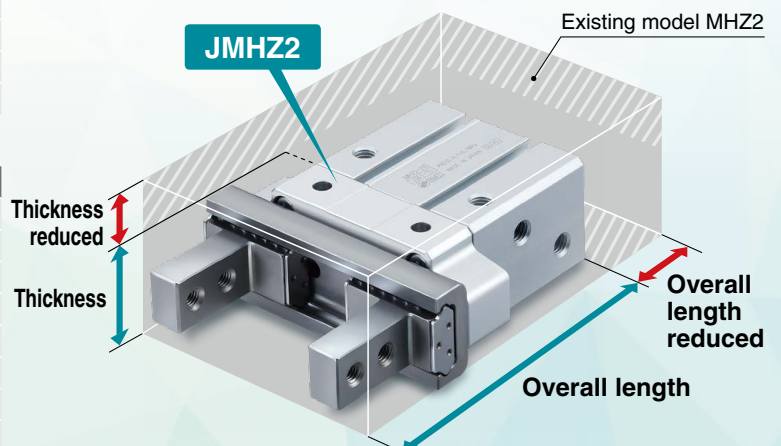
Bore size	JMHZ2		MHZ2	Reduction
8	Double acting	46.8	57	10.2
	Single acting	50.6		6.4
12	Double acting	52	67.3	15.3
	Single acting	57.5		9.8
16	Double acting	65.5	84.8	19.3
	Single acting	73		11.8
20	Double acting	81	102.7	21.7
	Single acting	91		11.7

### Thickness reduction [mm]

Bore size	JMHZ2	MHZ2	Reduction
8	13	16.4	3.4
12	17	23.6	6.6
16	20	27.6	7.6
20	26	33.6	7.6

### Weight reduction [g]

Bore size [mm]	JMHZ2		MHZ2	Reduction
8	Double acting	31	55	24
	Single acting	35		20
12	Double acting	62	115	53
	Single acting	72		43
16	Double acting	128	230	102
	Single acting	142		88
20	Double acting	240	420	180
	Single acting	270		150

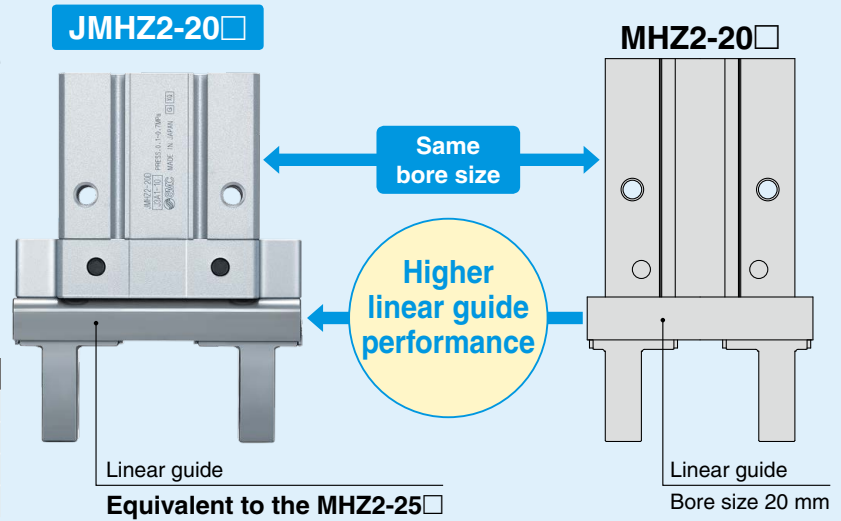


## The guide performance is improved. Higher rigidity

- A linear guide equivalent to that of a cylinder one bore size larger is used.
- Higher opening/closing stroke

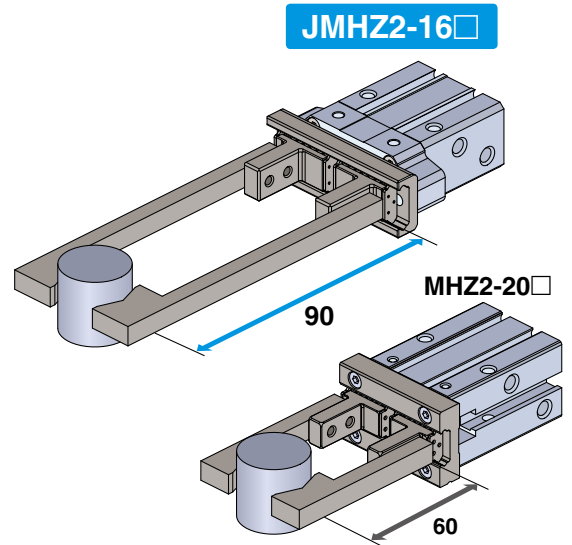
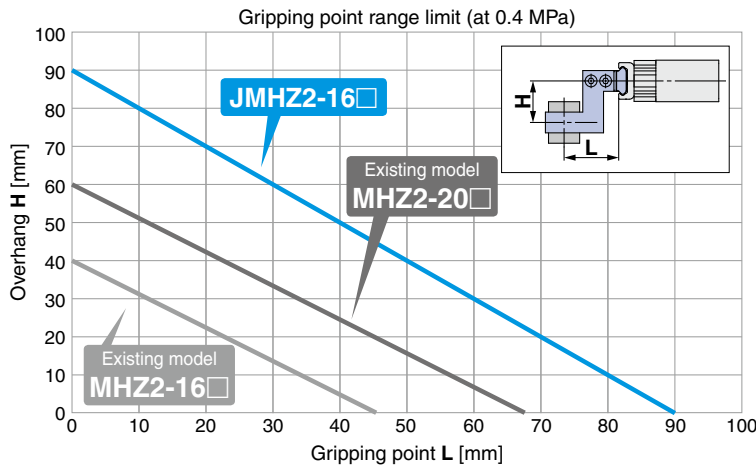
### Linear guide

Model	Linear guide
JMHZ2-8□	Equivalent to the MHZ2-10□
JMHZ2-12□	Equivalent to the MHZ2-16□
JMHZ2-16□	Equivalent to the MHZ2-20□
JMHZ2-20□	Equivalent to the MHZ2-25□

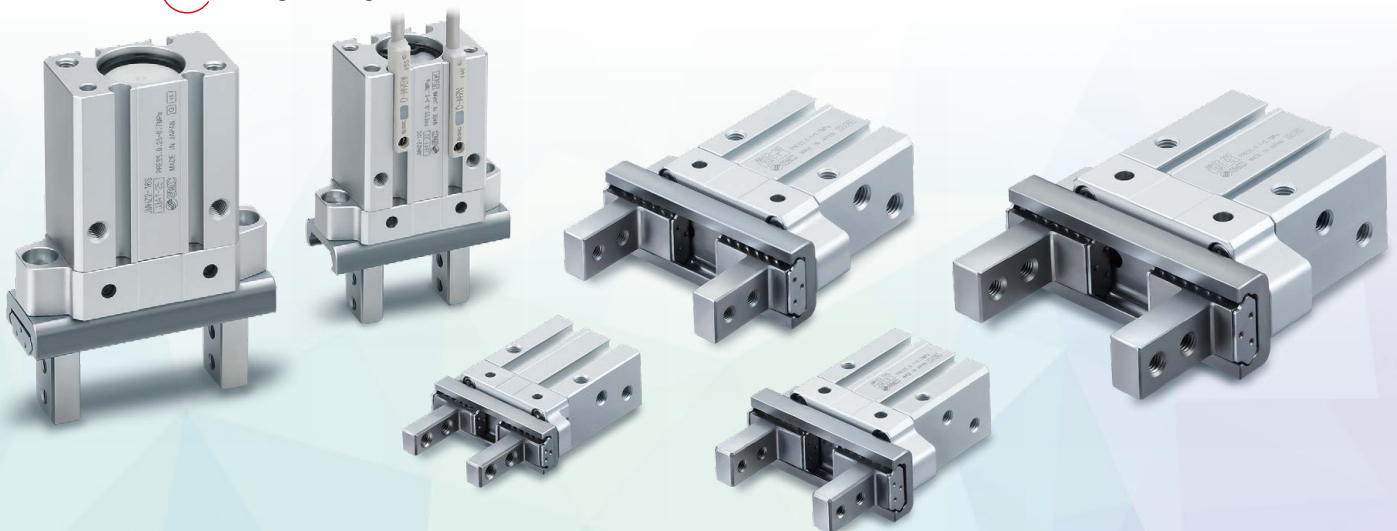


## Longer gripping point

A longer gripping point can be used with a cylinder one bore size smaller.

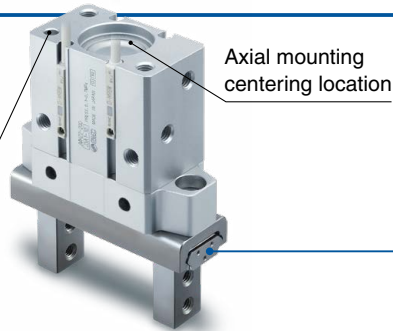


**New** Single acting



## High precision

Improved remounting accuracy  
Knock positioning pin hole



With high-precision linear guide  
Repeatability:  $\pm 0.01$  mm

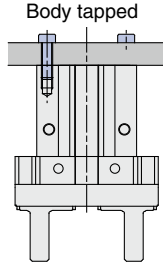
### Linear guide

Model	Linear guide
JMHZ2-8□	Equivalent to the MHZ2-10□
JMHZ2-12□	Equivalent to the MHZ2-16□
JMHZ2-16□	Equivalent to the MHZ2-20□
JMHZ2-20□	Equivalent to the MHZ2-25□

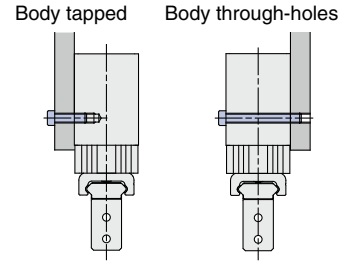
## High degree of mounting flexibility

Can be mounted 3 ways, from 2 directions

### Axial mounting

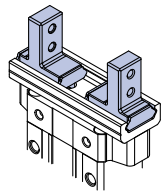


### Lateral mounting

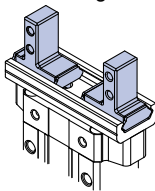


## Finger options

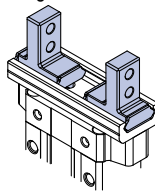
Basic (Tapped in opening/closing direction)



Side tapped mounting

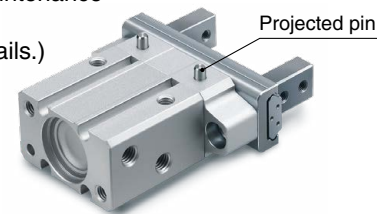


Through-holes in opening/closing direction



## **New** Positioning pins are provided.

Configured for easier maintenance  
(Made to order:  
Refer to page 20 for details.)

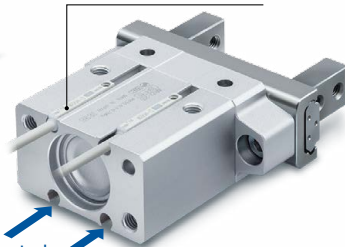


## Compact auto switches are mountable.

Solid state auto switch  
D-M9□



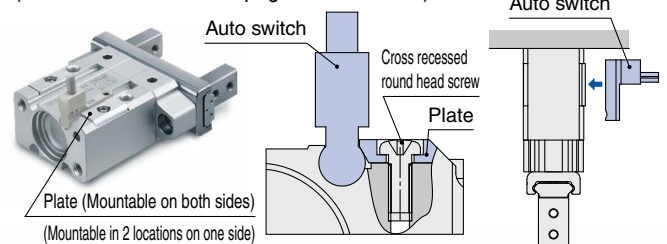
Solid state auto switch



Can be mounted  
on the opposite side

## **New** The auto switch can be mounted from the side.

The auto switch can be mounted even when the head side is blocked.  
(Made to order: Refer to page 21 for details.)



## Series Variations

Series	Bore size [mm]	Action	Opening/Closing stroke (Both sides) [mm]	Mounting orientation	Finger option
<b>Compact type JMHZ2</b> 	8	Double acting Single acting	4	· Axial mounting · Lateral mounting	· Basic (Tapped in opening/closing direction) · Side tapped mounting · Through-holes in opening/closing direction
	12		6		
	16		10		
	20		14		

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# JMHZ2 Series Model Selection

## Model Selection

### Selection Procedure

**Step 1** Check the effective gripping force.

**Step 2** Check the gripping point.

**Step 3** Check the external force on fingers.

### Step 1 Check the gripping force.

Check the conditions.

Calculate the required gripping force.

Select the model from gripping force graph.

#### Example

Workpiece mass:  
0.1 kg

Gripping method:  
External gripping

#### Guidelines for the selection of the gripper with respect to workpiece mass

- Although conditions differ according to the workpiece shape and the coefficient of friction between the attachments and the workpiece, select a model that can provide a gripping force of at least 10 to 20 times\*<sup>1</sup> greater than the workpiece weight.
- \*<sup>1</sup> For further details, refer to the model selection illustration.

- Further allowance should be provided when great acceleration or impact is expected during workpiece transfer.

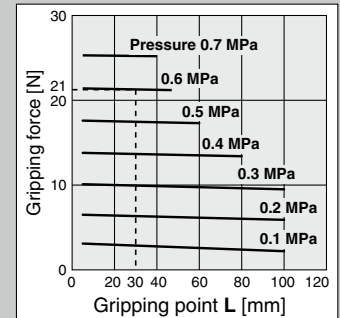
Example) For setting the gripping force to be at least 20 times greater than the workpiece weight:

Required gripping force = 0.1 kg x 20 x 9.8 m/s<sup>2</sup> ≈ 19.6 N or more

Gripping point:  
30 mm

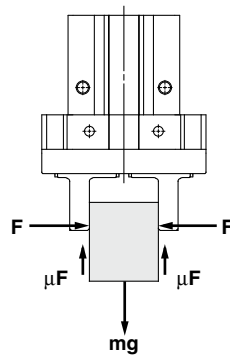
Operating pressure:  
0.6 MPa

#### JMHZ2-12D External Gripping Force



- When the JMHZ2-12D is selected  
A gripping force of 21 N is obtained from the intersection point of gripping point L = 30 mm and a pressure of 0.6 MPa.
- The gripping force is 21 times greater than the workpiece weight, and therefore satisfies a gripping force setting value of 20 times or more.

### Model Selection Illustration



#### "Gripping force at least 10 to 20 times greater than the workpiece weight"

"At least 10 to 20 times greater than the workpiece weight" recommended by SMC is calculated with a margin of "a" = 4, which allows for impacts that occur during normal transportation, etc.

When $\mu = 0.2$	When $\mu = 0.1$
$F = \frac{mg}{2 \times 0.2} \times 4$	$F = \frac{mg}{2 \times 0.1} \times 4$
$= 10 \times mg$	$= 20 \times mg$

10 x Workpiece weight

20 x Workpiece weight

When gripping a workpiece as in the figure to the left, and with the following definitions,

**F**: Gripping force [N]

$\mu$ : Coefficient of friction between the attachments and the workpiece

**m**: Workpiece mass [kg]

**g**: Gravitational acceleration (= 9.8 m/s<sup>2</sup>)

**mg**: Workpiece weight [N]

the conditions under which the workpiece will not drop are

$$2 \times \mu F > mg$$

Number of fingers

and therefore,

$$F > \frac{mg}{2 \times \mu}$$

With "a" representing the margin,

"F" is determined by the following formula:

$$F = \frac{mg}{2 \times \mu} \times a$$

- \* Even in cases where the coefficient of friction is greater than  $\mu = 0.2$ , for reasons of safety, select a gripping force which is at least 10 to 20 times greater than the workpiece weight, as recommended by SMC.
- \* If high acceleration, or impact forces are encountered during motion, a further margin should be considered.

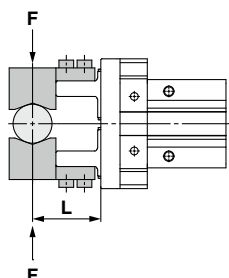
## Model Selection

### Step 1 Check the effective gripping force: JMHZ2 Series, Double Acting

#### External gripping state

- Indication of effective gripping force  
The gripping force shown in the graphs to the right represents the gripping force of one finger when all fingers and attachments are in contact with the workpiece.

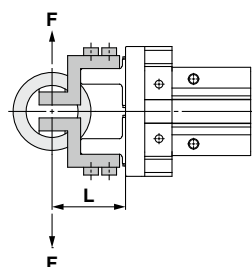
F = One finger thrust



#### Internal gripping state

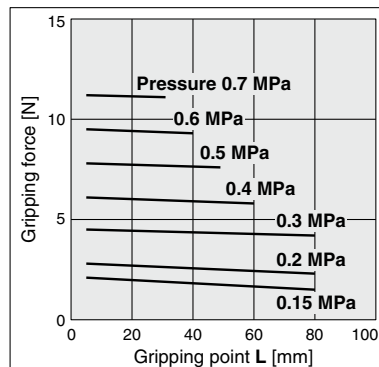
- Indication of effective gripping force  
The gripping force shown in the graphs to the right represents the gripping force of one finger when all fingers and attachments are in contact with the workpiece.

F = One finger thrust

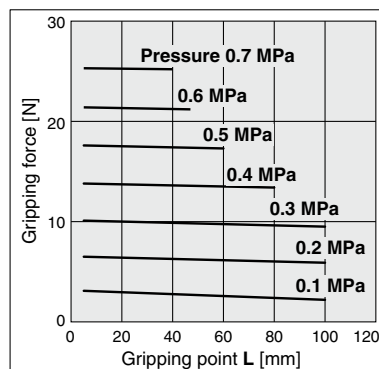


#### External Gripping Force

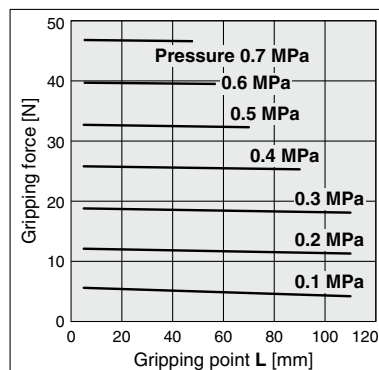
##### JMHZ2-8D



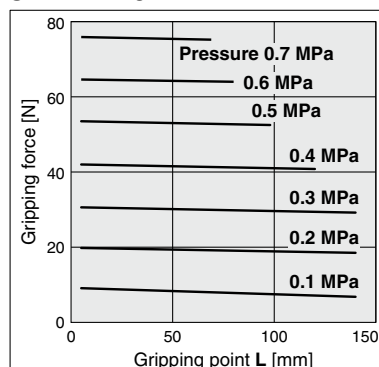
##### JMHZ2-12D



##### JMHZ2-16D

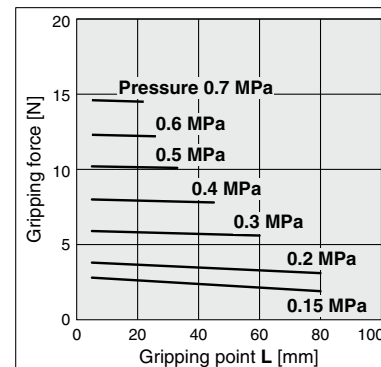


##### JMHZ2-20D

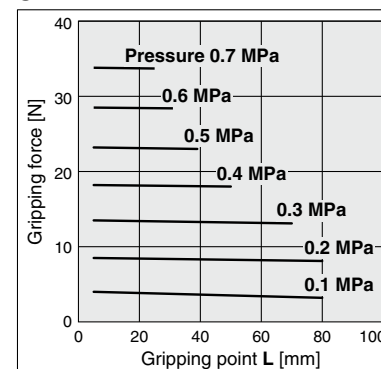


#### Internal Gripping Force

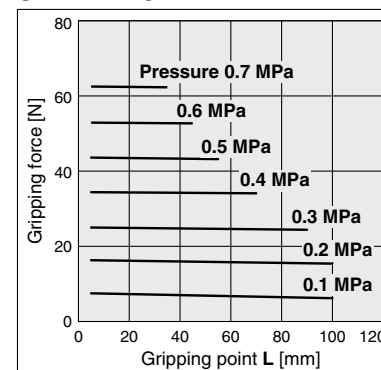
##### JMHZ2-8D



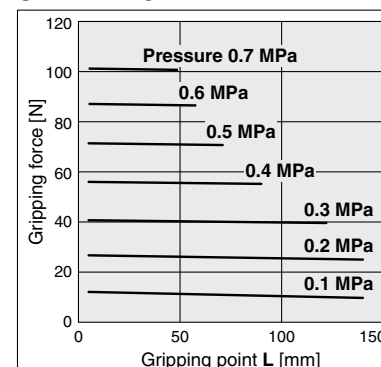
##### JMHZ2-12D



##### JMHZ2-16D



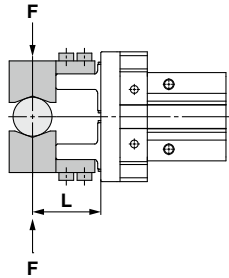
##### JMHZ2-20D



## Step 1 Check the effective gripping force: JMHZ2 Series, Single Acting

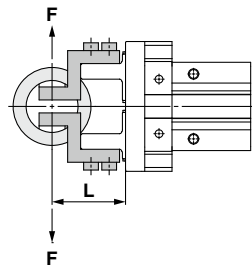
### External gripping state

- Indication of effective gripping force  
The gripping force shown in the graphs to the right represents the gripping force of one finger when all fingers and attachments are in contact with the workpiece.  
 $F$  = One finger thrust



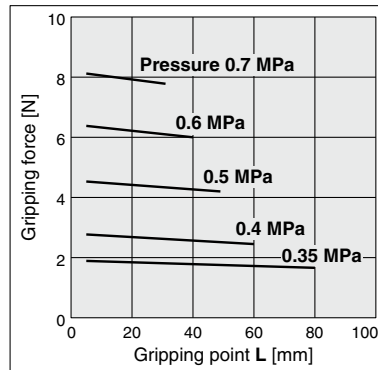
### Internal gripping state

- Indication of effective gripping force  
The gripping force shown in the graphs to the right represents the gripping force of one finger when all fingers and attachments are in contact with the workpiece.  
 $F$  = One finger thrust

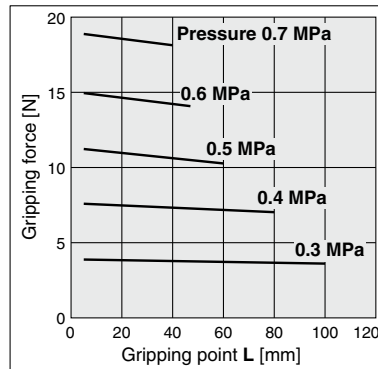


### External Gripping Force

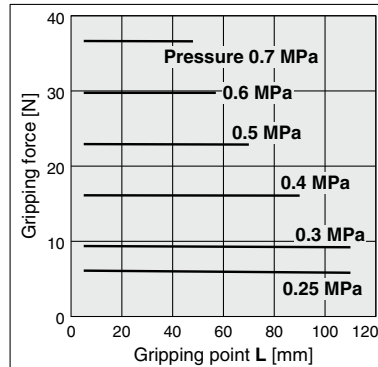
#### JMHZ2-8S



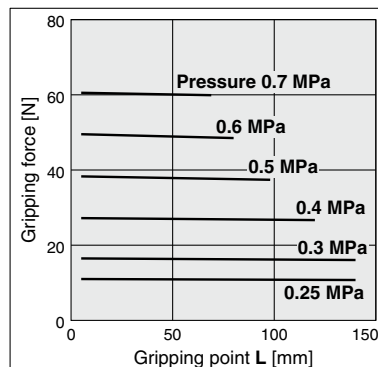
#### JMHZ2-12S



#### JMHZ2-16S

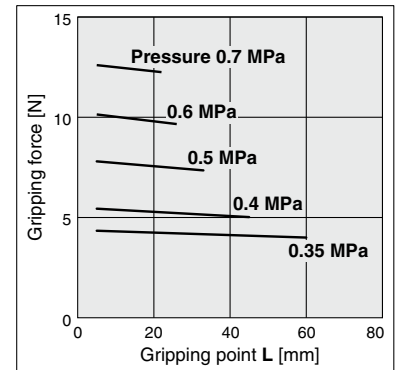


#### JMHZ2-20S

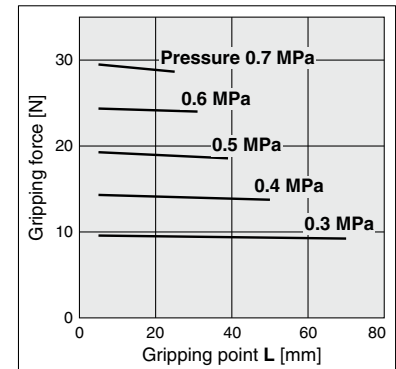


### Internal Gripping Force

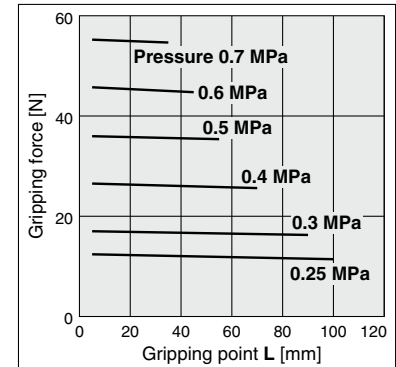
#### JMHZ2-8C



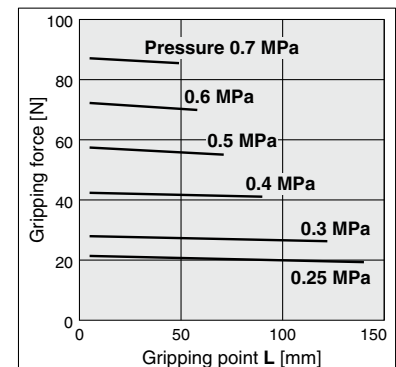
#### JMHZ2-12C



#### JMHZ2-16C



#### JMHZ2-20

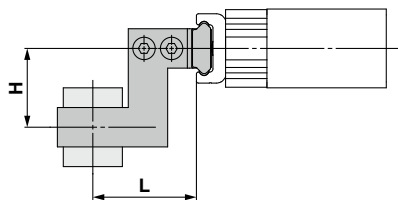


# JMHZ2 Series

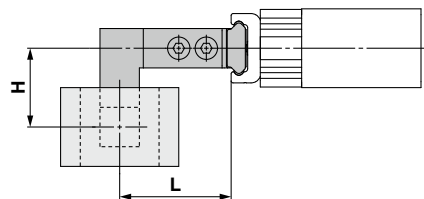
## Model Selection

### Step 2 Check the gripping point: JMHZ2 Series

#### External gripping state



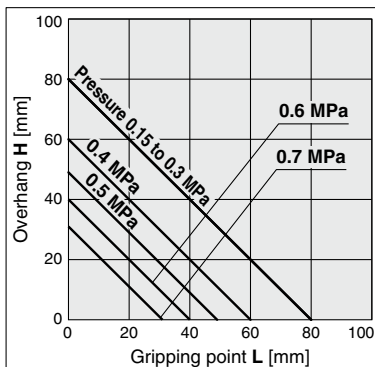
#### Internal gripping state



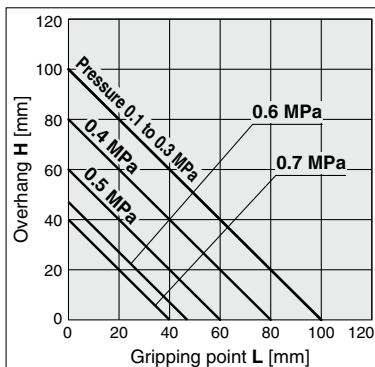
- The air gripper should be operated so that the workpiece gripping point "L" and the amount of overhang "H" stay within the range shown for each operating pressure given in the graphs to the right.
- If the workpiece gripping point goes beyond the range limits, this will have an adverse effect on the life of the air gripper.

#### External Grip

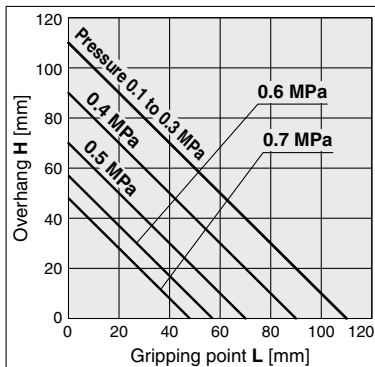
##### JMHZ2-8□



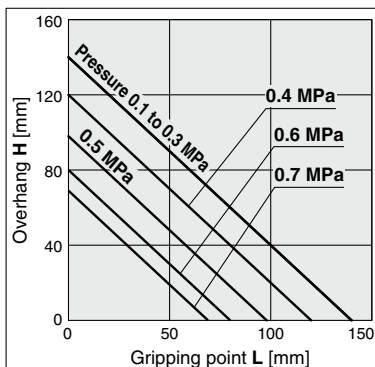
##### JMHZ2-12□



##### JMHZ2-16□

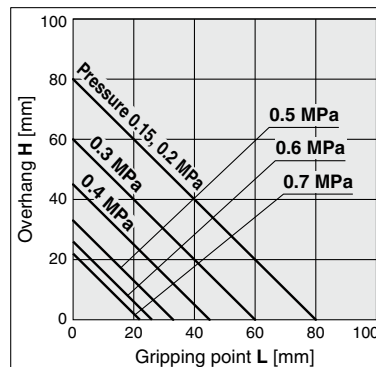


##### JMHZ2-20□

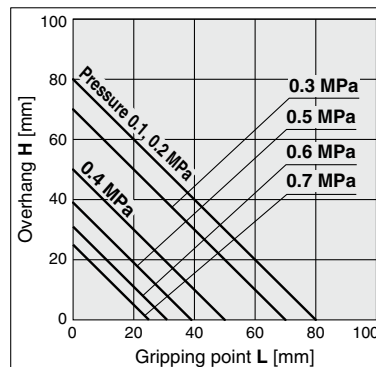


#### Internal Grip

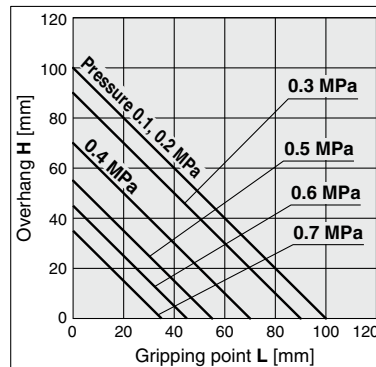
##### JMHZ2-8□



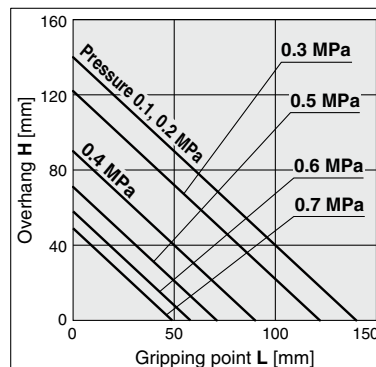
##### JMHZ2-12□



##### JMHZ2-16□

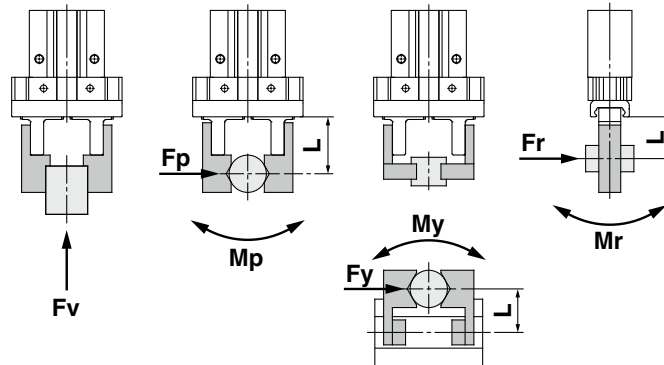


##### JMHZ2-20□





## Step 3 Check the external force on fingers: JMHZ2 Series



L: Distance to the point at which the load is applied [mm]

Model	Maximum allowable moment/load*1 *2				
	Vertical load <b>Fvmax</b> [N]	Pitch moment <b>Mpmax</b> [N·m]	Yaw moment <b>Mymax</b> [N·m]	Roll moment <b>Mrmax</b> [N·m]	Maximum lateral load <b>Fp, Fy, Fr</b> [N]*3
<b>JMHZ2-8</b>	58	0.26	0.26	0.52	14
<b>JMHZ2-12</b>	98	0.68	0.68	1.36	33
<b>JMHZ2-16</b>	147	1.32	1.32	2.64	62
<b>JMHZ2-20</b>	265	2.1	2.1	4.2	100

\*1 Inertial loads will be generated at the stroke end when the product is used for transportation. Consider the rate of acceleration.

\*2 Ensure moments and loads are the allowable values or less.

\*3 Even when the dimension L is short, the maximum lateral load should not be exceeded.

When combining a vertical load and moment, make sure the load factor is 1 or less according to the equation below.

$F_v/F_{vmax} + M_p/M_{pmax} + M_y/M_{ymax} + M_r/M_{rmax} \leq 1$  (Load factor)

## Calculation Examples of External Force

### 1 Workpiece insertion

#### When a moment in one direction is applied

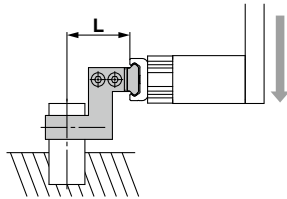
When a workpiece held by JMHZ2-16D at  $L = 30$  mm, a roll moment  $M_r$  is generated due to load  $F_r = 20$  [N].

$$M_r = F_r \times L \times 10^{-3} \times 1 \quad (*1: \text{Constant for unit conversion})$$

$$= 20 \times 30 \times 10^{-3}$$

$$= 0.6 \text{ [N·m]}$$

The moment  $M_r = 0.6$  [N·m] is the allowable moment of 2.64 [N·m] or less. The load  $F_r = 20$  [N] is the allowable load of 62 [N] or less. The product is suitable for the workpiece.



### 2 Workpiece transfer

#### When moments in multiple directions are applied

Hold the workpiece using JMHZ2-16D to transport it horizontally.

Attachment mass (One side)  $m_1$ : 0.05 [kg]

Workpiece mass  $m_2$ : 0.3 [kg]

Acceleration load  $A$  is generated when stopping at the end of transportation:  $3g$  ( $g$ : Gravitational acceleration =  $9.8 \text{ m/s}^2$ )

Calculate the followings: Load: Mass of the attachment and workpiece x acceleration (including their own weight). Moment: Mass x distance to the center of gravity of the attachment and mass x distance to the center of gravity of the workpiece.

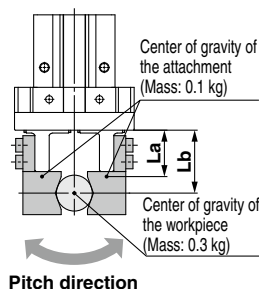
#### 1. Pitch direction (Moment due to acceleration speed)

$$F_p = (m_1 \times 2 + m_2) \times A$$

$$= (0.05 \times 2 + 0.3) \times 3 \times 9.8$$

$$= 11.76 \text{ [N]}$$

Distance to the center of gravity of the attachment  $L_a = 20$  mm,  
Distance to the center of gravity of the workpiece  $L_b = 30$  mm



$$M_p = (m_1 \times L_a \times 10^{-3} \times 1 \times 2 + m_2 \times L_b \times 10^{-3} \times 1) \times A$$

(\*1: Constant for unit conversion)

$$= (0.05 \times 20 \times 10^{-3} \times 2 + 0.3 \times 30 \times 10^{-3}) \times 3 \times 9.8$$

$$\approx 0.32 \text{ [N·m]}$$

#### 2. Yaw direction (Moment due to acceleration speed)

Distance to the center of gravity of the attachment  $L_a = 15$  mm,  
Distance to the center of gravity of the workpiece  $L_b = 18$  mm

$$F_y = (m_1 \times 2 + m_2) \times A$$

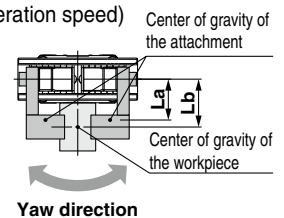
$$= (0.05 \times 2 + 0.3) \times 3 \times 9.8$$

$$= 11.76 \text{ [N]}$$

$$M_y = (m_1 \times L_a \times 10^{-3} \times 1 \times 2 + m_2 \times L_b \times 10^{-3} \times 1) \times A$$

$$= (0.05 \times 15 \times 10^{-3} \times 2 + 0.3 \times 18 \times 10^{-3}) \times 3 \times 9.8$$

$$\approx 0.20 \text{ [N·m]}$$



#### 3. Roll direction (Moment due to the own weight of the attachment and workpiece)

Distance to the center of gravity of the attachment  $L_a = 20$  mm,  
Distance to the center of gravity of the workpiece  $L_b = 30$  mm

$$F_r = (m_1 \times 2 + m_2) \times g$$

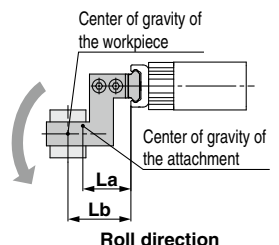
$$= (0.05 \times 2 + 0.3) \times 9.8$$

$$= 3.92 \text{ [N]}$$

$$M_r = (m_1 \times L_a \times 10^{-3} \times 1 \times 2 + m_2 \times L_b \times 10^{-3} \times 1) \times g$$

$$= (0.05 \times 20 \times 10^{-3} \times 2 + 0.3 \times 30 \times 10^{-3}) \times 9.8$$

$$\approx 0.11 \text{ [N·m]}$$



Load factor:  $M_p/M_{pmax} + M_y/M_{ymax} + M_r/M_{rmax} = 0.32/1.32 + 0.2/1.32 + 0.11/2.64 = 0.44 \leq 1$

Loads:  $F_p$ ,  $F_y$ , and  $F_r$  of each direction are each within the max. allowable lateral load of 62 [N]. Therefore, the product is suitable for the workpiece.

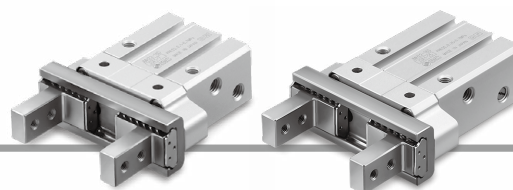
# Compact Type Parallel Style Air Gripper

## JMHZ2 Series

ø8, ø12, ø16, ø20

RoHS

### How to Order



### Bore Size

ø8 to ø20

JMHZ2-16D-M9BW

Number of fingers  
2 2

Bore size	
8	8 mm
12	12 mm
16	16 mm
20	20 mm

### Action

D	Double acting
S	Single acting (Normally open)
C	Single acting (Normally closed)

Made-to-order individual specifications  
For details, refer to page 10.

### Number of auto switches

Nil	2
S	1
n	n

### Auto switch

Nil	Without auto switch (Built-in magnet)
-----	---------------------------------------

\* For applicable auto switches, refer to the table below.

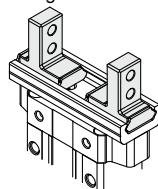
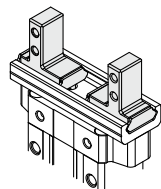
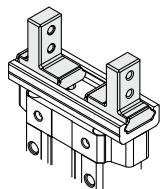
### Finger option

[Standard]

Nil: Basic

1: Side tapped mounting

2: Through-holes in opening/closing direction



### Moisture Control Tube IDK Series



When operating an actuator with a small bore size and a short stroke at a high frequency, dew condensation (water droplets) may occur inside the piping depending on the conditions. Simply connecting the moisture control tube to the actuator will prevent dew condensation from occurring. For details, refer to the IDK series in the **Web Catalog** and the Best Pneumatics Catalog.

**Applicable Auto Switches**/Refer to the **Web Catalog** and the Best Pneumatics Catalog for further information on auto switches.

Type	Special function	Electrical entry	Indicator light	Wiring (Output)	Load voltage		Auto switch model		Lead wire length [m]*1				Pre-wired connector	Applicable load			
					DC		AC	Perpendicular	In-line	0.5 (Nil)	1 (M)	3 (L)				5 (Z)	
Solid state auto switch	—	Grommet	Yes	3-wire (NPN)	5 V, 12 V	—	M9NV	M9N	●	●	●	○	○	IC circuit	Relay PLC		
				3-wire (PNP)			M9PV	M9P	●	●	●	○	○				
				2-wire			M9BV	M9B	●	●	●	○	○				
	Diagnostic indication (2-color indicator)			3-wire (NPN)	5 V, 12 V		M9NWV	M9NW	●	●	●	○	○	IC circuit			
				3-wire (PNP)			M9PWV	M9PW	●	●	●	○	○				
				2-wire			M9BWV	M9BW	●	●	●	○	○				
	Water resistant (2-color indicator)			3-wire (NPN)	5 V, 12 V		M9NAV*2	M9NA*2	○	○	●	○	○	IC circuit			
				3-wire (PNP)			M9PAV*2	M9PA*2	○	○	●	○	○				
				2-wire			12 V	M9BAV*2	M9BA*2	○	○	●	○			○	—

\*1 Lead wire length symbols: 0.5 m..... Nil  
1 m..... M  
3 m..... L  
5 m..... Z

\*2 Water-resistant type auto switches can be mounted on the above models, but SMC cannot guarantee water resistance.

\* Auto switches marked with "○" are produced upon receipt of order.

\* When using the 2-color indicator type, please make the setting so that the indicator is lit in red to ensure the detection at the proper position of the air gripper.

\* An auto switch with a reduced overall length for the D-M9□ is available upon request. (Produced upon receipt of order)  
Please contact your local sales representative for more details.

# Compact Type Parallel Style Air Gripper **JMHZ2 Series**



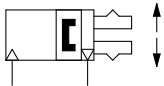
## Specifications

Bore size [mm]			8	12	16	20
Fluid			Air			
Operating pressure	Double acting		ø8: 0.15 to 0.7 MPa ø12 to ø20: 0.1 to 0.7 MPa			
	Single acting	Normally open	ø8: 0.35 to 0.7 MPa ø12: 0.3 to 0.7 MPa ø16 to ø20: 0.25 to 0.7 MPa			
		Normally closed				
Ambient and fluid temperatures			-10 to 60°C (No freezing)			
Repeatability			±0.01 mm			
Max. operating frequency			120 c.p.m.			
Lubricant			Non-lube			
Action			Double acting, Single acting			
Auto switch (Option)* <sup>1</sup>			Solid state auto switch (3-wire, 2-wire)			

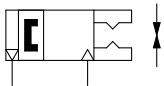
\*1 Refer to pages 16 to 18 for details on auto switches.

## Symbol

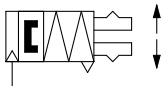
Double acting, Internal grip



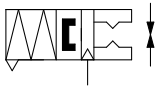
Double acting, External grip



Single acting (Normally closed), Internal grip



Single acting (Normally open), External grip



## Model

Action	Model	Bore size [mm]	Gripping force*1		Opening/ Closing stroke (Both sides) [mm]	Weight*2 [g]	Volume [cm³]		
			Effective gripping force per finger [N]				Finger opening port	Finger closing port	
			External	Internal					
Double acting	JMHZ2-8D	8	7.8	10.5	4	32	0.3	0.2	
	JMHZ2-12D	12	17.5	23.3	6	61	0.6	0.4	
	JMHZ2-16D	16	32.7	43.5	10	119	1.6	1.1	
	JMHZ2-20D	20	54.2	72.2	14	244	3.3	2.2	
Single acting	Normally open	JMHZ2-8S	8	4.5	—	4	35	0.3	0.2
		JMHZ2-12S	12	11.2	—	6	72	0.8	0.6
		JMHZ2-16S	16	22.9	—	10	142	2.2	1.5
		JMHZ2-20S	20	38.3	—	14	270	4.5	3.1
	Normally closed	JMHZ2-8C	8	—	7.8	4	35	0.3	0.2
		JMHZ2-12C	12	—	19.3	6	72	0.8	0.5
		JMHZ2-16C	16	—	36.0	10	142	2.4	1.3
		JMHZ2-20C	20	—	57.4	14	270	4.7	2.6

\*1 At a pressure of 0.5 MPa, gripping point L = 20 mm, center of stroke

\*2 Excluding the auto switch weight



**Made-to-Order Individual Specifications**  
(For details, refer to pages 20 and 21.)

Symbol	Specifications
-X6900□	With positioning pins on the lateral mounting surface
-X7460	Lateral auto switch mounting

Refer to pages 16 to 18 for grippers with auto switches.

- Auto Switch Installation Examples and Mounting Positions
- Auto Switch Hysteresis
- Auto Switch Mounting
- Protrusion of Auto Switch from Edge of Body

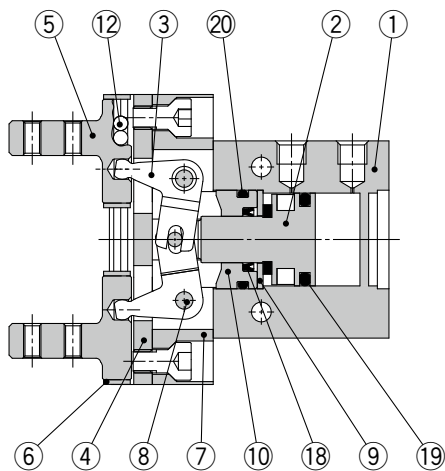
## ⚠ Precautions

Be sure to read this before handling the products. Refer to page 22 for details.

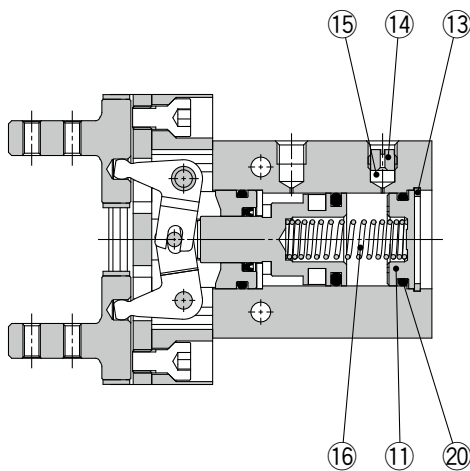
# JMHZ2 Series

## Construction: JMHZ2-8□ to 20□

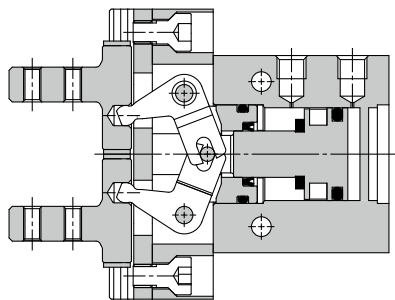
### Double acting, With fingers open



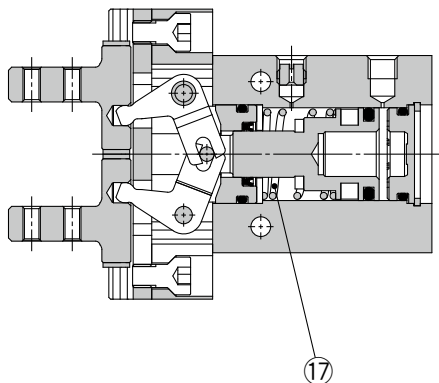
### Single acting, Normally open



### Double acting, With fingers closed



### Single acting, Normally closed



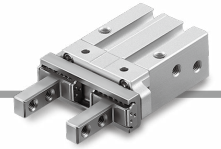
### Component Parts

No.	Description	No.	Description
1	Body A	11	Cap
2	Piston assembly	12	Steel ball
3	Lever	13	Type C retaining ring for hole
4	Guide	14	Exhaust plug A
5	Finger	15	Exhaust filter A
6	Roller stopper	16	N.O. spring
7	Body B	17	N.C. spring
8	Lever shaft	18	Rod seal
9	Seal support	19	Piston seal
10	Rod cover	20	Gasket

### Replacement Parts

Description		JMHZ2-8	JMHZ2-12	JMHZ2-16	JMHZ2-20	Contents
Seal kit	JMHZ2-□□D	JMHZ8-PS	JMHZ12-PS	JMHZ16-PS	JMHZ20-PS	⑱⑲⑳
	JMHZ2-□□S	JMHZ8S-PS	JMHZ12S-PS	JMHZ16S-PS	JMHZ20S-PS	
	JMHZ2-□□C					
Finger assembly	JMHZ2-□□□	JMHZ-A0802	JMHZ-A1202	JMHZ-A1602	JMHZ-A1602	④⑤⑥⑫ Mounting screw
	JMHZ2-□□□1	JMHZ-A0802-1	JMHZ-A1202-1	JMHZ-A1602-1	JMHZ-A1602-1	
	JMHZ2-□□□2	JMHZ-A0802-2	JMHZ-A1202-2	JMHZ-A1602-2	JMHZ-A1602-2	
Piston assembly	JMHZ2-□□D	JMHZ-A0803	JMHZ-A1203	JMHZ-A1603	JMHZ-A2003	②
	JMHZ2-□□S	JMHZ-A0803S	JMHZ-A1203S	JMHZ-A1603S	JMHZ-A2003S	
	JMHZ2-□□C	JMHZ-A0803C				
Lever assembly		JMHZ-A0804	JMHZ-A1204	JMHZ-A1604	JMHZ-A2004	③

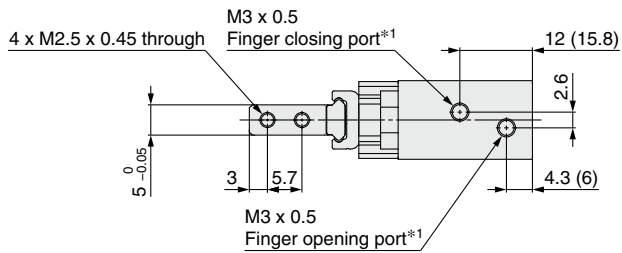
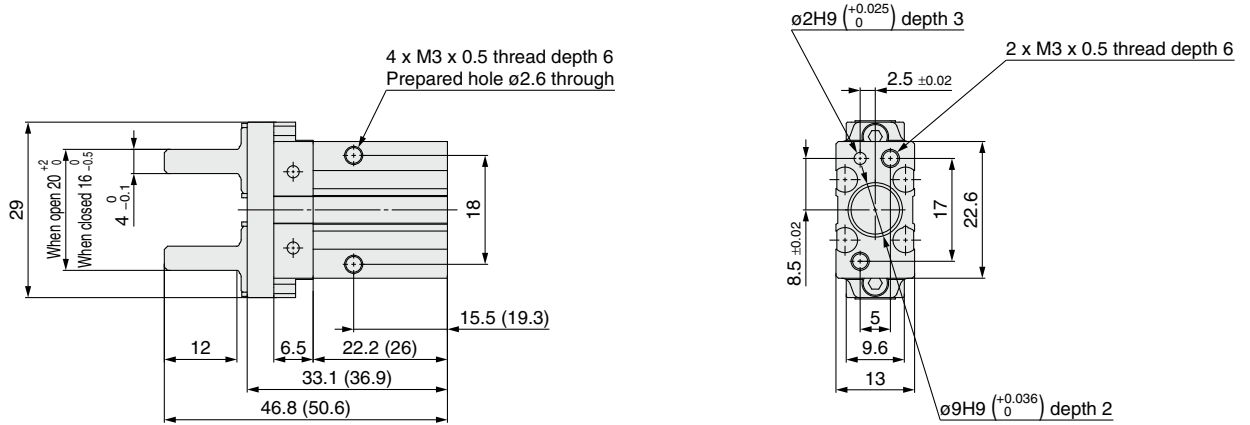
\* Finger option  
1 = Side tapped, 2 = Through-hole  
\* The seal kit does not include a grease pack. Order it separately. Grease pack part number: GR-S-010 (10 g)



## Dimensions

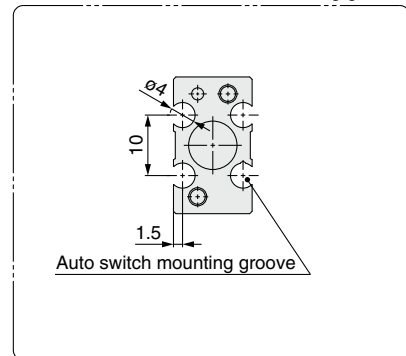
### Basic type: JMHZ2-8□

The values inside ( ) are dimensions for the single acting type.

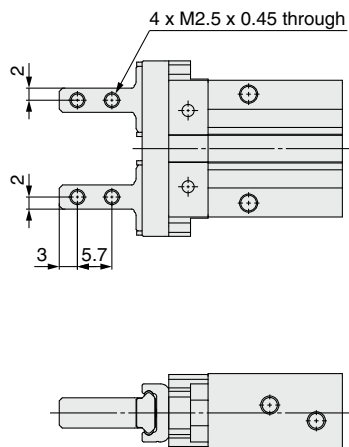


\*1 For single action, the port on one side is a breathing hole.

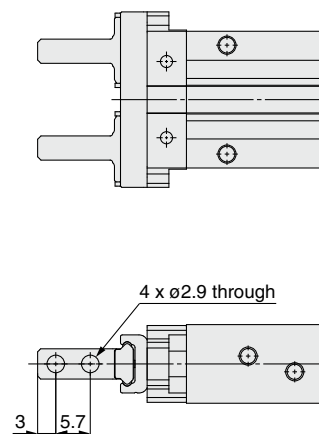
### Dimensions of auto switch mounting groove



### Side tapped mounting JMHZ2-8□1



### Through-holes in opening/closing direction JMHZ2-8□2



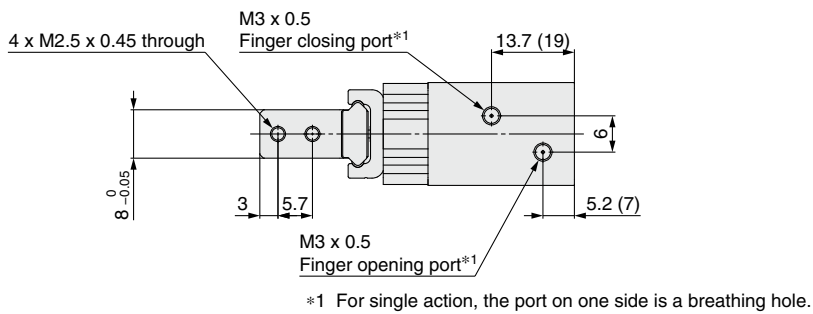
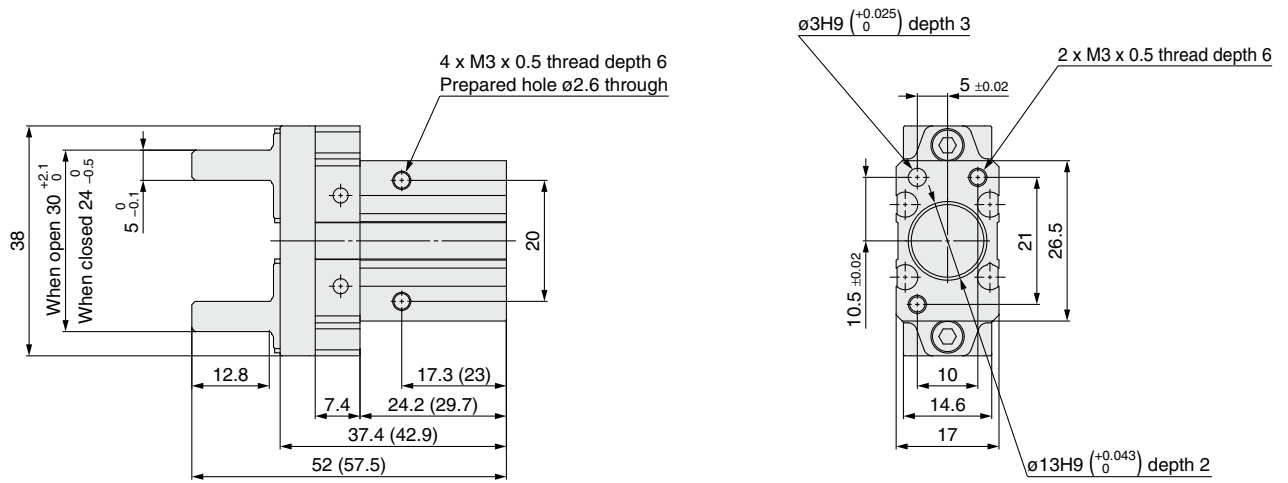
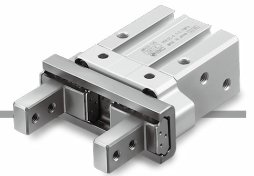


# JMHZ2 Series

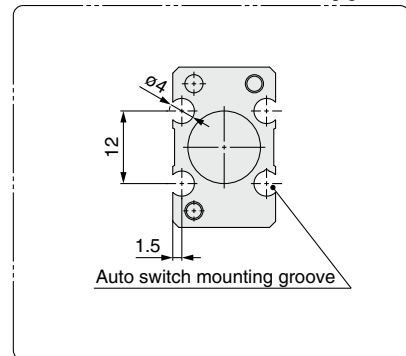
## Dimensions

### Basic type: JMHZ2-12□

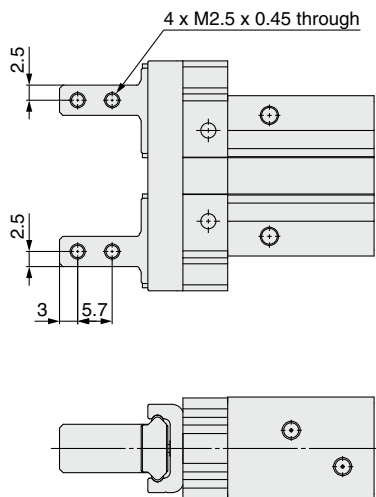
The values inside ( ) are dimensions for the single acting type.



### Dimensions of auto switch mounting groove

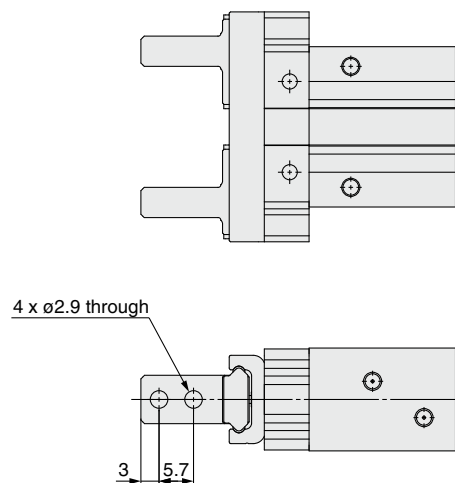


### Side tapped mounting JMHZ2-12□1

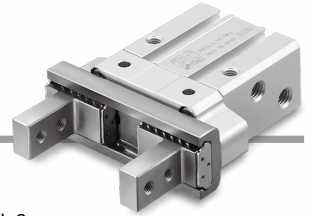


\* Other dimensions are the same as the basic type.

### Through-holes in opening/closing direction JMHZ2-12□2



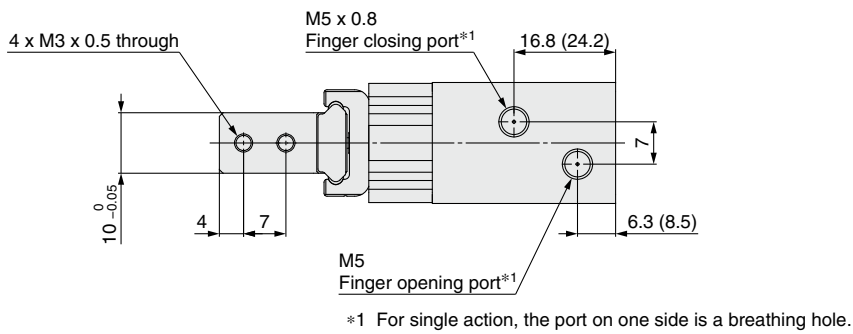
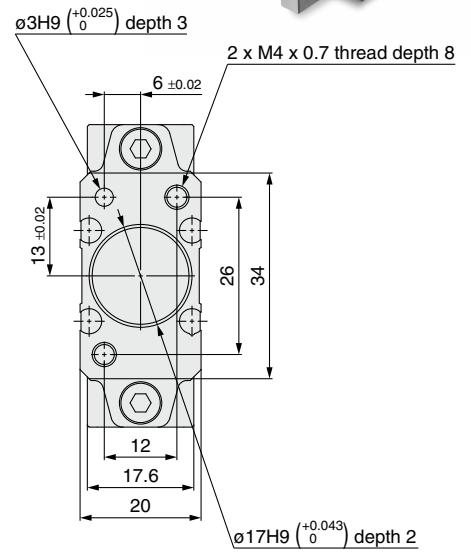
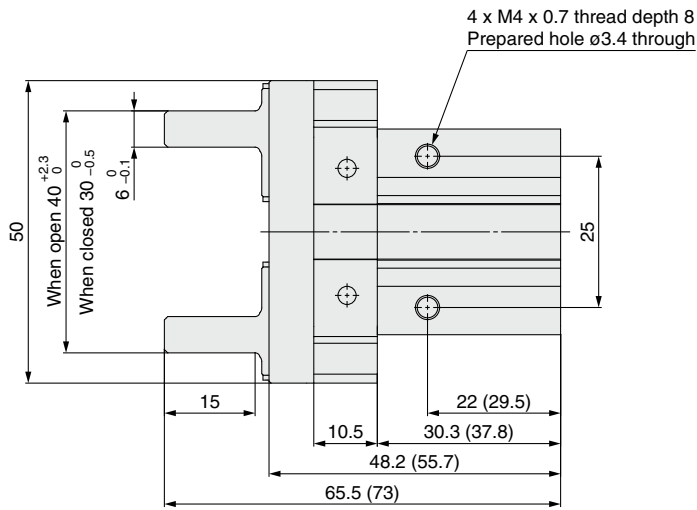
\* Other dimensions are the same as the basic type.



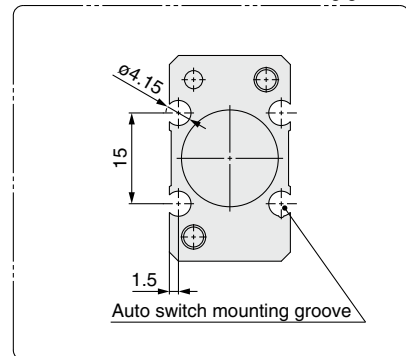
## Dimensions

### Basic type: JMHZ2-16□

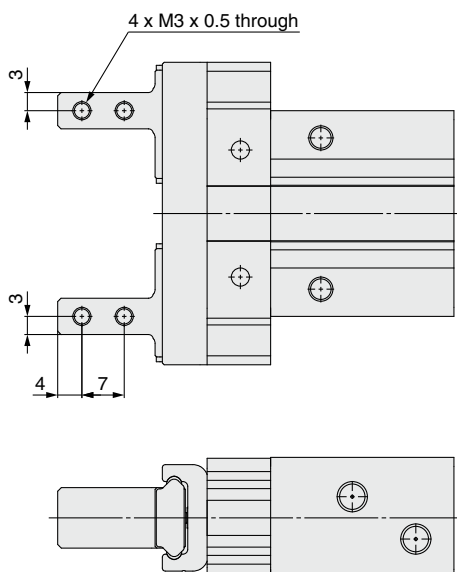
The values inside ( ) are dimensions for the single acting type.



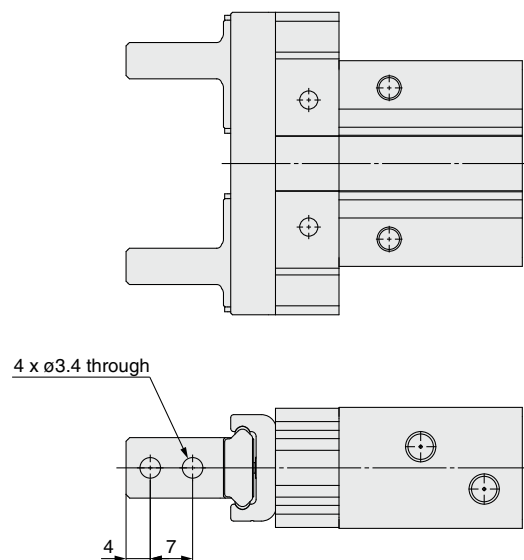
### Dimensions of auto switch mounting groove



### Side tapped mounting JMHZ2-16□1



### Through-holes in opening/closing direction JMHZ2-16□2

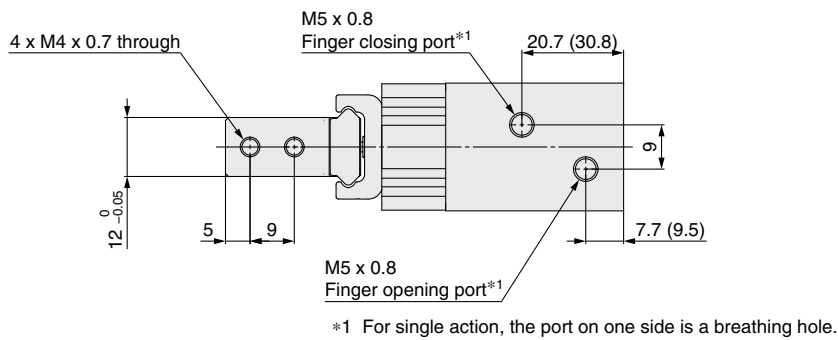
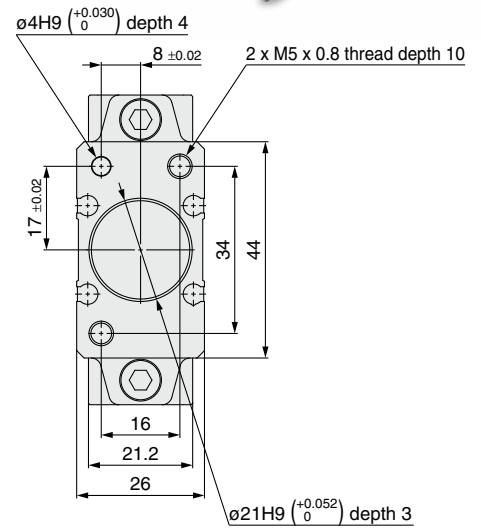
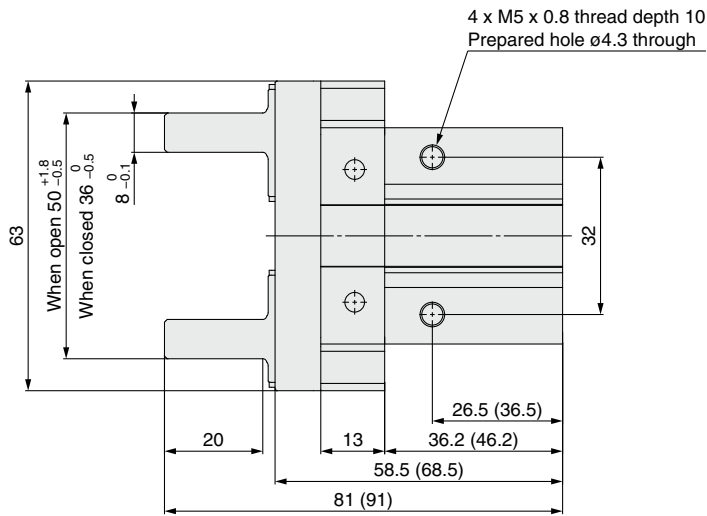
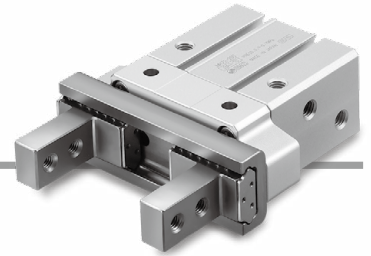


# JMHZ2 Series

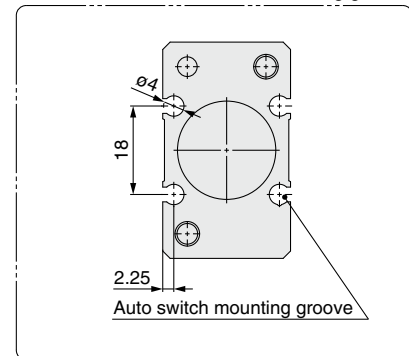
## Dimensions

### Basic type: JMHZ2-20□

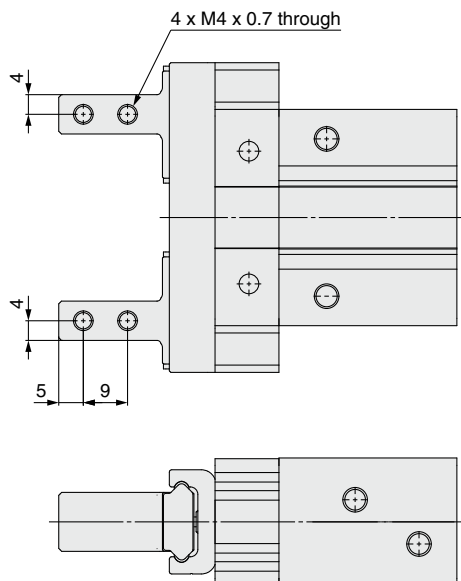
The values inside ( ) are dimensions for the single acting type.



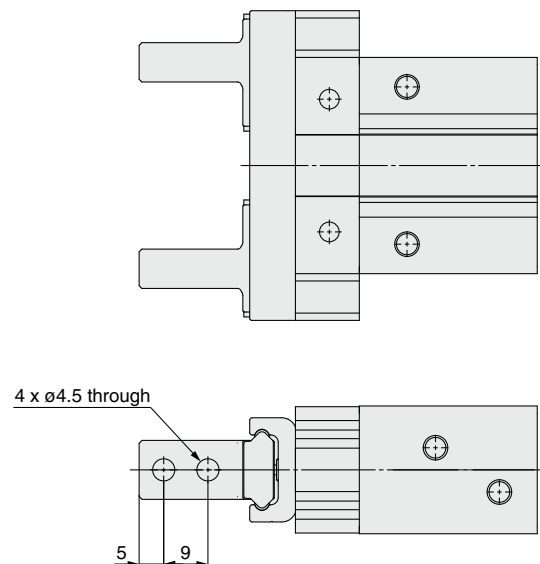
### Dimensions of auto switch mounting groove



### Side tapped mounting JMHZ2-20□1



### Through-holes in opening/closing direction JMHZ2-20□2



\* Other dimensions are the same as the basic type.

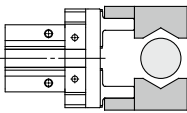
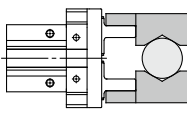
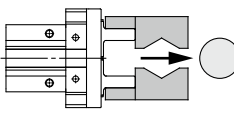
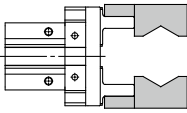
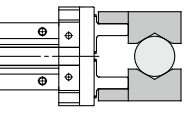
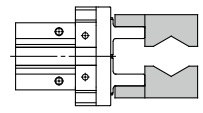
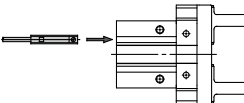
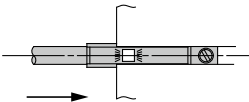
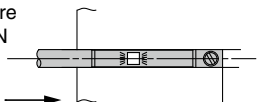
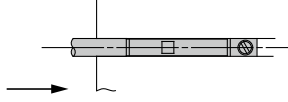
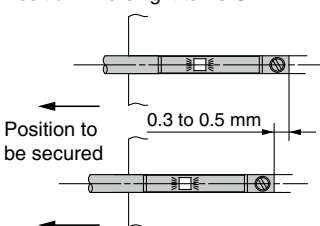
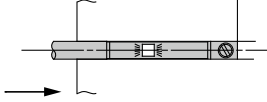
\* Other dimensions are the same as the basic type.

# JMHZ2 Series

## Auto Switch Installation Examples and Mounting Positions

Various auto switch applications are possible through different combinations of auto switch quantities and detecting positions.

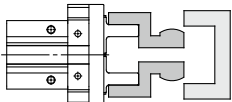
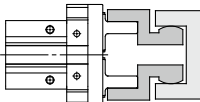
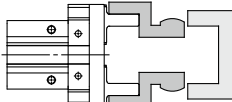
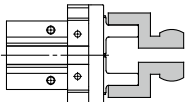
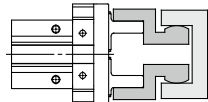
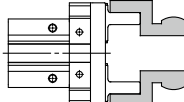
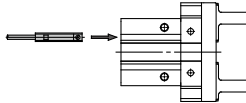
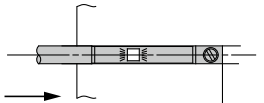
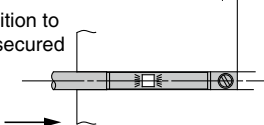
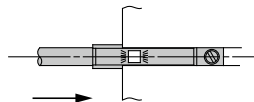
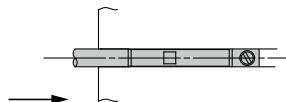
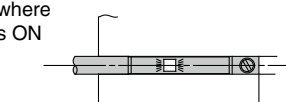
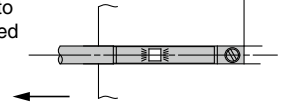
### 1) Detection when Gripping Exterior of a Workpiece

Detection example		① Confirmation of fingers in reset position	② Confirmation of a workpiece held	③ Confirmation of a workpiece released
Position to be detected		Position of fingers fully open 	Position when gripping a workpiece 	Position of fingers fully closed 
Operation of auto switches		When fingers return: Auto switch to turn ON (Light ON)	When gripping a workpiece: Auto switch to turn ON (Light ON)	When a workpiece is not held (Abnormal operation): Auto switch to turn ON (Light ON)
Detection combinations	One auto switch * One position, any of ①, ② and ③ can be detected.	●	●	●
	Two auto switches * Two positions of ①, ② and ③ can be detected.	Pattern	A	●
			B	—
			C	●
How to determine auto switch installation position  At no pressure or low pressure, connect the auto switch to a power supply, and follow the directions.		Step 1) Fully open the fingers. 	Step 1) Position fingers for gripping a workpiece. 	Step 1) Fully close the fingers. 
		Step 2) Insert the auto switch into the auto switch mounting groove in the direction as shown in the illustration below. 		
		Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates. 	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates and fasten it at a position 0.3 to 0.5 mm in the direction of the arrow beyond the position where the indicator light illuminates. 	
		Step 4) Slide the auto switch further in the direction of the arrow until the indicator light goes out. 		
		Step 5) Slide the auto switch in the opposite direction and fasten it at a position 0.3 to 0.5 mm beyond the position where the indicator light illuminates. 	Position where light turns ON 	

- \* It is recommended that gripping of a workpiece be performed close to the center of the finger stroke.
- \* When holding a workpiece close at the end of opening/closing stroke of fingers, detecting performance of the combinations listed in the table above may be limited, depending on the hysteresis of an auto switch, etc.

Various auto switch applications are possible through different combinations of auto switch quantities and detecting positions.

## 2) Detection when Gripping Interior of a Workpiece

Detection example		① Confirmation of fingers in reset position	② Confirmation of a workpiece held	③ Confirmation of a workpiece released
Position to be detected		Position of fingers fully closed 	Position when gripping a workpiece 	Position of fingers fully open 
Operation of auto switches		When fingers return: Auto switch to turn ON (Light ON)	When gripping a workpiece: Auto switch to turn ON (Light ON)	When a workpiece is not held (Abnormal operation): Auto switch to turn ON (Light ON)
Detection combinations	One auto switch * One position, any of ①, ② and ③ can be detected.	●	●	●
	Two auto switches * Two positions of ①, ② and ③ can be detected.	Pattern	A	●
			B	—
			C	●
How to determine auto switch installation position  At no pressure or low pressure, connect the auto switch to a power supply, and follow the directions.		Step 1) Fully close the fingers. 	Step 1) Position fingers for gripping a workpiece. 	Step 1) Fully open the fingers. 
		Step 2) Insert the auto switch into the auto switch mounting groove in the direction as shown in the illustration below. 		
		Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates and fasten it at a position 0.3 to 0.5 mm in the direction of the arrow beyond the position where the indicator light illuminates. Position where light turns ON  0.3 to 0.5 mm Position to be secured 	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates. 	
		Step 4) Slide the auto switch further in the direction of the arrow until the indicator light goes out. 		
		Step 5) Slide the auto switch in the opposite direction and fasten it at a position 0.3 to 0.5 mm beyond the position where the indicator light illuminates. Position where light turns ON  0.3 to 0.5 mm Position to be secured 		

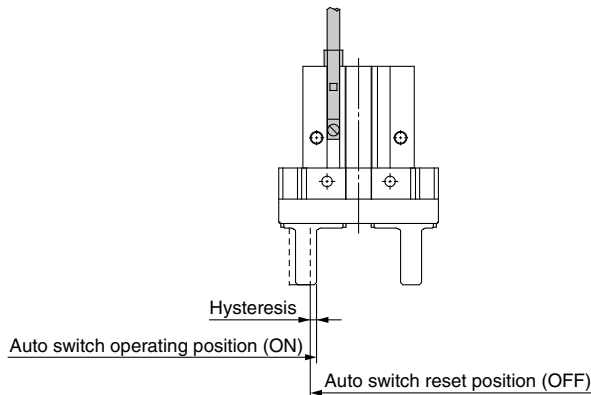
\* • It is recommended that gripping of a workpiece be performed close to the center of the finger stroke.

• When holding a workpiece close at the end of opening/closing stroke of fingers, detecting performance of the combinations listed in the table above may be limited, depending on the hysteresis of an auto switch, etc.



## Auto Switch Hysteresis

Auto switches have hysteresis similar to micro switches. Use the table below as a guide when adjusting auto switch positions, etc.

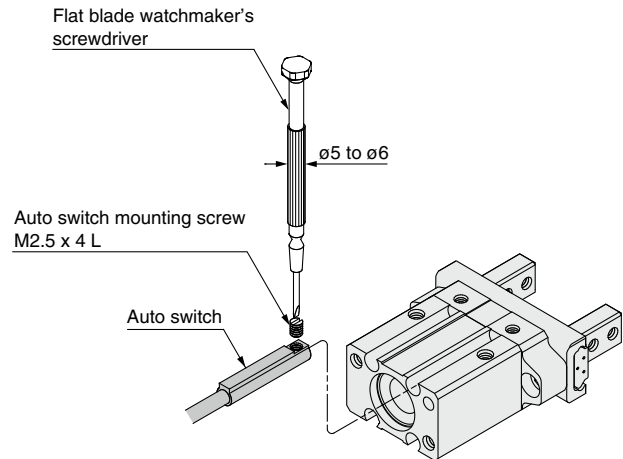


### Hysteresis

Auto switch model	
Model	D-M9□(V) D-M9□W(V) D-M9□A(V)
JMHZ2-8	0.7
JMHZ2-12	0.6
JMHZ2-16	0.7
JMHZ2-20	0.6

## Auto Switch Mounting

To set the auto switch, insert the auto switch into the auto switch installation groove of the gripper from the direction as shown in the illustration below. After setting the position, tighten the attached auto switch mounting screw with a flat blade watchmaker's screwdriver.



\* Use a watchmaker's screwdriver with a grip diameter of 5 to 6 mm to tighten the auto switch mounting screw. Also, tighten with a torque of about 0.05 to 0.15 N·m, or about 0.05 to 0.10 N·m for D-M9□A(V).

## Protrusion of Auto Switch from Edge of Body

The amount of auto switch protrusion from the body end surface is shown in the table below. Use this as a standard when mounting, etc.

### Protrusion of Auto Switch

[mm]

Lead wire type			In-line entry		Perpendicular entry	
Illustration			In-line entry		Perpendicular entry	
Auto switch			In-line entry		Perpendicular entry	
Finger position			In-line entry		Perpendicular entry	
Air gripper model			D-M9□ D-M9□W	D-M9□A	D-M9□V D-M9□WV	D-M9□AV
Double acting	JMHZ2-8D	Open	5	7	3	5
		Closed	7.5	9.5	5.5	7.5
	JMHZ2-12D	Open	3.5	5.5	1.5	3.5
		Closed	7.5	9.5	5.5	7.5
	JMHZ2-16D	Open	—	2.0	—	—
		Closed	5.5	7.5	3.5	5.5
	JMHZ2-20D	Open	—	—	—	—
		Closed	4	6	2	4
Single acting (Normally open)	JMHZ2-8S	Open	1	3	—	1
		Closed	4	6	2	4
	JMHZ2-12S	Open	2	4	—	2
		Closed	6	8	4	6
	JMHZ2-16S	Open	—	—	—	—
		Closed	4	6	2	4
	JMHZ2-20S	Open	—	—	—	—
		Closed	2	4	—	2
Single acting (Normally closed)	JMHZ2-8C	Open	4	6	2	4
		Closed	6	8	4	6
	JMHZ2-12C	Open	2	4	—	2
		Closed	6	8	4	6
	JMHZ2-16C	Open	—	—	—	—
		Closed	4	6	2	4
	JMHZ2-20C	Open	—	—	—	—
		Closed	2	4	—	2

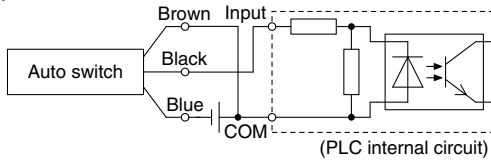
\* There is no protrusion for sections of the table with no values entered.

# Prior to Use

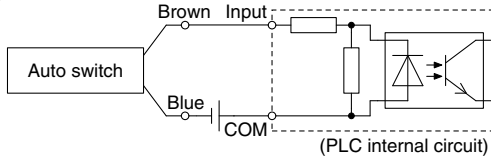
## Auto Switch Connections and Examples

### Sink Input Specifications

#### 3-wire, NPN

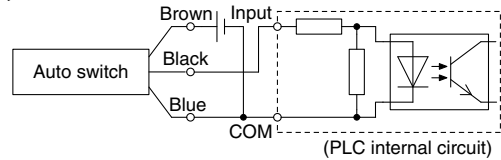


#### 2-wire

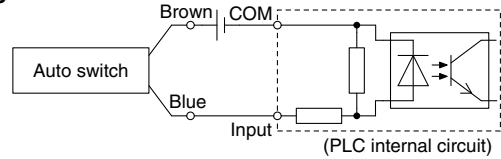


### Source Input Specifications

#### 3-wire, PNP



#### 2-wire



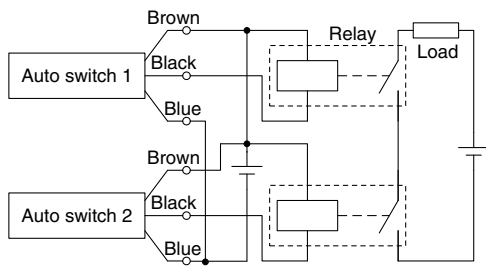
Connect according to the applicable PLC input specifications, as the connection method will vary depending on the PLC input specifications.

### Examples of AND (Series) and OR (Parallel) Connections

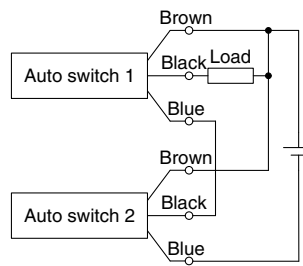
\* When using solid state auto switches, ensure the application is set up so the signals for the first 50 ms are invalid. Depending on the operating environment, the product may not operate properly.

#### 3-wire AND connection for NPN output

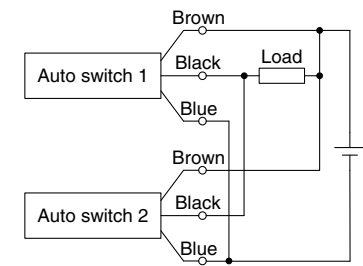
(Using relays)



(Performed with auto switches only)

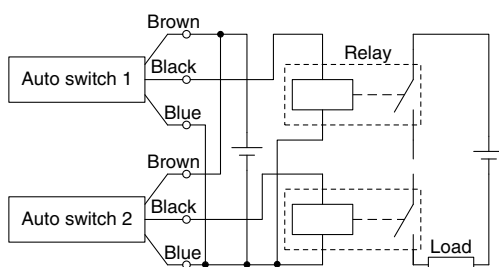


#### 3-wire OR connection for NPN output

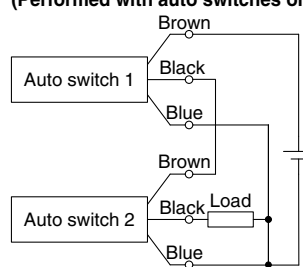


#### 3-wire AND connection for PNP output

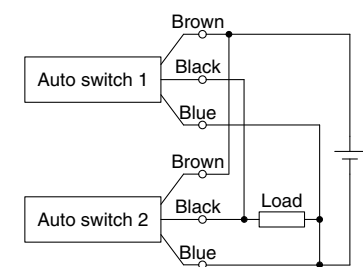
(Using relays)



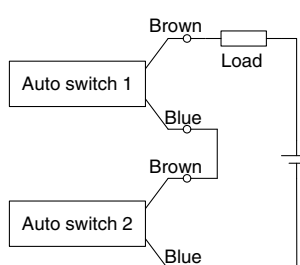
(Performed with auto switches only)



#### 3-wire OR connection for PNP output



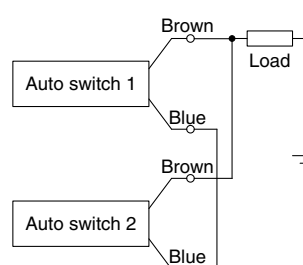
#### 2-wire AND connection



When two auto switches are connected in series, a load may malfunction because the load voltage will decline when in the ON state. The indicator lights will light up when both of the auto switches are in the ON state. Auto switches with a load voltage less than 20 V cannot be used. Please contact SMC if using AND connection for a heat-resistant solid state auto switch or a trimmer switch.

Example) Load voltage at ON  
 Power supply voltage: 24 VDC  
 Internal voltage drop: 4 V  
 Load voltage at ON = Power supply voltage –  
 Internal voltage drop x 2 pcs.  
 = 24 V – 4 V x 2 pcs.  
 = 16 V

#### 2-wire OR connection



Example) Load voltage at OFF  
 Leakage current: 1 mA  
 Load impedance: 3 kΩ  
 Load voltage at OFF = Leakage current x 2 pcs. x  
 Load impedance  
 = 1 mA x 2 pcs. x 3 kΩ  
 = 6 V

(Solid state)  
 When two auto switches are connected in parallel, malfunction may occur because the load voltage will increase when in the OFF state.

(Reed)  
 Because there is no current leakage, the load voltage will not increase when turned OFF. However, depending on the number of auto switches in the ON state, the indicator lights may sometimes grow dim or not light up, due to the dispersion and reduction of the current flowing to the auto switches.

## 1 With Positioning Pins on the Lateral Mounting Surface

Symbol  
**-X6900**

The lever shaft can be extended and used as a positioning pin for lateral mounting.

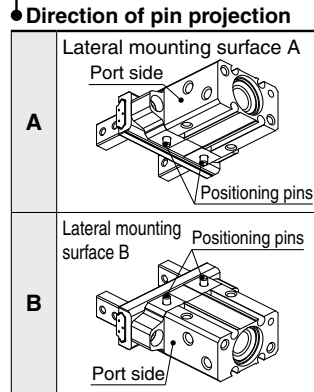
### How to Order

JMHZ2 - **8** **D** **A** - X6900 **A**

Bore size	
8	8 mm
12	12 mm
16	16 mm
20	20 mm

Action	
D	Double acting
S	Single acting (Normally open)
C	Single acting (Normally closed)

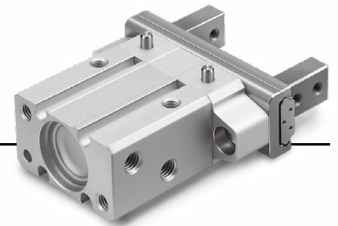
Finger option	
Nil	Standard
1	Side tapped mounting
2	Through-holes in opening/closing direction



### Specifications

Bore size [mm]	8, 12, 16, 20
Pin mounting surface	Lateral mounting surface
Pin diameter	Refer to the dimensions.
Mounting position	Refer to the dimensions.
Other specifications	The same as those of the standard type

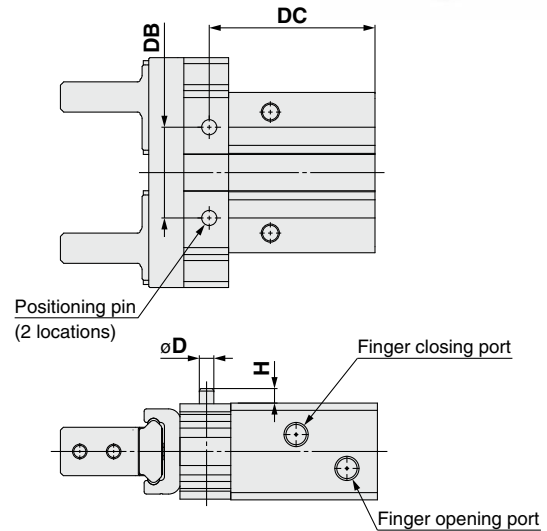
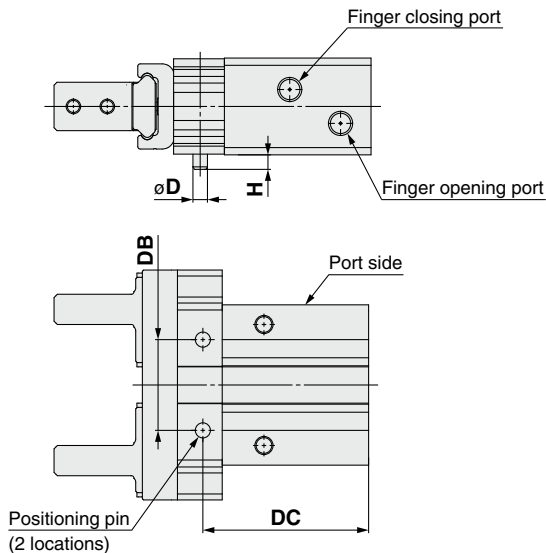
● With positioning pins on the lateral mounting surface



### Dimensions

JMHZ2-□-X6900A

JMHZ2-□-X6900B



Model	øD	H	DB	DC
JMHZ2-8	ø2h8 ( $\begin{smallmatrix} 0 \\ -0.014 \end{smallmatrix}$ )	2.5	12.6 ±0.06	25.5 (29.3)
JMHZ2-12	ø2.5h8 ( $\begin{smallmatrix} 0 \\ -0.014 \end{smallmatrix}$ )	2.5	15 ±0.06	27.4 (32.9)
JMHZ2-16	ø3h8 ( $\begin{smallmatrix} 0 \\ -0.014 \end{smallmatrix}$ )	3	21 ±0.06	35.3 (42.8)
JMHZ2-20	ø4h8 ( $\begin{smallmatrix} 0 \\ -0.018 \end{smallmatrix}$ )	4	27 ±0.06	42.3 (52.3)

\* The values inside ( ) are dimensions for the single acting type.

## 2 Lateral Auto Switch Mounting

Symbol  
**-X7460**

The auto switch can be replaced even when the head side is blocked.

### How to Order

JMHZ2 - **8** D **-X7460**

Bore size	
8	8 mm
12	12 mm
16	16 mm
20	20 mm

• Lateral auto switch mounting

#### Finger option

Nil	Standard
1	Side tapped mounting
2	Through-holes in opening/closing direction

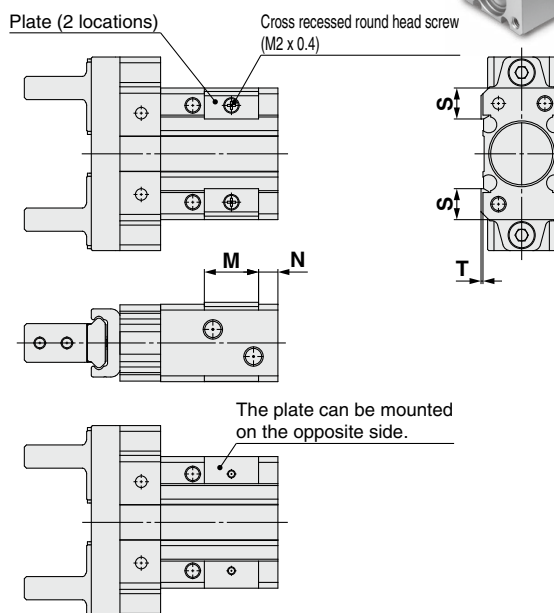
#### Action

D	Double acting
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### Specifications

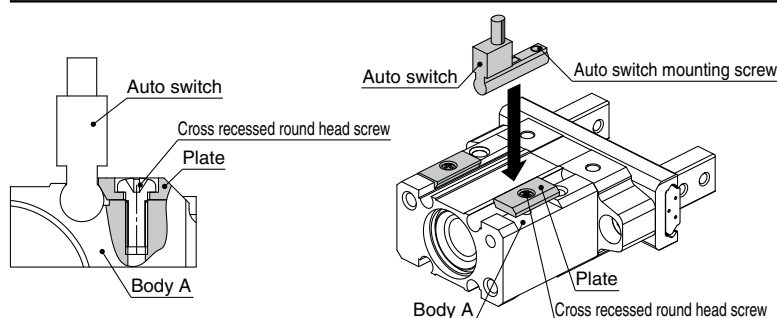
Mounting	Plate mounting (Exclusive body)
Mounting position	Lateral mounting surface (2 surfaces)
Other specifications	The same as those of the standard type

### Dimensions



Model	N	M	S	T
JMHZ2-8	1.2	12	4.8	0.5
JMHZ2-12	3	12	5.75	0.5
JMHZ2-16	5	14	8	0.5
JMHZ2-20	8	14	11.5	—

### Auto Switch Replacement



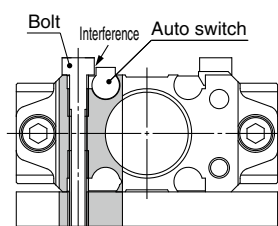
#### Auto Switch Replacement

- Loosen the cross recessed round head screw to create a gap between the plate and body A, and then replace the auto switch.
- When tightening the cross recessed round head screw, be careful not to press the auto switch housing with the plate. (To secure the auto switch, tighten the auto switch mounting screw.)
- The tightening torque for cross recessed round head screws should be approximately 0.09 to 0.15 N·m.

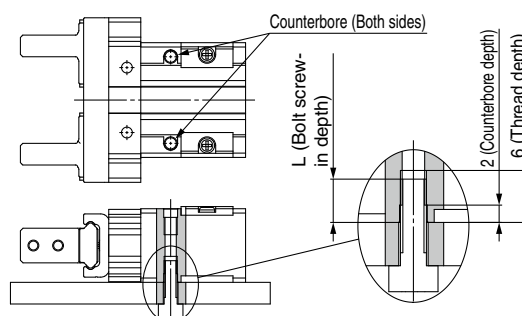
### Mounting Precautions

#### ⚠ Caution

- For bore sizes 8 to 16, the auto switch interferes with the bolt for through-hole mounting, so it cannot be replaced from the plate side.



- There are counterbores for bore sizes 8 and 12. Select the bolt length so that the screw-in depth L will be 5 to 6 mm.





## Operating Environment

## Handling

Finite orbit type guide is used in the actuator finger part. By using this, when there are inertial force which cause by movements or rotation to the actuator, steel ball will move to one side and this will cause a large resistance and degrade the accuracy. When there are inertial force which cause by movements or rotation to the actuator, operate the finger to full stroke.

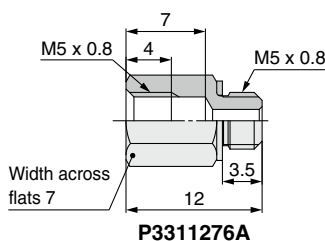
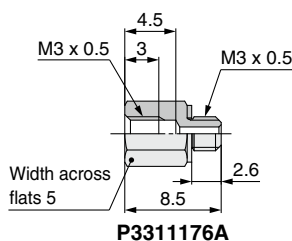
Use the hole at the end of the body for positioning, etc.

Model	Hole diameter	Hole depth [mm]
JMHZ2-8	$\varnothing 9H9^{+0.036}_0$	2
JMHZ2-12	$\varnothing 13H9^{+0.043}_0$	2
JMHZ2-16	$\varnothing 17H9^{+0.043}_0$	2
JMHZ2-20	$\varnothing 21H9^{+0.052}_0$	3

Attachment

A long or heavy attachment increases the inertia force required to open or close the fingers. This may cause unsteady movement of fingers and decrease the life of the gripper. Design the attachment as short and light as possible referring to the mass specified in the table below.


Model	Extension fitting
<b>JMHZ2-8</b>	P3311176A
<b>JMHZ2-12</b>	
<b>JMHZ2-16</b>	P3311276A
<b>JMHZ2-20</b>	







## Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of “**Caution**,” “**Warning**” or “**Danger**.” They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC)\*1), and other safety regulations.

 **Caution:** **Caution** indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.

 **Warning:** **Warning** indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.

 **Danger :** **Danger** indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.

\*1) ISO 4414: Pneumatic fluid power – General rules relating to systems.  
ISO 4413: Hydraulic fluid power – General rules relating to systems.  
IEC 60204-1: Safety of machinery – Electrical equipment of machines.  
(Part 1: General requirements)  
ISO 10218-1: Manipulating industrial robots – Safety.  
etc.

### Warning

#### 1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications.

Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results. The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product. This person should also continuously review all specifications of the product referring to its latest catalog information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

#### 2. Only personnel with appropriate training should operate machinery and equipment.

The product specified here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained and experienced.

#### 3. Do not service or attempt to remove product and machinery/equipment until safety is confirmed.

1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.
2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant products carefully.
3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.

#### 4. Contact SMC beforehand and take special consideration of safety measures if the product is to be used in any of the following conditions.

1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
2. Installation on equipment in conjunction with atomic energy, railways, air navigation, space, shipping, vehicles, military, medical treatment, combustion and recreation, or equipment in contact with food and beverages, emergency stop circuits, clutch and brake circuits in press applications, safety equipment or other applications unsuitable for the standard specifications described in the product catalog.
3. An application which could have negative effects on people, property, or animals requiring special safety analysis.
4. Use in an interlock circuit, which requires the provision of double interlock for possible failure by using a mechanical protective function, and periodical checks to confirm proper operation.

### Caution

#### 1. The product is provided for use in manufacturing industries.

The product herein described is basically provided for peaceful use in manufacturing industries.  
If considering using the product in other industries, consult SMC beforehand and exchange specifications or a contract if necessary.  
If anything is unclear, contact your nearest sales branch.

## Limited warranty and Disclaimer/ Compliance Requirements

The product used is subject to the following “Limited warranty and Disclaimer” and “Compliance Requirements”.

Read and accept them before using the product.

### Limited warranty and Disclaimer

1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered, whichever is first.\*2)  
Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.
2. For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided.  
This limited warranty applies only to our product independently, and not to any other damage incurred due to the failure of the product.
3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalog for the particular products.

#### \*2) Vacuum pads are excluded from this 1 year warranty.

A vacuum pad is a consumable part, so it is warranted for a year after it is delivered.  
Also, even within the warranty period, the wear of a product due to the use of the vacuum pad or failure due to the deterioration of rubber material are not covered by the limited warranty.

### Compliance Requirements

1. The use of SMC products with production equipment for the manufacture of weapons of mass destruction (WMD) or any other weapon is strictly prohibited.
2. The exports of SMC products or technology from one country to another are governed by the relevant security laws and regulations of the countries involved in the transaction. Prior to the shipment of a SMC product to another country, assure that all local rules governing that export are known and followed.

### Caution

#### SMC products are not intended for use as instruments for legal metrology.

Measurement instruments that SMC manufactures or sells have not been qualified by type approval tests relevant to the metrology (measurement) laws of each country. Therefore, SMC products cannot be used for business or certification ordained by the metrology (measurement) laws of each country.

### Revision History

- Edition B** \* A single acting type has been added.  
\* Made-to-order options have been added:  
① With positioning pins on the lateral mounting surface  
② Lateral auto switch mounting

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## Safety Instructions

Be sure to read the “Handling Precautions for SMC Products” (M-E03-3) and “Operation Manual” before use.